Capturing Nonlinearity using Splines

Data Mining Prof. Dawn Woodard School of ORIE Cornell University

Outline

- 1 Reading
- **2** Extending Linear Regression
 - Implementation in R
- 3 Splines

Reading

Assigned reading for this week: JWHT Chapter 7 up through 7.4.

Additivity Assumption

Multiple linear regression as we have described it so far has **ADDITIVITY** and **LINEARITY** assumptions: i.e.,

 $E(Y | x_1, ..., x_p)$ is the sum of terms that are each linear in one predictor.

$$E(Y | x_1, \ldots, x_p) = \beta_0 + \beta_1 x_1 + \ldots + \beta_p x_p.$$

E.g., for p = 2 the prediction surface $E(Y | x_1, x_2)$ as a function of x_1 and x_2 is a plane. For p > 2 the surface is a hyperplane.

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Additivity Assumption

To weaken the additivity assumption one can include "interaction effects." For instance when p=2 you can change the linear regression model to

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + \epsilon$$
$$\epsilon \sim N(0, \sigma^2)$$

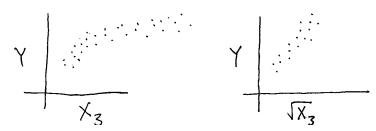
Then $E(Y | x_1, x_2)$ is no longer restricted to be a hyperplane.

Additivity Assumption

Example:

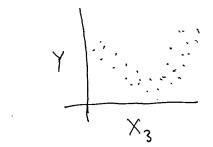
Linearity Assumption

Similarly, there are tricks to get away from the **linearity assumption**. We know one already: if the relationship between predictors and outcome is nonlinear, sometimes transforming one or both leads to a linear relationship.



Linearity Assumption

But this doesn't always work. For instance:



Here there are no monotonic transformations f and g of x_3 and Y that can make the relationship between $f(x_3)$ and g(Y) linear.

Linearity Assumption

One can handle a situation like this by including quadratic and/or higher-order **polynomial terms** in the regression model, e.g. when p = 1 take

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_1^2 + \beta_3 x_1^3 + \epsilon$$
$$\epsilon \sim N(0, \sigma^2)$$

Here we are assuming a cubic instead of linear relationship between x_1 and Y, which is much less restrictive!

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Implementation in R

It is extremely easy to include interaction and polynomial terms in the regression model in R. Notice that a model like

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_2^2 + \beta_4 x_1 x_2 + \epsilon$$

can be viewed as a standard multiple linear regression model, where there are 4 predictors: $\tilde{x}_1 = x_1$, $\tilde{x}_2 = x_2$, $\tilde{x}_3 = x_2^2$, and $\tilde{x}_4 = x_1x_2$.

$$Y = \beta_0 + \beta_1 \tilde{x}_1 + \beta_2 \tilde{x}_2 + \beta_3 \tilde{x}_3 + \beta_4 \tilde{x}_4 + \epsilon$$

Implementation in R

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_2^2 + \beta_4 x_1 x_2 + \epsilon$$

To fit this model in R:

Implementation in R

It's tempting to include a lot of interactions and high-order polynomial terms in the model, to make the model less restrictive. But beware of the risk of overfitting!!!

A popular approach is to include some of these terms, but then do model selection to cut back on the number of terms.

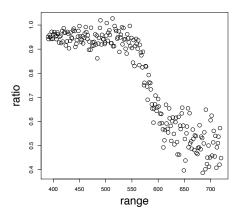
Sometimes the relationship between a continuous predictor x and the expected value of the outcome Y can't be captured effectively using a low-degree polynomial.

For now let's focus on the case of a single predictor, although this can easily be generalized to more than one.

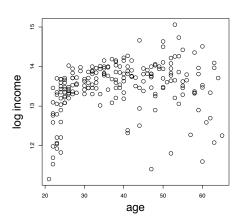
Note: Don't use splines unless simpler approaches don't work AND a scatterplot of y vs. x shows nonlinear, nonpolynomial behavior

The first dataset today regards the LIDAR (light detection and ranging) technique, which uses the reflection of laser-emitted light to detect chemical componds in the atmosphere. This is useful for **monitoring air pollution**.

Range: distance traveled before the light is reflected back to its source Ratio: ratio of received light from two laser sources



Another example: predicting income based on age



One approach to handle nonlinearity would be to divide the domain of *x* into intervals, and fit a different line within each interval:

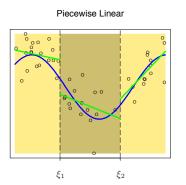


Figure from Hastie, Tibshirani, and Friedman (2009). This is simulated data, where the true expectation of Y is shown in blue.

But we generally would prefer that the prediction were continuous

One would like to fit a line in each interval, but restrict the prediction to be continuous:

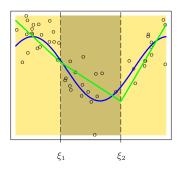


Figure from Hastie, Tibshirani, and Friedman (2009).

Functions that are linear in the intervals $(-\infty, \xi_1)$, (ξ_1, ξ_2) , and (ξ_2, ∞) and are continuous at ξ_1 and ξ_2 can be written in the form

$$\beta_0 + \beta_1 x + \beta_2 (x - \xi_1)_+ + \beta_3 (x - \xi_2)_+$$

where t_+ denotes the positive part. Here's a plot of $(x - \xi_1)_+$:

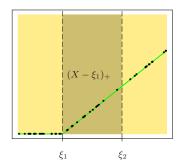


Figure from HTF text

So we can fit the model:

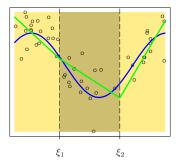
$$Y = \beta_0 + \beta_1 x + \beta_2 (x - \xi_1)_+ + \beta_3 (x - \xi_2)_+ + \epsilon$$

 $\epsilon \sim N(0, \sigma^2)$

How?

How to choose the knots?

Perhaps we would like a smoother function to predict *Y*. Our function has a discontinuous first derivative at the knots, and so is sensitive to our choice of the knots.



If we want the function to be continuous and have continuous first derivatives, we can fit a quadratic function in each interval, and restrict the function to be smooth in these ways. With 2 knots this corresponds to fitting a function of the form

$$\beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 (x - \xi_1)_+^2 + \beta_4 (x - \xi_2)_+^2$$

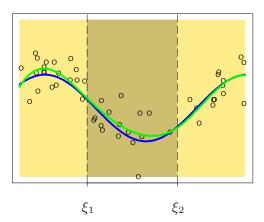
Why?

These "quadratic splines" are a common choice. It's also common to use "cubic splines" to get an even smoother function; these ensure that the function and its first and second derivatives are continuous. With 2 knots this corresponds to fitting a function of the form

$$\beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \beta_4 (x - \xi_1)_+^3 + \beta_5 (x - \xi_2)_+^3$$

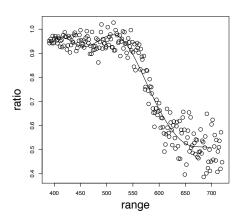
So our statistical model is

Here's the cubic spline fit for the simulated data example:

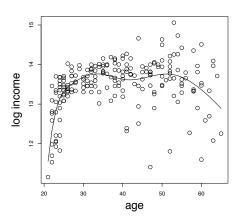


The estimated curve is very close to the true curve!

Here's the cubic spline prediction function for the LIDAR data:



Here it is for the income / age data:



R code for cubic spline fit, 4 knots:

