**SLAD Dataset Release Agreement**

The Visual, Sensing and Intelligent System Lab of Shandong University has constructed the vessel re-identification dataset (referred to as SLAD in the following text). The aims of the SLAD dataset include (1) providing a comprehensive benchmark to validate the effectiveness of a wide range of computer vision algorithms; (2) facilitating a wide range of novel research topics related to “vessels”. **Therefore, the SLAD dataset is now made available for research purpose only on a case-by-case basis.** The Visual, Sensing and Intelligent System Lab of Shandong University is serving as the technical agent for distribution of the dataset. Any researcher who requests the SLAD dataset must sign this agreement and thereby agree to obey the restrictions listed in this document. Failure to observe the restrictions will result in access being denied for the request of the future version of the SLAD dataset.

The researcher(s) agrees to the following restrictions on the SLAD dataset:

1. The SLAD dataset is available for non-commercial research purposes only.

2. You agree not to reproduce, duplicate, copy, sell, trade, resell or exploit for any commercial purposes, any portion of the annotated data.

3. You agree not to further copy, publish or distribute any portion of the SLAD dataset. Except, for internal use at a single site within the same organization it is allowed to make copies of the dataset.

4. The Visual, Sensing and Intelligent System Lab of Shandong University reserves the right to terminate your access to the database at any time.

5. All submitted papers or any public text using the SLAD dataset must cite the following paper:

Mingxin Zhang, Qian Zhang, Ran Song, Paul L. Rosin, Wei Zhang: **Ship Landmark: An Informative Ship Image Annotation and Its Applications**. IEEE Transactions on Intelligent Transportation Systems.

6. The final explanation of this agreement refers to the Visual, Sensing and Intelligent System Lab of Shandong University.

Printed Name: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Position: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Signature: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Date: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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