TASK:2

Implementation of Hill climbing algorithm for Heuristic search approach
Tools- Python, Online Simulator - https://graphonline.ru/en/
PROBLEM STATEMENT: CO1 S3
A hiker who is trying to reach the peak of a tall mountain. The hiker has a map of the mountain, but it provides a partial view of the terrain. The goal of the hiker is to find the best path to the peak using the
climbing algorithm. The mountain is represented as a grid of cells, where each cell has a specific elevation

only hillvalue (height). The hiker starts at a random cell and can move to neighboring cells (up, down, left, or right). The elevation of the cell the hiker is currently at is called the current elevation.

The hiker needs to find the path that leads to the highest peak on the mountain. However, the hill-climbing algorithm has some limitations. Sometimes, it may get stuck in a local maximum, where the hiker reaches a peak that is not the highest overall

HILL CLIMBING

AIM

To implement the Hill Climbing algorithm using heuristic search in Python to help a hiker find a path to the highest reachable peak on a mountain.

ALGORITHM

- 1. Choose a starting cell randomly on the grid.
- 2. Check the elevation (height) of the current cell.
- 3. Look at the 4 neighbors (up, down, left, right).
- 4. Compare elevations:
- Find the neighbor with the highest elevation.
- Only choose it if it is higher than the current cell.
- 5. Move to that higher neighbor.
- 6. Repeat steps 2–5 until:
- No neighbor is higher than the current cell.
- 7. Stop. You've reached a peak (maybe local, maybe global).

PROGRAM

Hill Climbing Algorithm (Heuristic Search)

import random

def get_neighbors(x, y, rows, cols):

```
directions = [(-1, 0), (1, 0), (0, -1), (0, 1)] \# up, down, left, right
  neighbors = []
  fordx,dy in directions:
    nx,ny = x + dx, y + dy
    if 0 \le nx \le nx \le ny \le cols:
       neighbors.append((nx, ny))
  return neighbors
def hill_climbing(grid, start):
  rows, cols = len(grid), len(grid[0])
  x, y = start
  current_path = [(x, y)]
  current\_elevation = grid[x][y]
  while True:
     neighbors = get neighbors(x, y, rows, cols)
     best_neighbor = None
     fornx,ny in neighbors:
       ifgrid[nx][ny] > current elevation:
          ifbest_neighbor is None or grid[nx][ny] > grid[best_neighbor[0]][best_neighbor[1]]:
            best neighbor = (nx, ny)
     if best neighbor:
       x, y = best neighbor
       current_path.append((x, y))
       current elevation = grid[x][y]
     else:
```

```
return current path, current elevation
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```
# Example mountain grid with elevation values
mountain = [
  [1, 2, 3, 4],
  [2, 3, 8, 5],
  [3, 4, 9, 6],
  [2, 5, 6, 7]
]
# Start at a random position
start_x = random.randint(0, len(mountain) - 1)
start_y = random.randint(0, len(mountain[0]) - 1)
start_position = (start_x, start_y)
print(f"Starting at position: {start_position} with elevation {mountain[start_x][start_y]}")
path, peak_elevation = hill_climbing(mountain, start_position)
print("Path to peak:")
print(path)
print(f"Peak elevation reached: {peak elevation}")
```

OUTPUT

```
ESTART: D:/VTU26778/task2.py = Starting at position: (1, 0) with elevation 2

Path to peak:
[(1, 0), (2, 0), (2, 1), (2, 2)]

Peak elevation reached: 9
```

RESULT

Thus, the Implementation of Hill climbing algorithm for Heuristic search approach to help a hiker find a path to the highest reachable peak on a mountain using python was successfully executed and output was verified.