

# Handout 3

## Empirical Bayes (continued). Computing Bayesian estimators

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### 1 Empirical Bayes (ANOVA)(required)<sup>1</sup>.

**James-Stein (revisited).** Suppose  $\bar{X} = (\bar{X}_1, \bar{X}_2, \dots, \bar{X}_p)$  has a  $p$ -variate normal distribution with known  $\sigma_n^2 = \sigma^2/n$ . That is

$$\bar{X}_i \sim N(\mu_i, \sigma^2/n) \quad i = 1, 2, \dots, p \quad (1.1)$$

$$\mu_i \sim N(0, \tau^2) \quad i = 1, 2, \dots, p \text{ independent} \quad (1.2)$$

The Bayesian estimator of  $\theta$  is

$$\delta_i^B(\bar{X}) := \mathbb{E}[\theta \mid \bar{X}] = \frac{\tau^2}{\tau^2 + \sigma_n^2} \bar{X}_i, \quad i = 1, 2, \dots, p.$$

The Bayesian estimator requires plugging in a value of  $\tau^2$ . The empirical Bayesian agrees with the Bayes model but refuses to specify values of  $\tau^2$ . Instead, it estimates  $\tau^2$ . In the last lecture, we considered using MLE to estimate  $\tau^2$ .

For the today's lecture, we will consider an unbiased estimator of  $\frac{\sigma^2}{\tau^2 + \sigma^2}$  instead. Define the James-Stein estimator as

$$\delta_i^{JS}(X) = \left(1 - \frac{(p-2)\sigma_n^2}{\|\bar{X}\|^2}\right) \bar{X}_i, \quad i = 1, 2, \dots, p.$$

Recall that James-Stein was introduced as an estimator whose frequentist risk is smaller than MLE for all values of  $\mu$ . However, in practice shrinkage to zero may be a poor choice if  $\|\mathbb{E}[X]\|$  is very far from zero. Instead, we may want to estimate the shrinkage point from the data. The next example elaborates on this.

**One-way Analysis of Variance (ANOVA).** Consider the many means model

$$X_{ij} \sim N(\mu_i, \sigma^2) \quad j = 1, 2, \dots, n \text{ independent}, \quad i = 1, 2, \dots, p \quad (1.3)$$

$$\mu_i \sim N(\mu, \tau^2) \quad i = 1, 2, \dots, p \text{ independent} \quad (1.4)$$

The goal is to estimate  $\mu = (\mu_1, \mu_2, \dots, \mu_p) \in \mathbb{R}^p$ . Similar to (1.1)-(1.2), we postulate a common mean for  $\mu_i$ , but unlike (1.2), we refuse to specify its exact value. The MLE (**unrestricted**) estimator of  $\mu$  is a vector of group specific means

$$\bar{X}_i := n^{-1} \sum_{j=1}^n X_{ij}, \quad i = 1, 2, \dots, p.$$

The unrestricted estimator does not require specification of the prior (1.4). The frequentist risk of MLE estimator of  $p\sigma_n^2 = p/n\sigma^2$ .

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<sup>1</sup>This section is based on Lehmann and Casella, Chapter 4.6.

1. **Both  $\mu$  and  $\tau^2$  known.** Next, consider imposing the prior distribution (1.4). This prior is similar to (1.2), except the prior mean  $\mu$  may not be zero. Assuming both  $\mu$  and  $\sigma^2$  are known, the Bayes posterior mean for each  $i$  is

$$\delta_i^B(\bar{X}) = \frac{\sigma_n^2}{\sigma_n^2 + \tau^2} \mu + \frac{\tau^2}{\sigma_n^2 + \tau^2} \bar{X}_i, \quad i = 1, 2, \dots, p,$$

which is a weighted average of MLE (unrestricted estimator)  $\bar{X}$  and the common (known) mean  $\mu$ .

2.  **$\mu$  is unknown,  $\tau^2$  is known.** If  $\mu$  is unknown, we replace it by MLE. The MLE of  $\mu$  is the full sample mean

$$\bar{\bar{X}} := p^{-1} \sum_{i=1}^p \bar{X}_i = (np)^{-1} \sum_{i=1}^p \sum_{j=1}^n X_{ij}.$$

The Empirical Bayes estimator is

$$\delta_i^{EB}(\bar{X}) := \frac{\sigma_n^2}{\sigma_n^2 + \tau^2} \bar{\bar{X}} + \frac{\tau^2}{\sigma_n^2 + \tau^2} \bar{X}_i, \quad i = 1, 2, \dots, p.$$

which is a weighted average of MLE (unrestricted estimator)  $\bar{X}$  and the grand mean  $\bar{\bar{X}}$  (restricted estimator).

3. **Both  $\mu$  and  $\tau^2$  unknown.** The  $\delta_i^{EB}$  takes the form

$$\delta_i^L(\bar{X}) := \bar{\bar{X}} + \left( 1 - \frac{(p-3)\sigma_n^2}{p^{-1} \sum_{i=1}^p (\bar{X}_i - \bar{\bar{X}})^2} \right) (\bar{X}_i - \bar{\bar{X}}).$$

, which was first derived by Lindley (1962) and examined in detail by Efron and Morris (1972a 1972b, 1973a, 1973b).

**ANOVA with a regression submodel.** Shrinking to a common mean (1.4) may still be restrictive. If we have observed covariates, we may allow the shrinkage point to vary with observed covariates.

$$\begin{aligned} X_{ij} &\sim N(\mu_i, \sigma^2) \quad j = 1, 2, \dots, n, \quad i = 1, 2, \dots, p \text{ independent} \\ \mu_i &\sim N(\alpha + \beta t_i, \tau^2) \quad i = 1, 2, \dots, p \text{ independent} \end{aligned}$$

where  $t = (t_1, t_2, \dots, t_p)$  is a vector of observed characteristics. Take

$$\bar{t} := p^{-1} \sum_{i=1}^p t_i.$$

The Bayes estimator of  $\mu_i$  is calculated assuming the parameters are known. The (partial) empirical Bayesian agrees with the Bayes model but refuses to specify values of  $\alpha$  and  $\beta$  (but assumes  $\tau^2$  is known). Instead, we estimate  $\alpha$  and  $\beta$  using MLE. This method has two steps:

1. Derive the likelihood function of  $\bar{X}_i$  as a function of  $\alpha$  and  $\beta$ . For each  $i = 1, 2, \dots, p$ ,

$$\bar{X}_i \sim N(\alpha + \beta t_i, \tau^2 + \sigma_n^2), \quad i = 1, 2, \dots, n.$$

2. Specify the total likelihood function for  $\bar{X} = (\bar{X}_1, \dots, \bar{X}_p)$ . It is equal to

$$\prod_{i=1}^p f_{\bar{X}_i}(\bar{x}_i \mid \alpha, \beta) \sim \prod_{i=1}^p \frac{1}{(\sqrt{2\pi\sigma_n^2})^p} \exp^{-(\bar{x}_i - \alpha - \beta t_i)^2 / 2\sigma_n^2}$$

3. The negative log likelihood is a convex function of  $\alpha, \beta$

$$\sum_{i=1}^p (\bar{x}_i - \alpha - \beta \bar{t}_i)^2.$$

Taking FOC conditions gives the OLS estimators of  $\alpha$  and  $\beta$ :

$$\hat{\alpha} = \bar{\bar{X}} - \hat{\beta} \bar{\bar{t}}, \quad \hat{\beta} := \frac{\sum_{i=1}^p (\bar{X}_i - \bar{\bar{X}})(\bar{t}_i - \bar{\bar{t}})}{\sum_{i=1}^p (\bar{t}_i - \bar{\bar{t}})^2}.$$

1. **Both  $\alpha$  and  $\beta$  and  $\tau^2$  known.** The Bayes estimator of  $\mu_i$  is

$$\delta_i^B(\bar{X}) = \frac{\sigma_n^2}{\sigma_n^2 + \tau^2}(\alpha + \beta \bar{t}_i) + \frac{\tau^2}{\sigma_n^2 + \tau^2} \bar{X}_i, \quad i = 1, 2, \dots, p.$$

2.  **$\alpha$  and  $\beta$  are unknown;  $\tau^2$  is known.** The empirical Bayes estimator is

$$\delta_i^{EB1}(\bar{X}) := \frac{\sigma_n^2}{\sigma_n^2 + \tau^2}(\hat{\alpha} + \hat{\beta} \bar{t}_i) + \frac{\tau^2}{\sigma_n^2 + \tau^2} \bar{X}_i, \quad i = 1, 2, \dots, p.$$

3. **Both  $\alpha$  and  $\beta$  and  $\tau^2$  unknown.** Here, we replace  $\frac{\sigma_n^2}{\sigma_n^2 + \tau^2}$  by an unbiased estimator. The empirical Bayes estimator is

$$\delta_i^{EB2}(\bar{X}) := \hat{\alpha} + \hat{\beta} \bar{t}_i + \left( 1 - \frac{(p-4)\sigma_n^2}{p^{-1} \sum_{i=1}^p (\bar{X}_i - \hat{\alpha} - \hat{\beta} \bar{t}_i)^2} \right) (\bar{X}_i - \hat{\alpha} - \hat{\beta} \bar{t}_i).$$

## 2 Computing Bayesian Estimators.

### 2.1 Acceptance-Rejection Sampling. (Required).

Posterior distribution is key to construct Bayes estimators. However, posterior distribution

$$\pi(\theta|x) = \frac{f(x|\theta)\pi(\theta)}{\int_{\tilde{\theta}} f(x|\tilde{\theta})\pi(\tilde{\theta})d\tilde{\theta}}$$

is often difficult to compute: denominator is intractable. Do not calculate the posterior. Simulate from the posterior! Generate a random sample  $\theta_1, \theta_2, \dots, \theta_B$  from  $\pi(\theta | \text{data})$   $B$  times.

$$\frac{1}{B} \sum_{b=1}^B \theta_i \rightarrow \mathbb{E}[\theta | \text{data}]$$

Notation

- $\pi$  - the target distribution, which we want to simulate from
- $q$  - the distribution we CAN simulate from
- $\pi(x) = f(x)/k$  is known up to constant
- there exists  $c$  such that  $f(x) \leq cq(x)$

Clever ways to get from  $q$  to  $\pi$ :

- (1) Draw from  $q$ , but discard some draws (A-R)

- (2) Draw from  $q$ . Discarding a draw means staying at the present (current) draw. Accepting a draw means moving to the proposed state (MCMC).

Goal is to simulate  $\xi \sim \pi(x)$ . But  $\pi(x)$  has an intractable (cannot be evaluated) denominator. Acceptance-Rejection algorithm is

1. Draw  $z \sim q(\cdot)$ ,  $u \sim U[0, 1]$  independently
2. If  $u \leq \frac{f(z)}{cq(z)}$ , accept  $\xi = z$ . Otherwise, discard the draw.

Let  $\xi$  be the first draw in the retained pool that is not rejected. The CDF of  $\xi$  is

$$\Pr(\xi \leq x) = \Pr\left(z_1 \leq x, u_1 \leq \frac{f(z_1)}{cq(z_1)}\right) \quad (2.1)$$

$$+ \Pr\left(\text{first draw rejected}, z_2 \leq x, u_2 \leq \frac{f(z_2)}{cq(z_2)}\right) + \dots + \Pr\left(k-1 \text{ draw rejected}, z_k \leq x, u_k \leq \frac{f(z_k)}{cq(z_k)}\right) + \dots \quad (2.2)$$

For each  $k$ , the draw  $(z_k, u_k)$  is independent of prior history of acceptance and rejections. That is,

$$\Pr\left(k-1 \text{ draw rejected}, z_k \leq x, u_k \leq \frac{f(z_k)}{cq(z_k)}\right) = \bar{\rho}^{k-1} \Pr\left(z_k \leq x, u_k \leq \frac{f(z_k)}{cq(z_k)}\right). \quad (2.3)$$

Furthermore, the draws  $(z_k, u_k)$  have identical distribution irrespective of prior history of acceptance and rejections. Therefore,

$$\begin{aligned} \Pr(\xi \leq x) &= \Pr\left(z \leq x, u \leq \frac{f(z)}{cq(z)}\right) (1 + \bar{\rho} + \bar{\rho}^2 + \dots) \\ &= \frac{1}{1 - \bar{\rho}} \int_{-\infty}^x \frac{f(z)}{cq(z)} q(z) dz \\ &= \frac{1}{1 - \bar{\rho}} \int_{-\infty}^x \frac{f(z)}{cq(z)} q(z) dz \\ &= \frac{1}{c(1 - \bar{\rho})} \int_{-\infty}^x f(z) dz. \end{aligned}$$

A-R algorithm is

1. Draw  $z \sim q(\cdot)$ ,  $u \sim U[0, 1]$  independently
2. If  $u \leq \frac{f(z)}{cq(z)}$ , accept  $\xi = z$ . Otherwise, discard the draw.

Problems with A-R algorithm:

- if we choose  $c$  and  $q(z)$  poorly, then  $f(z)/cq(z)$  could be very small for many  $z$
- small  $f(z)/cq(z)$  means we have to reject many draws before we accept one

Difficult to choose  $c$  and  $q(z)$  when we do not know much about  $\pi(z)$ . Rarely used in practice. A more sophisticated version of A-R is MCMC (Markov Chain Monte Carlo) sampling method, which is optional in this course.

## 2.2 Markov Chain Monte Carlo (Optional)

Same as in the earlier section, the goal is to simulate from the posterior distribution  $\pi$  but  $\pi$  is the target density that has no closed form because the denominator is intractable. We can only compute the numerator  $f(x)$  where  $\pi(x) = f(x)/k$ . In Acceptance-Rejection method, each draw  $(z, u)$  is independent of the past draws. Relying on independence has substantially simplified the theoretical argument (see (2.3)). However, a cost of independence is that we cannot use past draws to decide where/how to sample the next draw, which may lead to inefficient (time-consuming) sampling.

A MCMC method sacrifices the independence property (2.3) in favor of using proposal distribution that depend on the past state. A sequence of draws from the proposal distribution is no longer independent, but is a Markov chain. Below, I define some basic quantities of a Markov chain.

**Definition 1** (Markov chain). *A sequence  $\{x_t\}$  is a first-order Markov chain if for any set  $A$*

$$P(x_{t+1} \in A \mid x_t = x, x_{t-1}, \dots) = P(x_{t+1} \in A \mid x_t = x). \quad (2.4)$$

**Definition 2** (Transition kernel). *The function*

$$P(x, A) := P(x_t \in A \mid x_{t-1} = x)$$

*is a transition kernel. Let  $q(x, y)$  be a proposal distribution of sampling the next state  $y$  given the current state  $x$ . The transition kernel  $P(x, A)$  corresponding to  $q(x, y)$  is*

$$P(x, A) := \int_{y \in A} q(x, y) dy \quad (2.5)$$

**Definition 3** (Invariant distribution). *A distribution  $\pi^*$  is an invariant distribution for the kernel  $P(x, A)$  if*

$$\pi^*(y) dy = \int_R \pi^*(x) P(x, dy) dx. \quad (2.6)$$

With a large number of draws, the Markov chain converges to its invariant distribution. A classic Markov problem is to find  $\pi^*$  given the transition kernel  $P(x, A)$ . Our problem is reverse problem - to find transition kernel  $P(x, A)$  so that the target  $\pi$  distribution is its invariant distribution:

$$\pi^* = \pi.$$

A sufficient condition for the distribution  $\pi$  to be invariant for the kernel  $P(x, A)$  is to obey reversibility condition:

$$\pi(x)q(x, y) = \pi(y)q(y, x). \quad (2.7)$$

**Lemma 1.** *If  $q(x, y)$  obeys (2.7),  $\pi^* = \pi$  obeys (2.6) with  $P(x, A)$  in (2.5).*

*Proof.* We need to check that  $\pi$  satisfies definition of invariant distribution. For any set  $A$

$$\begin{aligned} \int_R \pi^*(x) P(x, dy) dy dx &= \int_R \pi^*(x) q(x, y) dy dx = \int_R \pi^*(y) q(y, x) dy dx \\ &= \pi^*(y) \left( \int_R q(y, x) dx \right) dy \\ &= \pi^*(y) \cdot (1) dy. \end{aligned}$$

□

Note that the condition (2.7) requires knowing  $\pi(x)$  up to the denominator. Indeed, (2.7) holds if and only if

$$f(x)q(x, y) = f(y)q(y, x). \quad (2.8)$$

which we can verify. If we can find  $q(x, y)$  such that (2.7) holds, then, sampling a Markov chain from the proposal distribution  $q(y, x)$  gives the target distribution in the limit.

In most cases, the proposal distribution  $q(x, y)$  may not obey (2.8). Does it mean we should discard  $q(x, y)$ ? No! We can borrow some idea from Acceptance-Rejection method. Let

- $x$  is the current draw
- $y$  is the next candidate draw from  $q(x, \cdot)$  (move  $x \rightarrow y$ )
- w.p.  $r(x)$ , accept  $y$ . w.p.  $1 - r(x)$ , stay at  $x$  and discard  $y$  (stay  $x \rightarrow x$ )

Our goal is to find  $q(x, y)$  and  $r(x)$  so that the limiting distribution of the chain is  $\pi$ .

For a given  $x, y$ , suppose (2.8) fails and  $f(x)q(x, y) > f(y)q(y, x)$ . Introduce ratio function  $\alpha(x, y)$  is

$$\pi(x)q(x, y)\alpha(x, y) = \pi(y)q(y, x)\alpha(y, x),$$

Define

$$\alpha(x, y) = \min \left\{ 1, \frac{\pi(y)q(y, x)}{\pi(x)q(x, y)} \right\}.$$

Since  $\alpha(y, x) < 1$ , the probability of move is less than one

$$\int q(y, x)\alpha(y, x)dy = r(x) < 1.$$

Define the probability of stay at  $x$  is

$$1 - r(x) = 1 - \int q(y, x)\alpha(y, x)dy$$

$P(x, dy)$  is a valid transition kernel

$$P(x, dy) = q(y, x)\alpha(y, x)dy + r(x)\delta_x(dy)$$

Indeed,  $\int_R P(x, dy) = 1$  since  $\int_R q(y, x)\alpha(y, x)dy = 1 - r(x)$  and  $r(x) \int_R \delta_x(dy) = r(x) \cdot 1$

**Definition 4** (Metropolis-Hastings algorithm). *Given a draw  $x_t$ , the next draw  $x_{t+1}$  is generated as*

1. Draw  $y$  from  $q(x_t, \cdot)$
2. Calculate  $\alpha(x_t, y) = \min \left\{ 1, \frac{f(y)q(y, x_t)}{f(x_t)q(x_t, y)} \right\}$
3. Draw  $u \sim U[0, 1]$
4. If  $u < \alpha(x_t, y)$ , then  $x_{t+1} = y$ . Otherwise,  $x_{t+1} = x_t$ .

**Lemma 2.** *The proposal distribution  $q(y, x)\alpha(y, x)$  obeys reversibility condition for  $\pi$  (2.7).*

*Proof.*

$$\begin{aligned} \int \pi(x)P(x, A)dx &= \int \left( \int_A p(x, y)dy \right) \pi(x)dx + \int (1 - r(x))\delta_x(A)\pi(x)dx \\ &= \int_A \int p(x, y)\pi(x)dx dy + \int_A (1 - r(x))\pi(x)dx \\ &= \int_A \int p(y, x)\pi(y)dx dy + \int_A (1 - r(x))\pi(x)dx \\ &= \int_A \pi(y) \left( \int p(y, x)dx \right) dy + \int_A (1 - r(x))\pi(x)dx \\ &= \int_A \pi(y)r(y)dy + \int_A (1 - r(x))\pi(x)dx = \pi(A) \end{aligned}$$

□

**Example 1** (Random walk chain). *Consider a proposal distribution with*

$$y = x + \epsilon, \quad \epsilon \sim N(0, \sigma^2)$$

*whose proposal distribution is*

$$q(x, y) = \phi((y - x)/\sigma) = \frac{1}{\sqrt{2\pi}\sigma} \exp^{-(y-x)^2/2\sigma^2} = q(y, x)$$

*The ratio function is*

$$\alpha(x, y) = \min \left\{ 1, \frac{f(y)q(y, x)}{f(x)q(x, y)} \right\}$$

*Since  $N(0, 1)$  is symmetric,  $q(y, x) = q(x, y)$  and*

$$\alpha(x, y) = \min \left\{ 1, \frac{f(y)}{f(x)} \right\}.$$