TUNING OF VISUALIZATION ALGORITHMS WITH USER CONSTRAINTS FOR t-SNE

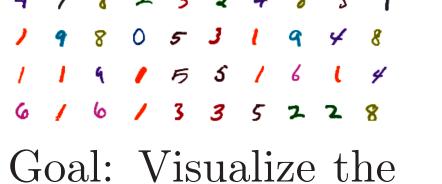
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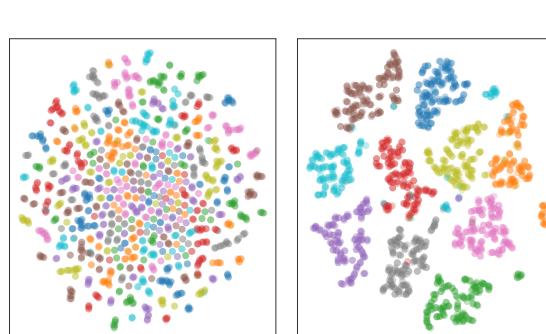
Difficulty in choosing a good parameter for a visualization algorithm (t-SNE)

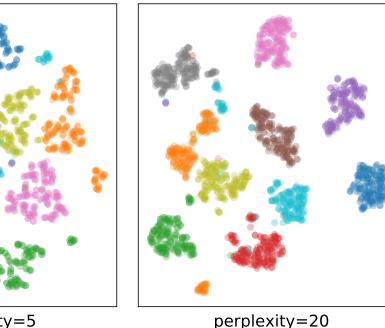
Problematic and Motivation

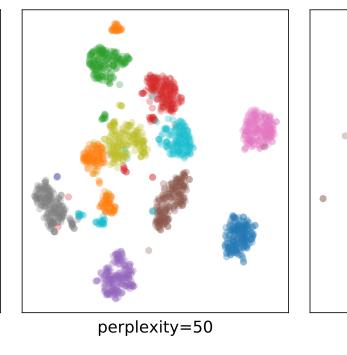
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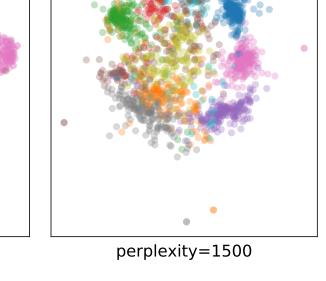
high dimensional data











t-SNE is sensitive to the *perplexity* parameter, which is **important** but very hard to understand and to tune.

Proposed Solution

Use the users' **feedback** to steer the visualization.

- Let users define their requirements in form of pairwise constraints [A] between examples.
- The *perplexity* is automatically chosen based on the user's **constraint scores** B.
- Evaluate the proposed visualization in quantitative comparison with the state-of-the-art quality metrics [C].

USER PAIRWISE CONSTRAINTS A

What are expressed by user (in high dim.)

Two similar examples \rightarrow Must link. Two dissimilar examples \rightarrow Cannot link.

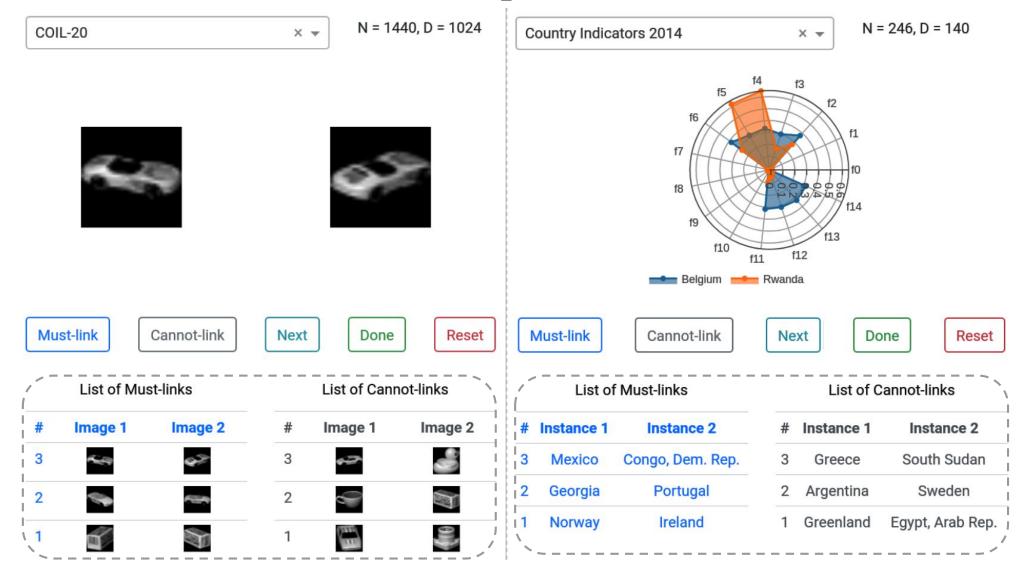


Figure: The interface for collecting users' feedback for image and tabular data.

What are translated to the algorithm (in low dim.)

Points connected by a Must link $(\mathcal{M}) \to \text{must stay close together}$. Points connected by a Cannot link $(\mathcal{C}) \to \text{must stay far apart}$.

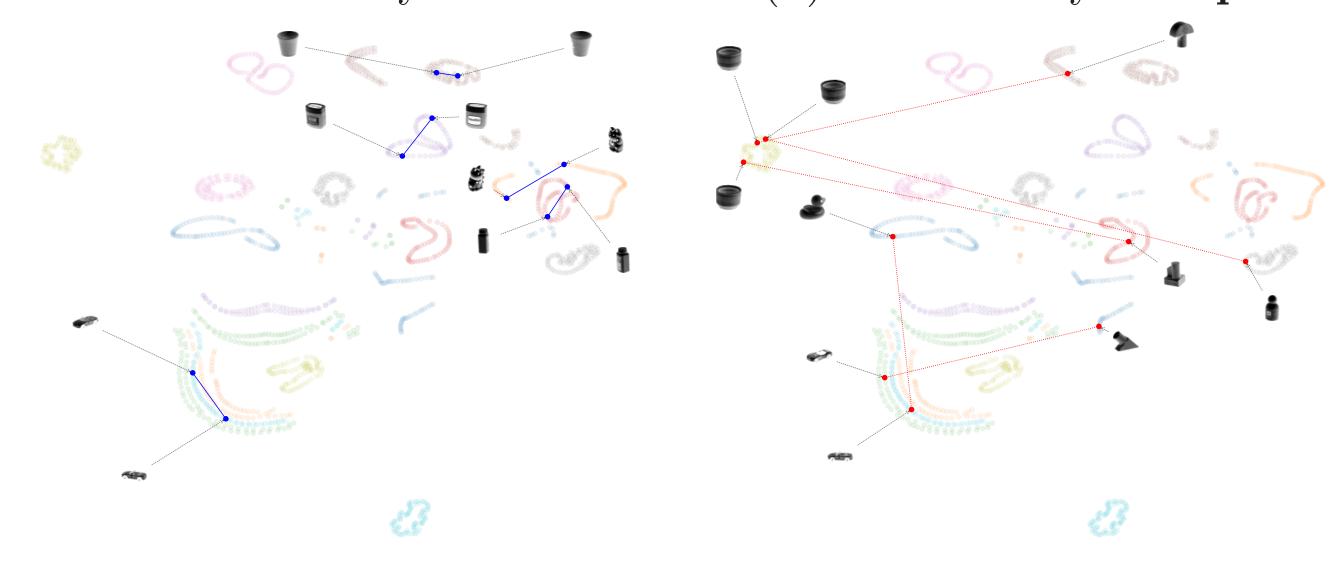


Figure: The user constraints in the visualization of the COIL20 dataset

Constraint-Preserving Scores [B]

- Consider the points in the visualization (low dim.)
- q_{ij} = probability of i and jbeing neighbors.
- $S_{\mathcal{M}} = \frac{1}{|\mathcal{M}|} \sum_{(i,j) \in \mathcal{M}} \log q_{ij}$.
- $S_{\mathcal{C}} = -\frac{1}{|\mathcal{C}|} \sum_{(i,j) \in \mathcal{C}} \log q_{ij}$.
- $S_{\mathcal{M}+\mathcal{C}} = S_{\mathcal{M}} + S_{\mathcal{C}}$.

B

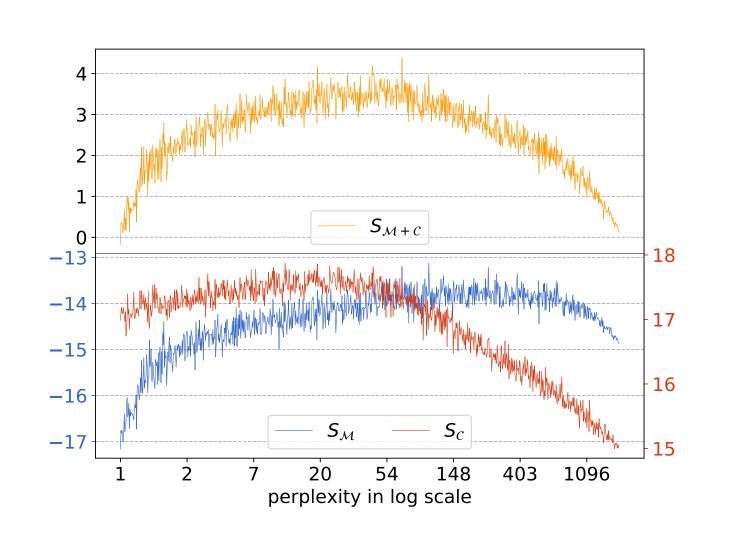


Figure : Constraint-preserving scores

with 50 constraints for MNIST dataset.

• NMS: Stress of pairwise dis-

• CC: Pearson corr. coeff.

QUALITY METRICS [C]

- tance orders comparison
- CCA: Stress with accent put on low dim.
- NLM: Stress with accent put on high dim.
- $AUC_{log}RNX$: How neighbors in high dim. are preserved in low dim.

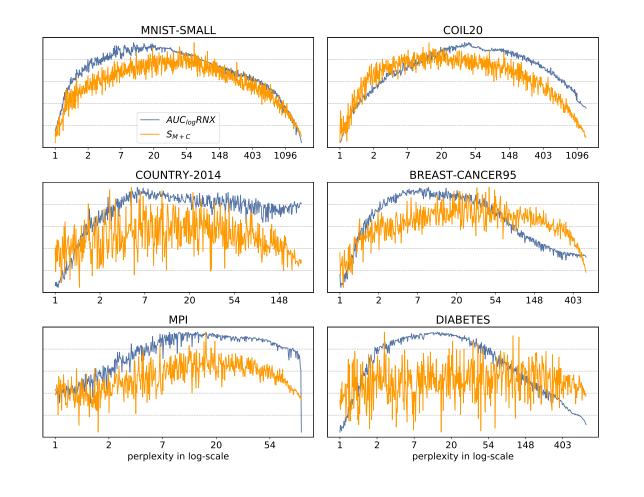


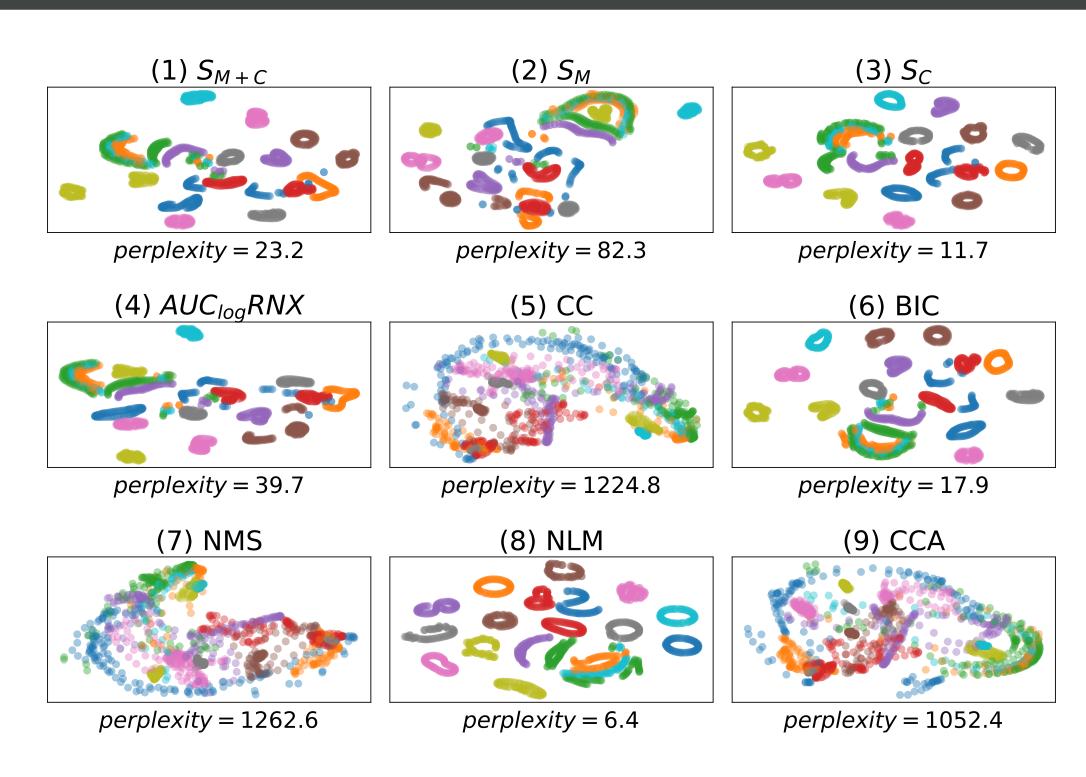
Figure: Compare $S_{\mathcal{M}+\mathcal{C}}$ and $\mathbf{AUC}_{log}\mathbf{RNX}$ for six datasets.

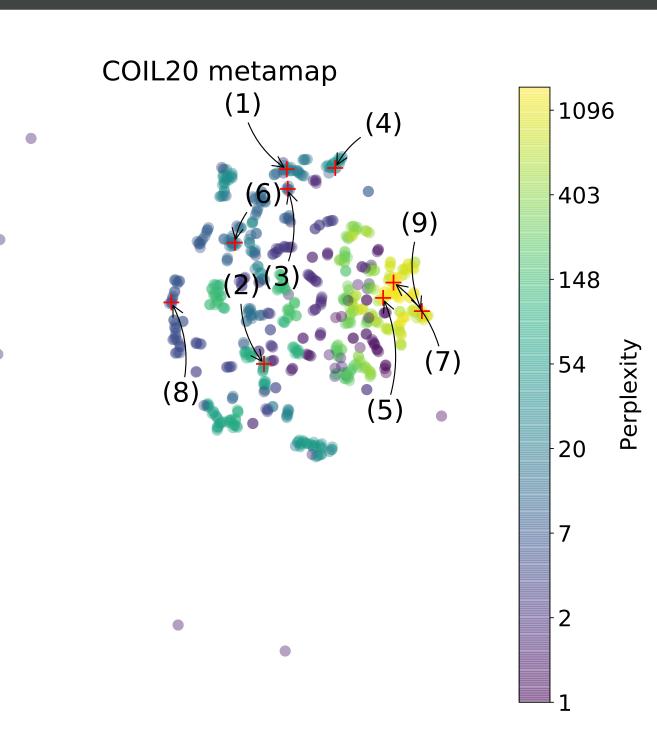
B

Our constraint scores agree with the quality metrics.

ALL VISUALIZATIONS IN ONE PLACE: META-PLOT

Can easily find the perplexity that maximizes $S_{\mathcal{M}}$, $S_{\mathcal{C}}$ or $S_{\mathcal{M}+\mathcal{C}}$.





CONCLUSION

- Consider user knowledge under the form of constraints to find the most suitable visualization.
- Make complex visualization technique (t-SNE) accessible to users by freeing them from the tedious task of selecting the hyperparameter.
- Heavy computation due to the pre-calculation of many possible embeddings.



