

Predictive Accuracy of Regression / Regression Trees

Data Mining
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- Training the Tree
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Predictive Accuracy of Regression

So far we have discussed two different types of supervised learning:

- 1 Classification (categorical outcome)
- 2 Regression (continuous outcome)

Evaluating Accuracy:

- For classification we evaluated the accuracy of our method by calculating % misclassified in the validation or test data (or looking at false pos. and false neg. rates separately)
- For regression how might we measure predictive accuracy?

Predictive Accuracy of Regression

- Often we measure predictive accuracy using the **root mean square error on the validation/test data** (smaller is better):

$$\text{RMSE} = \sqrt{\frac{1}{M} \sum_{i=1}^M (Y_i - \hat{Y}_i)^2}$$

where M is the # of test observations.

- Alternative: Mean absolute error:

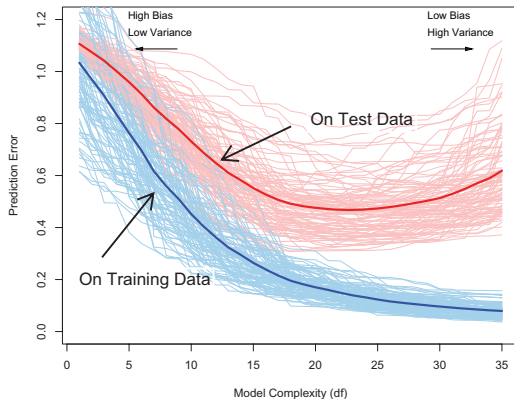
Model Selection for Linear Regression

Which predictor variables to include in the regression model?

- Why is it not necessarily best to include all the available predictors?

Model Selection for Linear Regression

Recall the complexity / accuracy curve. How might “model complexity” be measured for our linear regression model?



Model Selection for Linear Regression

What's a good way to choose a set of predictors that yields high **predictive** accuracy (accuracy on unseen data such as test data)?

All Subsets Regression

- All Subsets Regression means that we compare **all possible subsets of the predictors**, and choose a model based on some criterion, like the one on the previous slide.
- What happens as the number of available predictors gets large?

Forward Stepwise Selection

Forward stepwise selection is an alternative:



Backward Stepwise Selection

Backward stepwise selection is similar:

Definition of Regression Trees

- Regression trees are a method for prediction of a continuous outcome (as for linear regression)
- they partition the space \mathbb{R}^p of the predictor vector (X_1, \dots, X_p) and predict a fixed value \hat{Y} on each of the partition sets.

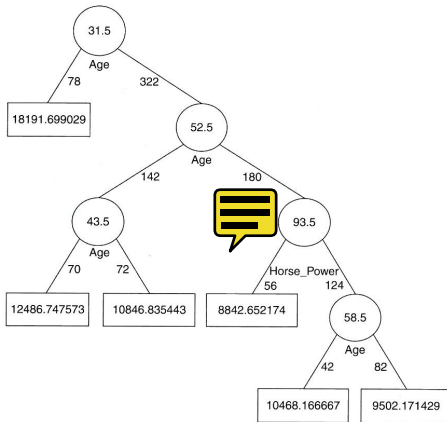
- In particular:



- These splits correspond to simple logical rules for prediction.
 - Example:

Definition of Regression Trees

A tree for predicting the price of used Toyota Corollas (SPB text):





Definition of Regression Trees

- Key: Regression trees are **flexible enough to accurately approximate almost any relationship between predictors & outcome** (by making the tree big enough)!
- Can the same predictor can appear in more than one split of the tree?

Training the Tree

Training:

- **Outcome:** Y (continuous)
Predictors: X_1, \dots, X_p with n observations in training data
- For a tree T , the predicted value \hat{Y} in each leaf is taken to be: 
- We want to learn the tree structure T from the data, i.e.: 

Training the Tree

Define:

- $|T| = \#$ terminal nodes ("leaves") in tree T
- $m = 1, \dots, |T|$: terminal node index
- R_m : region in \mathbb{R}^p corresponding to terminal node m
- N_m : $\#$ training observations in R_m

Training the Tree

Want a tree T that has low error on the training data, meaning low sum of squared error:



- The **predicted value** \hat{Y} for leaf m is called:
- The **residual sum of squares** (also called the “sum of squared errors”) on the training data is:



Training the Tree

We want a tree that is not too big, while having low RSS. Why?

We use a **criterion for picking a tree** that penalizes the size of the tree:

$$C_{\alpha}(T) = \text{RSS}(T) + \alpha|T|$$

for $\alpha > 0$



Training the Tree

- But: cannot simply evaluate $C_\alpha(T)$ for all possible trees

- Why?



- Another difficulty: don't know what α to use

Pruning: removing a subtree

Solution:

Let $T \subseteq T_0$ be any tree that can be obtained from T_0 by "pruning" (removing a subtree)

- Instead of considering all trees, consider all trees $T \subseteq T_0$ where T_0 is a "full" tree that is good in some sense.
- e.g.: prune at $(*)$



Training the Tree

Note: Pruning ALWAYS increases the RSS . Why?

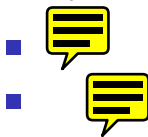


Conversely, splitting a terminal node always decreases RSS .



Training a Tree

- A full tree means that none of its terminal nodes can be split any farther because it either



- We will obtain a "good" full tree as follows.

Growing the Tree

Growing the tree::

1. Start with the tree that has no splits (all observations are in the single terminal node)
2. Split at the variable j and cut point s that yields the largest decrease in $RSS(T)$



3. 

4. Repeat until obtaining a full tree T_0 .

Growing the Tree

Pruning the Tree

After growing the tree, we **prune it back** using “**weakest-link**” pruning.

The “**weakest link**” is the internal node that produces the smallest “per-node increase” in $RSS(T)$ when pruned; continue until we get the single-node tree.

$$\text{per-node increase} = \frac{\Delta \text{ in } RSS(T)}{\Delta \text{ in } |T|}$$



Weakest-link pruning:

Weakest-link pruning:

- Start at T_0
- Prune weak link to get $T(1)$
- Prune weak link of $T(1)$ to get $T(2)$
- Continue to get sequence of trees

$T_0, T(1), T(2), \dots, T(L)$, for some integer L

- $T(L)$ is the tree with a single terminal node.

Weakest-link pruning

For any α , one can show that

- there is a unique tree $T_\alpha \subseteq T_0$ that minimizes C_α
- the sequence of trees $T_0, T(1), T(2), \dots, T(L)$ obtained from T_0 by weakest link pruning **must** contain T_α !

Weakest-link pruning

Now we have to choose **one** of these trees. We can use:

- RMSE on validation data
- RMSE from cross-validation

Summary

Summary: Tree training by "grow & prune"

- Have a criterion $C_\alpha(T)$ that combines
 - how accurate tree is on training data ($RSS(T)$)
 - size $|T|$ of the tree
- Instead of considering all possible trees (too many), consider only trees $T \subseteq T_0$ for some good full tree T_0
- Get T_0 by growing the tree, decreasing $RSS(T)$ as much as possible at each step

Summary

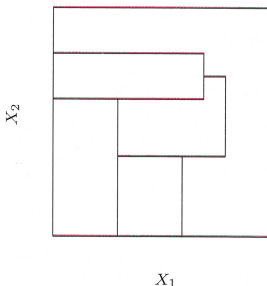
Procedure:

- Grow tree
- Prune, obtaining $T_0, T(1), T(2), \dots, T(L)$
- Choose one of these trees by accuracy on validation data

Regression Trees

Consider applying regression trees with $p = 2$ continuous predictors and a continuous outcome variable.

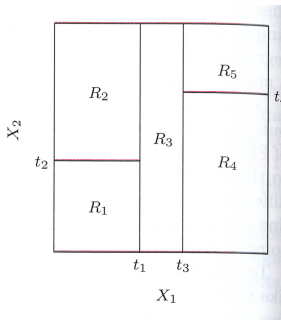
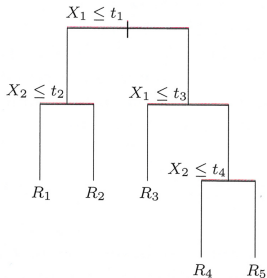
T/F: the following partition of the predictor space could be obtained using regression trees:



A: True; B: False

Regression Trees

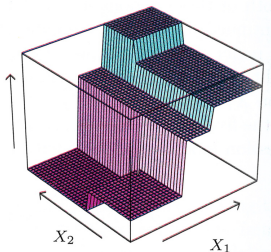
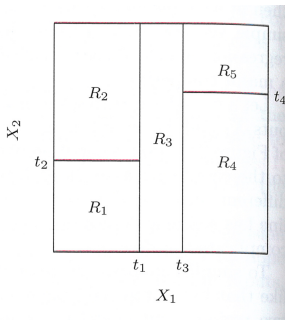
Here's another example of regression trees for $p = 2$ predictors:



Plots from Hastie, Tibshirani, and Freedman (2009).

Regression Trees

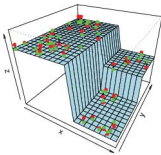
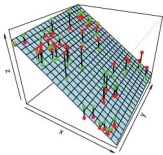
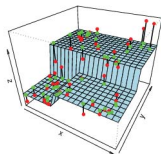
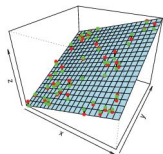
For the same example, here's a perspective plot of \hat{Y} vs. X_1 and X_2 :



Plots from Hastie, Tibshirani, and Freedman (2009).

Regression Trees

Now compare the surface of \hat{Y} vs. X_1 and X_2 , for a regression tree and for linear regression.



Plots from Rafael Irizarry's course notes.

Regression Trees

Advantage(s) of regression trees over linear regression:



Advantage(s) of linear regression over regression trees:

