TASK 2 Hill climbing algorithm for Heuristic search

Implementation of Hill climbing algorithm for Heuristic search approach using following constraints in python.

- i. Create a function generating all neighbours of a solution
- ii. Create a function calculating the length of a route
- iii. Create a random solution generator
- iv. Create a Travelling salesman problem

Tools- Python, Online Simulator - https://graphonline.ru/en/

PROBLEM STATEMENT:

CO1 S3

Imagine a mountain climber trying to reach the highest point of a mountain range. The terrain is represented as a 1D array of elevations (like hill heights at different points). The climber starts at a random position and uses the hill climbing heuristic to move only to higher neighboring positions. The goal is to find the local or global maximum elevation

TASK-2

Implementation of Hill climbing algorithm for Heuristic search approach

AIM

To implement the Hill Climbing algorithm as a Heuristic Search technique for solving optimization problems, where the objective is to find the best possible solution (maximum or minimum) based on a heuristic value.

ALGORITHM

- Start at a random position on the terrain.
- Check the neighboring positions (left and right).
- Compare the elevation of the current position with neighbors.
- Move to the neighbor with the highest elevation, if it's higher than the current one.
- Repeat steps 2–4 until no neighbor has a higher elevation.
- Stop you've reached a peak (highest nearby point).

PROGRAM

Hill Climbing for Peak Finding

```
import random
def generate neighbors(position, terrain):
  neighbors = []
  if position > 0:
     neighbors.append(position - 1)
  if position < len(terrain) - 1:
     neighbors.append(position + 1)
  return neighbors
def heuristic(position, terrain):
  return terrain[position]
def get random position(terrain):
  return random.randint(0, len(terrain) - 1)
def hill climbing(terrain):
  current position = get random position(terrain)
  current value = heuristic(current position, terrain)
  print(f'Starting at position {current position} with elevation {current value}")
  while True:
     neighbors = generate neighbors(current position, terrain)
     best neighbor = current position
     best value = current value
     for neighbor in neighbors:
       neighbor value = heuristic(neighbor, terrain)
       if neighbor value > best value:
          best value = neighbor_value
          best neighbor = neighbor
```

```
if best_value == current_value:
    break
else:
    current_position = best_neighbor
    current_value = best_value
    print(f'Moving to position {current_position} with elevation {current_value}")

print(f'Reached peak at position {current_position} with elevation {current_value}")

terrain = [10, 20, 15, 25, 30, 40, 35, 25, 50, 45]

hill_climbing(terrain)
```

OUTPUT

===== RESTART: C:/Users/manja/OneDrive/Pictures/Desktop/vtu26083-task2.py ==== Starting at position 9 with elevation 45
Moving to position 8 with elevation 50
Reached peak at position 8 with elevation 50

