

Wavefield simulations of earthquakes in southern Alaska for tomographic inversion

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Overview

We assemble a catalog of moment tensors (Silwal and Tape, 2016) and a three-dimensional seismic velocity model for southern Alaska, in preparation for an iterative tomographic inversion using spectral-element and adjoint methods. The primary geometrical interfaces in the model are the Moho surface, the basement surface of major sedimentary basins, and the topographic surface. The crustal and upper mantle tomographic model is from Eberhart-Phillips et al. (2006), but modified by removing the uppermost slow layer, then embedding the Cook Inlet basin model. We compute 3D synthetic seismograms using the spectral-element method. We demonstrate the accuracy of the initial three-dimensional reference model by comparing 3D synthetics with observed data for several earthquakes originating in the crust and underlying subducting slab. Full waveform similarity between data and synthetics over the period range 5 s to 50 s provides a solid basis for an iterative inversion. The target resolution of the crustal structure is 4 km vertically and 20 km laterally. We use surface wave and body wave measurements from local earthquakes to obtain moment tensors that will be used within our tomographic inversion. Local slab events down to 180 km depth, in addition to pervasive crustal seismicity, should enhance resolution.

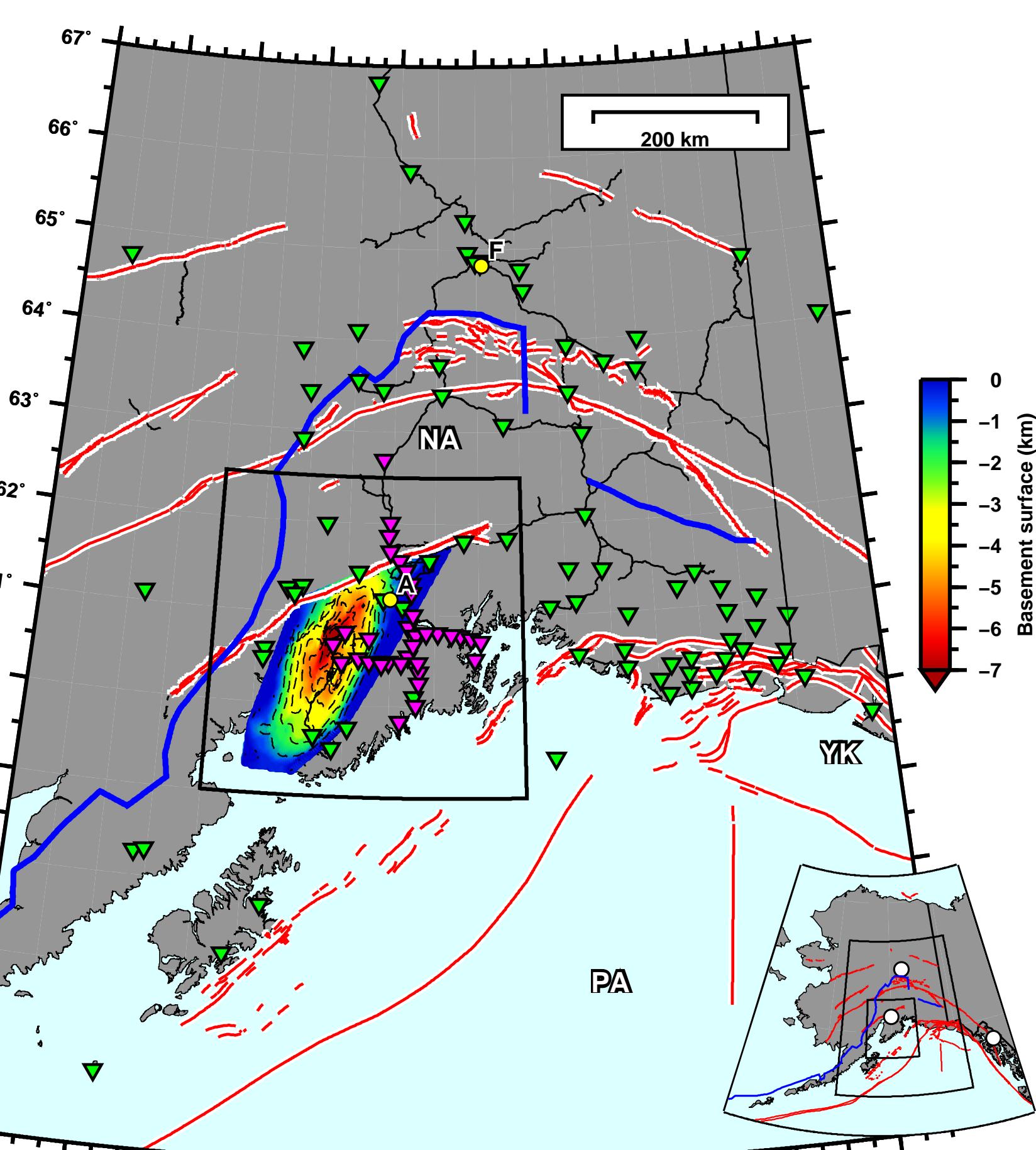


Figure 1: (top) Active faults (red) and the broadband station coverage in Alaska for the time period of this study, 15 August 2007 to 15 August 2009 (green = permanent stations; magenta = MOOS stations). The tertiary basement surface of Cook Inlet basin is color coded for depth. (bottom) Moment tensor beachballs for 106 events presented in the catalog (Silwal and Tape, 2016).

Grid search for best moment tensor

We perform a grid search in the moment tensor model space $\mathbf{m} = (\phi, \delta, \lambda, M_w, z)$.

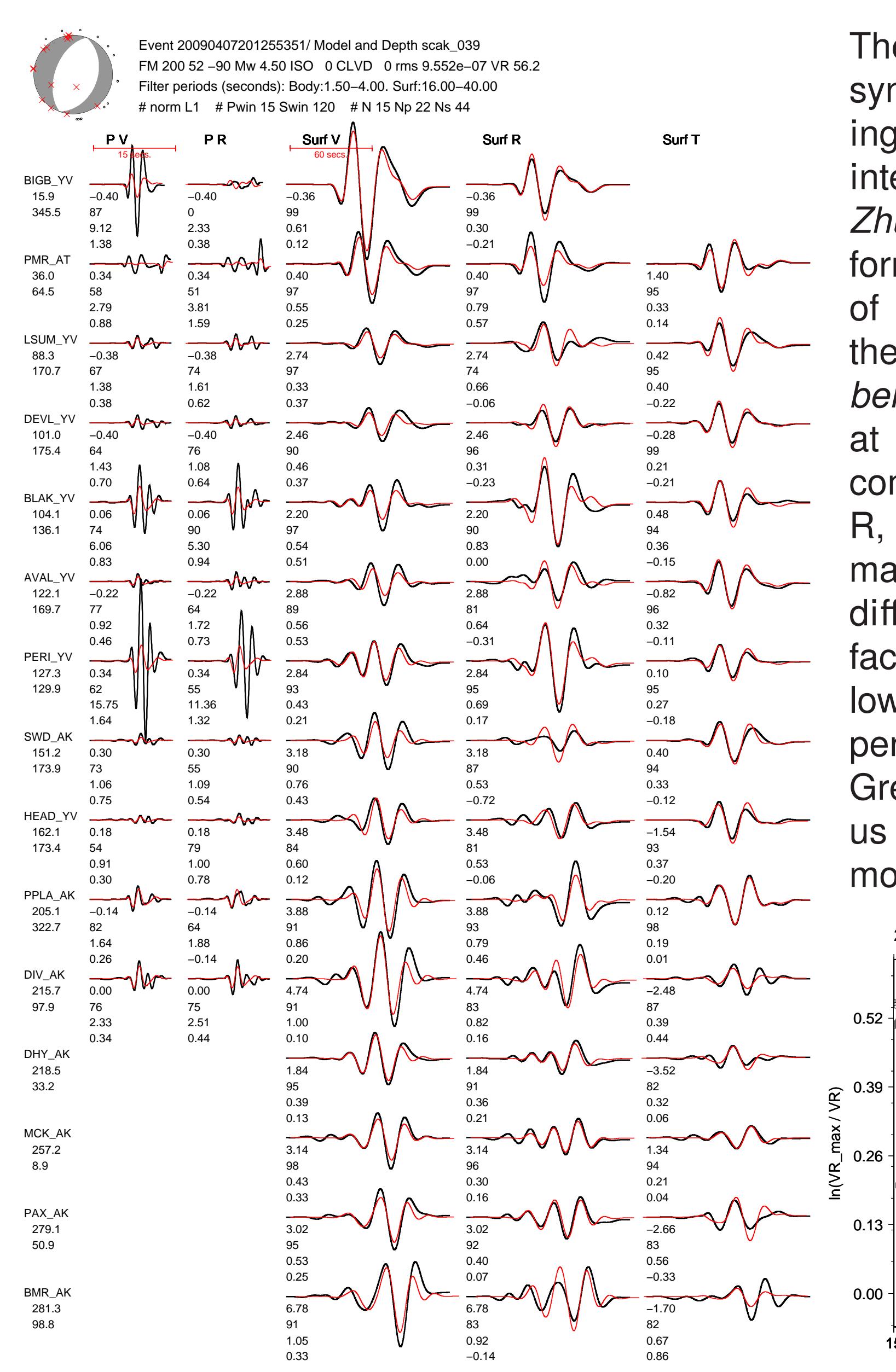


Figure 2: (left) Moment tensor solution and waveform comparisons for the example event in Anchorage, April 7, 2009. Waveform fit between the data (black) and the synthetics (red). Number below the waveforms are, from top to bottom, (1) time shift required for matching the synthetics with the data; (2) maximum cross-correlation percentage between data and synthetics; (3) the percentage of the total misfit; (4) log amplitude between data and synthetics in each window. Number below the station name are distance and azimuth. (right) Grid search for best fitting depth. Blue ticks mark the layer boundaries in the 1D model used in the inversion.

Southern Alaska velocity model

We use 3D velocity model of Alaska obtained from Eberhart-Phillips et al. (2006) and embed the Cook Inlet basin model (Shellenbaum et al., 2010) on it. Topography is included in the mesh, and the model is extrapolated wherever necessary. The mesh includes 2 tripling layer at ~8 km and ~50 km. The dimensions of the mesh are: Latitude = [59, 62.5], Longitude = [-154, -147]; and extends to the depth of 400 km. For the 3D adjoint tomographic inversions this will be our starting model.

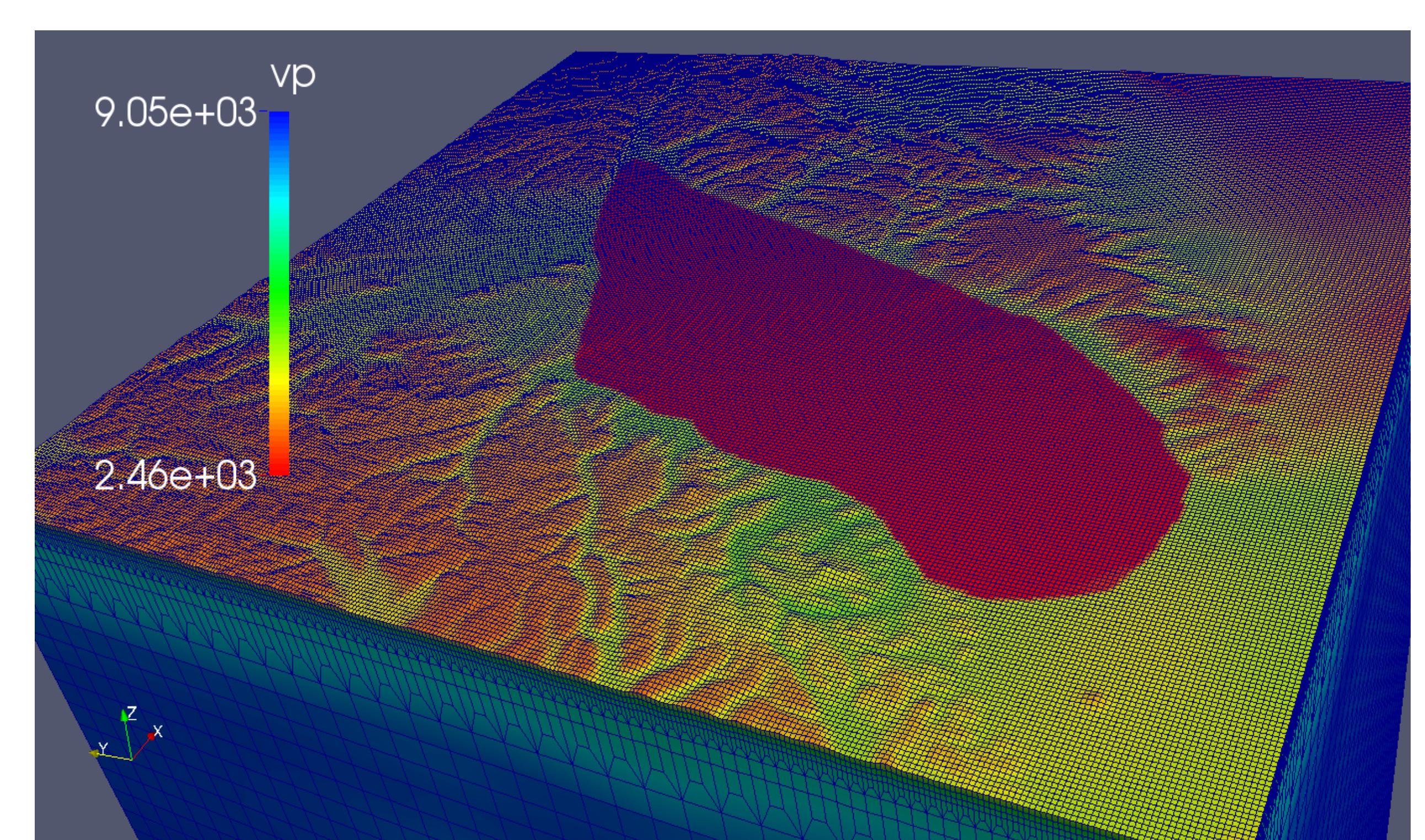


Figure 3: Mesh of southern Alaska with the Eberhart2006 3D velocity model and the Cook Inlet basin (Shellenbaum2010).

Effects of Cook Inlet basin

(a) Extrapolated crust (MOD_A) (b) Shallow crust + Basin (MOD_B)

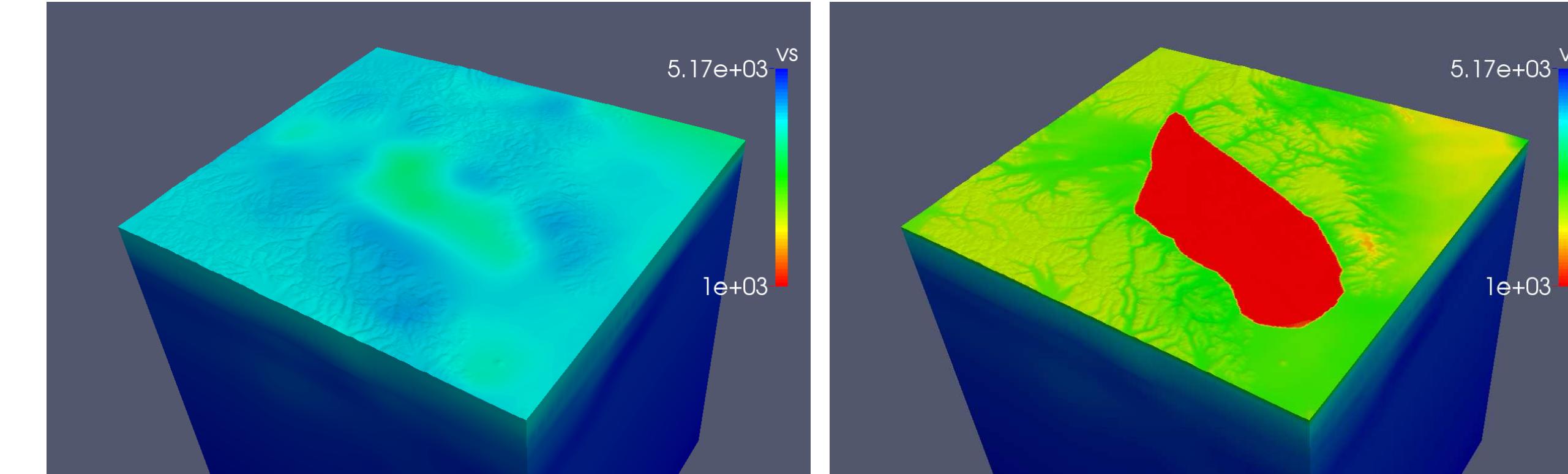
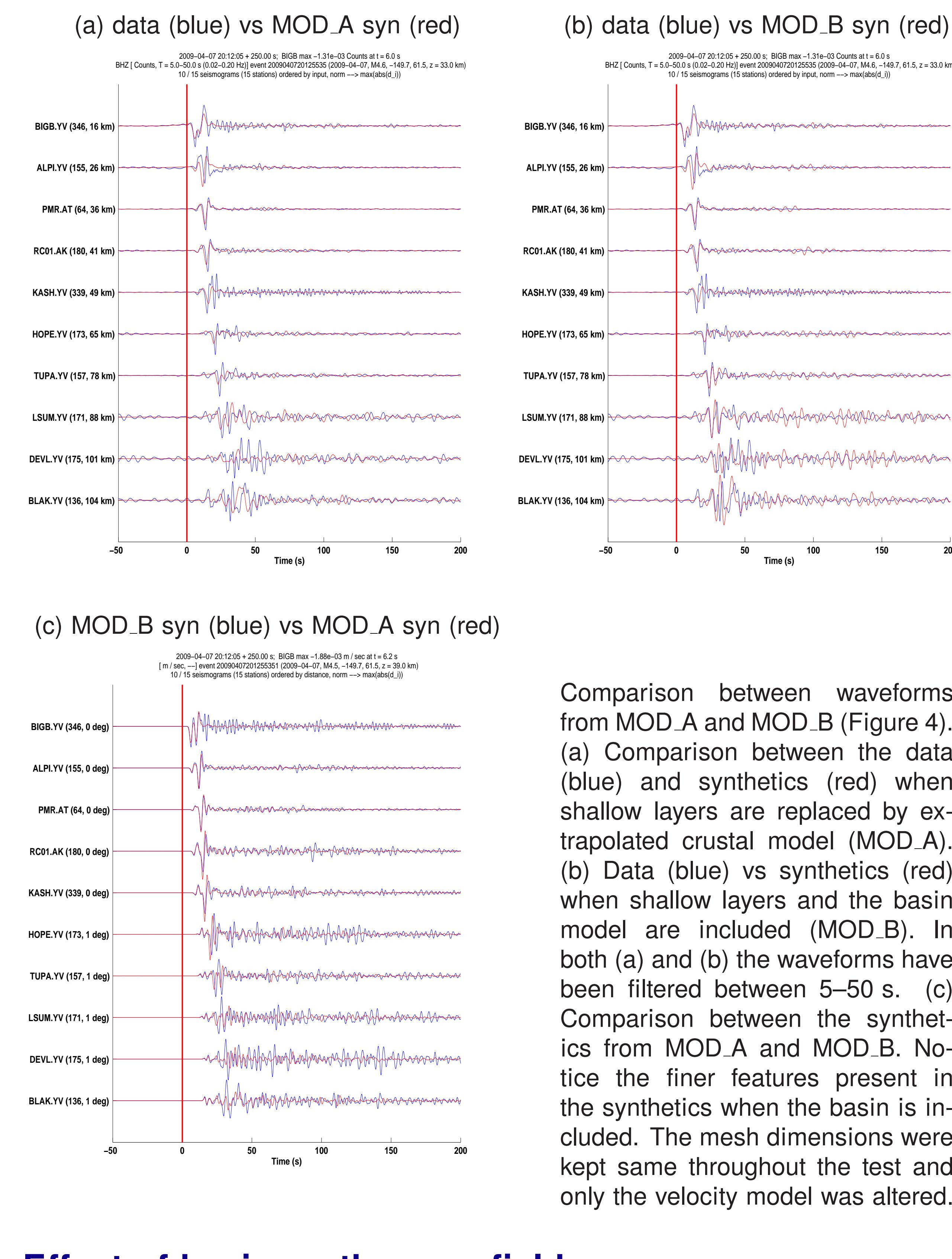


Figure 4: Two different velocity models for studying the effects shallow layers on the waveform. (a) MOD_A - We remove the shallow layer (top 1 km) from the Eberhart2006 model and extrapolate the remaining crustal model upwards. (b) MOD_B - Shallow crustal layer from Eberhart2006 are included and the basin model Shellenbaum2010 has been embedded in it.



Effect of basin on the wavefield

Simulations of M7.1 Iniskin earthquake

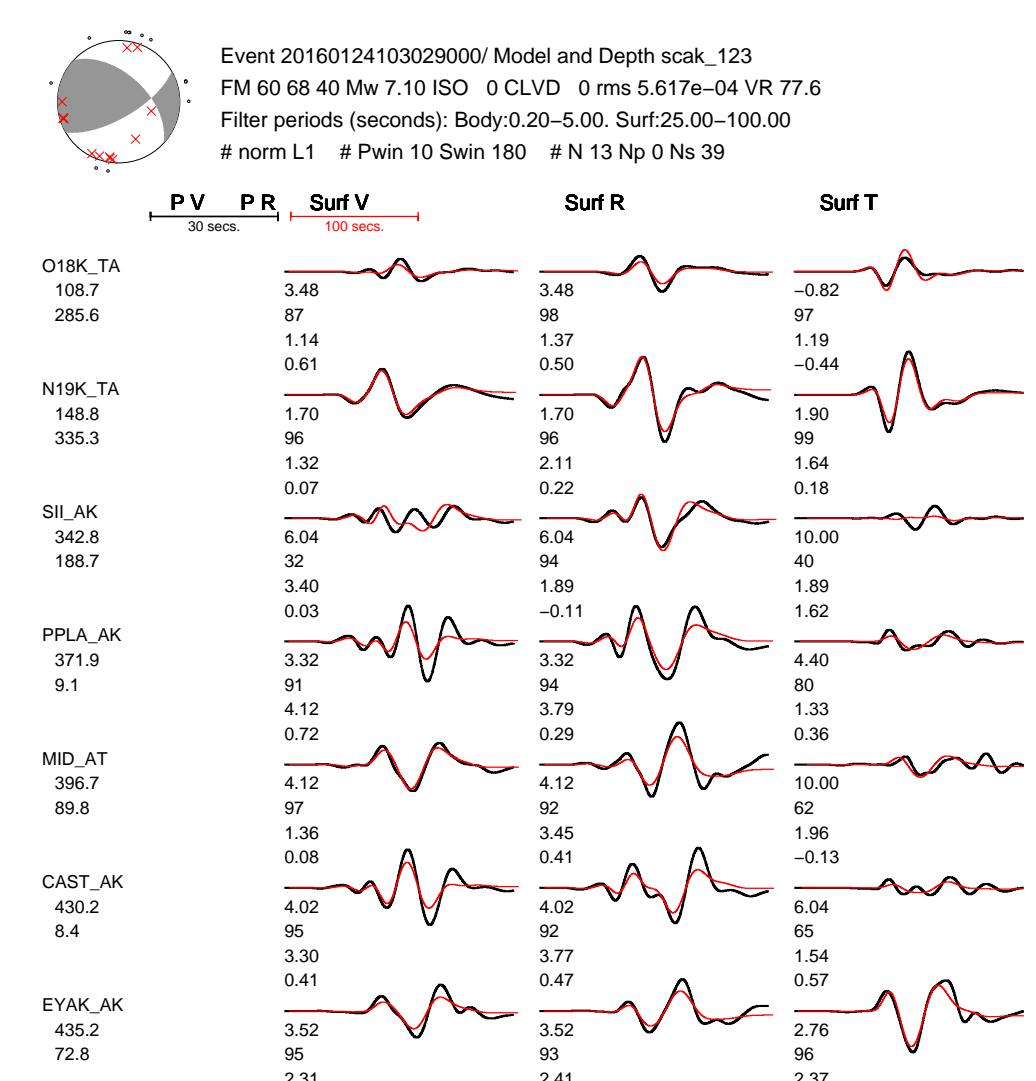


Figure 6: Synthetics for Iniskin earthquake using the 3D velocity model as described earlier (with half duration = 2 sec). (b) The source was estimated using surface waves at 25 - 200 sec generated using 1D SCAK model.

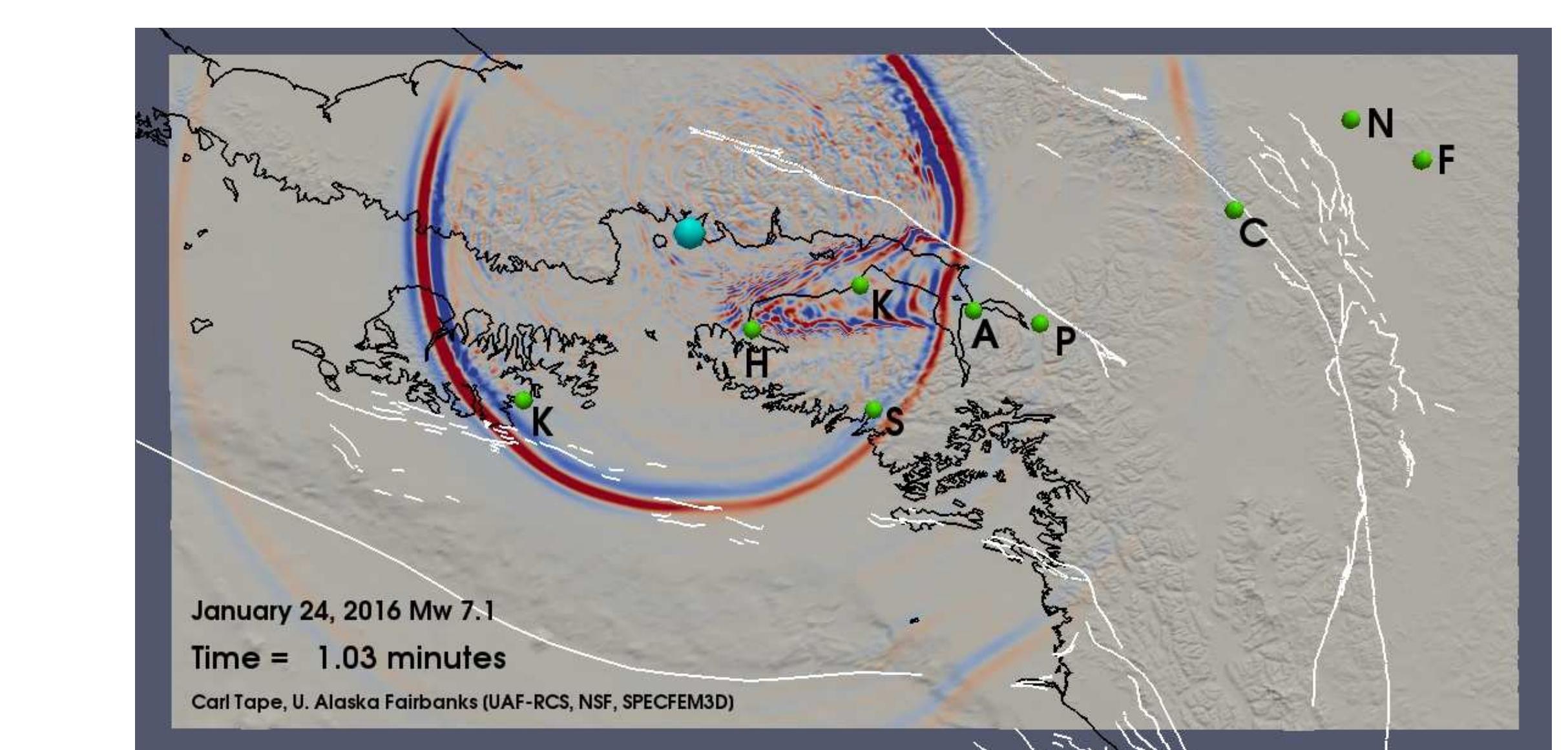


Figure 7: (a) Wavefield simulation of January 24, 2016, M7.1 Iniskin earthquake. <http://www.giseis.alaska.edu/input/carl/research/earthquakes/iniskin.html>

Summary

1. We perform moment tensor inversions in southern Alaska for 159 earthquakes between 2007-01-01 and 2014-05-01 (Silwal and Tape, 2016). The inversions were performed using body waves (1–3 s) and surface waves (16–40 s).
2. Wavefield simulation within a 3D earth structure model produce synthetic seismograms that differ significantly from 1D synthetics but are close enough to observed seismograms to allow us to quantify the waveform misfit and to use these differences within an adjoint tomographic inversion.
3. We examine the influence of the shallowest (slow) layers on 3D synthetic seismograms. It appears that the detailed model for Cook Inlet basin is necessary for achieving reasonable waveform fits, even at relatively long periods (>5 s).
4. Our next step is to calculate 3D synthetic seismograms for all earthquakes, then evaluate a misfit function, then calculate volumetric event kernels to be used within the tomographic inversion, following previous efforts such as in southern California (e.g., Tape et al., 2009).

Acknowledgements

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References

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Figure 5: Snapshots of a 3D wavefield simulation of , showing the strong influence of the Cook Inlet basin on the wavefield. Blue circles denote permanent broadband stations. Note the striking effect due to the slow wave speeds within Cook Inlet sedimentary basin. A = Anchorage, K = Kenai, RV = Redoubt volcano.