

# TUNING OF VISUALIZATION ALGORITHMS WITH USER CONSTRAINTS FOR $t$ -SNE

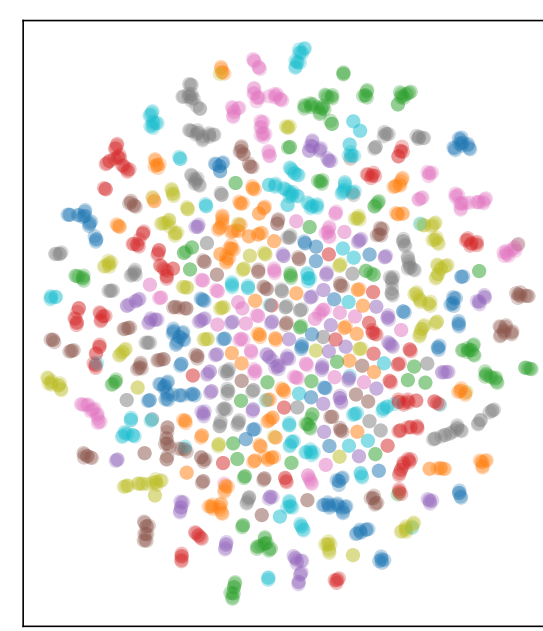
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## DIFFICULTY IN CHOOSING A GOOD PARAMETER FOR A VISUALIZATION ALGORITHM (T-SNE)

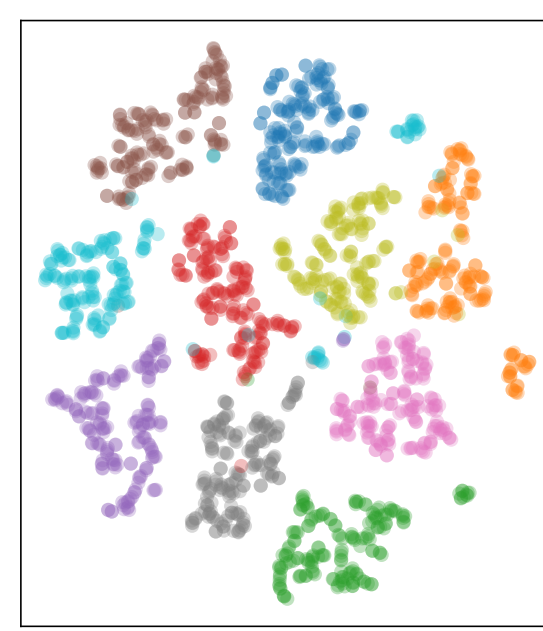
### Problematic and Motivation

7 7 7 9 7 7 9 7 4 7  
7 9 9 7 7 4 7 7 7 7  
9 7 7 4 7 4 4 4 4 7  
9 1 1 7 9 7 7 9 9 4  
2 1 1 1 5 1 9 1 7  
7 9 7 5 0 9 1 4 4 6  
4 7 8 2 3 2 4 8 5 7  
7 9 8 0 5 3 1 9 4 8  
1 1 9 1 5 5 1 6 1 4  
6 1 6 1 3 3 5 2 2 8

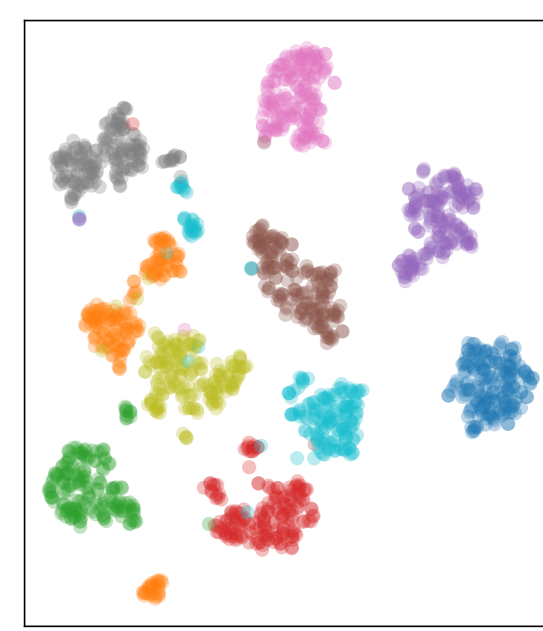
Goal: Visualize the high dimensional data



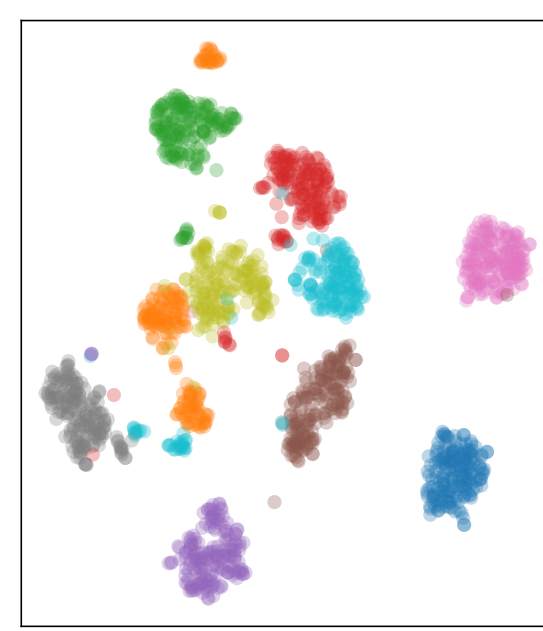
perplexity=1



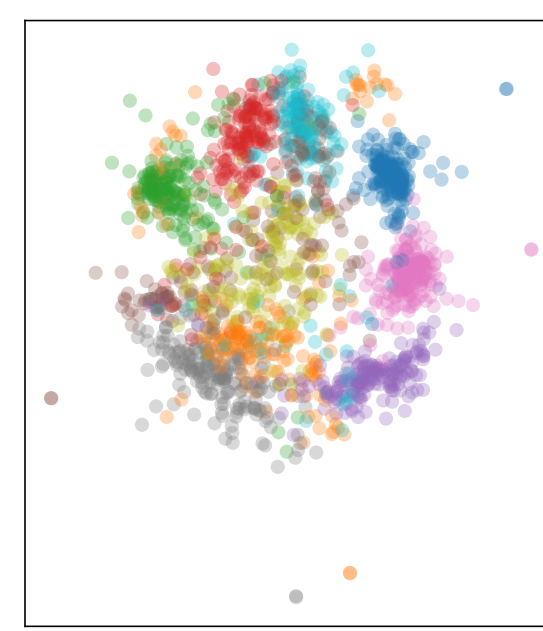
perplexity=5



perplexity=20



perplexity=50



perplexity=1500

t-SNE is sensitive to the *perplexity* parameter, which is **important** but very **hard to understand and to tune**.

### Proposed Solution

Use the users' feedback to **steer the visualization**.

- Let users define their requirements in form of **pairwise constraints**[A] between examples.
- The *perplexity* is automatically chosen based on the user's **constraint scores**[B].
- Evaluate the proposed visualization in quantitative comparison with the state-of-the-art quality metrics[C].

## USER PAIRWISE CONSTRAINTS [A]

What are expressed by user (in high dim.)

Two **similar** examples → **Must link**.

Two **dissimilar** examples → **Cannot link**.

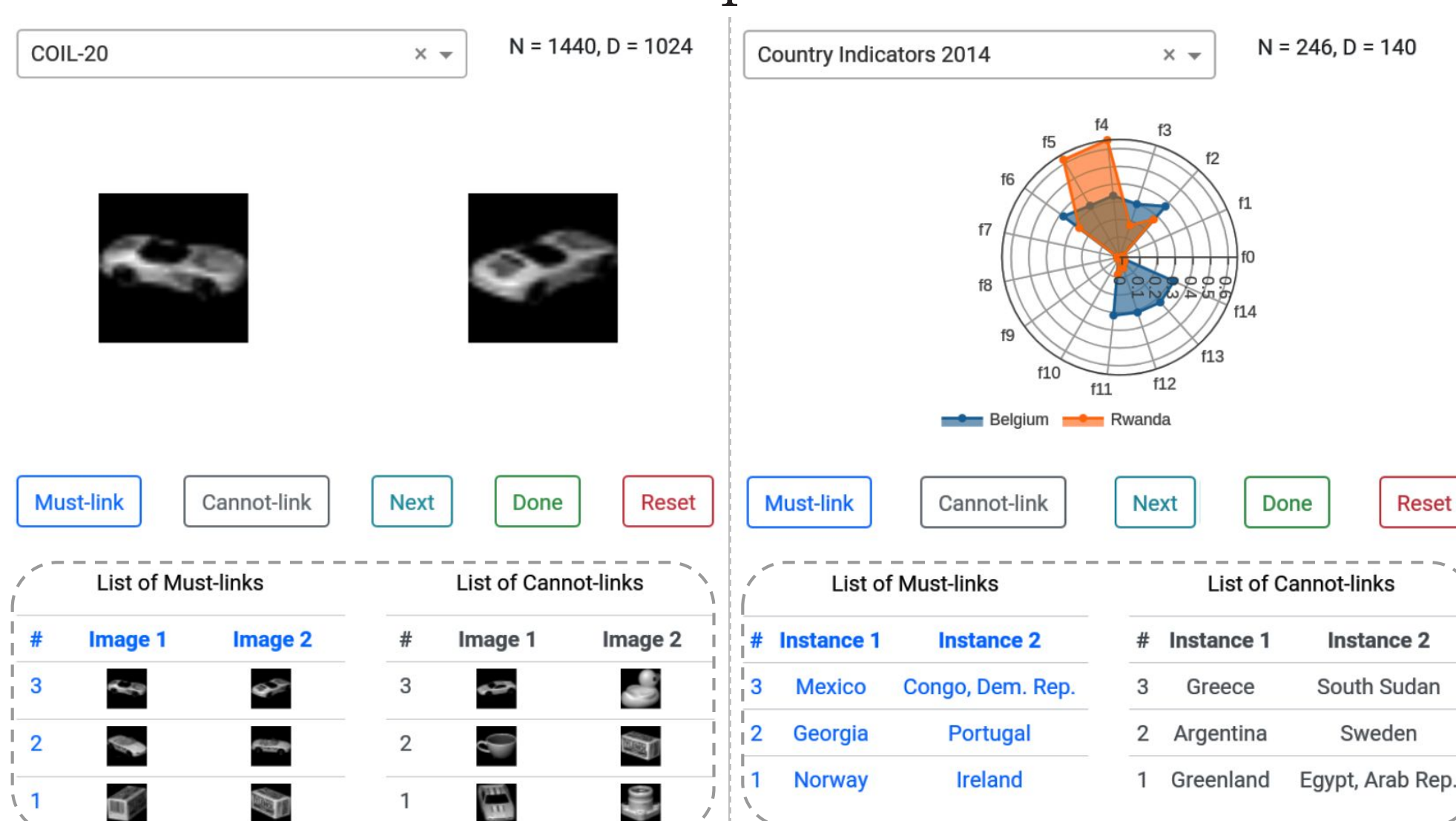


Figure: The interface for collecting users' feedback for image and tabular data.

What are translated to the algorithm (in low dim.)

Points connected by a **Must link** ( $\mathcal{M}$ ) → must stay **close together**.

Points connected by a **Cannot link** ( $\mathcal{C}$ ) → must stay **far apart**.

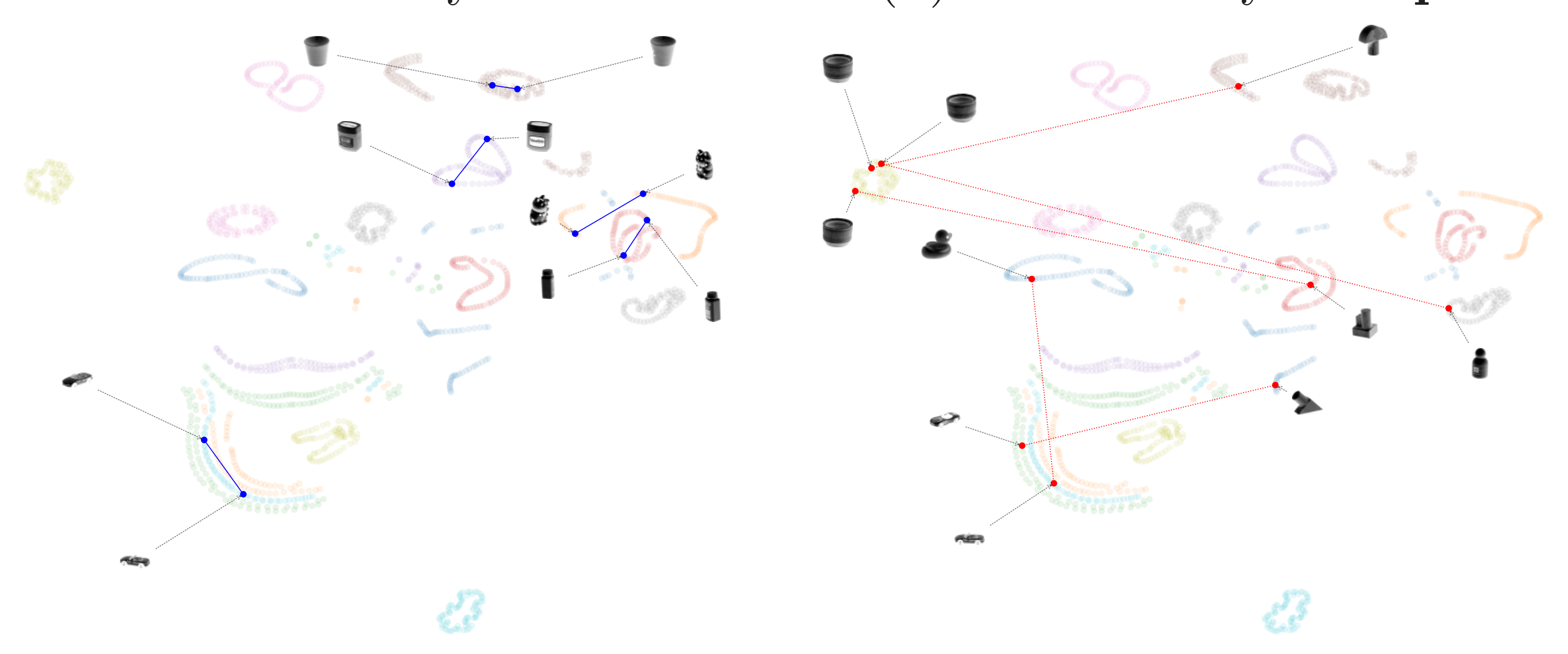


Figure: The user constraints in the visualization of the COIL20 dataset.

## CONSTRAINT-PRESERVING SCORES [B]

- Consider the points in the visualization (low dim.)
- $q_{ij}$  = probability of  $i$  and  $j$  being neighbors.
- $S_M = \frac{1}{|\mathcal{M}|} \sum_{(i,j) \in \mathcal{M}} \log q_{ij}$ .
- $S_C = -\frac{1}{|\mathcal{C}|} \sum_{(i,j) \in \mathcal{C}} \log q_{ij}$ .
- $S_{M+C} = S_M + S_C$ .

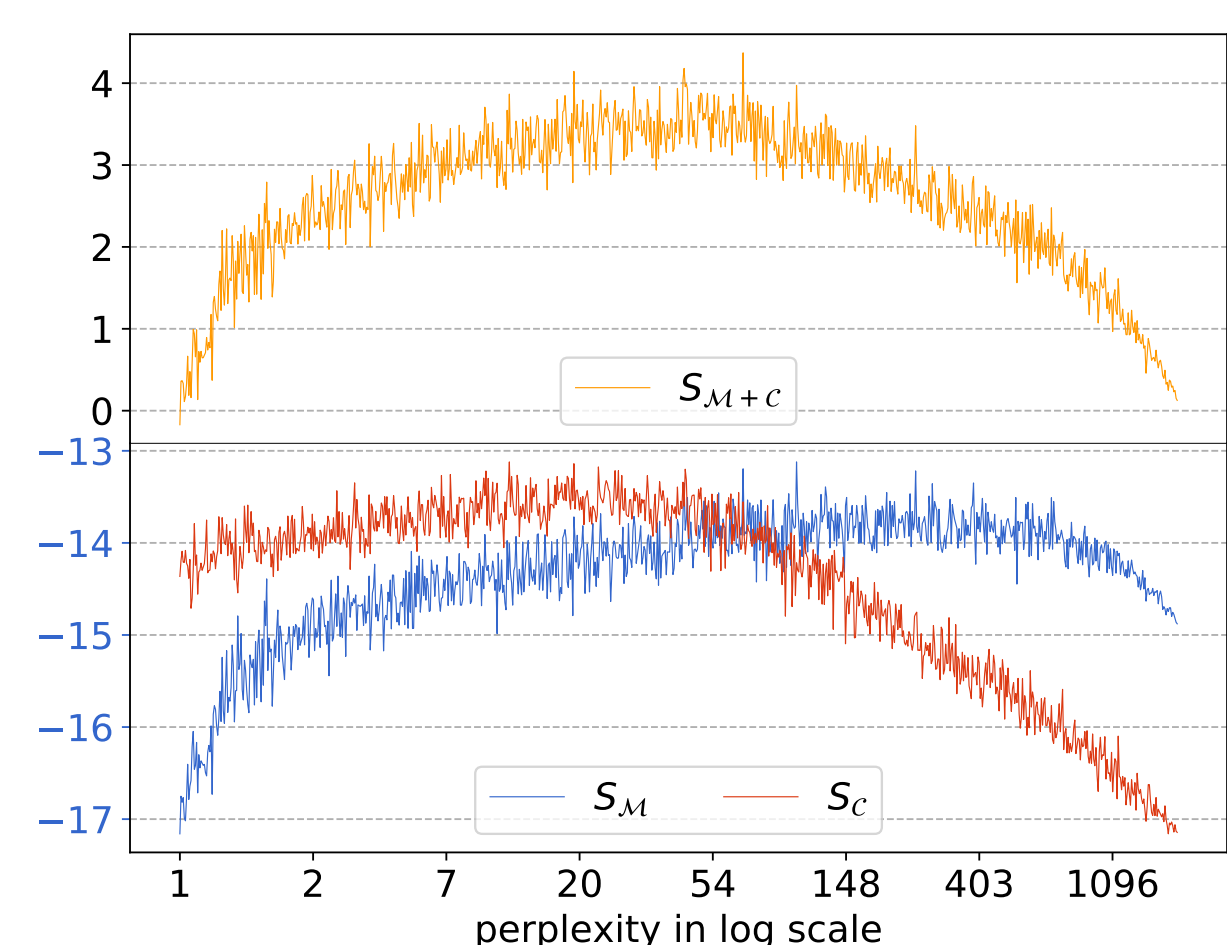


Figure :Constraint-preserving scores with 50 constraints for MNIST dataset.



Can easily find the perplexity that maximizes  $S_M$ ,  $S_C$  or  $S_{M+C}$ .

## QUALITY METRICS [C]

- **CC**: Pearson corr. coeff.
- **NMS**: Stress of pairwise distance orders comparison
- **CCA**: Stress with accent put on low dim.
- **NLM**: Stress with accent put on high dim.
- **AUC<sub>log</sub>RNX**: How neighbors in high dim. are preserved in low dim.

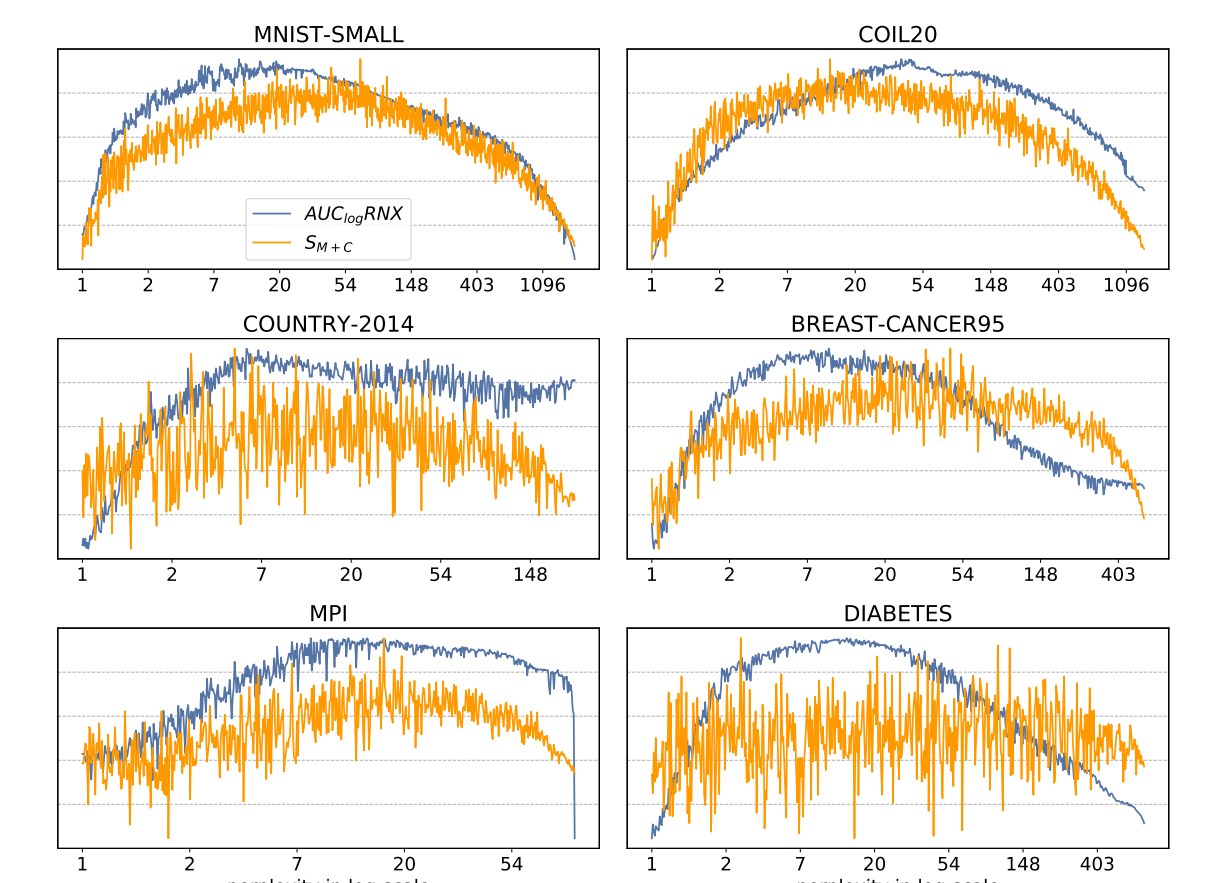
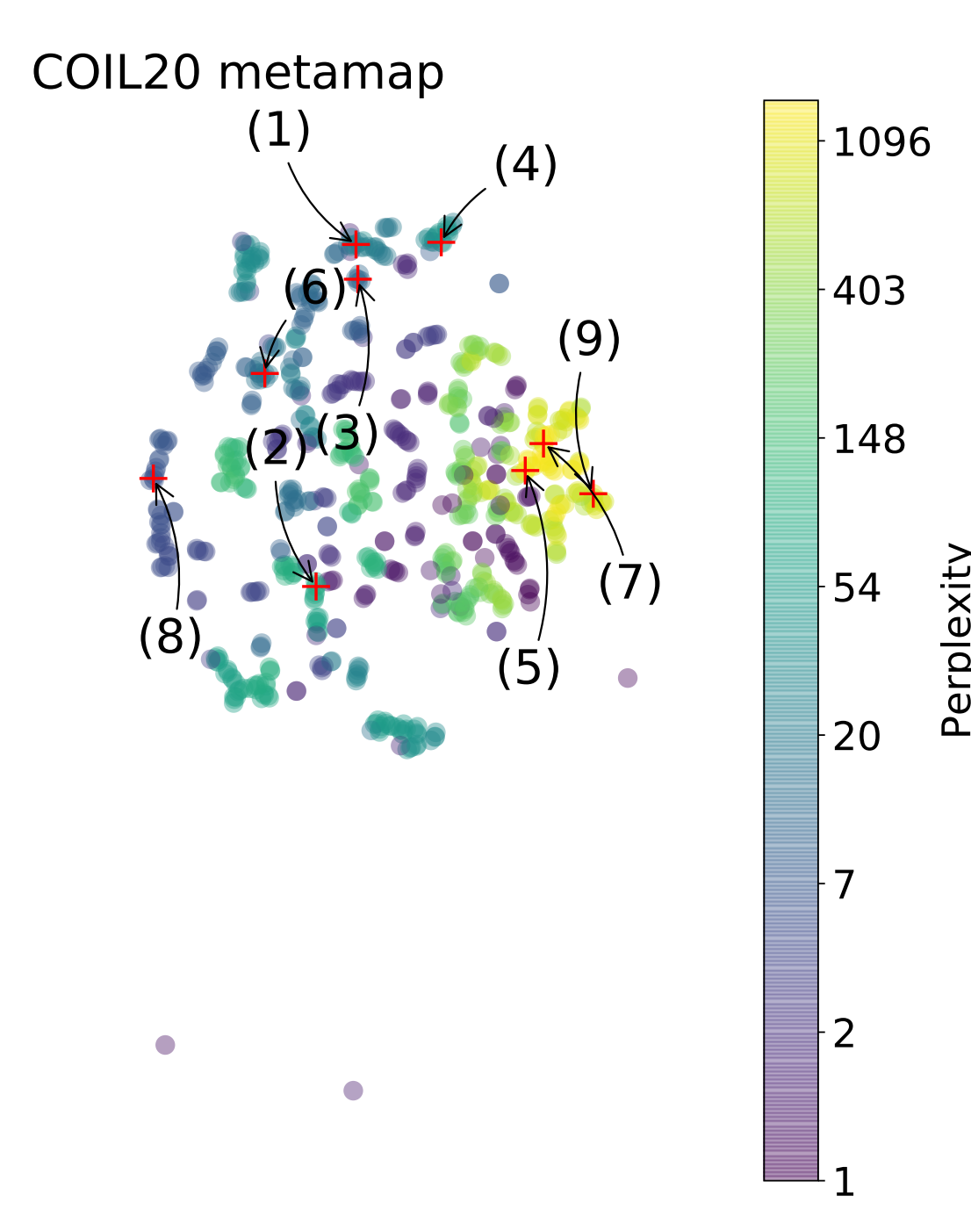
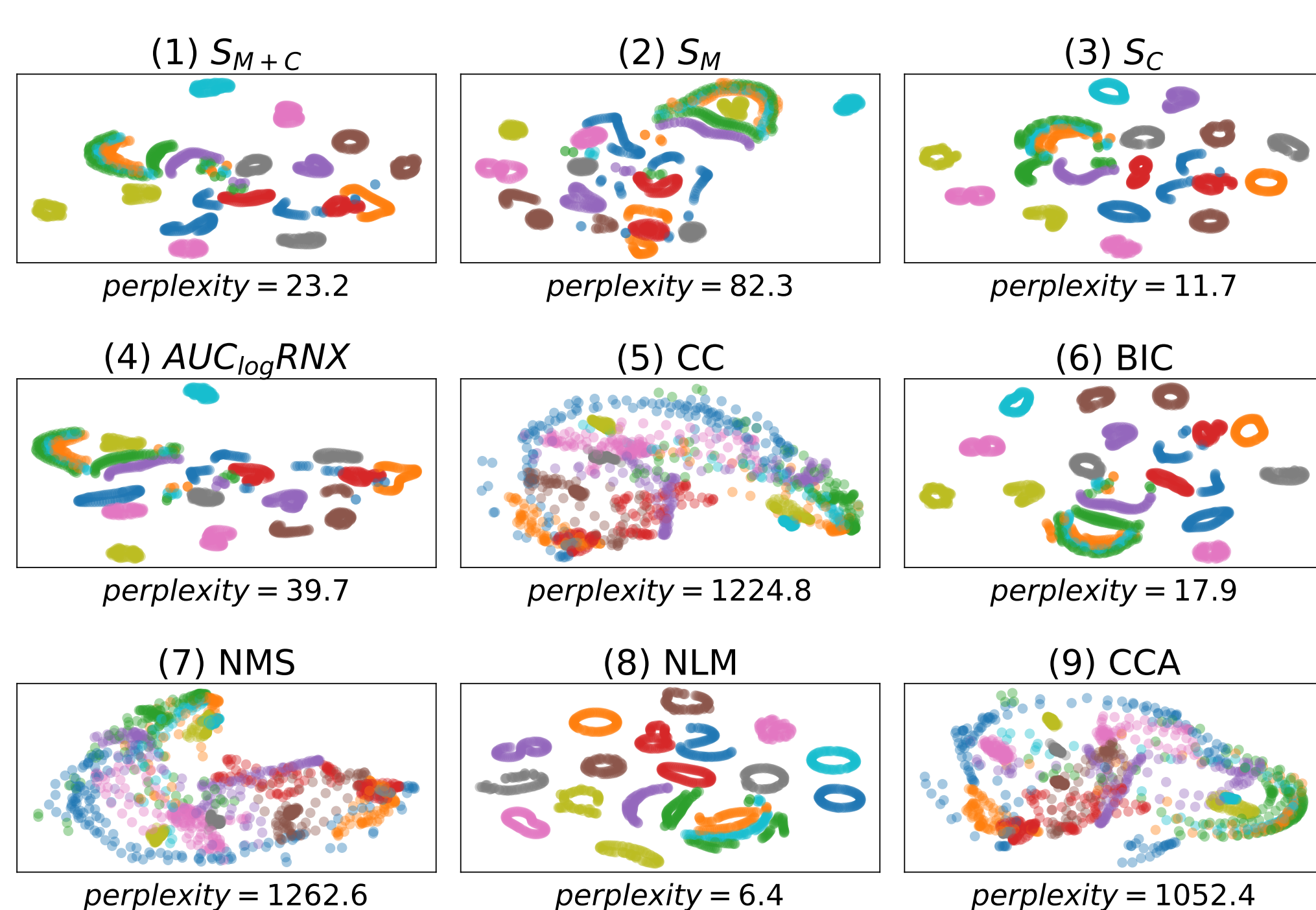


Figure: Compare  $S_{M+C}$  and  $AUC_{log}RNX$  for six datasets.



Our constraint scores agree with the quality metrics.

## ALL VISUALIZATIONS IN ONE PLACE: META-PLOT



## CONCLUSION

✓ Consider *user knowledge* under the form of constraints to find the most suitable visualization.

✓ Make complex visualization technique ( $t$ -SNE) *accessible* to users by freeing them from the tedious task of selecting the hyperparameter.

✗ *Heavy computation* due to the pre-calculation of many possible embeddings.