

view_frames Result

Recorded at time: 1542430638.730

odom

base_footprint

base_link

caster_back_link

caster_front_link

cliff_sensor_front_link

cliff_sensor_left_link

cliff_sensor_right_link

gyro_link

base_scan

wheel_left_link

wheel_right_link

Broadcaster: /mobile_base_nodelet_manager
Average rate: 20.504 Hz
Most recent transform: 1542430638.698 (0.033 sec old)
Buffer length: 4.926 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1542430638.730 sec old)
Buffer length: 0.000 sec

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Average rate: 10000.000 Hz
Most recent transform: 0.000 (1542430638.730 sec old)
Buffer length: 0.000 sec

Broadcaster: /base_scan
Average rate: 35.526 Hz
Most recent transform: 1542430638.698 (0.032 sec old)
Buffer length: 4.926 sec

Broadcaster: /base_scan
Average rate: 35.526 Hz
Most recent transform: 1542430638.698 (0.032 sec old)
Buffer length: 4.926 sec