

CUTIE: Learning to Understand Documents with Convolutional Universal Text Information Extractor

Xiaohui Zhao, Zhuo Wu, and Xiaoguang Wang

New IT Accenture

xh.zhao@outlook.com zhuo.wu@accenture.com danny.x.wang@accenture.com

Abstract

Extracting key information from documents, such as receipts or invoices, and preserving the interested texts to structured data is crucial in the document-intensive streamline processes of office automation in areas that includes but not limited to accounting, financial, and taxation areas. To avoid designing expert rules for each specific type of document, some published works attempt to tackle the problem by learning a model to explore the semantic context in text sequences based on the Named Entity Recognition (NER) method in the NLP field. In this paper, we propose to harness the effective information from both semantic meaning and spatial distribution of texts in documents. Specifically, our proposed model, Convolutional Universal Text Information Extractor (CUTIE), applies convolutional neural networks on gridded texts where texts are embedded as features with semantical connotations. We further explore the effect of employing different structures of convolutional neural network and propose a fast and portable structure. We demonstrate the effectiveness of the proposed method on a dataset with up to 6,980 labelled receipts, without any pre-training or post-processing, achieving state of the art performance that is much higher than BERT but with only 1/10 parameters and without requiring the 3,300M word dataset for pre-training. Experimental results also demonstrate that the CUTIE being able to achieve state of the art performance with much smaller amount of training data.

1. Introduction

Implementing Scanned receipts OCR and information extraction (SROIE) is of great benefit to services and applications such as efficient archiving, compliance check, and fast indexing in the document-intensive streamline processes of office automation in areas that includes but not limit to accounting, financial, and taxation areas. There are two specific tasks involved in SROIE: receipt OCR and key information extraction. In this work, we focus on the second

task that is rare in published research. In fact, key information extraction faces big challenges, where different types of document structures and vast number of potential interested key words introduces great difficulties. Although the commonly used rule-based method can be implemented with carefully designed expert rules, it can only work on specific type of documents and takes no lesser effort to adapt to new type of documents. Therefore, it is desirable to have a learning-based key information extraction method with limited requirement of human resources and solely employing the deep learning technique without designing expert rules for any specific type of documents.

CloudScan is a learning based invoice analysis system [9]. Aiming to not rely on invoice layout templates, CloudScan trains a model that could be generalized to unseen invoice layouts, where a model is trained either using Long Short Term Memory (LSTM) or Logistic Regression (LR) with expert designed rules as training features. This turns out to be extremely similar with solving a Named Entity Recognition (NER) or slot filling task. For that reason, several models can be employed, e.g., the Bi-directional Encoder Representations from Transformers (BERT) model is a recently proposed state of the art method and has achieved great success in a wide of range of NLP tasks including NER [7]. However, the NER models were not originally designed to solve the key information extraction problem in SROIE. To employ NER models, text words in the original document are aligned as a long paragraph in line-based rule. In fact, documents, such as receipts and invoices, present with various styles of layouts that were designed for different scenarios or from different enterprise entities. The order or word-to-word distance of the texts in the line-base-aligned long paragraph tend to vary greatly due to layout variations, which is difficult to be handled with the natural language oriented methods. Typical example of documents with different layouts are illustrated in Fig. 2.

In this work, attempting to involve the spatial information into the key information extraction process, we propose to tackle this problem by using the CNN based network structure and involve the semantic features in a care-

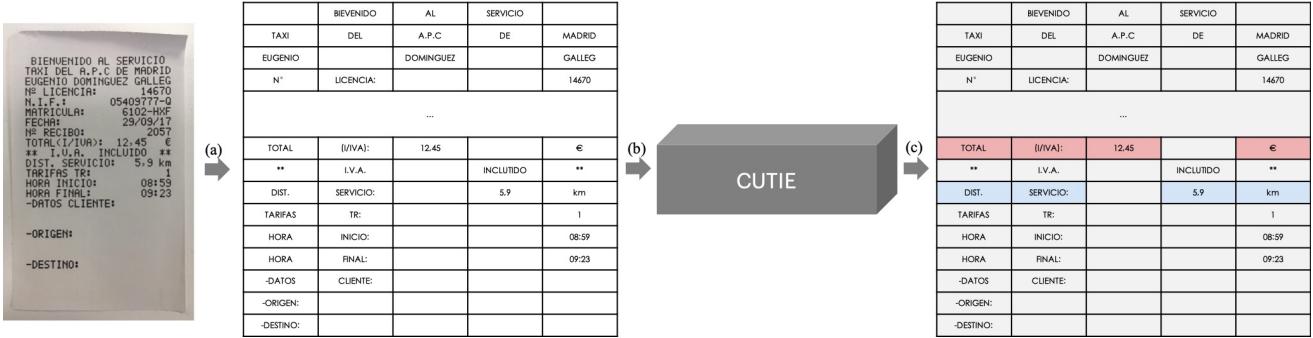


Figure 1. Framework of the proposed method, (a) positional map the scanned document image to a grid with text's relative spatial relation preserved, (b) feed the generated grid into the CNN for extracting key information, (c) reverse map the extracted key information for visual reference.

fully designed fashion. In particular, our proposed model, called Convolutional Universal Text Information Extractor (CUTIE), tackles the key information extraction problem by applying convolutional deep learning model on the gridded texts, as illustrated in Fig. 1. The gridded texts is formed with the proposed grid positional mapping method, where the grid is generated with the principle that is preserving texts' relative spatial relationship in the original scanned document image. The rich semantic information is encoded from the gridded texts at the very beginning stage of the convolutional neural network with a word embedding layer. The CUTIE allows for simultaneously looking into both semantical information and spatial information of the texts in the scanned document image and can reach a new state of the art result for key information extraction, which outperforms BERT model but without demanding of pretraining on a huge text dataset [7, 12].

2. Related Works

Several rule-based invoice analysis systems were proposed in [10, 6, 8]. Intellix by DocuWare requires the a template being annotated with relevant fields [10]. For that reason, a collection of templates have to be constructed. SmartFix employs specifically designed configuration rules for each template [6]. Esser et al. uses a dataset of fixed key information positions for each template [8]. It is not hard to find that the rule-based methods rely heavily on the pre-defined template rules to extract information from specific invoice layouts.

CloudScan is a work attempting to extract key information with learning based models [9]. Firstly, N-grams features are formed by connecting expert designed rules calculated results on texts of each document line. Then, the features are feed to train a RNN-based or a logistic regression based classifier for key information extraction. Certain post-processing are added to further enhance extraction results. However, the line-based feature extraction method

can not achieve its best performance if document texts are not perfectly aligned in line. Moreover, the RNN-based classifier, bi-directional LSTM model in CloudScan, has limited ability to learn relationship among distant words.

Bidirectional Encoder Representations from Transformers (BERT) is a recently proposed model that is pre-trained on a huge dataset and can be fine-tuned for a specific task, including Named Entity Recognition (NER), which outperforms most of the state of the art results in several NLP tasks [7]. Since the previous learning based methods treats the key information extraction problem as a NER problem, applying BERT can achieve better result than bi-LSTM in CloudScan.

3. Methods

In this section, we introduce the method proposed for creating grid data for model training. We then present the network architectures that capture long distance information and avoid information loss in the convolutional neural networks that have striding or pooling processes.

3.1. Grid Positional Mapping

To generate input grid data for the convolutional neural network, the scanned document image are processed by an OCR engine to acquire the texts and their absolute / relative positions. Let the scanned document image be of shape (w, h) , the minimum bounding box around the i -th interested text s_i be b_i that is restricted by two corner coordinates, where the upper-left corner coordinate in the scanned document be (x_{left}^i, y_{top}^i) and the bottom right of the bounding box be $(x_{right}^i, y_{bottom}^i)$. To avoid the affects from overlapped bounding boxes and reveal the actual relative position among texts, we calculate the center point (c_x^i, c_y^i) of the bounding boxes as the reference position. It is not hard to find that involving pre-processes that combine texts into meaningful entities will benefit the grid positional mapping process. However, this is not the major purpose of

this paper and we leave it to future researches. In this paper, we tokenize the text words with a greedy longest-match-first algorithm using a pre-defined dictionary [1].

Let the grid positional mapping process be G and the target grid size be (c_{gm}, r_{gm}) . To generate the grid data, the goal of G is to map the texts from the original scanned document image to the target grid, such that the mapped grid preserves the original spatial relationship among texts yet more suitable to be used as the input for the convolutional neural network. The mapping position of texts in the grid is calculated as

$$c_x^i = c_{gm} \frac{x_{left} + \frac{(x_{right} - x_{left})}{2}}{w} \quad (1)$$

$$r_y^i = r_{gm} \frac{y_{top} + \frac{(y_{bottom} - y_{top})}{2}}{h} \quad (2)$$

For tokenized texts, the bounding box is horizontally divided into multiple boxes and their row and col reference positions are calculated using the same criteria as Equ. 1 and Equ. 2, separately. Furthermore, to enhance the capability of CUTIE to better handle documents with different layouts, we augment the grid data to shapes with different rows and columns by random sampling a Gaussian distribution for with probability

$$p_c(k) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(k-c_{gt})^2}{2\sigma^2}} \quad (3)$$

$$p_r(k) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(k-r_{gt})^2}{2\sigma^2}} \quad (4)$$

where c_{gt} is the mean center of the target augment grid size, r_{gt} is the mean center of the target augment grid size, and σ is the standard deviation.

3.2. CUTIE Model

Through matching the output of CUTIE with the labelled grid data, the model learns to generate the label for each text in the grid input via exploring both the spatial and semantic features. For that reason, the task of CUTIE bears resemblance to the semantic segmentation task in the computer vision field but with more sparse data distributions. Specifically, the mapped grid contains scattered data points (text tokens) in contrast to the images bespread with pixels. The grid positional mapped key texts are either close to or distant to each other due to different types of document layouts. Therefore, incorporating multi-scale context processing ability benefits the network.

In fact, several methods have been proposed in the semantic segmentation field to capture multi-scale contexts in the input data. The methods of image pyramid and the encoder-decoder structure both aim at exploiting multi-scale information. The interested objects from different



Figure 2. Example of scanned taxi receipt images. We provide two colored rectangles to help readers find the key information about distance of travel and total amount with blue and red, respectively. Note the different types of spatial layouts and key information texts in these receipt images.

scales become prominent in the former networks by using multiple scaled input data to gather multi-scale features. The later networks shrink feature maps to enlarge receptive fields and reduce computation burdens, and then capture finer details by gradually recovering the spatial information from lower layer features. However, spatial resolution is reduced in the encoding process and the decoding process exploits only high resolution but low-level features to recover the spatial resolution, the consecutive striding encoding process decimates detail information [11]. Moreover, the encoding and decoding process applies shape restricts to the grid shape augmentation process as introduced in Section 3.1.

Instead, the field of view of filters can also be effectively enlarged and multi-scale contexts can be captured by combining multi-resolution features [11] or by applying atrous convolution [2, 3, 4, 5]. To capture long distance connection and avoid potential information loss in the encoding process, we propose two different network architectures and compare their performance in Section 4. In fact, we had experimented with various types of model structures and only detail two of them here to avoid being a tedious paper. Specifically, the proposed CUTIE-A is a high capacity convolutional neural network that fuses multi-resolution features without losing high-resolution features, the proposed CUTIE-B is a convolutional network with atrous convolution for enlarging field of view and Atrous Spatial Pyramid Pooling (ASPP) module to capture multi-scale contexts.

Both CUTIE-A and CUTIE-B conducts semantical meaning encoding process with a word embedding layer in the very beginning stage. The cross entropy loss function

Table 1. Statistic of the numbers of labelled receipt document images and key information classes in the dataset.

	Training Set	Test Set	#classes
ME	1109	475	9
Taxi	2514	1077	6
Hotel	1353	452	9

is applied to compare the predicted token class grid and the ground truth grid.

3.2.1 CUTIE-A

CUTIE-A avoids information loss in the encoding process while taking advantage of encoders by combining encoding results to the maintained high-resolution representations through the entire convolutional process. Similar to HRNet proposed in [11], a high-resolution network without striding is employed as the backbone network and several high-to-low resolution sub networks are gradually added and connected to the backbone major network. During the connecting process of the major network and sub networks, multi-scale features are fused to generate rich representations.

3.2.2 CUTIE-B

CUTIE-B is constructed with a single backbone network but employs atrous convolution to capture long distance connections. For atrous convolution, let the input feature map be m , filter be w and output be n , for each position i , atrous convolution is applied over the input feature map m as

$$n[i] = \sum_k m[i + r \cdot k]w[k] \quad (5)$$

where r is the atrous rate that indicates the sampling stride of the input signal, which is implemented as convolving the input feature with up sampled filters by inserting $r - 1$ zeros between two consecutive filter values along each spatial dimension. Standard convolution is a special case of atrous convolution with $r = 1$ [3].

4. Experiments

The proposed method is evaluated on a dataset with 3 types of scanned document images, which contain 8 key information classes and 1 don't care class. For each specific key information class, multiple tokens can be included. The overall performance is referred as strict average precision (AP) and measured in terms of per-class accuracy across the 9 classes, where one class is determined as correct only when every single token in the class is correct. To achieve deeper analysis of the performance of the proposed method, we propose to use one more criteria, soft average precision

(softAP), where the prediction of a key information class is determined as correct as if positive ground truths are correctly predicted even if some false positives are included in the final prediction. SoftAP is important since it indicates model's capability of extracting correct key information with tolerance of incorporating certain false positives. In fact, post processing can be employed to eliminate the false positives. Therefore, joint analysis of AP and softAP provides a better understanding of the model performance.

We compare the performance of the proposed method with two state of the art methods CloudScan [9] and BERT [7]. For comparison, the Cloud Scan model for SROIE is trained from scratch but with several expert designed features as described in [9]. The BERT model for SROIE is transform learned with the Google released base model that is pre-trained on a huge dataset with 3,300M words [7, 1]. Furthermore, post-processing is applied to the BERT results to eliminate certain errors and enhance accuracy. It is worth noting that the CloudScan based method and BERT based method were implemented by other teams. For that reason, there is minor difference in numbers of training / test data. To provide a fair comparison, we also provide ablation study to evaluate the influence of number of training images in CUTIE. We will also provide results generated using the same dataset in the next version of this paper.

We use a learning rate of $1e-3$ with Adam optimizer and step decay learning strategy. The learning rate is dropped to $1e-4$ and $1e-5$ on the 15,000-th and 30,000-th steps, respectively. The training is terminated within 40,000 steps with batch size of 32. We train our model on Tesla V100 GPU where 11 to 19GB memories is used depending the configuration of the model framework and size of the dataset. Instance normalization is involved to facilitate training. Our model is trained end-to-end without piecewise pretraining of any component. The default embedding size is 128, target augmentation shape is 64 for both row and column. The dataset is split as training set and test set with ratio of 75 : 25. No pre-processing or post-processing are involved in CUTIE.

4.1. Dataset

The dataset contains 6,980 annotated scanned Spanish receipt documents, including taxi receipts, meals entertainment (ME) receipts, and hotel receipts, with 9 different key information classes, as reported in Table 1. We generate the texts and corresponding bounding boxes with Google's OCR API. Each text and their bounding box is manually labelled as one of the 9 different classes: 'DontCare', 'VendorName', 'VendorTaxID', 'InvoiceDate', 'InvoiceNumber', 'ExpenseAmount', 'BaseAmount', 'TaxAmount', and 'TaxRate'. We then employ the tokenizer introduced in Section 3.1 to segment texts into minimum token units, where text bounding boxes are also segmented accordingly.

Table 2. Performance comparison on different types of documents. Post-processing is abbreviated as pp.

Method	#Params	Taxi	ME	Hotel
CloudScan[9]	-	82 / -	64 / -	60 / -
BERT[7]+pp	110M	87.0 / -	80.3 / -	79.4 / -
CUTIE-A	67M	91.2 / 98.1	84.8 / 93.5	62.7 / 88.9
CUTIE-B	14M	95.2 / 97.6	84.3 / 92.4	70.8 / 89.4



Figure 3. Example of CUTIE inference results. Color legend in the top-left corner indicates the key information classes. Each color indicates a key information class, where filled rectangles are the ground truths while the boundary-only rectangles are the inference results. The result is perfectly correct as if the filled rectangles overlap with the boundary-only rectangles. We mask out certain personal information with filled gray rectangle in the figure.

The dataset in this work is much more difficult than the neat scanned document images, since various layouts of receipts were captured in different scenarios using ordinary mobile phone camera. Examples of the scanned document images in our dataset are illustrated in Figure 2, note that the colored rectangles is only for visual reference and the actual labelled data is in token-level rather than the line-level that is shown in the figure.

4.2. Overall Performance

We report results of our method in terms of AP and compare with other state of the art methods in Table 2. We also provides softAP results for CUTIE-A and CUTIE-B in Table 2, where both the softAP of CUTIE-A and CUTIE-B exceeds their AP by a large margin. Examples of inference results are illustrated in Figure 3. Our big network CUTIE-A achieves 91.2% AP and 98.1% softAP on taxi receipts, 84.8% AP and 93.5% softAP on meals entertainment receipts, and 62.7% AP and 88.0% softAP on hotel receipts, outperforming other methods in almost all of the test cases. Compared to CloudScan, our big network CUTIE-A improves AP by 20.8% AP on meals entertainment receipts, 9.2% on taxi receipt, and 2.7% on hotel receipts; our small network CUTIE-B improves AP by 13.2 on taxi receipts, 20.3% points on meals entertainment receipts, and 10.8% on hotel receipts. Furthermore, compared to BERT, where model is pre-trained on a dataset with 3,300M words and transfer learned on our dataset, our big network CUTIE-B improves AP by 4.2% and 4.5% in taxi receipts and meals entertainment while using only 1/2 parameters, our small network CUTIE-B improves AP by 8.2% and 4.0% in taxi receipts and meals entertainment but with much less complexity and smaller model size with only 1/9 parameters without requiring a huge dataset for model pretraining. We will further prove in Section 4.3.2 that CUTIE-B is also able to achieve state of the art performance with only 1/10 of BERT’s parameters. Although CUTIE-B is smaller in capacity, it outperforms CUTIE-A in several assessment criterias. This is because CUTIE-B enlarges field of view by employing the atrous convolution rather than the pooling or striding processes, the CUTIE-B model has larger field of view and better understanding of tokens’ relative spatial relationship since no restrictions is applied on the feature maps shapes.

It is worth noting that the difference of AP in the hotel receipt column actually leads to interesting findings. One of the finding is that if we neglect the ‘VendorName’ class in the evaluation criteria, the AP is increased to from 70.8% to 76.9% and the softAP drops to 83.8%, indicating that CUTIE is capable of extracting the interested ‘VendorName’ texts but sometimes involves texts that are not in the ground truth label. Another finding is that the hotel receipts are quite different from the meals entertainment receipts and

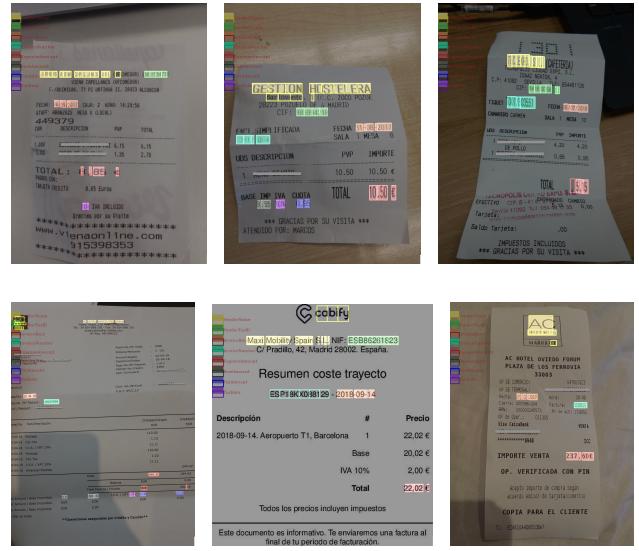


Figure 4. False positive examples of CUTIE prediction results. Color legend in the top-left corner indicates the key information classes. Each color indicates a key information class, where filled rectangles are the ground truths while the boundary-only rectangles are the inference results. The false positives are results with the boundary-only rectangles being not overlapped with the filled rectangles. We mask out certain personal information with filled gray rectangle in the figure.

the taxi receipts, where key information appears multi times in different areas of the receipt, whereas the human labelers tend to label only one of their appearances. We look deeper into this in the following part of this section by analyzing some inference result cases.

Typical examples of receipts with low AP but high softAP score are shown in Figure 4. Most of the false positive cases occur in the ‘VendorName’ class, where names tend to greatly vary and leads to difficulty in model inference. However, it is not hard to find that these false positives can be easily avoided by appending a dictionary based post processor to the key information extractor. One rare false positive case, the third receipt in the first row, is a ‘L’ letter being mis-recognized as ‘1’ by the employed OCR engine. Although the letter shows distinct appearance from the other digits in the scanned receipt image, it is mis-interpreted as one part of the ‘BaseAmount’ class due to its close spatial location to the digits and it-self being a digit. It also can be seen in the first receipt in the second row that several spatial distant digits were wrongly predicted as in the ‘BaseAmount’ class. Although these are rare cases in our test set, it still suggests that incorporating image-level information may further boost the inference accuracy inspite of the already involved semantical and spatial features.

Furthermore, we find that some wrong cases are actu-

ally correct since the ground truth were wrongly labelled by the human labelers. As illustrated in Figure 5, the 'VendorName' appears twice in the scanned image but only being labelled once in both the first and second receipt in the first row, while the model correctly interprets both occurrence as the 'VendorName' in the first receipt and correctly interprets the second occurrence in the second receipt. Furthermore, 'TaxRate' is neglected to be labeled in the third receipt in the first row and 'VendorName' is wrongly labelled in the first receipt in the second row. The third receipt in the second row and the first and second receipt in the third row are all neglected with labelling 'TaxRate', and the third receipt in the third row is neglected with labelling 'BaseAmount' while the trained model correctly inferred the right class. It is not hard to find that the trained model produces even better results than human labeler on these receipts, which further proves the effectiveness of the proposed method.

4.3. Ablation Studies

Although we have demonstrated extremely strong empirical results, the results presented are achieved by combination of each aspect of the CUTIE framework. In this section, we perform ablation studies over a number of facets of CUTIE in order to have a better understanding of their relative importance. CUTIE-B is employed as the default model with grid augmentation, embedding size of 128, and 75% of dataset as training data.

4.3.1 Effect of Grid Augmentation on Understanding Spatial Information

One of our core claim is that the high performance CUTIE is achieved by jointly analysis of the semantical and spatial information with the proposed framework. The highly effective spatial analysis ability is enabled by the CUTIE framework in contrast with the previous NER based methods. The grid augmentation process further enhances this ability. To provide more evidence to this claim, we evaluate CUTIE with or without the grid augmentation process to test the model performance in terms of spatial diversity. Results are presented in Table 5. We can see that adding the grid augmentation process in CUTIE significantly improves the performance. These results demonstrate that CUTIE can greatly benefit from enhancing data diversity in spatial distribution. For that reason, further analysis about grid augmentation techniques may enhance CUTIE's performance, *e.g.*, randomly moving certain texts upward, downward, leftward, or rightward by several pixels during the grid positional mapping process.

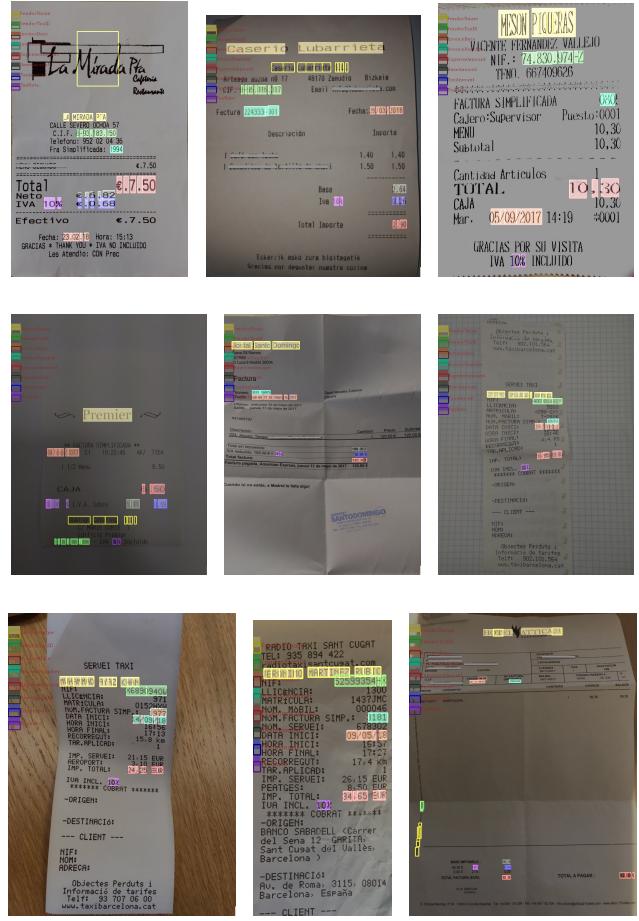


Figure 5. False positive examples of CUTIE prediction results, where the error is actually caused by the wrong labelling of human labeler. Color legend in the top-left corner indicates the key information classes. Each color indicates a key information class, where filled rectangles are the ground truths while the boundary-only rectangles are the inference results. We mask certain personal information with filled gray rectangle in the figure.

4.3.2 Impact of Semantical Information Capacity

Next, we evaluate the impact of semantical information of CUTIE by comparing evaluation with different word embedding sizes. As reported in Table 3, CUTIE performs in a bell shape curve as the embedding size increases. The best performance is achieved by CUTIE-B with 85.0% in AP and 92.9% in softAP using embedding size of 64. One interesting finding is that the CUTIE model achieves good performance even with limited semantical information capacity. We infer the reason is that, for the SROIE problem with 9 key information classes, there are a small amount of key tokens provide the majority of contribution to the model inference and the model can achieve good performance by paying special attention to these key tokens. It

Table 3. Performance evaluation of CUTIE on ME with different embedding size.

Embedding Size	1	2	4	8	16	32	64	128	256	512
#Params	10.6M	10.6M	10.7M	10.7M	10.9M	11.3M	12.1M	13.6M	16.6M	22.7M
AP	79.1	82.8	83.1	82.8	84.9	84.8	85.0	84.3	84.6	84.4
softAP	87.3	90.3	90.4	92.0	91.4	91.2	92.9	92.4	91.9	91.9

Table 4. Performance evaluation of CUTIE-B on ME with different number of training samples.

Percentage(%)	3	12	21	30	39	48	57	66	75
AP	56.2	76.4	79.6	80.8	82.6	81.4	83.4	85.0	84.3
softAP	76.0	86.5	88.7	90.3	90.5	90.7	90.7	91.1	91.5

Table 5. Performance evaluation of CUTIE on ME with or without the grid augmentation process.

	w/o augmentation	w augmentation
AP	83.3	84.3
softAP	93.7	92.4

is also indicated in the result that too large embedding size also decreases the model performance. To further enhance the model performance, it might help to randomly mask out certain texts during the grid positional mapping process, such that the model learns inter-text relationship better with / without certain words present in the grid and further improves in generality.

4.3.3 Impact of Number of Training Samples

To evaluate the impact of different number of training samples on model performance, we train CUTIE with 3%, 12%, 21%, 30%, 39%, 48%, 57%, 66%, and 75% of our dataset and report results in Table 4. It is not hard to find from the result that more training data leads to better performance either in terms of AP or softAP. CUTIE-B achieves the highest AP 85.0% with 66% of dataset as training samples and the highest softAP 91.5% with 75% of dataset as training samples. It is worth noting that CUTIE-B is already capable of achieving 79.6% AP and 88.7% softAP with only 21% of dataset as training samples, which further proves the efficiency of the proposed method being capable of achieving good results with limited amount of training data.

5. Discussion

Automatically extracting interested words / information from the scanned document images is of great interest to various services and applications. This paper proposes CUTIE to tackle this problem without requirement of any pre-training or post processing. Experimental results verifies the effectiveness of the proposed method. In contrast to the previous methods, the proposed method is easy to train

and requires much smaller amount of training data while achieving state of the art performance. The performance gain is mainly achieved by exploring three key factors: the spatial relationship among texts, the semantic information of texts, and the grid positional mapping mechanism. One interesting finding is that the trained CUTIE model correctly predicts certain key information that is neglected to be labelled by the human labeler, which further proves the effectiveness of the proposed method. It is also worth mention that, as observed from experimental results, incorporating better semantical feature processing module or involving image-level features may further boost the model performance and we leave it to future research.

References

- [1] BERT. <https://github.com/google-research/bert>.
- [2] L. Chen, G. Papandreou, I. Kokkinos, K. Murphy, and A. L. Yuille. Semantic image segmentation with deep convolutional nets and fully connected crfs. *CoRR*, abs/1412.7062, 2014.
- [3] L. Chen, G. Papandreou, I. Kokkinos, K. Murphy, and A. L. Yuille. Deeplab: Semantic image segmentation with deep convolutional nets, atrous convolution, and fully connected crfs. *CoRR*, abs/1606.00915, 2016.
- [4] L. Chen, G. Papandreou, F. Schroff, and H. Adam. Rethinking atrous convolution for semantic image segmentation. *CoRR*, abs/1706.05587, 2017.
- [5] L. Chen, Y. Zhu, G. Papandreou, F. Schroff, and H. Adam. Encoder-decoder with atrous separable convolution for semantic image segmentation. *CoRR*, abs/1802.02611, 2018.
- [6] A. Dengel and B. Klein. smartfix: A requirements-driven system for document analysis and understanding. volume 2423, pages 433–444, 08 2002.
- [7] J. Devlin, M. Chang, K. Lee, and K. Toutanova. BERT: pre-training of deep bidirectional transformers for language understanding. *CoRR*, abs/1810.04805, 2018.
- [8] D. Esser, D. Schuster, K. Muthmann, and A. Schill. Automatic indexing of scanned documents - a layout-based approach. volume 8297, 01 2012.
- [9] R. B. Palm, O. Winther, and F. Laws. Cloudscan - A configuration-free invoice analysis system using recurrent neural networks. *CoRR*, abs/1708.07403, 2017.

- [10] D. Schuster, K. Muthmann, D. Esser, A. Schill, M. Berger, C. Weidling, K. Aliyev, and A. Hofmeier. Intellix - end-user trained information extraction for document archiving. 08 2013.
- [11] K. Sun, B. Xiao, D. Liu, and J. Wang. Deep high-resolution representation learning for human pose estimation, 2019.
- [12] A. Vaswani, N. Shazeer, N. Parmar, J. Uszkoreit, L. Jones, A. N. Gomez, L. Kaiser, and I. Polosukhin. Attention is all you need. *CoRR*, abs/1706.03762, 2017.

6. APPENDIX

6.1. Model Structure

We report the CUTIE-B model in Table 6. Tokens are firstly embedd into 128 dimensional features. Then, 4 consecutive convolution operations are conducted in the conv block with stride 1 and 4 consecutive atrous convolution are conducted in the atrous conv block with stride 1 and rate 2. Following the atrous conv block, an ASPP module is employed to fuse multi-resolution features. The low level but high resolution feature from the 1st output of the convolution block is also added to the model in the shortcut layer with a concatenation operation and a 1×1 convolution. Finally, inference output is achieved through a 1×1 convolution.

Table 6. Structure of the proposed CUTIE-B model.

layer name	operations	input dimension	output dimension	comments
embedding layer	-	20000	128	
conv block	$[3 \times 5] \times 4$	256	256	stride=1
atrous conv block	$[3 \times 5] \times 4$	256	256	stride=1, rate=2
ASPP module	$[3 \times 5] \times 3$, global pooling, concat, 1×1	256	256	stride=1, rate={4,8,16}
shorcut layer	concat, 1×1	256	64	
output layer	1×1	64	9	