

Image Denoising with Union of Directional Orthonormal DWTs

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ABSTRACT

- A novel image denoising technique is proposed by using directional lapped orthogonal transforms (DirLOTs).
- A redundant dictionary is constructed with multiple hierarchical DirLOTs and it is applied to solve the basis pursuit denoising (BPDN) problem.
- The denoising performance is evaluated for several images through the heuristic shrinkage and block-coordinate-relaxation algorithm.

Key words— DirLOT, Basis pursuit, Wavelet denoising, Heuristic shrinkage, Block-coordinate-relaxation (BCR) algorithm

Introduction

- A common problem of image denoising, i.e. removal of additive white Gaussian noise (AWGN) from an observed image is dealt with.
- Purpose is to find a good candidate image $\hat{\mathbf{x}}$ of \mathbf{x}^* only from \mathbf{x} .

$$\underbrace{\mathbf{x}}_{\text{Observed image}} = \underbrace{\mathbf{x}^*}_{\text{Original image}} + \underbrace{\mathbf{w}}_{\text{White Gaussian noise}}$$

- Popular denoising approaches include solving the basis pursuit denoising (BPDN) problem.
- BPDN assumes that the candidate $\hat{\mathbf{x}}$ is expressed by a linear-combination of image prototypes (atoms) in a dictionary \mathbf{D} :

$$\underbrace{\hat{\mathbf{x}}}_{\text{Candidate image}} = \underbrace{\mathbf{D}}_{\text{Dictionary}} \underbrace{\hat{\mathbf{y}}}_{\text{Coefs.}},$$

where $\hat{\mathbf{y}}$ refers to the solution of

$$\hat{\mathbf{y}} = \arg \min_{\mathbf{y}} \frac{1}{2} \underbrace{\|\mathbf{x} - \mathbf{D}\mathbf{y}\|_2^2}_{\text{Fidelity}} + \underbrace{\lambda^T |\mathbf{y}|}_{\text{Sparsity}}.$$

- In this work, we suggest to adopt

Union of Directional Symmetric Orthonormal DWTs as a Dictionary \mathbf{D}

Review of Directional LOTs (DirLOTs)

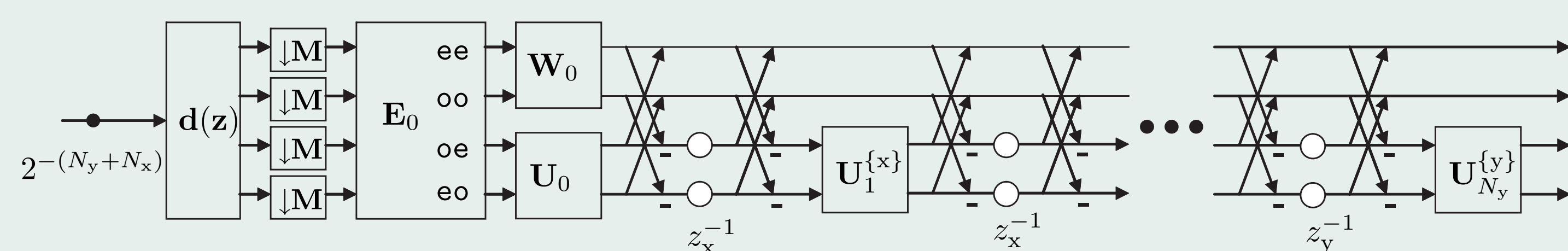
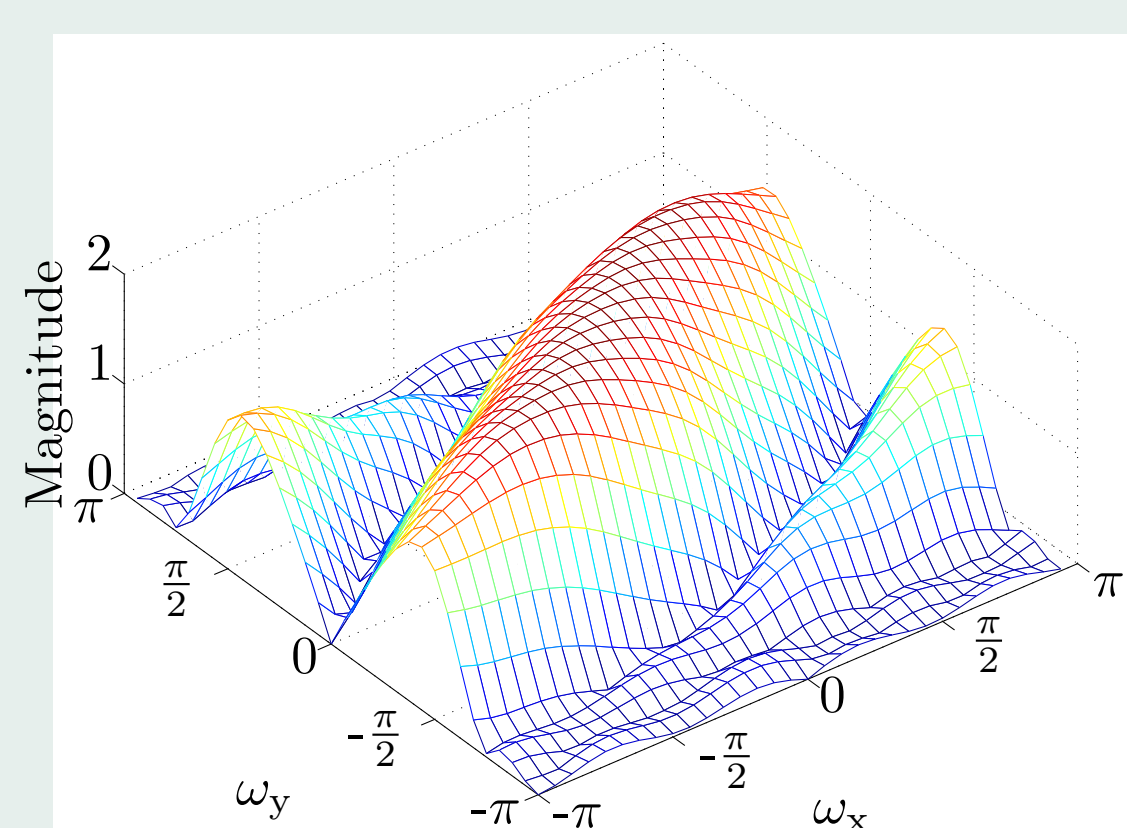
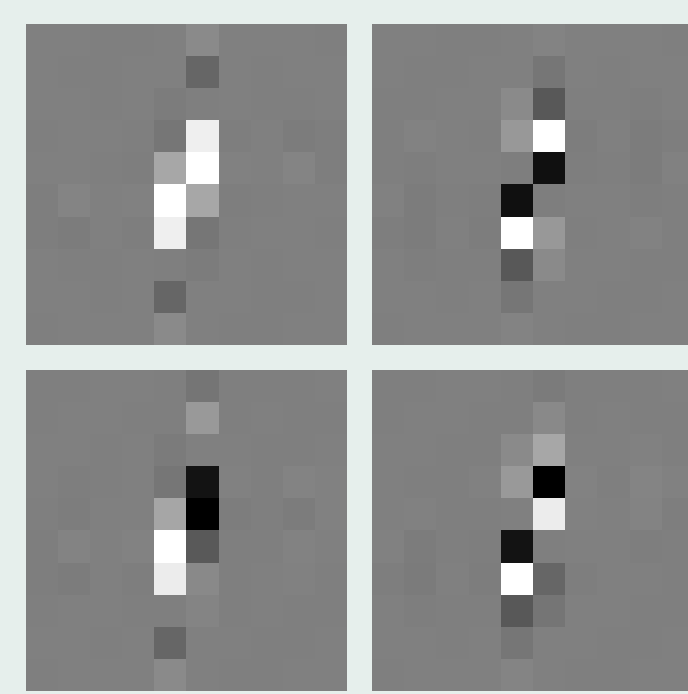


Figure: Lattice structure of a 2-D non-separable lapped orthogonal transform.



(a) $|H_0(e^{j\omega_y}, e^{j\omega_x})|$



(b) Basis images

Figure: A design example of 2 x 2-Ch. DirLOT with the 2-order trend vanishing moments (TVMs) of $\phi = \frac{\pi}{6}$, where $[N_y, N_x]^T = [4, 4]^T$, i.e. the basis size is 10×10 .

- DirLOTs are 2-D non-separable lapped orthogonal transforms with directional characteristics [ICIP2010, PCS2010, APSIPA2010].
- Bases are symmetric and real-valued, and have compact-support.

Union of Directional Symmetric Orthonormal DWTs (DirSOWTs)

- Suggestion of dictionary \mathbf{D}

$$\mathbf{D} = [\Phi_{0\cup\frac{\pi}{2}}^T \Phi_{\phi_1}^T \Phi_{\phi_2}^T \Phi_{\phi_3}^T \dots \Phi_{\phi_{K-1}}^T]$$

- $\Phi_{0\cup\frac{\pi}{2}}$: Nondirectional SOWT.
- Φ_{ϕ} : Directional SOWT for TVM direction ϕ .
- \mathbf{D} becomes a normalized tight frame and satisfies

$$\mathbf{D}\mathbf{D}^T = \sum_{k=0}^{K-1} \Phi_k^T \Phi_k = \mathbf{K}\mathbf{I}$$

where K is the redundancy.

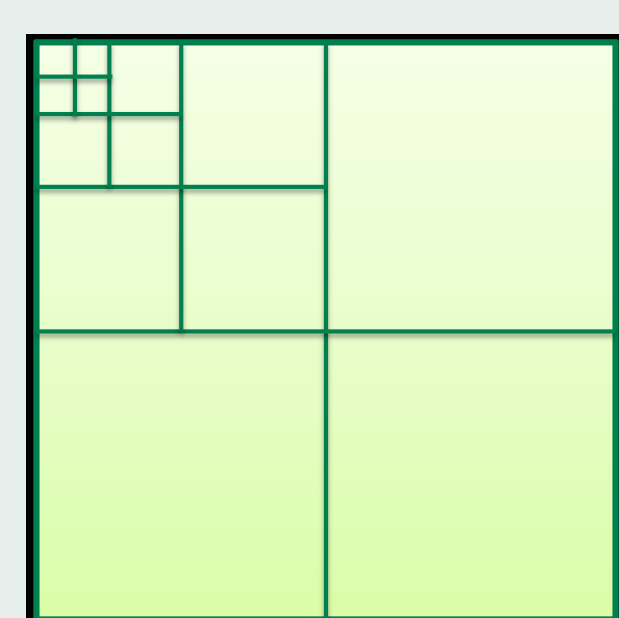


Figure: DWT decomposition

Heuristic Shrinkage and BCR Iterative-shrinkage

- Heuristic shrinkage is available for tight frames and simply calculates

$$\hat{\mathbf{y}} = \frac{1}{K} \text{Shrink}(\mathbf{D}^T \mathbf{x})$$

- BCR Iterative-shrinkage Alg. is available for union of orthogonal transforms and iteratively solves

$$\hat{\mathbf{y}}_k = \arg \min_{\mathbf{y}_k} \frac{1}{2} \|(\tilde{\mathbf{y}}_k + \Phi_k(\mathbf{x} - \tilde{\mathbf{x}})) - \mathbf{y}_k\|_2^2 + \lambda_k^T |\mathbf{y}_k|$$

where $\tilde{\mathbf{y}}_k$ and $\tilde{\mathbf{x}}$ are the estimations of \mathbf{y}_k and \mathbf{x}^* in the previous step, respectively. \mathbf{y}_k , $\hat{\mathbf{y}}_k$ and λ_k are the k -th subvector of \mathbf{y} , $\hat{\mathbf{y}}$ and λ , respectively.

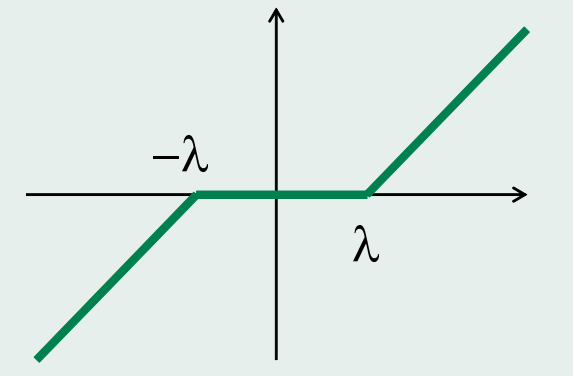


Figure: Soft-shrinkage function

Experimental Results

Table: Adopted transforms and the features.

Abbrv.	Features	K
DB5	Daubechies' least asymmetric compactly-supported wavelet with five VMs, separable, orthonormal	1
SON4	Symmetric orthonormal DWT with two VMs of $[N_y, N_x]^T = [4, 4]^T$, nonseparable, nondirectional	1
NSCT	Nonsubsampled contourlet with $2^3, 2^3, 2^4, 2^4$ directions in the scales from coarser to finer, near tight, symmetric	49
UDN4	Union of SON4 and DirSOWTs with two TVMs of $[N_y, N_x]^T = [4, 4]^T$, multidirectional, tight, symmetric	19

- UDN4: TVM direction $\phi_k \in \{-\frac{4\pi}{18}, -\frac{3\pi}{18}, -\frac{2\pi}{18}, \dots, \frac{13\pi}{18}\}$, $K = 1 + 18 = 19$
- Sweeping scalar $\lambda = \lambda 1$

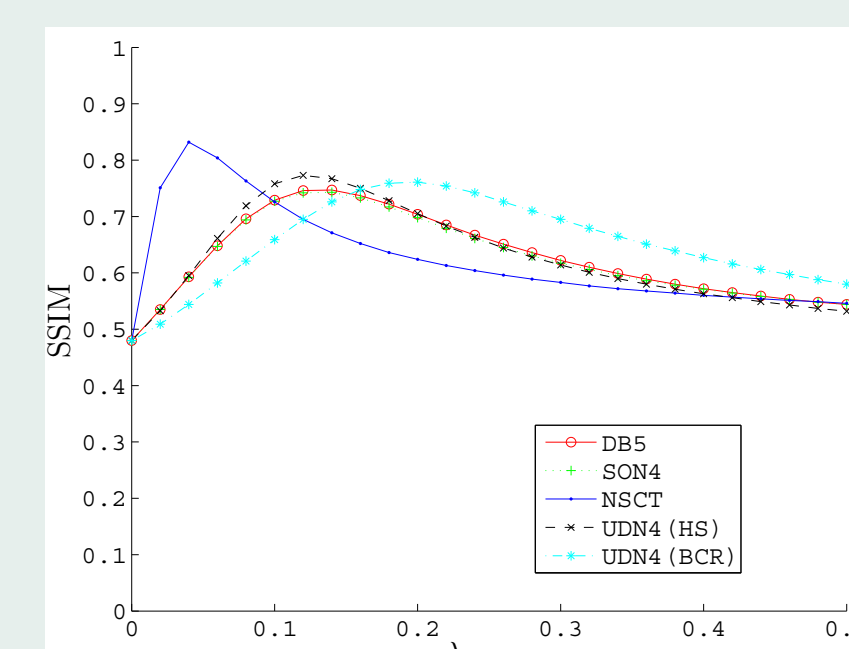


Figure: Denoising evaluation in terms of SSIM index for "barbara" with AWGN ($\sigma = 20$).



(a) Original (b) Noisy picture (c) DB5


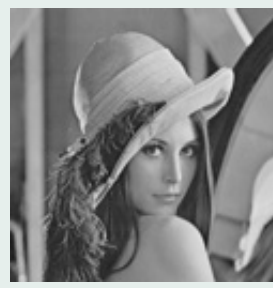

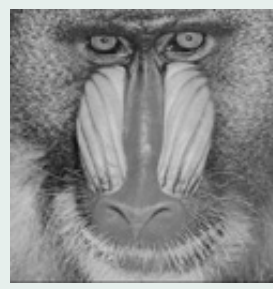


(d) NSCT (e) UDN4(HS) (f) UDN4(BCR)

Figure: Denoising results. (a)Original picture, (b) Noisy picture with AWGN ($\sigma = 20$), (c)-(f) Denoised pictures.

- Adaptive determination of vector λ

Table: Comparison of SSIM indexes among four transforms for various pictures and noise levels, where BayesShrink was used to determine the parameter λ .

	σ	DB5	SON4	NSCT (HS)	UDN4 (HS) (BCR)	
 <i>goldhill</i>	20	0.726	0.723	0.753	0.746	0.725
	30	0.668	0.664	0.666	0.684	0.664
	40	0.625	0.621	0.592	0.640	0.621
 <i>lena</i>	20	0.794	0.793	0.780	0.814	0.792
	30	0.749	0.748	0.693	0.768	0.748
	40	0.719	0.720	0.616	0.736	0.720
 <i>barbara</i>	20	0.748	0.760	0.767	0.778	0.750
	30	0.680	0.671	0.687	0.681	0.685
	40	0.626	0.608	0.619	0.623	0.633
 <i>baboon</i>	20	0.668	0.714	0.757	0.698	0.730
	30	0.558	0.606	0.653	0.591	0.613
	40	0.486	0.515	0.566	0.505	0.523

Conclusions

- Proposed to apply a union of DirLOTs to image denoising
- Perceptually preferable results were given with a simple computation
- Prospective performance was shown with iterative shrinkage Alg.
- Future works include the application to image restoration.

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