Shellsort overview

Idea. Move entries more than one position at a time by h-sorting the array.

an h–sorted array is h interleaved sorted subsequences

h = 4

L	E	E	A	M	H	L	E	P	S	O	L	T	S	X	R

L ——————— M ——————— P ——————— T

E ——————— H ——————— S ——————— S

E ——————— L ——————— O ——————— X

A ——————— E ——————— L ——————— R
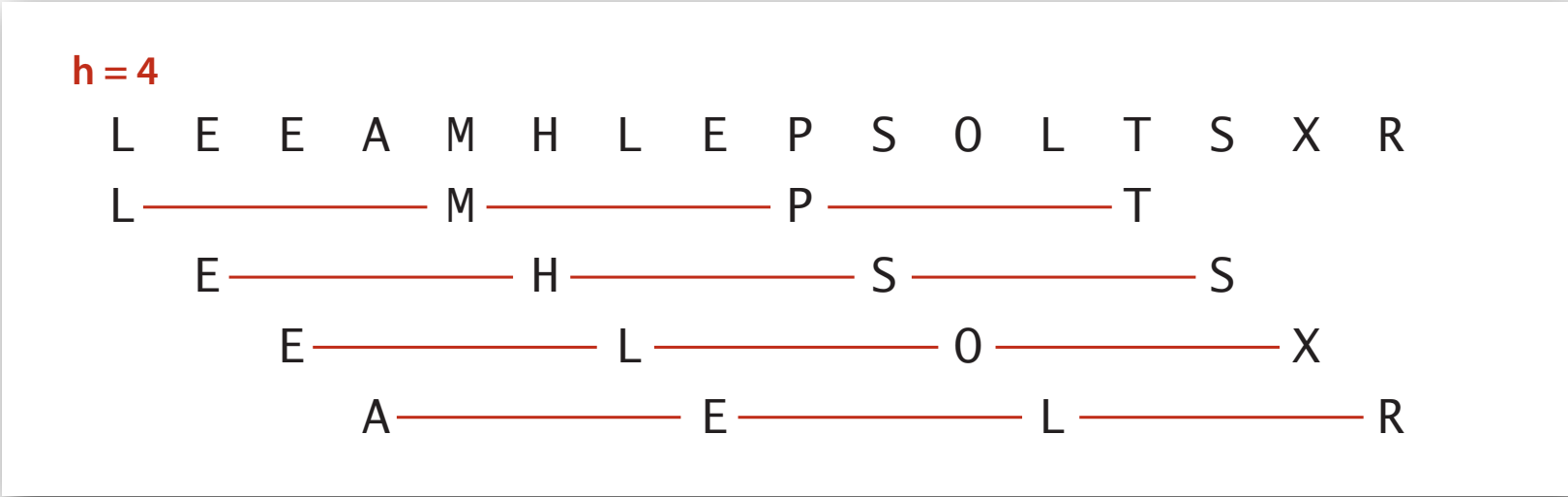
Shellsort. [Shell 1959] h-**sort** the array for decreasing sequence of values of h.

input	S	H	E	L	L	S	O	R	T	E	X	A	M	P	L	E
13-sort	P	H	E	L	L	S	O	R	T	E	X	A	M	S	L	E
4-sort	L	E	E	A	M	H	L	E	P	S	O	L	T	S	X	R
1-sort	A	E	E	E	H	L	L	L	M	O	P	R	S	S	T	X

How to h-sort an array? Insertion sort, with stride length h.

3–sorting an array

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

Why insertion sort?

- Big increments $\Rightarrow$ small subarray.
- Small increments $\Rightarrow$ nearly in order. [stay tuned]

Shellsort example: increments 7, 3, 1

input

S	O	R	T	E	X	A	M	P	L	E

7-sort

S	O	R	T	E	X	A	M	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	L	T	E	X	A	S	P	R	E
M	O	L	E	E	X	A	S	P	R	T

3-sort

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

1-sort

A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	R	S	X	T
A	E	E	L	M	O	P	R	S	T	X

result

A	E	E	L	M	O	P	R	S	T	X

4

Proposition. A g-sorted array remains g-sorted after h-sorting it.

7-sort

M	O	R	T	E	X	A	S	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	L	T	E	X	A	S	P	R	E
M	O	L	E	E	X	A	S	P	R	T
M	O	L	E	E	X	A	S	P	R	T

3-sort

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

still 7-sorted

Challenge. Prove this fact—it's more subtle than you'd think!

Powers of two. 1, 2, 4, 8, 16, 32, ...
No.

Powers of two minus one. 1, 3, 7, 15, 31, 63, ...
Maybe.

→ 3x + 1. 1, 4, 13, 40, 121, 364, ...
OK. Easy to compute.   merging of $(9 \times 4^i) - (9 \times 2^i) + 1$ and $4^i - (3 \times 2^i) + 1$

Sedgewick. 1, 5, 19, 41, 109, 209, 505, 929, 2161, 3905, ...
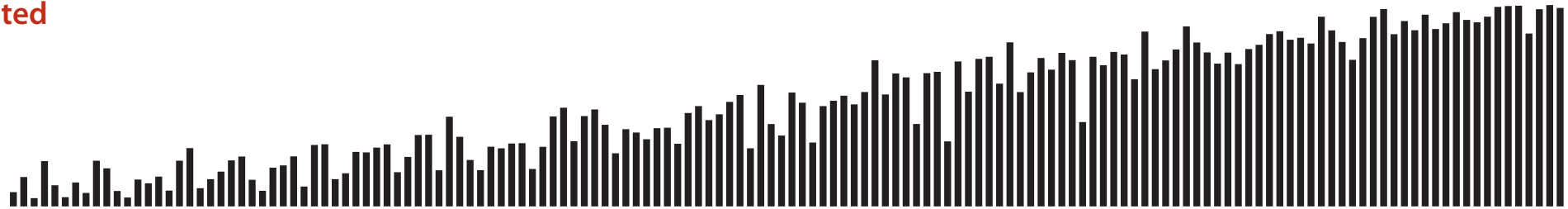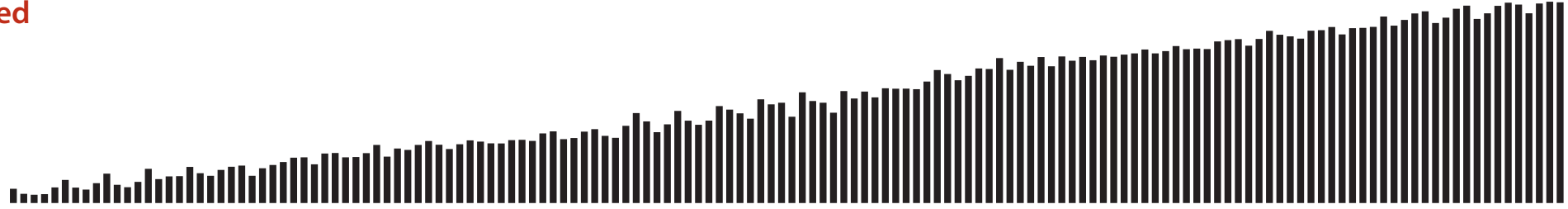Good. Tough to beat in empirical studies.

Shellsort: visual trace

input
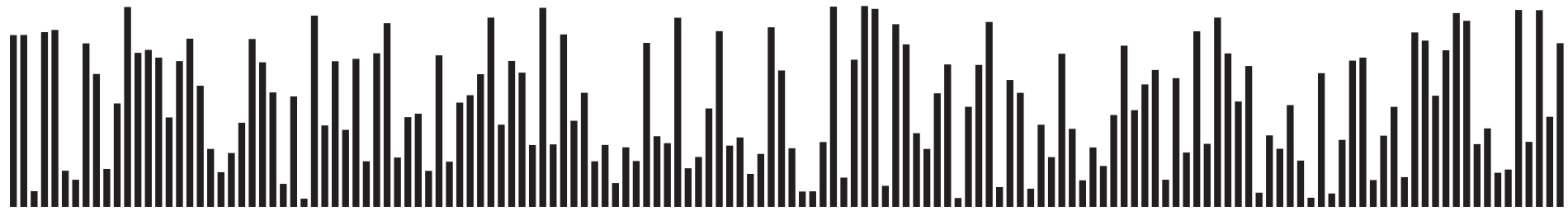
40-sorted
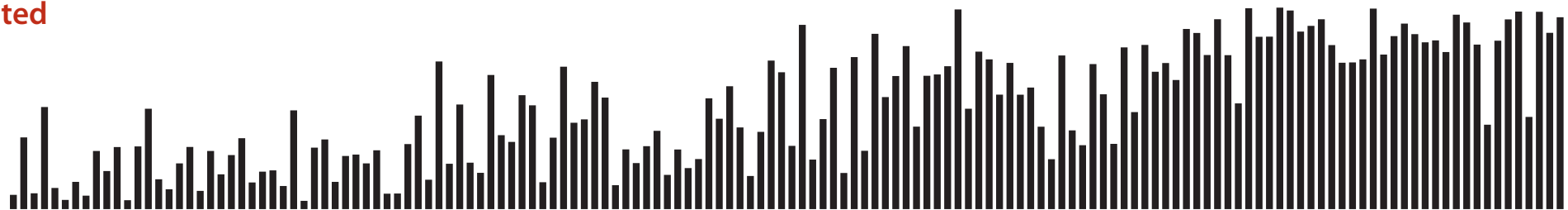
13-sorted
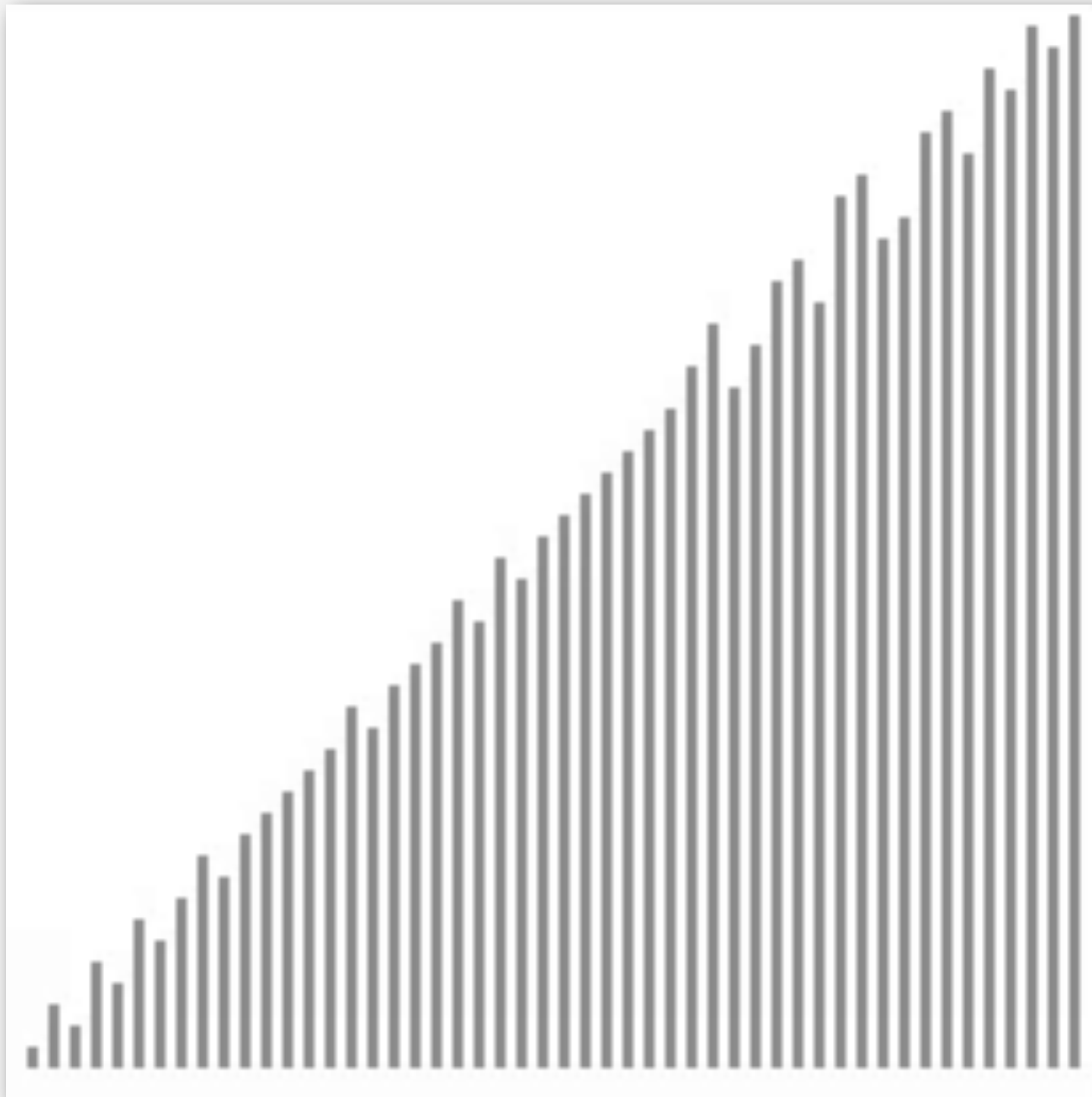
4-sorted

result

Shellsort: animation

50 random items

http://www.sorting-algorithms.com/shell-sort
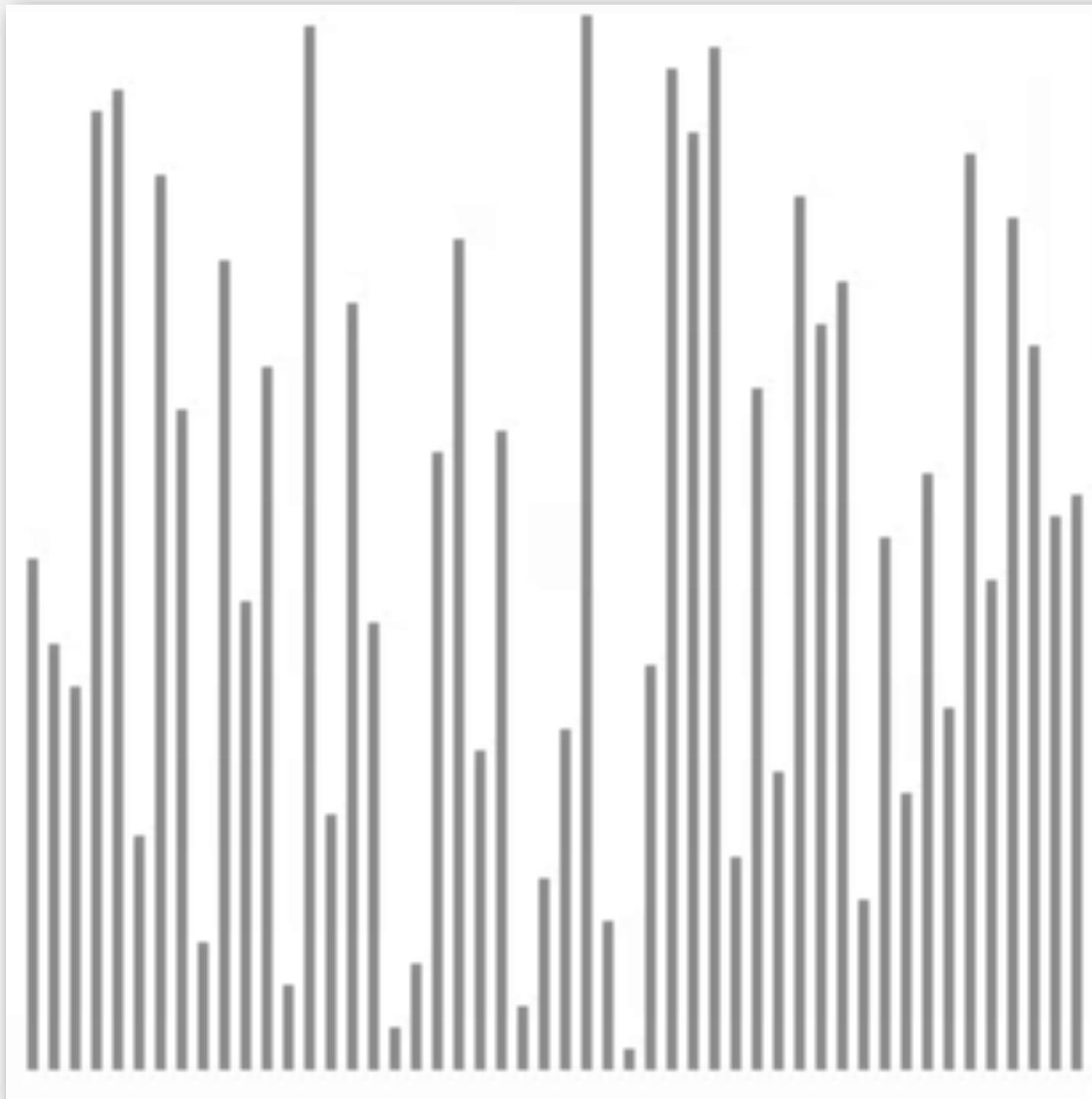
▲ algorithm position

h-sorted

current subsequence

other elements

Shellsort: animation

50 partially-sorted items

▲ algorithm position

h-sorted

current subsequence

other elements

Shellsort: analysis

Proposition. The worst-case number of compares used by shellsort with the
3x+1 increments is $O(N^{3/2})$.

Property. The number of compares used by shellsort with the 3x+1 increments
is at most by a small multiple of N times the # of increments used.

N	compares	N	2.5 N lg N
5,000	93	58	106
10,000	209	143	230
20,000	467	349	495
40,000	1022	855	1059
80,000	2266	2089	2257

measured in thousands

Remark. Accurate model has not yet been discovered (!)

Why are we interested in shellsort?

Example of simple idea leading to substantial performance gains.

Useful in practice.
- Fast unless array size is huge.
- Tiny, fixed footprint for code (used in embedded systems).
- Hardware sort prototype.

- Shellsort: Tradeoff between size and partial order in the subseq
  - beginning: shorter;
  - later in the sort subsequence are partially ordered

Simple algorithm, nontrivial performance, interesting questions.
- Asymptotic growth rate?
- Best sequence of increments?
- Average-case performance?

MERGESORT

‣ **mergesort**
‣ **bottom-up mergesort**
‣ **sorting complexity**
‣ **stability**

Critical components in the world's computational infrastructure.

- Full scientific understanding of their properties has enabled us to develop them into practical system sorts.
- Quicksort honored as one of top 10 algorithms of 20th century in science and engineering.

Mergesort.

- Java sort for objects.
- Perl, C++ stable sort, Python stable sort, Firefox JavaScript, ...

Quicksort.

- Java sort for primitive types.
- C qsort, Unix, Visual C++, Python, Matlab, Chrome JavaScript, ...

Mergesort

Basic plan.

- Divide array into two halves.
- Recursively sort each half.
- Merge two halves.

input	M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
sort left half	E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
sort right half	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
merge results	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Mergesort overview

First Draft
of a
Report on the
EDVAC

John von Neumann
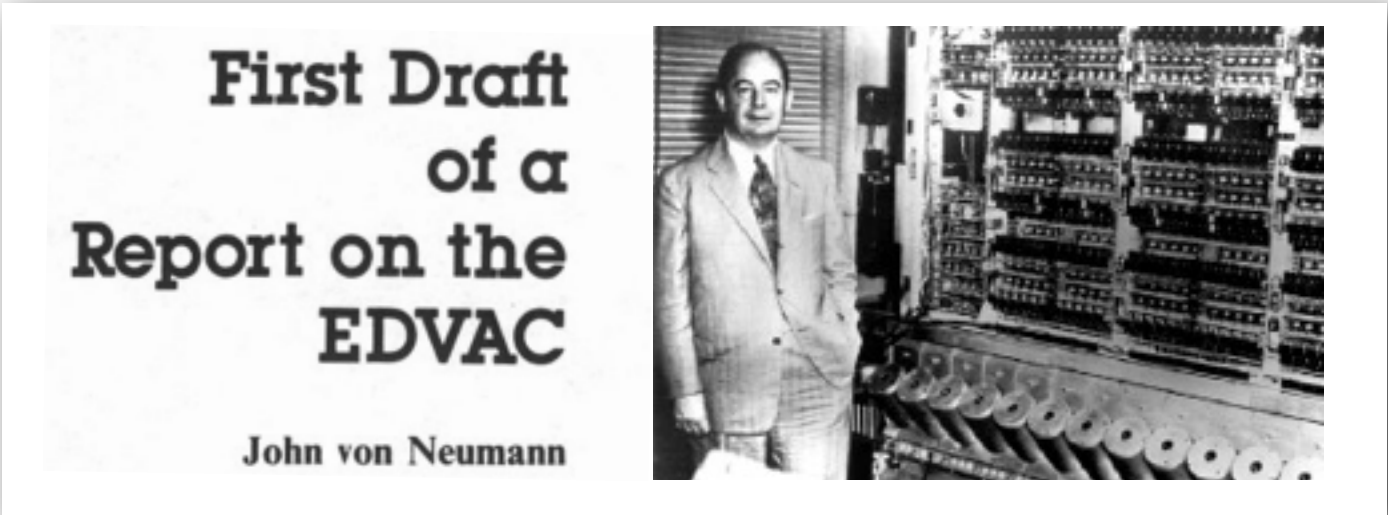
Merging

Q. How to combine two sorted subarrays into a sorted whole.

A. Use an auxiliary array.

	a[]										i	j	aux[]									
k	0	1	2	3	4	5	6	7	8	9			0	1	2	3	4	5	6	7	8	9
input	E	E	G	M	R	A	C	E	R	T			–	–	–	–	–	–	–	–	–	–
copy	E	E	G	M	R	A	C	E	R	T			E	E	G	M	R	A	C	E	R	T
											0	5										
0	A										0	6	E	E	G	M	R	A	C	E	R	T
1	A	C									0	7	E	E	G	M	R		C	E	R	T
2	A	C	E								1	7	E	E	G	M	R			E	R	T
3	A	C	E	E							2	7		E	G	M	R			E	R	T
4	A	C	E	E	E						2	8			G	M	R			E	R	T
5	A	C	E	E	E	G					3	8			G	M	R				R	T
6	A	C	E	E	E	G	M				4	8				M	R				R	T
7	A	C	E	E	E	G	M	R			5	8					R				R	T
8	A	C	E	E	E	G	M	R	R		5	9									R	T
9	A	C	E	E	E	G	M	R	R	T	6	10										T
merged result	A	C	E	E	E	G	M	R	R	T												

Abstract in-place merge trace

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Mergesort: trace

			lo			hi	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a[]																
						M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	0,	0,	1)			E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	2,	2,	3)			E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	0,	1,	3)			E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	4,	4,	5)			E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	6,	6,	7)			E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	4,	5,	7)			E	G	M	R	E	O	R	S	T	E	X	A	M	P	L	E
merge(a,	0,	3,	7)			E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
merge(a,	8,	8,	9)			E	E	G	M	O	R	R	S	E	T	X	A	M	P	L	E
merge(a,	10,	10,	11)			E	E	G	M	O	R	R	S	E	T	A	X	M	P	L	E
merge(a,	8,	9,	11)			E	E	G	M	O	R	R	S	A	E	T	X	M	P	L	E
merge(a,	12,	12,	13)			E	E	G	M	O	R	R	S	A	E	T	X	M	P	L	E
merge(a,	14,	14,	15)			E	E	G	M	O	R	R	S	A	E	T	X	M	P	E	L
merge(a,	12,	13,	15)			E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
merge(a,	8,	11,	15)			E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
merge(a,	0,	7,	15)			A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Trace of merge results for top-down mergesort

result after recursive call

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Mergesort: animation

50 random items
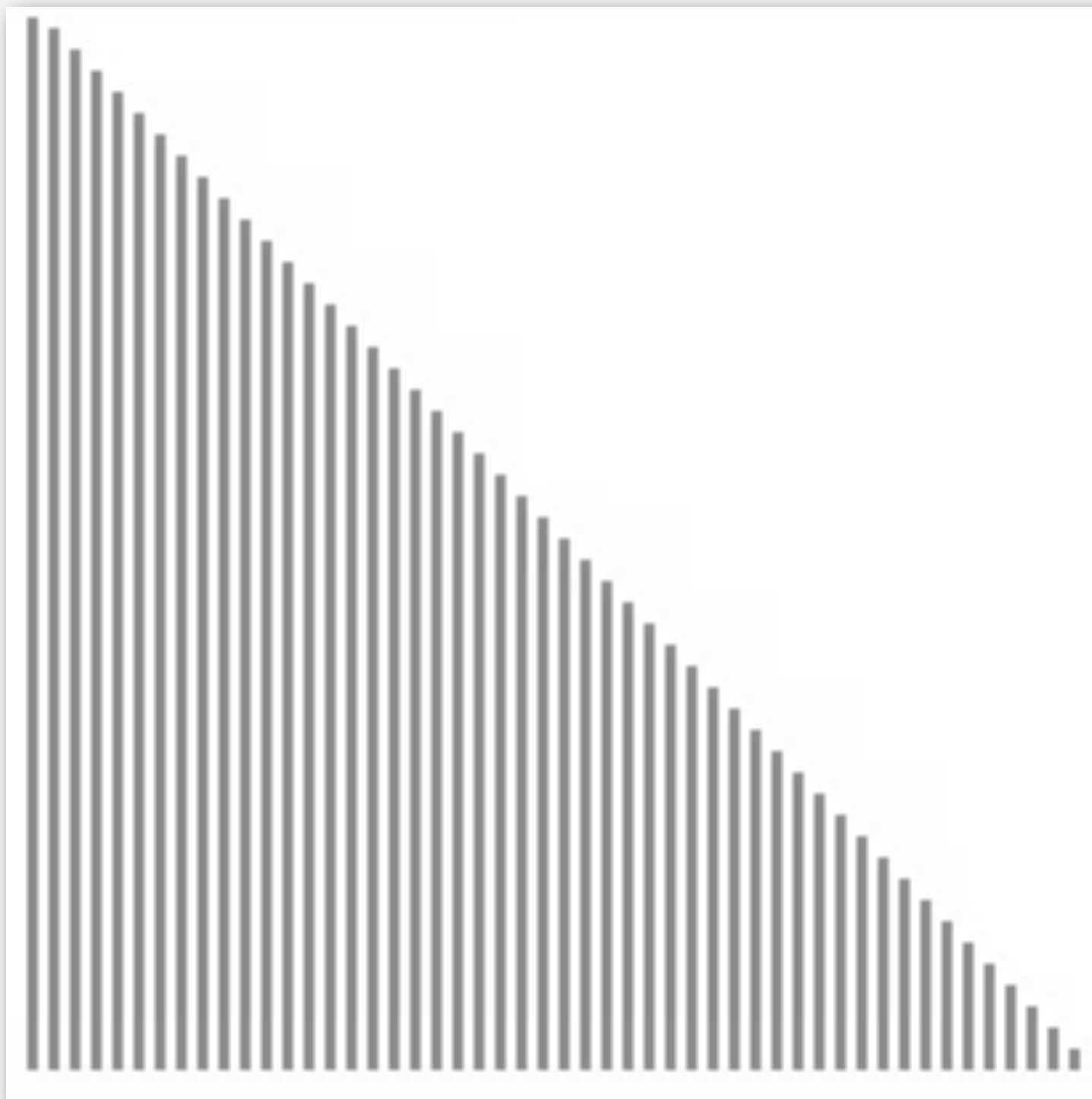

http://www.sorting-algorithms.com/merge-sort
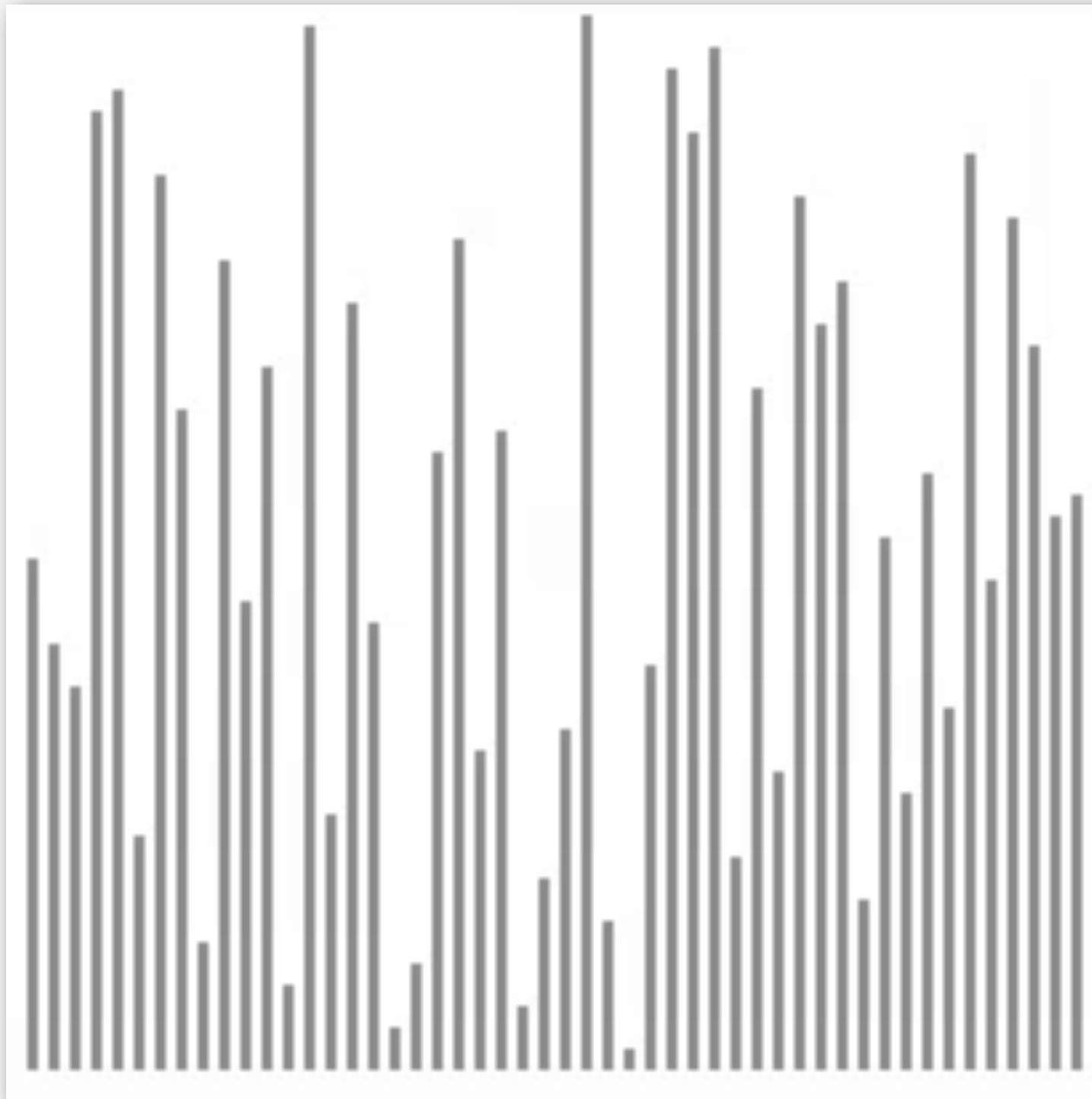
▲ algorithm position

in order

current subarray

not in order

Mergesort: animation

50 reverse-sorted items

▲ algorithm position

in order

current subarray

not in order

http://www.sorting-algorithms.com/merge-sort

Mergesort: empirical analysis

Running time estimates:

- Laptop executes 10^8 compares/second.
- Supercomputer executes 10^{12} compares/second.

	insertion sort (N			mergesort (N log N)		
computer	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min
super	instant	1 second	1 week	instant	instant	instant

Bottom line. Good algorithms are better than supercomputers.

Proposition. Mergesort uses at most $N \lg N$ compares and $6\,N \lg N$ array accesses to sort any array of size N.

Pf sketch. The number of compares $C(N)$ and array accesses $A(N)$ to mergesort an array of size N satisfy the recurrences:

$$C(N) \leq C(\lceil N/2 \rceil) + C(\lfloor N/2 \rfloor) + N \quad \text{for } N > 1, \text{ with } C(1) = 0.$$

left half   right half   merge

$$A(N) \leq A(\lceil N/2 \rceil) + A(\lfloor N/2 \rfloor) + 6\,N \quad \text{for } N > 1, \text{ with } A(1) = 0.$$

We solve the simpler divide-and-conquer recurrence when N is a power of 2.

result holds for all N

$$D(N) = 2\,D(N/2) + N, \text{ for } N > 1, \text{ with } D(1) = 0.$$

Divide-and-conquer recurrence: proof by picture

Proposition. If $D(N)$ satisfies $D(N) = 2\,D(N/2) + N$ for $N > 1$, with $D(1) = 0$, then $D(N) = N \lg N$.

Pf 1. [assuming N is a power of 2]

$$N \lg N$$

Proposition. If $D(N)$ satisfies $D(N) = 2\,D(N/2) + N$ for $N > 1$, with $D(1) = 0$, then $D(N) = N \lg N$.

Pf 2. [assuming N is a power of 2]

$$D(N) \;\; = \;\; 2\,D(N/2) \; + \; N$$

given

$$D(N)\,/\,N \;\; = \;\; 2\,D(N/2)\,/\,N \; + \; 1$$

divide both sides by N

$$= \;\; D(N/2)\,/\,(N/2) \; + \; 1$$

algebra

$$= \;\; D(N/4)\,/\,(N/4) \; + \; 1 \; + \; 1$$

apply to first term

$$= \;\; D(N/8)\,/\,(N/8) \; + \; 1 \; + \; 1 \; + \; 1$$

apply to first term again

$$\cdots$$

$$= \;\; D(N/N)\,/\,(N/N) + \; 1 + 1 \; + \; ... \; + \; 1$$

$$= \;\; \lg N$$

stop applying, D(1) = 0

Proposition. If $D(N)$ satisfies $D(N) = 2\,D(N/2) + N$ for $N > 1$, with $D(1) = 0$, then $D(N) = N \lg N$.

Pf 3. [assuming N is a power of 2]

- Base case: $N = 1$.
- Inductive hypothesis: $D(N) = N \lg N$.
- Goal: show that $D(2N) = (2N) \lg (2N)$.

$$D(2N) = 2\,D(N) + 2N \qquad \text{given}$$

$$= 2\,N \lg N + 2N \qquad \text{inductive hypothesis}$$

$$= 2\,N\,(\lg (2N) - 1) + 2N \qquad \text{algebra}$$

$$= 2\,N \lg (2N) \qquad \text{QED}$$

Proposition. Mergesort uses extra space proportional to N.

Pf. The array `aux[]` needs to be of size N for the last merge.

two sorted subarrays

| A | C | D | G | H | I | M | N | U | V | | B | E | F | J | O | P | Q | R | S | T |

| A | B | C | D | E | F | G | H | I | J | M | N | O | P | Q | R | S | T | U | V |

merged result
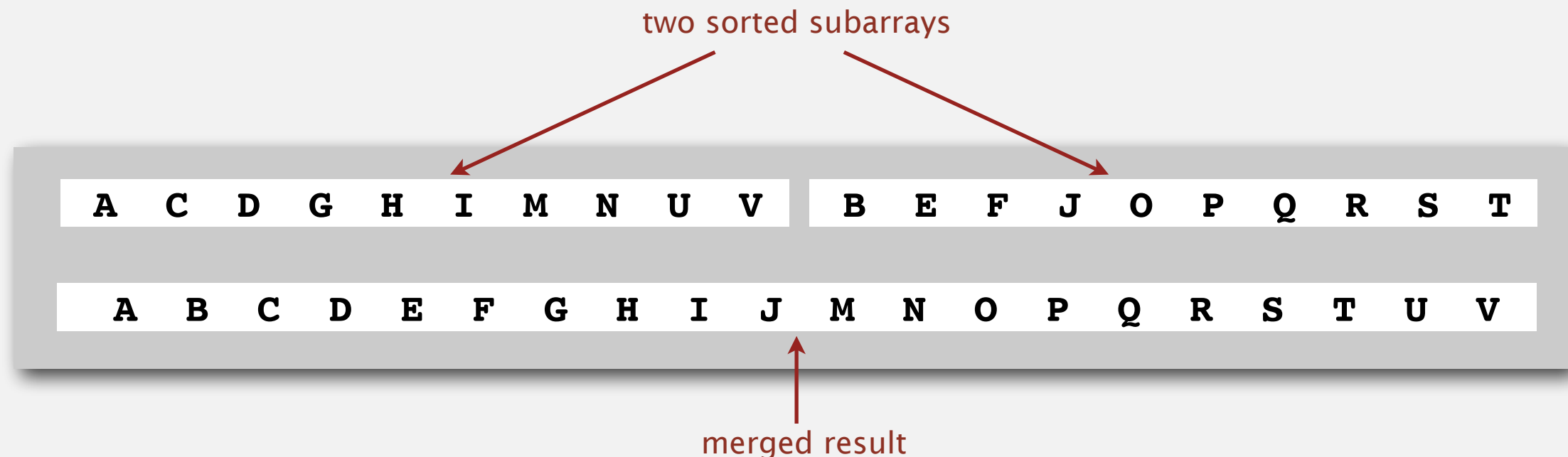
Def. A sorting algorithm is in-place if it uses $O(\log N)$ extra memory.

Ex. Insertion sort, selection sort, shellsort.

Mergesort: practical improvements

Use insertion sort for small subarrays.

- Mergesort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for $\approx$ 7 items.

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1) Insertion.sort(a, lo, hi);
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    merge(a, aux, lo, mid, hi);
}
```

Mergesort: practical improvements

Stop if already sorted.

- Is biggest item in first half ≤ smallest item in second half?
- Helps for partially-ordered arrays.

A	B	C	D	E	F	G	H	I	J	M	N	O	P	Q	R	S	T	U	V

A	B	C	D	E	F	G	H	I	J	M	N	O	P	Q	R	S	T	U	V

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    if (!less(a[mid+1], a[mid])) return;
    merge(a, aux, lo, mid, hi);
}
```

Mergesort: practical improvements

Eliminate the copy to the auxiliary array. Save time (but not space)
by switching the role of the input and auxiliary array in each recursive call.
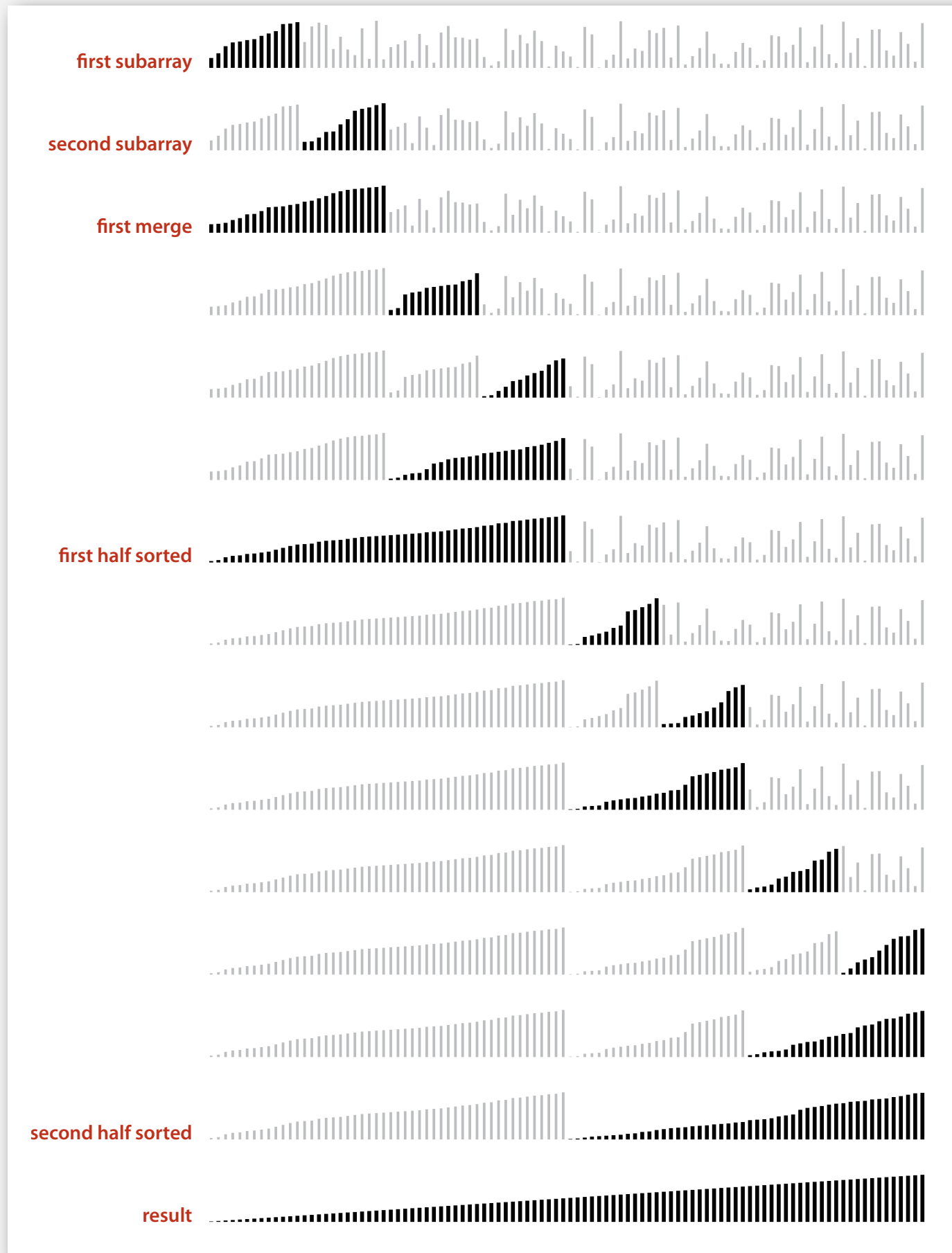
```
private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if        (i > mid)              aux[k] = a[j++];
        else if (j > hi)                 aux[k] = a[i++];
        else if (less(a[j], a[i]))  aux[k] = a[j++];       ⟵    merge from a[] to aux[]
        else                             aux[k] = a[i++];
    }
}


private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (aux, a, lo, mid);
    sort (aux, a, mid+1, hi);
    merge(aux, a, lo, mid, hi);
}
```

switch roles of aux[] and a[]

Mergesort: visualization

- first subarray
- second subarray
- first merge
- first half sorted
- second half sorted
- result

Bottom-up mergesort

Basic plan.

- Pass through array, merging subarrays of size 1.
- Repeat for subarrays of size 2, 4, 8, 16, ….

```
                                        a[i]
                    0   1   2   3   4   5   6   7   8   9  10  11  12  13  14  15
                    M   E   R   G   E   S   O   R   T   E   X   A   M   P   L   E
    sz = 1
    merge(a,  0,  0,  1)    E   M   R   G   E   S   O   R   T   E   X   A   M   P   L   E
    merge(a,  2,  2,  3)    E   M   G   R   E   S   O   R   T   E   X   A   M   P   L   E
    merge(a,  4,  4,  5)    E   M   G   R   E   S   O   R   T   E   X   A   M   P   L   E
    merge(a,  6,  6,  7)    E   M   G   R   E   S   O   R   T   E   X   A   M   P   L   E
    merge(a,  8,  8,  9)    E   M   G   R   E   S   O   R   E   T   X   A   M   P   L   E
    merge(a, 10, 10, 11)    E   M   G   R   E   S   O   R   E   T   A   X   M   P   L   E
    merge(a, 12, 12, 13)    E   M   G   R   E   S   O   R   E   T   A   X   M   P   L   E
    merge(a, 14, 14, 15)    E   M   G   R   E   S   O   R   E   T   A   X   M   P   E   L

  sz = 2
  merge(a,  0,  1,  3)      E   G   M   R   E   S   O   R   E   T   A   X   M   P   E   L
  merge(a,  4,  5,  7)      E   G   M   R   E   O   R   S   E   T   A   X   M   P   E   L
  merge(a,  8,  9, 11)      E   G   M   R   E   O   R   S   A   E   T   X   M   P   E   L
  merge(a, 12, 13, 15)      E   G   M   R   E   O   R   S   A   E   T   X   E   L   M   P

 sz = 4
 merge(a,  0,  3,  7)       E   E   G   M   O   R   R   S   A   E   T   X   E   L   M   P
 merge(a,  8, 11, 15)       E   E   G   M   O   R   R   S   A   E   E   L   M   P   T   X

sz = 8
merge(a,  0,  7, 15)        A   E   E   E   E   G   L   M   M   O   P   R   R   S   T   X
```

Bottom line. No recursion needed!
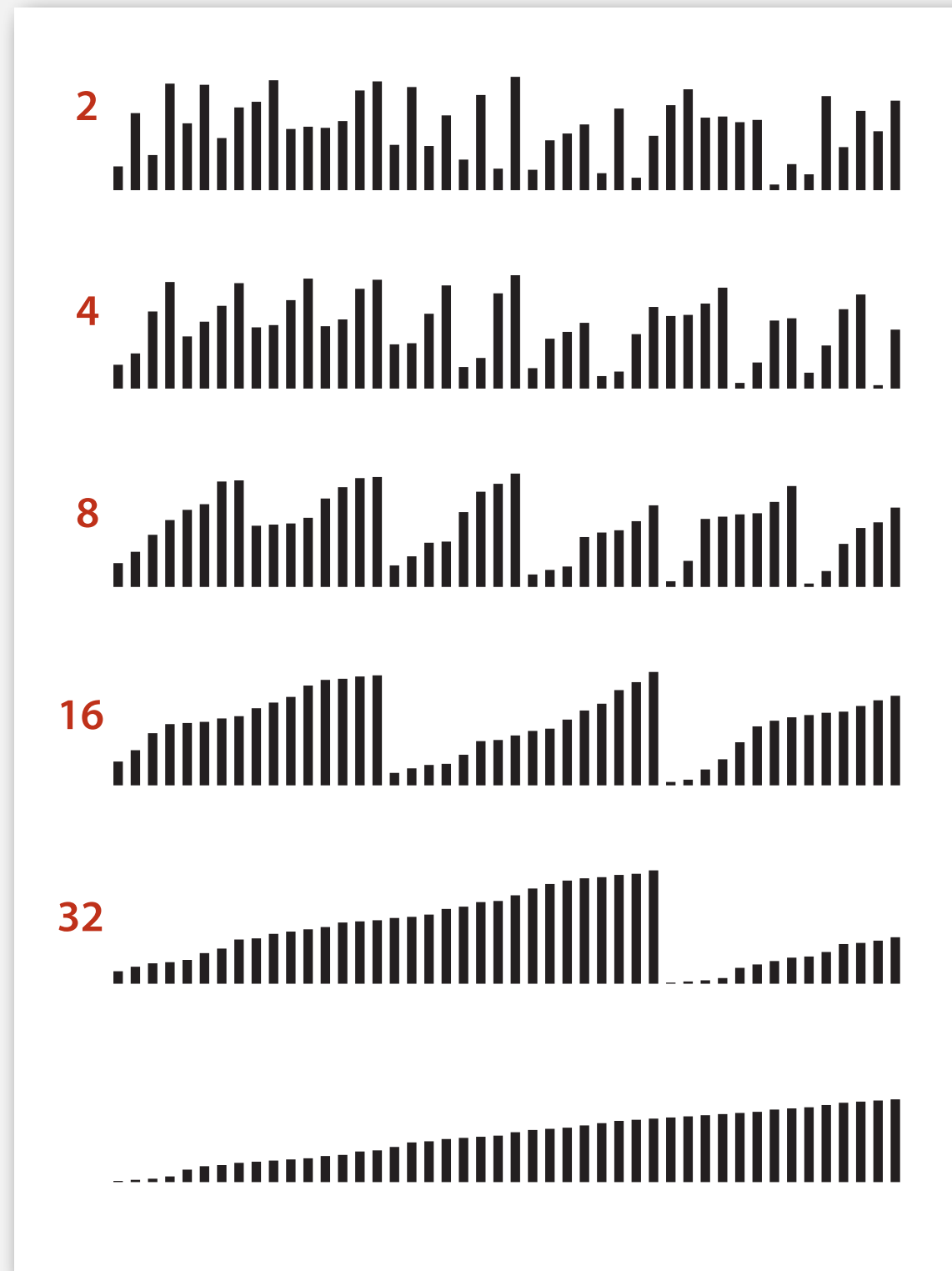
2

4

8

16

32

Computational complexity. Framework to study efficiency of algorithms for solving a particular problem X.

Model of computation. Allowable operations.

Cost model. Operation count(s).

Upper bound. Cost guarantee provided by some algorithm for X.

Lower bound. Proven limit on cost guarantee of all algorithms for X.

Optimal algorithm. Algorithm with best possible cost guarantee for X.
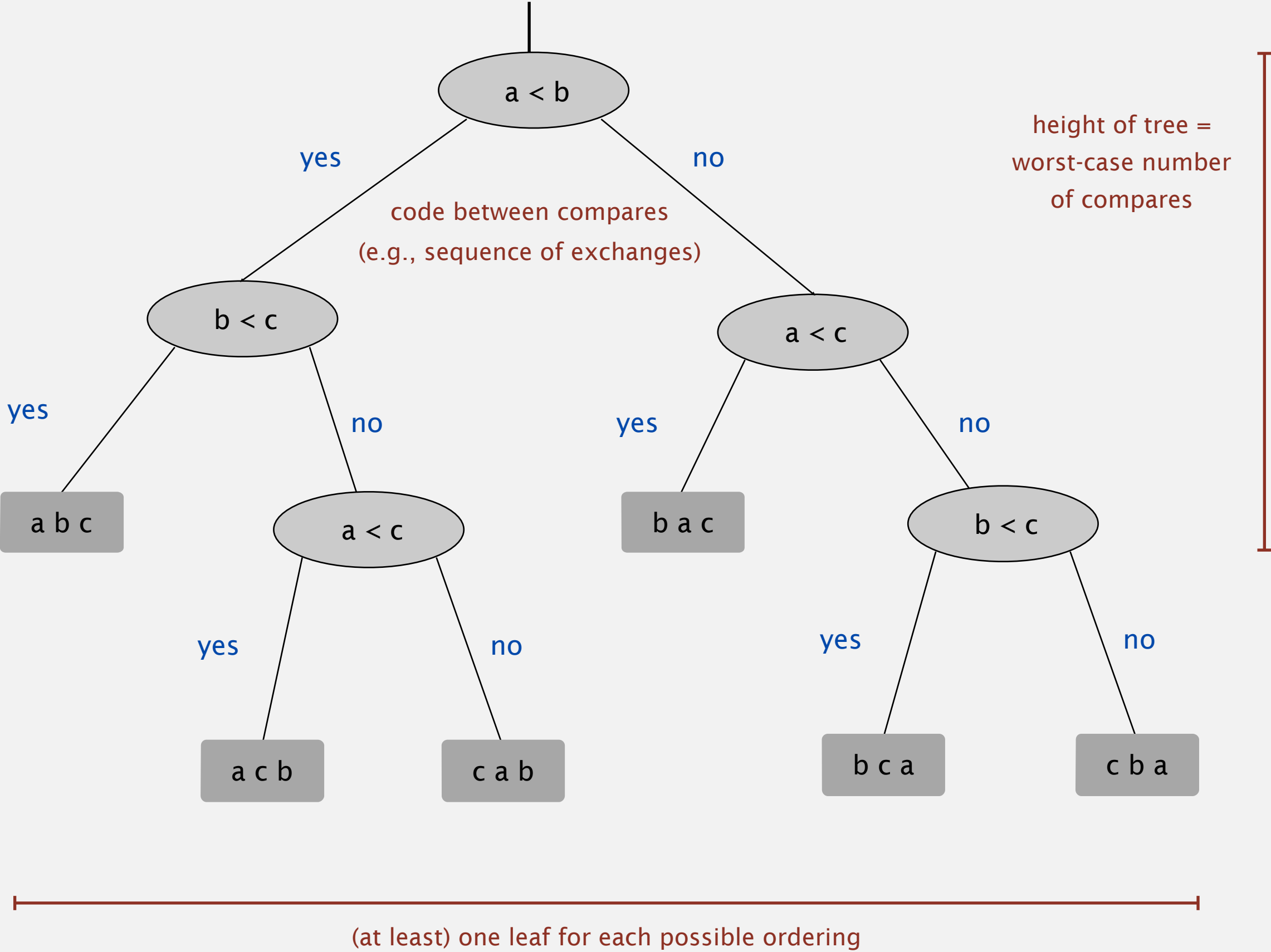
lower bound ~ upper bound

Example: sorting.

- Model of computation: decision tree.   can access information only through compares
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound: ?
- Optimal algorithm: ?

Decision tree (for 3 distinct items a, b, and c)

a < b

yes   no

code between compares
(e.g., sequence of exchanges)

height of tree =
worst-case number
of compares

b < c

a < c

yes   no

yes   no

a b c

a < c

b a c

b < c

yes   no
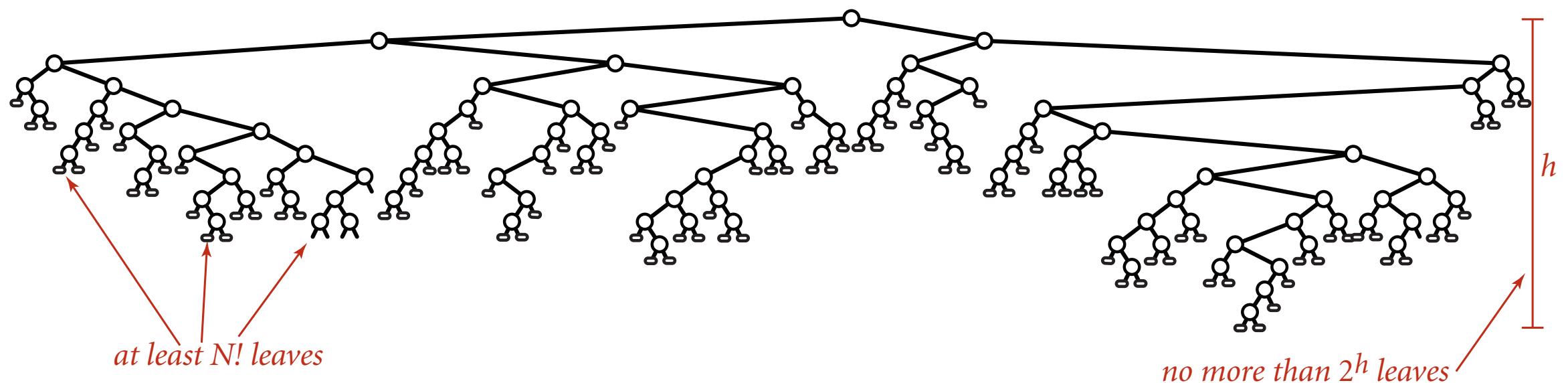
yes   no

a c b   c a b

b c a   c b a

(at least) one leaf for each possible ordering

Proposition. Any compare-based sorting algorithm must use at least $\lg(N!) \sim N \lg N$ compares in the worst-case.

Pf.

- Assume array consists of N distinct values a_1 through a_N.
- Worst case dictated by height h of decision tree.
- Binary tree of height h has at most 2^h leaves.
- $N!$ different orderings $\Rightarrow$ at least $N!$ leaves.

at least N! leaves

no more than 2^h leaves

h

Compare-based lower bound for sorting

Proposition. Any compare-based sorting algorithm must use at least $\lg(N!) \sim N \lg N$ compares in the worst-case.

Pf.

- Assume array consists of N distinct values a_1 through a_N.
- Worst case dictated by height h of decision tree.
- Binary tree of height h has at most 2^h leaves.
- $N!$ different orderings $\Rightarrow$ at least $N!$ leaves.

$$2^h \geq \#\text{ leaves} \geq N!$$
$$\Rightarrow h \geq \lg(N!) \sim N \lg N$$

Stirling's formula

Model of computation. Allowable operations.

Cost model. Operation count(s).

Upper bound. Cost guarantee provided by some algorithm for X.

Lower bound. Proven limit on cost guarantee of all algorithms for X.

Optimal algorithm. Algorithm with best possible cost guarantee for X.

Example: sorting.

- Model of computation: decision tree.
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound: $\sim N \lg N$.
- Optimal algorithm = mergesort.

First goal of algorithm design: optimal algorithms.

Complexity results in context

Other operations? Mergesort is optimal with respect to number of compares (e.g., but not with respect to number of array accesses).

Space?
- Mergesort is not optimal with respect to space usage.
- Insertion sort, selection sort, and shellsort are space-optimal.

Challenge. Find an algorithm that is both time- and space-optimal.

Lessons. Use theory as a guide.
Ex. Don't try to design sorting algorithm that guarantees $\frac{1}{2} N \lg N$ compares.

Lower bound may not hold if the algorithm has information about:
- The initial order of the input.
- The distribution of key values.
- The representation of the keys.

Partially-ordered arrays. Depending on the initial order of the input,
we may not need $N \lg N$ compares.

insertion sort requires only N−1
compares if input array is sorted

Duplicate keys. Depending on the input distribution of duplicates,
we may not need $N \lg N$ compares.

stay tuned for 3-way quicksort

Digital properties of keys. We can use digit/character compares instead of
key compares for numbers and strings.

radix sorts..

‣ mergesort

‣ bottom-up mergesort

‣ sorting complexity

‣ **stability**

A typical application. First, sort by name; then sort by section.

`Selection.sort(a, Student.BY_NAME);`

`Selection.sort(a, Student.BY_SECTION);`

Andrews	3	A	664-480-0023	097 Little
Battle	4	C	874-088-1212	121 Whitman
Chen	3	A	991-878-4944	308 Blair
Fox	3	A	884-232-5341	11 Dickinson
Furia	1	A	766-093-9873	101 Brown
Gazsi	4	B	766-093-9873	101 Brown
Kanaga	3	B	898-122-9643	22 Brown
Rohde	2	A	232-343-5555	343 Forbes

Furia	1	A	766-093-9873	101 Brown
Rohde	2	A	232-343-5555	343 Forbes
Chen	3	A	991-878-4944	308 Blair
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Kanaga	3	B	898-122-9643	22 Brown
Gazsi	4	B	766-093-9873	101 Brown
Battle	4	C	874-088-1212	121 Whitman

@#%&@! Students in section 3 no longer sorted by name.

A stable sort preserves the relative order of items with equal keys.

Stability

Q. Which sorts are stable?

A. Insertion sort and mergesort (but not selection sort or shellsort).

sorted by time	sorted by location (not stable)	sorted by location (stable)
Chicago 09:00:00	Chicago 09:25:52	Chicago 09:00:00
Phoenix 09:00:03	Chicago 09:03:13	Chicago 09:00:59
Houston 09:00:13	Chicago 09:21:05	Chicago 09:03:13
Chicago 09:00:59	Chicago 09:19:46	Chicago 09:19:32
Houston 09:01:10	Chicago 09:19:32	Chicago 09:19:46
Chicago 09:03:13	Chicago 09:00:00	Chicago 09:21:05
Seattle 09:10:11	Chicago 09:35:21	Chicago 09:25:52
Seattle 09:10:25	Chicago 09:00:59	Chicago 09:35:21
Phoenix 09:14:25	Houston 09:01:10	Houston 09:00:13
Chicago 09:19:32	Houston 09:00:13	Houston 09:01:10
Chicago 09:19:46	Phoenix 09:37:44	Phoenix 09:00:03
Chicago 09:21:05	Phoenix 09:00:03	Phoenix 09:14:25
Seattle 09:22:43	Phoenix 09:14:25	Phoenix 09:37:44
Seattle 09:22:54	Seattle 09:10:25	Seattle 09:10:11
Chicago 09:25:52	Seattle 09:36:14	Seattle 09:10:25
Chicago 09:35:21	Seattle 09:22:43	Seattle 09:22:43
Seattle 09:36:14	Seattle 09:10:11	Seattle 09:22:54
Phoenix 09:37:44	Seattle 09:22:54	Seattle 09:36:14

no longer sorted by time

still sorted by time

Note. Need to carefully check code ("less than" vs "less than or equal to").

Proposition. Insertion sort is stable.

```
public class Insertion
{
   public static void sort(Comparable[] a)
   {
      int N = a.length;
      for (int i = 0; i < N; i++)
         for (int j = i; j > 0 && less(a[j], a[j-1]); j--)
            exch(a, j, j-1);
   }
}
```

i	j	0	1	2	3	4
0	0	B	A	A	A	B
1	0	A	B	A	A	B
2	1	A	A	B	A	B
3	2	A	A	A	B	B
4	4	A	A	A	B	B
		A	A	A	B	B

Pf. Equal items never move past each other.

Proposition. Selection sort is not stable.

```
public class Selection
{
   public static void sort(Comparable[] a)
   {
      int N = a.length;
      for (int i = 0; i < N; i++)
      {
         int min = i;
         for (int j = i+1; j < N; j++)
            if (less(a[j], a[min]))
               min = j;
         exch(a, i, min);
      }
   }
}
```

i	min	0	1	2
0	2	B	B	A
1	1	A	B	B
2	2	A	B	B
		A	B	B

Pf by counterexample. Long-distance exchange might move an item past some equal item.

Proposition. Shellsort sort is not stable.

```
public class Shell
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        int h = 1;
        while (h < N/3) h = 3*h + 1;
        while (h >= 1)
        {
            for (int i = h; i < N; i++)
            {
                for (int j = i; j > h && less(a[j], a[j-h]); j -= h)
                    exch(a, j, j-h);
            }
            h = h/3;
        }
    }
}
```

h	0	1	2	3	4
	B	B	B	B	A
4	A	B	B	B	B
1	A	B	B	B	B
	A	B	B	B	B

Pf by counterexample. Long-distance exchanges.

Proposition. Mergesort is stable.

```
public class Merge
{
   private static Comparable[] aux;
   private static void merge(Comparable[] a, int lo, int mid, int hi)
   {  /* as before */  }


   private static void sort(Comparable[] a, int lo, int hi)
   {
      if (hi <= lo) return;
      int mid = lo + (hi - lo) / 2;
      sort(a, lo, mid);
      sort(a, mid+1, hi);
      merge(a, lo, mid, hi);
   }


   public static void sort(Comparable[] a)
   {  /* as before */  }
}
```

Pf. Suffices to verify that merge operation is stable.

Proposition. Merge operation is stable.

```
private static void merge(Comparable[] a, int lo, int mid, int hi)
{
    for (int k = lo; k <= hi; k++)
        aux[k] = a[k];


    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if        (i > mid)              a[k] = aux[j++];
        else if (j > hi)                 a[k] = aux[i++];
        else if (less(aux[j], aux[i]))   a[k] = aux[j++];
        else                             a[k] = aux[i++];

    }
}
```

0	1	2	3	4		5	6	7	8	9	10
A	A	A	B	D		A	A	C	E	F	G

Pf. Takes from left subarray if equal keys.

‣ **quicksort**
‣ **selection**
‣ **duplicate keys**
‣ **system sorts**

Two classic sorting algorithms

Critical components in the world's computational infrastructure.

- Full scientific understanding of their properties has enabled us
  to develop them into practical system sorts.

- **Quicksort honored as one of top 10 algorithms of 20th century
  in science and engineering.**

Mergesort.

- Java sort for objects.
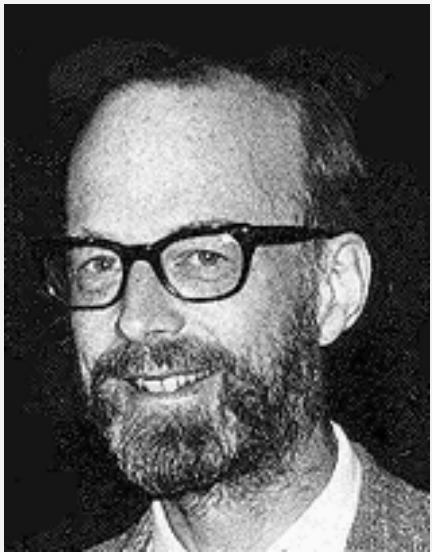- Perl, C++ stable sort, Python stable sort, Firefox JavaScript, ...

Quicksort.

- Java sort for primitive types.
- C qsort, Unix, Visual C++, Python, Matlab, Chrome JavaScript, ...

Quicksort

Basic plan.

- **Shuffle** the array.
- **Partition** so that, for some `j`
  - entry `a[j]` is in place
  - no larger entry to the left of `j`
  - no smaller entry to the right of `j`
- **Sort** each piece recursively.

Sir Charles Antony Richard Hoare
1980 Turing Award

input	Q	U	I	C	K	S	O	R	T	E	X	A	M	P	L	E
shuffle	K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
partition	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
sort left	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
sort right	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
result	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X

partitioning element

not greater   *not less*

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Quicksort partitioning

Basic plan.

- Scan `i` from left for an item that belongs on the right.
- Scan `j` from right for an item that belongs on the left.
- Exchange `a[i]` and `a[j]`.
- Repeat until pointers cross.

	i	j	v	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
initial values	0	16		K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
scan left, scan right	1	12		K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
exchange	1	12		K	C	A	T	E	L	E	P	U	I	M	Q	R	X	O	S
scan left, scan right	3	9		K	C	A	T	E	L	E	P	U	I	M	Q	R	X	O	S
exchange	3	9		K	C	A	I	E	L	E	P	U	T	M	Q	R	X	O	S
scan left, scan right	5	6		K	C	A	I	E	L	E	P	U	T	M	Q	R	X	O	S
exchange	5	6		K	C	A	I	E	E	L	P	U	T	M	Q	R	X	O	S
scan left, scan right	6	5		K	C	A	I	E	E	L	P	U	T	M	Q	R	X	O	S
final exchange	6	5		E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
result	6	5		E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S

Partitioning trace (array contents before and after each exchange)

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Quicksort: Java code for partitioning

```java
private static int partition(Comparable[] a, int lo, int hi)
{
    int i = lo, j = hi+1;
    while (true)
    {
        while (less(a[++i], a[lo]))          find item on left to swap
            if (i == hi) break;

        while (less(a[lo], a[--j]))          find item on right to swap
            if (j == lo) break;

        if (i >= j) break;                   check if pointers cross
        exch(a, i, j);                       swap
    }

    exch(a, lo, j);                  swap with partitioning item
    return j;           return index of item now known to be in place
}
```
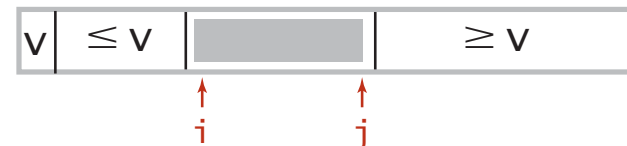
before | v | |
         ↑   ↑
         lo   hi

during | v | ≤ v | | ≥ v |
               ↑   ↑
               i   j

after | ≤ v | v | ≥ v |
         ↑   ↑   ↑
         lo   j   hi

Quicksort trace

	lo	j	hi	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
initial values				Q	U	I	C	K	S	O	R	T	E	X	A	M	P	L	E
random shuffle				K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
	0	5	15	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
	0	3	4	E	C	A	E	I	K	L	P	U	T	M	Q	R	X	O	S
	0	2	2	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	0	0	1	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	1		1	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	4		4	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	6	6	15	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	7	9	15	A	C	E	E	I	K	L	M	O	P	T	Q	R	X	U	S
	7	7	8	A	C	E	E	I	K	L	M	O	P	T	Q	R	X	U	S
	8		8	A	C	E	E	I	K	L	M	O	P	T	Q	R	X	U	S
	10	13	15	A	C	E	E	I	K	L	M	O	P	S	Q	R	T	U	X
	10	12	12	A	C	E	E	I	K	L	M	O	P	R	Q	S	T	U	X
	10	11	11	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
	10		10	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
	14	14	15	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
	15		15	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
result				A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X

no partition for subarrays of size 1

Quicksort trace (array contents after each partition)

Quicksort animation

50 random items
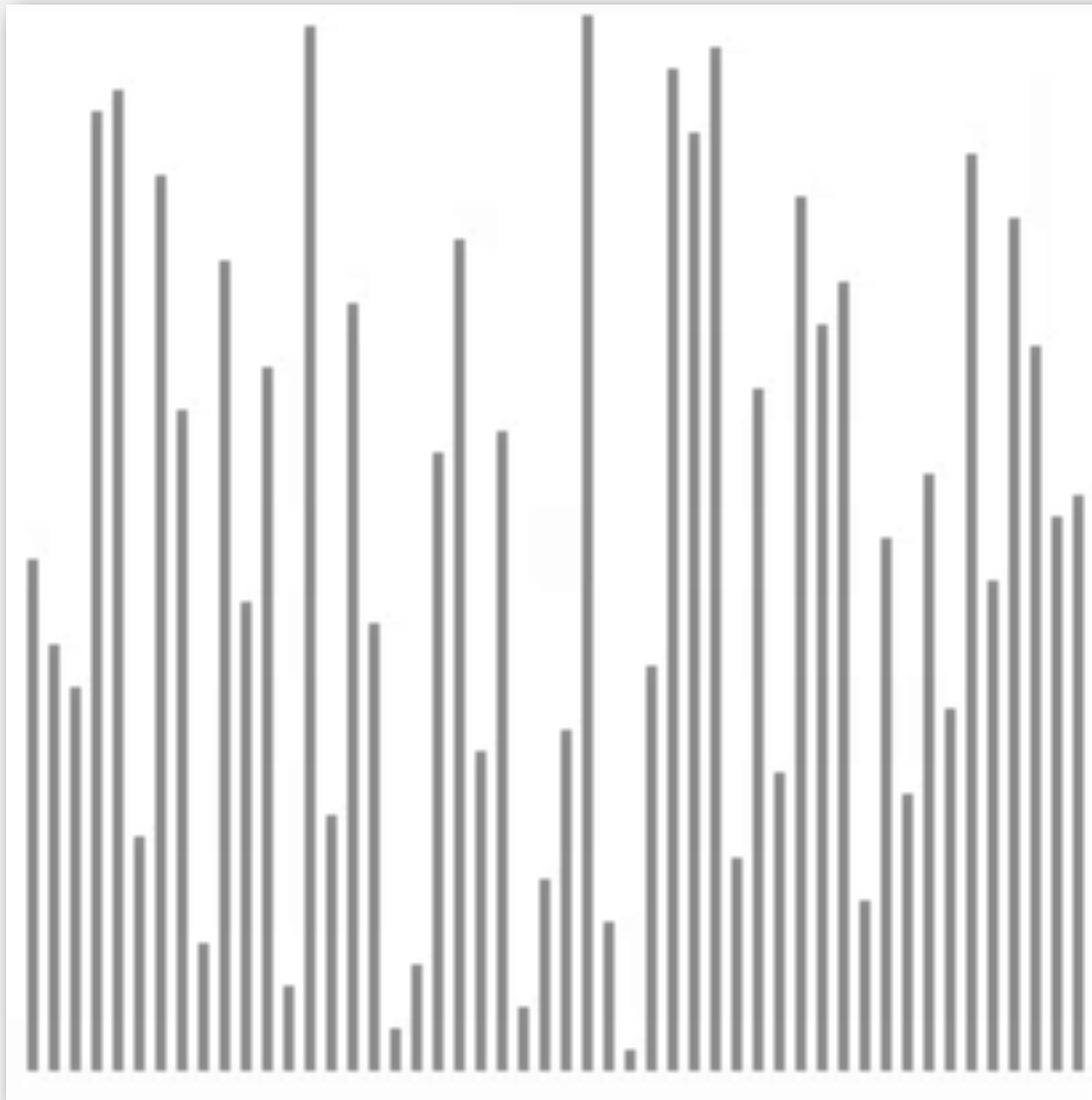
▲ algorithm position

in order

current subarray

not in order

Quicksort: implementation details

Partitioning in-place. Using an extra array makes partitioning easier (and stable), but is not worth the cost.

Terminating the loop. Testing whether the pointers cross is a bit trickier than it might seem.

Staying in bounds. The `(j == lo)` test is redundant (why?), but the `(i == hi)` test is not.

Preserving randomness. Shuffling is needed for performance guarantee.

Equal keys. When duplicates are present, it is (counter-intuitively) better to stop on keys equal to the partitioning item's key.

Quicksort: empirical analysis

Running time estimates:

- Home PC executes 10^8 compares/second.

- Supercomputer executes 10^{12} compares/second.

computer	insertion sort (N			mergesort (N log N)			quicksort (N log N)		
	thousand	million	billion	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min	instant	0.6 sec	12 min
super	instant	1 second	1 week	instant	instant	instant	instant	instant	instant

Lesson 1. Good algorithms are better than supercomputers.

Lesson 2. Great algorithms are better than good ones.

Best case. Number of compares is $\sim N \lg N$.

lo	j	hi	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
													a[ ]				
initial values			H	A	C	B	F	E	G	D	L	I	K	J	N	M	O
random shuffle			H	A	C	B	F	E	G	D	L	I	K	J	N	M	O
0	7	14	D	A	C	B	F	E	G	H	L	I	K	J	N	M	O
0	3	6	B	A	C	D	F	E	G	H	L	I	K	J	N	M	O
0	1	2	A	B	C	D	F	E	G	H	L	I	K	J	N	M	O
0		0	A	B	C	D	F	E	G	H	L	I	K	J	N	M	O
2		2	A	B	C	D	F	E	G	H	L	I	K	J	N	M	O
4	5	6	A	B	C	D	E	F	G	H	L	I	K	J	N	M	O
4		4	A	B	C	D	E	F	G	H	L	I	K	J	N	M	O
6		6	A	B	C	D	E	F	G	H	L	I	K	J	N	M	O
8	11	14	A	B	C	D	E	F	G	H	J	I	K	L	N	M	O
8	9	10	A	B	C	D	E	F	G	H	I	J	K	L	N	M	O
8		8	A	B	C	D	E	F	G	H	I	J	K	L	N	M	O
10		10	A	B	C	D	E	F	G	H	I	J	K	L	N	M	O
12	13	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
12		12	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
14		14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O

Quicksort: worst-case analysis

Worst case. Number of compares is $\sim \frac{1}{2} N^2$.

|	lo	j	hi											a[ ]					
				0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
initial values				A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
random shuffle				A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	0	0	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	1	1	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	2	2	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	3	3	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	4	4	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	5	5	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	6	6	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	7	7	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	8	8	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	9	9	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	10	10	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	11	11	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	12	12	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	13	13	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	14		14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
				A	B	C	D	E	F	G	H	I	J	K	L	M	N	O

Quicksort: average-case analysis

Proposition. The average number of compares C_N to quicksort an array of N distinct keys is $\sim 2N \ln N$ (and the number of exchanges is $\sim \frac{1}{3} N \ln N$).

Pf 1. C_N satisfies the recurrence $C_0 = C_1 = 0$ and for $N \geq 2$:

$$C_N \; = \; (N+1) \; + \; \frac{C_0 \; + \; C_1 \; + \; \ldots \; + C_{N-1}}{N} \; + \; \frac{C_{N-1} \; + \; C_{N-2} \; + \; \ldots \; + C_0}{N}$$

↑ partitioning   ↑ left   ↑ right   ↖ partitioning probability

- Multiply both sides by N and collect terms:

$$NC_N \; = \; N(N+1) \; + \; 2(C_0 \; + \; C_1 \; + \; \ldots \; + C_{N-1})$$

- Subtract this from the same equation for $N - 1$:

$$NC_N \; - \; (N-1)C_{N-1} \; = 2N \; + \; 2C_{N-1}$$

- Rearrange terms and divide by $N(N+1)$:

$$\frac{C_N}{N+1} \; = \; \frac{C_{N-1}}{N} \; + \; \frac{2}{N+1}$$

- Repeatedly apply above equation:

$$\begin{aligned}
\frac{C_N}{N+1} &= \frac{C_{N-1}}{N} + \frac{2}{N+1} \\
&= \frac{C_{N-2}}{N-1} + \frac{2}{N} + \frac{2}{N+1} \\
&= \frac{C_{N-3}}{N-2} + \frac{2}{N-1} + \frac{2}{N} + \frac{2}{N+1} \\
&= \frac{2}{3} + \frac{2}{4} + \frac{2}{5} + \ldots + \frac{2}{N+1}
\end{aligned}$$

previous equation

substitute previous equation

- Approximate sum by an integral:

$$\begin{aligned}
C_N &= 2(N+1)\left(\frac{1}{3} + \frac{1}{4} + \frac{1}{5} + \ldots \frac{1}{N+1}\right) \\
&\sim 2(N+1)\int_3^{N+1} \frac{1}{x}\, dx
\end{aligned}$$
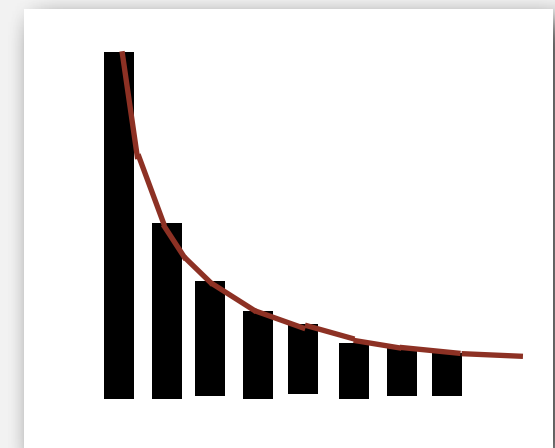
- Finally, the desired result:

$$C_N \sim 2(N+1)\ln N \approx 1.39 N \lg N$$

Quicksort: average-case analysis

Proposition. The average number of compares C_N to quicksort an array of N distinct keys is $\sim 2N \ln N$ (and the number of exchanges is $\sim \frac{1}{3} N \ln N$).

Pf 2. Consider BST representation of keys 1 to N.

shuffle

9	10	2	5	8	7	6	1	11	12	13	3	4

first partitioning
item

first partitioning
item in
left subarray
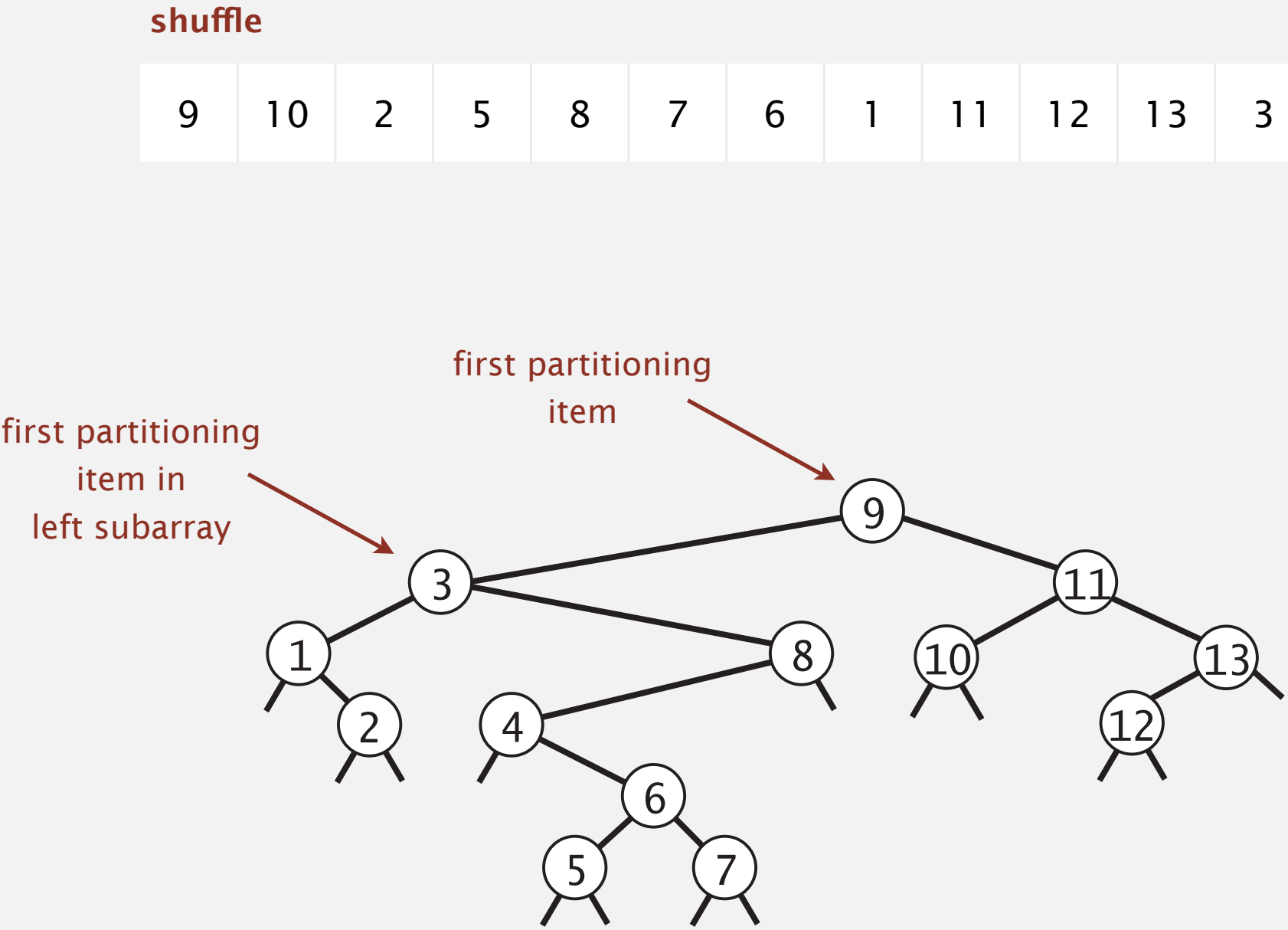
Quicksort: average-case analysis

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Pf 2. Consider BST representation of keys 1 to N.
- A key is compared only with its ancestors and descendants.
- Probability i and j are compared equals $2 / |j - i + 1|$.

3 and 6 are compared
(when 3 is partition)

1 and 6 are not compared
(because 3 is partition)
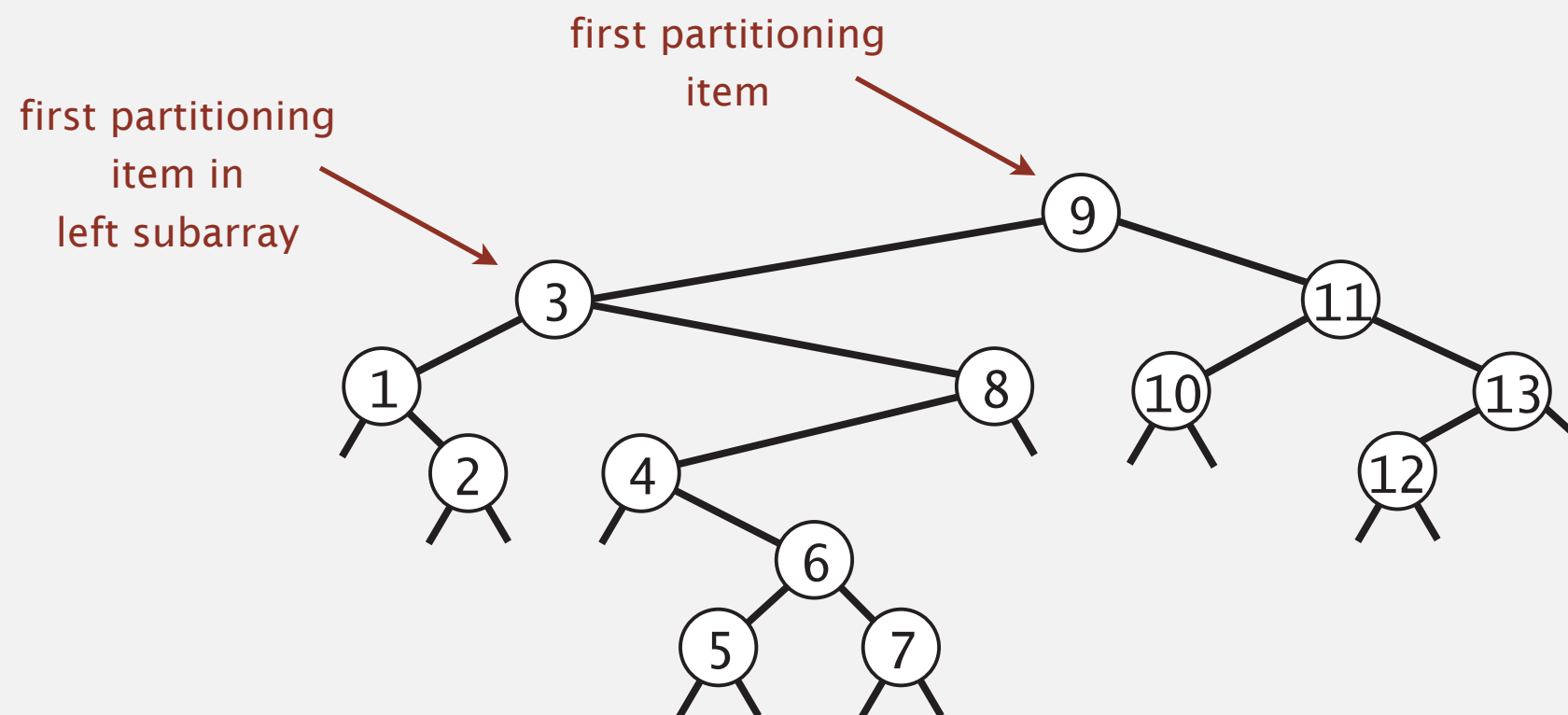
first partitioning
item

first partitioning
item in
left subarray

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Pf 2. Consider BST representation of keys 1 to N.

- A key is compared only with its ancestors and descendants.
- Probability i and j are compared equals $2 \,/\, |j - i + 1|$.

- Expected number of compares $=$ $\displaystyle \sum_{i=1}^{N} \sum_{j=i+1}^{N} \frac{2}{j - i + 1} \;=\; 2 \sum_{i=1}^{N} \sum_{j=2}^{N-i+1} \frac{1}{j}$

$$\leq \; 2N \sum_{j=1}^{N} \frac{1}{j}$$

$$\sim \; 2N \int_{x=1}^{N} \frac{1}{x} \, dx$$

$$= \; 2N \ln N$$

all pairs i and j

Quicksort: summary of performance characteristics

Worst case. Number of compares is quadratic.

- $N + (N-1) + (N-2) + \dots + 1 \sim \frac{1}{2} N^2.$
- More likely that your computer is struck by lightning bolt.

Average case. Number of compares is $\sim 1.39\, N \lg N.$

- 39% more compares than mergesort.
- But faster than mergesort in practice because of less data movement.

Random shuffle.

- Probabilistic guarantee against worst case.
- Basis for math model that can be validated with experiments.

Caveat emptor. Many textbook implementations go quadratic if array

- Is sorted or reverse sorted.
- Has many duplicates (even if randomized!)

Quicksort properties

Proposition. Quicksort is an in-place sorting algorithm.

Pf.

- Partitioning: constant extra space.
- Depth of recursion: logarithmic extra space (with high probability).

can guarantee logarithmic depth by
recurring on smaller subarray
before larger subarray

Proposition. Quicksort is not stable.

Pf.

i	j	0	1	2	3
		B	C	C	A
1	3	B	C	C	A
1	3	B	A	C	C
0	1	A	B	C	C

Quicksort: practical improvements

Insertion sort small subarrays.

- Even quicksort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for ≈ 10 items.
- Note: could delay insertion sort until one pass at end.

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1)
    {
        Insertion.sort(a, lo, hi);
        return;
    }
    int j = partition(a, lo, hi);
    sort(a, lo, j-1);
    sort(a, j+1, hi);
}
```

Quicksort: practical improvements
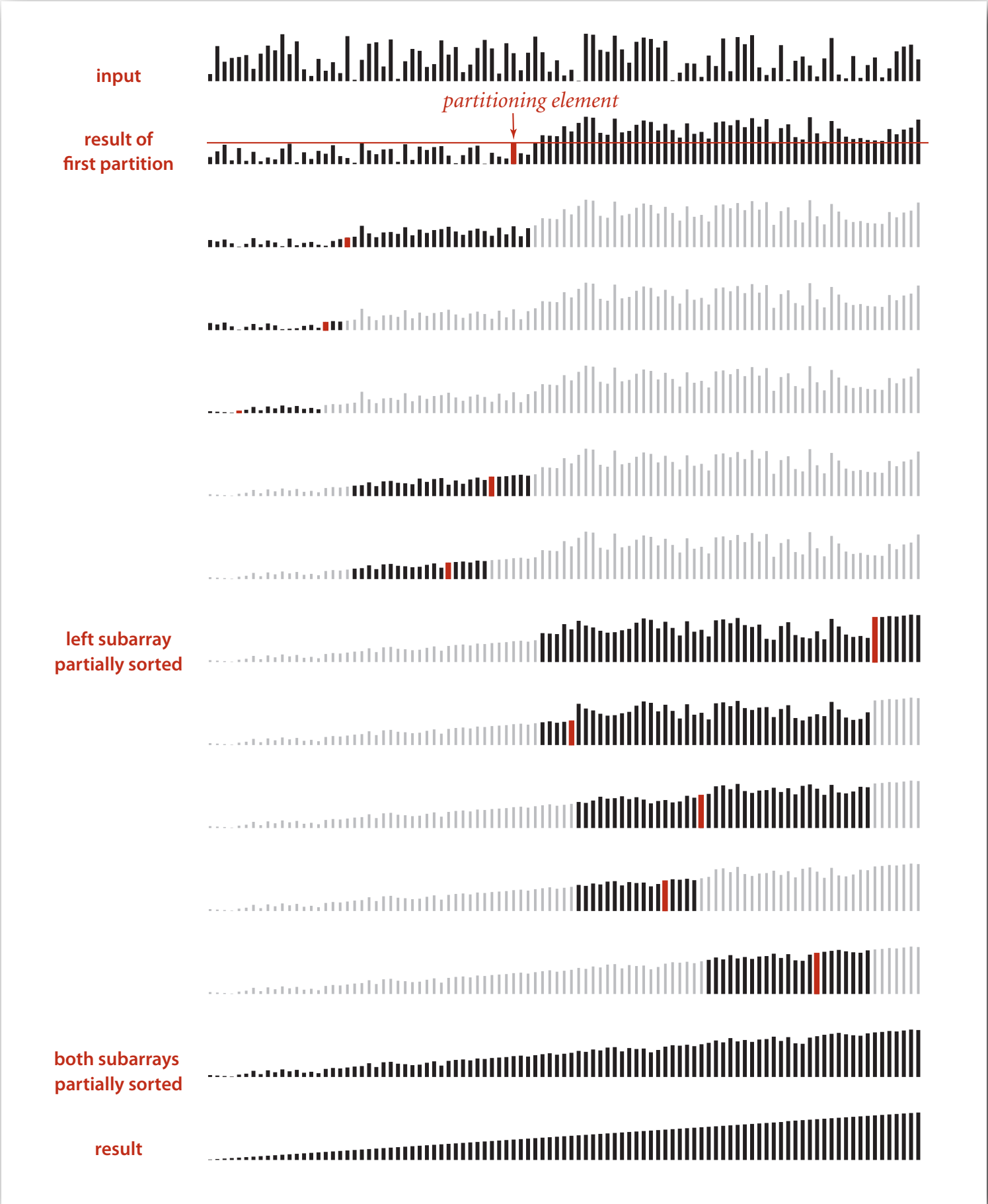
Median of sample.

- Best choice of pivot item = median.
- Estimate true median by taking median of sample.
- Median-of-3 (random) items.

~ 12/7 N ln N compares (slightly fewer)
~ 12/35 N ln N exchanges (slightly more)

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo) return;

    int m = medianOf3(a, lo, lo + (hi - lo)/2, hi);
    swap(a, lo, m);

    int j = partition(a, lo, hi);
    sort(a, lo, j-1);
    sort(a, j+1, hi);
}
```

input

partitioning element

result of
first partition

left subarray
partially sorted

both subarrays
partially sorted

result

Shuffling. Rearrange an array so that result is a uniformly random permutation.
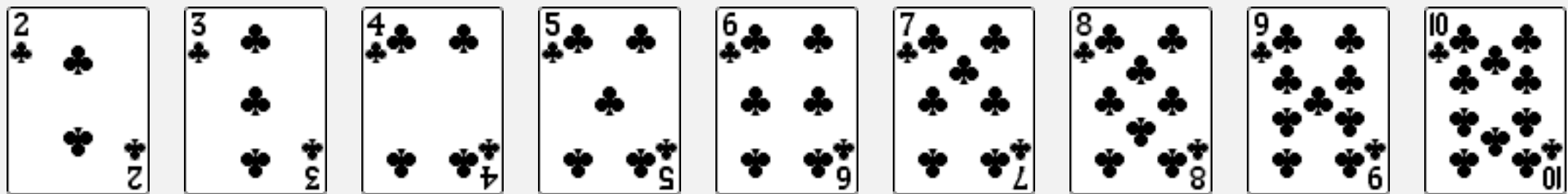
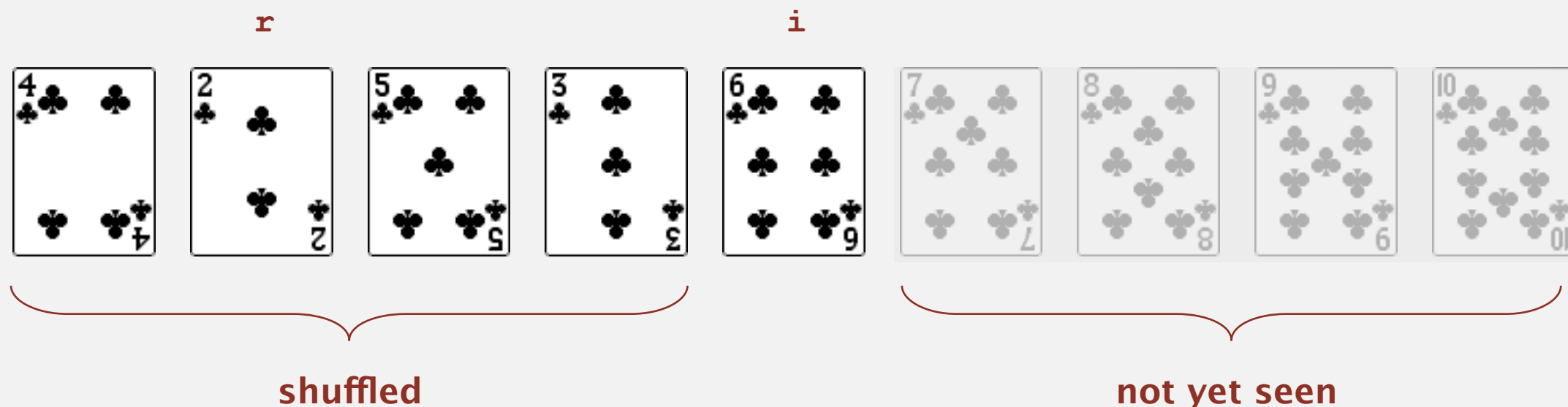Shuffling. Rearrange an array so that result is a uniformly random permutation.
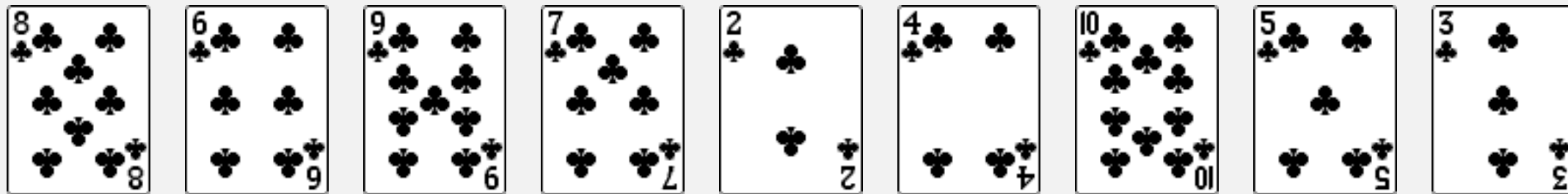
Knuth shuffle demo

Knuth shuffle. [Fisher-Yates 1938]

- In iteration `i`, pick integer `r` between `0` and `i` uniformly at random.
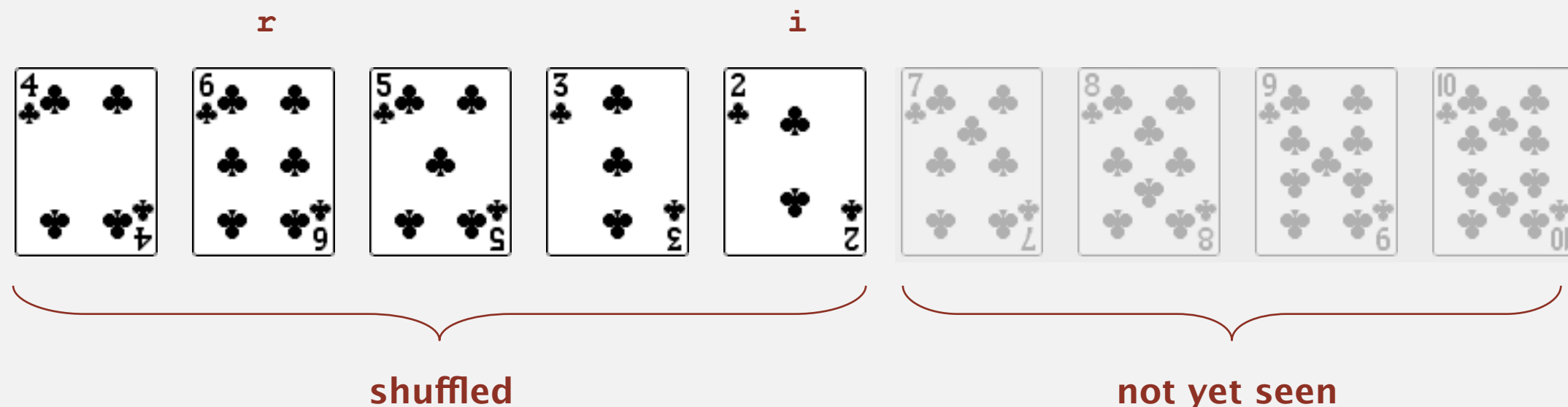
- Swap `a[i]` and `a[r]`.

r   i

shuffled   **not yet seen**

Proposition. Knuth shuffling algorithm produces a uniformly random
permutation of the input array in linear time.

assuming integers
uniformly at random

Knuth shuffle. [Fisher-Yates 1938]

- In iteration `i`, pick integer `r` between `0` and `i` uniformly at random.
- Swap `a[i]` and `a[r]`.

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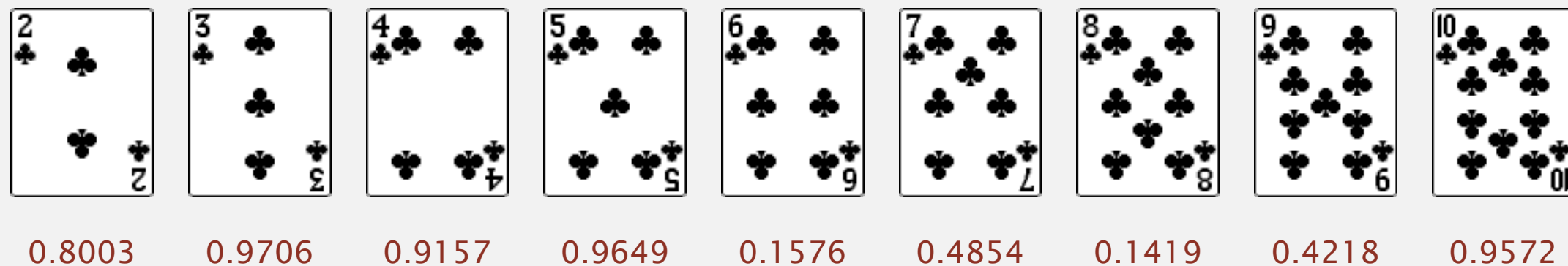Proposition. Knuth shuffling algorithm produces a uniformly random permutation of the input array in linear time.

assuming integers uniformly at random

Shuffle sort.

- Generate a random real number for each array entry.
- Sort the array.

↖ useful for shuffling
columns in a spreadsheet

| 0.8003 | 0.9706 | 0.9157 | 0.9649 | 0.1576 | 0.4854 | 0.1419 | 0.4218 | 0.9572 |

Proposition. Shuffle sort produces a uniformly random permutation of the input array, provided no duplicate values.

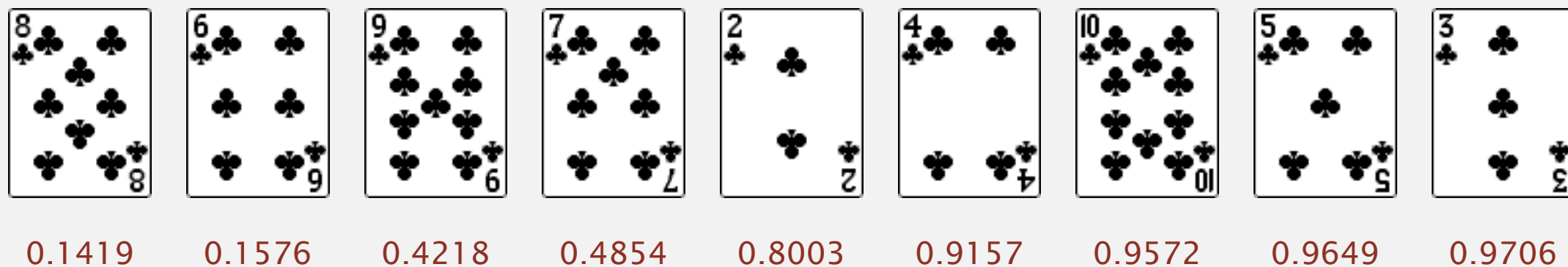↖ assuming real numbers
uniformly at random

Shuffle sort.

- Generate a random real number for each array entry.
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| 0.1419 | 0.1576 | 0.4218 | 0.4854 | 0.8003 | 0.9157 | 0.9572 | 0.9649 | 0.9706 |

Proposition. Shuffle sort produces a uniformly random permutation of the input array, provided no duplicate values.

assuming real numbers
uniformly at random

▸ quicksort

▸ **selection**

▸ duplicate keys

▸ system sorts

Goal. Given an array of N items, find the kth largest.

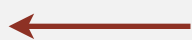Ex. Min $(k = 0)$, max $(k = N - 1)$, median $(k = N / 2)$.

Applications.

- Order statistics.
- Find the "top k."

Use theory as a guide.

- Easy $N \log N$ upper bound. How?
- Easy N upper bound for $k = 1, 2, 3$. How?
- Easy N lower bound. Why?

Which is true?

- $N \log N$ lower bound?   ⟵   is selection as hard as sorting?
- N upper bound?   ⟵   is there a linear-time algorithm for each k?
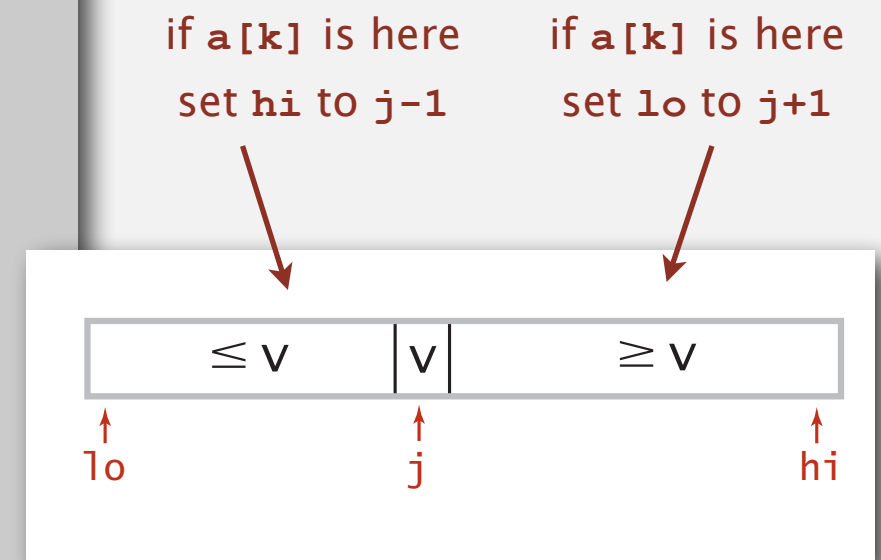
Quick-select

Partition array so that:

- Entry `a[j]` is in place.
- No larger entry to the left of `j`.
- No smaller entry to the right of `j`.

Repeat in one subarray, depending on `j`; finished when `j` equals `k`.

```java
public static Comparable select(Comparable[] a, int k)
{
    StdRandom.shuffle(a);
    int lo = 0, hi = a.length - 1;
    while (hi > lo)
    {
        int j = partition(a, lo, hi);
        if        (j < k) lo = j + 1;
        else if (j > k) hi = j - 1;
        else              return a[k];
    }
    return a[k];
}
```

if `a[k]` is here
set `hi` to `j-1`

if `a[k]` is here
set `lo` to `j+1`

| ≤ v | | v | | ≥ v |

lo   j   hi

Quick-select: mathematical analysis

Proposition. Quick-select takes linear time on average.

Pf sketch.

- Intuitively, each partitioning step splits array approximately in half:

  $N + N/2 + N/4 + \ldots + 1 \sim 2N$ compares.

- Formal analysis similar to quicksort analysis yields:

$$C_N = 2N + k \ln (N/k) + (N-k) \ln (N/(N-k))$$

(2 + 2 ln 2) N to find the median

Remark. Quick-select uses $\sim \frac{1}{2} N^2$ compares in the worst case, but (as with quicksort) the random shuffle provides a probabilistic guarantee.

Often, purpose of sort is to bring items with equal keys together.

- Sort population by age.
- Find collinear points.
- Remove duplicates from mailing list.
- Sort job applicants by college attended.

Typical characteristics of such applications.

- Huge array.
- Small number of key values.

```
Chicago 09:25:52
Chicago 09:03:13
Chicago 09:21:05
Chicago 09:19:46
Chicago 09:19:32
Chicago 09:00:00
Chicago 09:35:21
Chicago 09:00:59
Houston 09:01:10
Houston 09:00:13
Phoenix 09:37:44
Phoenix 09:00:03
Phoenix 09:14:25
Seattle 09:10:25
Seattle 09:36:14
Seattle 09:22:43
Seattle 09:10:11
Seattle 09:22:54
```

key

Duplicate keys

Mergesort with duplicate keys. Always between $\frac{1}{2} N \lg N$ and $N \lg N$ compares.

Quicksort with duplicate keys.

- Algorithm goes quadratic unless partitioning stops on equal keys!
- 1990s C user found this defect in `qsort()`.

several textbook and system
implementation also have this defect

S T O P O N E Q U A L K E Y S

swap

if we don't stop
on equal keys

if we stop
on equal
keys

Duplicate keys: the problem

Mistake. Put all items equal to the partitioning item on one side.

Consequence. $\sim \frac{1}{2}N^2$ compares when all keys equal.

B A A B A B B **B** C C C   A A A A A A A A A A **A**

Recommended. Stop scans on items equal to the partitioning item.

Consequence. $\sim N \lg N$ compares when all keys equal.

B A A B A **B** C C B C B   A A A A A **A** A A A A

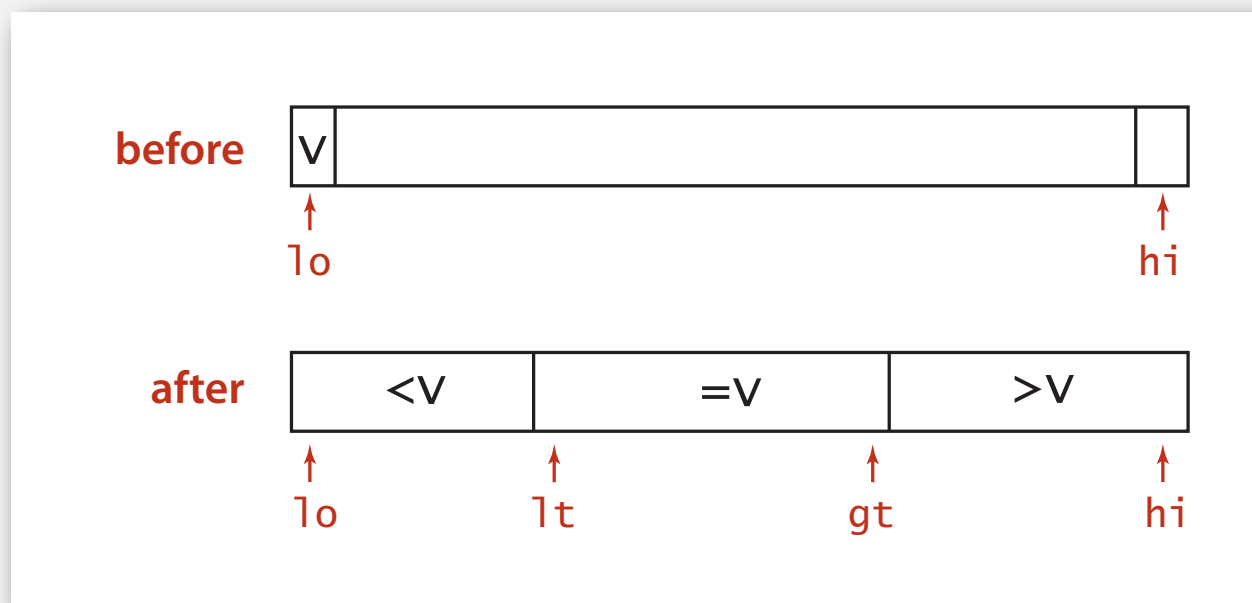Desirable. Put all items equal to the partitioning item in place.

A **A** **A** **B** **B** **B** **B** **B** C C C   **A** **A** **A** **A** **A** **A** **A** **A** **A** **A**

Goal. Partition array into 3 parts so that:

- Entries between `lt` and `gt` equal to partition item `v`.
- No larger entries to left of `lt`.
- No smaller entries to right of `gt`.

```
before   | V |                                    |   |
           ↑                                        ↑
           lo                                       hi

after    |     <V     |      =V      |     >V     |
           ↑            ↑              ↑            ↑
           lo           lt             gt           hi
```

Dutch national flag problem. [Edsger Dijkstra]

- Conventional wisdom until mid 1990s: not worth doing.
- New approach discovered when fixing mistake in C library `qsort()`.
- Now incorporated into `qsort()` and Java system sort.

Dijkstra 3-way partitioning algorithm

3-way partitioning.

- Let `v` be partitioning item `a[lo]`.
- Scan `i` from left to right.
  - `a[i]` less than `v`: exchange `a[lt]` with `a[i]` and increment both `lt` and `i`
  - `a[i]` greater than `v`: exchange `a[gt]` with `a[i]` and decrement `gt`
  - `a[i]` equal to `v`: increment `i`

Most of the right properties.

- In-place.
- Not much code.
- Linear time if keys are all equal.

| before	V			

↑ lo   ↑ hi

during	<V	=V		>V

↑ lt   ↑ i   ↑ gt

after	<V	=V	>V

↑ lo   ↑ lt   ↑ gt   ↑ hi
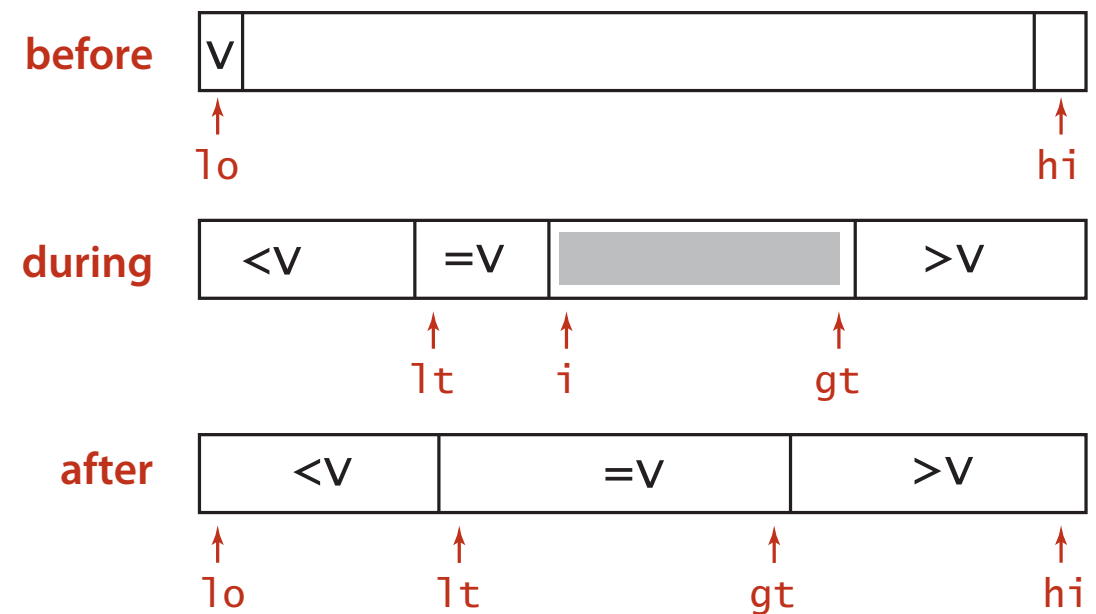
Dijkstra's 3-way partitioning: demo

a[]

lt	i	gt	0	1	2	3	4	5	6	7	8	9	10	11
0	0	11	R	B	W	W	R	W	B	R	R	W	B	R
0	1	11	R	B	W	W	R	W	B	R	R	W	B	R
1	2	11	B	R	W	W	R	W	B	R	R	W	B	R
1	2	10	B	R	R	W	R	W	B	R	R	W	B	W
1	3	10	B	R	R	W	R	W	B	R	R	W	B	W
1	3	9	B	R	R	B	R	W	B	R	R	W	W	W
2	4	9	B	B	R	R	R	W	B	R	R	W	W	W
2	5	9	B	B	R	R	R	W	B	R	R	W	W	W
2	5	8	B	B	R	R	R	W	B	R	R	W	W	W
2	5	7	B	B	R	R	R	R	B	R	W	W	W	W
2	6	7	B	B	R	R	R	R	B	R	W	W	W	W
3	7	7	B	B	B	R	R	R	R	R	W	W	W	W
3	8	7	B	B	B	R	R	R	R	R	W	W	W	W
3	8	7	B	B	B	R	R	R	R	R	W	W	W	W

3-way partitioning trace (array contents after each loop iteration)

equal to partitioning element
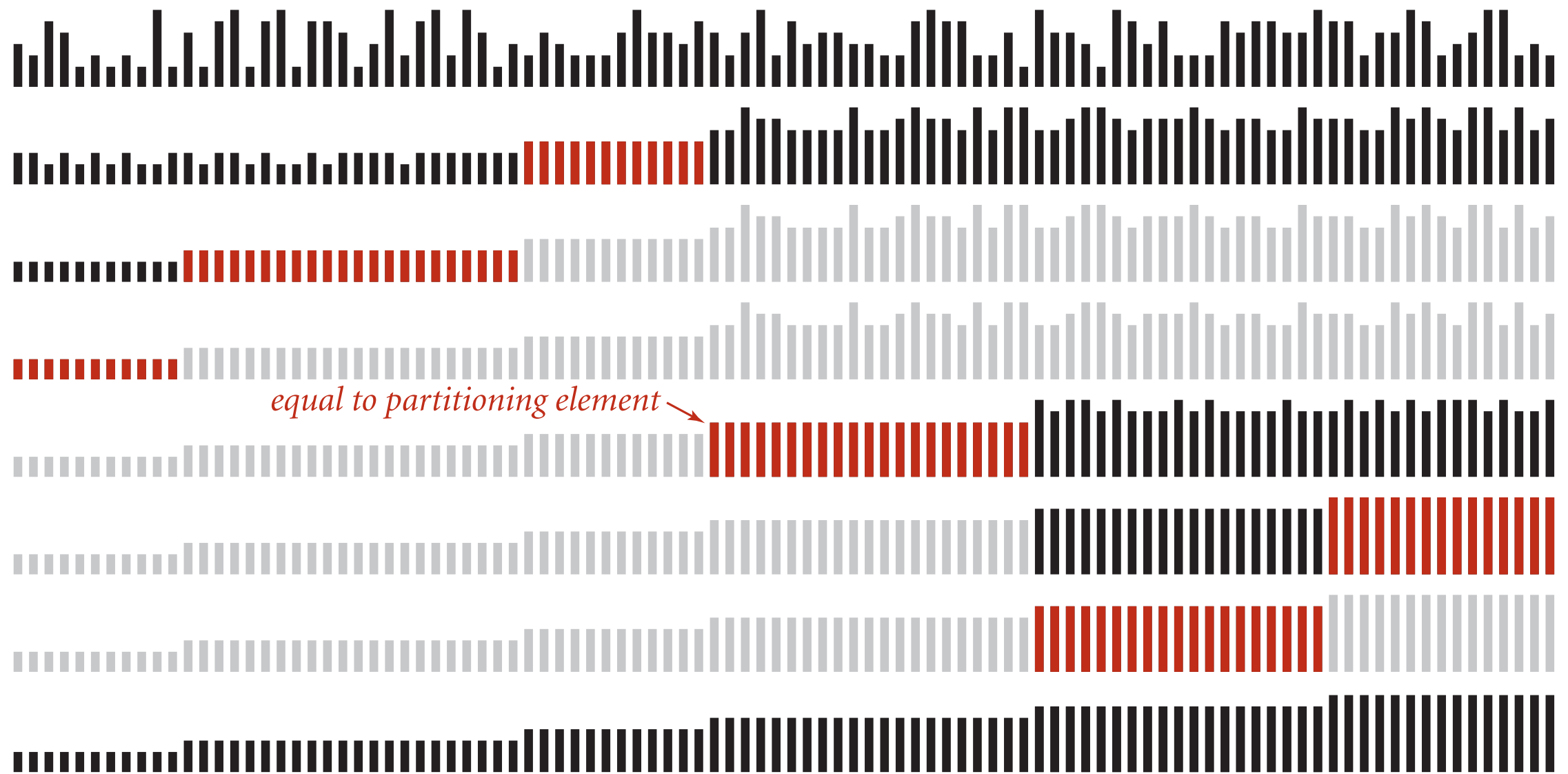
Sorting lower bound. If there are n distinct keys and the ith one occurs

x_i times, any compare-based sorting algorithm must use at least

$$\lg\left(\frac{N!}{x_1!\ x_2!\ \cdots\ x_n!}\right)\ \sim\ -\sum_{i=1}^{n} x_i \lg \frac{x_i}{N}$$

$N \lg N$ when all distinct;
linear when only a constant number of distinct keys

compares in the worst case.

proportional to lower bound

Proposition. [Sedgewick-Bentley, 1997]

Quicksort with 3-way partitioning is entropy-optimal.

Pf. [beyond scope of course]

Bottom line. Randomized quicksort with 3-way partitioning reduces running

time from linearithmic to linear in broad class of applications.

▸ selection

▸ duplicate keys

▸ comparators

▸ **Perspective of sorts…**

Sorting applications

Sorting algorithms are essential in a broad variety of applications:

- Sort a list of names.
- Organize an MP3 library.
- Display Google PageRank results.
- List RSS feed in reverse chronological order.

obvious applications

- Find the median.
- Find the closest pair.
- Binary search in a database.
- Identify statistical outliers.
- Find duplicates in a mailing list.

problems become easy once items are in sorted order

- Data compression.
- Computer graphics.
- Computational biology.
- Supply chain management.
- Load balancing on a parallel computer.

  . . .

non-obvious applications

Every system needs (and has) a system sort!

System sort: Which algorithm to use?

Many sorting algorithms to choose from:

Internal sorts.

- Insertion sort, selection sort, bubblesort, shaker sort.
- Quicksort, mergesort, heapsort, samplesort, shellsort.
- Solitaire sort, red-black sort, splaysort, Dobosiewicz sort, psort, ...

External sorts. Poly-phase mergesort, cascade-merge, oscillating sort.

String/radix sorts. Distribution, MSD, LSD, 3-way string quicksort.

Parallel sorts.

- Bitonic sort, Batcher even-odd sort.
- Smooth sort, cube sort, column sort.
- GPUsort.

System sort: Which algorithm to use?

Applications have diverse attributes.

- Stable?
- Parallel?
- Deterministic?
- Keys all distinct?
- Multiple key types?
- Linked list or arrays?
- Large or small items?
- Is your array randomly ordered?
- Need guaranteed performance?

many more combinations of attributes than algorithms

Elementary sort may be method of choice for some combination.

Cannot cover all combinations of attributes.

Q. Is the system sort good enough?

A. Usually.

Sorting summary

	inplace?	stable?	worst	average	best	remarks
selection	x		N	N	N	N exchanges
insertion	x	x	N	N	N	use for small N or partially ordered
shell	x		?	?	N	tight code, subquadratic
merge		x	N lg N	N lg N	N lg N	$N \log N$ guarantee, stable
quick	x		N	2 N ln N	N lg N	$N \log N$ probabilistic guarantee fastest in practice
3-way quick	x		N	2 N ln N	N	improves quicksort in presence of duplicate keys
???	x	x	N lg N	N lg N	N lg N	holy sorting grail

Which sorting algorithm?

lifo	find	data	data	data	data	hash	data
fifo	fifo	fifo	fifo	exch	fifo	fifo	exch
data	data	find	find	fifo	lifo	data	fifo
type	exch	hash	hash	find	type	link	find
hash	hash	heap	heap	hash	hash	leaf	hash
heap	heap	lifo	lifo	heap	heap	heap	heap
sort	less	link	link	leaf	link	exch	leaf
link	left	list	list	left	sort	node	left
list	leaf	push	push	less	find	lifo	less
push	lifo	root	root	lifo	list	left	lifo
find	push	sort	sort	link	push	find	link
root	root	type	type	list	root	path	list
leaf	list	leaf	leaf	sort	leaf	list	next
tree	tree	left	tree	tree	null	next	node
null	null	node	null	null	path	less	null
path	path	null	path	path	tree	root	path
node	node	path	node	node	exch	sink	push
left	link	tree	left	type	left	swim	root
less	sort	exch	less	root	less	null	sink
exch	type	less	exch	push	node	sort	sort
sink	sink	next	sink	sink	next	type	swap
swim	swim	sink	swim	swim	sink	tree	swim
next	next	swap	next	next	swap	push	tree
swap	swap	swim	swap	swap	swim	swap	type
original	?	?	?	?	?	?	sorted

Which sorting algorithm?

lifo	find	data	data	data	data	hash	data
fifo	fifo	fifo	fifo	exch	fifo	fifo	exch
data	data	find	find	fifo	lifo	data	fifo
type	exch	hash	hash	find	type	link	find
hash	hash	heap	heap	hash	hash	leaf	hash
heap	heap	lifo	lifo	heap	heap	heap	heap
sort	less	link	link	leaf	link	exch	leaf
link	left	list	list	left	sort	node	left
list	leaf	push	push	less	find	lifo	less
push	lifo	root	root	lifo	list	left	lifo
find	push	sort	sort	link	push	find	link
root	root	type	type	list	root	path	list
leaf	list	leaf	leaf	sort	leaf	list	next
tree	tree	left	tree	tree	null	next	node
null	null	node	null	null	path	less	null
path	path	null	path	path	tree	root	path
node	node	path	node	node	exch	sink	push
left	link	tree	left	type	left	swim	root
less	sort	exch	less	root	less	null	sink
exch	type	less	exch	push	node	sort	sort
sink	sink	next	sink	sink	next	type	swap
swim	swim	sink	swim	swim	sink	tree	swim
next	next	swap	next	next	swap	push	tree
swap	swap	swim	swap	swap	swim	swap	type

original	quicksort	mergesort	insertion	selection	merge BU	shellsort	sorted

101