

Let us write  $G(p, n) = \{p\text{-dimensional (vector) subspaces of } \mathbb{R}^{n \times p}\}$ . A hyperplane  $V \subseteq \mathbb{R}^{n \times p}$  is specified by  $n \times p$  matrix  $A = [\vec{a}_1, \vec{a}_2, \dots, \vec{a}_p] \in Mat_{n \times p}$  where  $\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_p\}$  is a basis for  $V$ . I.e., given  $A \in Mat_{n \times p}$ ,  $\text{rk} A = p$ , we get a  $p$ -hyperplane  $V \subseteq \mathbb{R}^{n \times p}$  by  $V = \text{span} \{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_p\}$ . Conversely, given any  $p$ -dim subspace  $V \subseteq \mathbb{R}^{n \times p}$ , there is a  $n \times p$  matrix  $A$  with  $\text{rk}(A) = p$ , from which  $V$  is obtained in the above way. Two matrices,  $A$  and  $B$ , determine the same subspace  $V \iff \exists g \in GL(p)$ , such that  $B = Ag$ .  $GL(p)$  stands for general linear group of degree  $p$  over real field.

We thus have the following setup. Let the set of all 2-frames be

$$F(p, n) = \{A \mid \text{rk} A = p\} \subseteq Mat_{n \times p}(\mathbb{R}) \simeq \mathbb{R}^{n \times p}$$

and consider on it the equivalence relation

$$B \sim A \text{ if } \exists g \in GL(p), \text{ s.t. } B = Ag$$

We have described a bijection of sets

$$F(p, n)/\sim \simeq G(p, n).$$

We will show that  $G(p, n)$  is a manifold equipped with a natural smooth structure. To achieve that we need to prove that:

- $G(p, n)$  has a countable base
- $G(p, n)$  is Hausdorff
- $G(p, n)$  is locally euclidean

**Proposition 0.0.1.**  $F(p, n)$  is an open subset of  $\mathbb{R}^{p \times n}$

**Lemma 0.0.1.** The rank of an  $m \times n$  matrix is  $r \iff$  some  $r \times r$  minor does not vanish, and every  $(r+1) \times (r+1)$  minor vanishes.

Since we know that for  $M \in F(p, n)^{\mathbb{C}}$ ,  $\text{rk} M < p$  lemma ?? tells us all  $p \times p$  minors of an arbitrary element  $A \in F(p, n)^{\mathbb{C}}$  vanish. Let's denote the determinant of each minor of  $A$  with  $S_i$ ,  $i \in (1, 2, \dots, \binom{n}{p})$ . Then consider a continuous map  $\psi : Mat_{n \times p} \rightarrow \mathbb{R}^{\binom{n}{p}}$ ,  $\psi(M) \rightarrow (S_1, S_2, \dots, S_{\binom{n}{p}})$ . We can express  $F(p, n)^{\mathbb{C}} = \psi^{-1}(\vec{0})$  because all minors vanish ( $\det=0$ ). A point  $\vec{0} \in \mathbb{R}^{\binom{n}{p}}$  is a closed set, and because continuity preserves the closedness,  $F(p, n)^{\mathbb{C}}$  is closed in  $Mat_{n \times p}$ , and since its complement is closed,  $F(p, n)$  is an open subset of  $Mat_{n \times p}(\mathbb{R})$ .

**Proposition 0.0.2.**  $\sim$  is an open equivalence relation on  $F(p, n)$

In other words we need to show that the map  $\pi : F(p, n) \rightarrow F(p, n)/\sim$  is an open map. Then  $\pi$  is a quotient map and  $F(p, n)/\sim$  is equipped with quotient topology.

**Lemma 0.0.2.** A subset of a quotient space is open if and only if its preimage under the canonical projection map is open in the original topological space.

Let  $U$  be an open in  $F(p, n)$ . Then for every  $g \in GL(p)$  the set  $Ug = \{xg | x \in U\}$  is an open subset of  $F(p, n)$ . Therefore  $\pi^{-1}\pi(U) = \bigcup_{g \in G} Ug$  is an open in  $F(p, n)$  because the union of open sets is open. And by ??  $\pi(U) = [U]$  is open in  $G(p, n)$ .  $\pi$  is a canonical quotient map, and  $F(p, n)/\sim$  is open in  $\mathbb{R}^{n \times p}$ .

**Lemma 0.0.3.** *if  $\beta = \{\beta_\alpha\}_\alpha$  is a base for a topology  $\mathcal{T}$  on a topological space  $S$ , and if  $f : S \rightarrow X$  is an open map, then the collection  $\{f(\beta_\alpha)\}_\alpha$  is a base for the topology on  $X$ .*

**Proof:** Let  $V$  be an open in  $X$  and  $y \in V$ . Choose  $x \in f^{-1}(y)$ . Since  $f^{-1}(V)$  is open there is a basis element  $U \in \beta$  s.t.  $x \in U \subset f^{-1}(V)$  which implies that  $y \in f(U) \subset V$ . Since  $y$  is arbitrary, and  $f(U) \subset f(\beta)$  the collection  $\{f(\beta_\alpha)\}_\alpha$  is a base for the topology on  $X$ .

We have that  $F(p, n)$  has a second countable base since it is a subspace of  $\mathbb{R}^{n \times p}$ . Thus by lemma ??, we have that the base of  $G(p, n)$  is second countable.

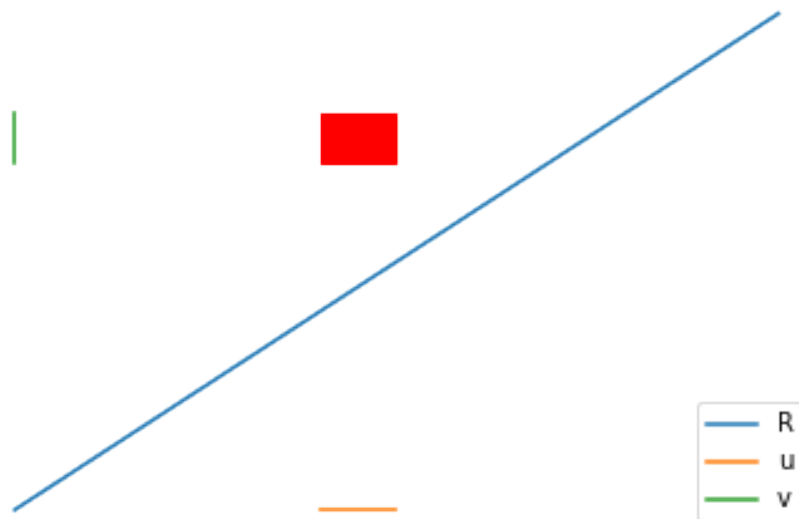
**Proposition 0.0.3.** *The graph of the equivalence relation on  $F(p, n)$  is a closed subset of  $F(p, n) \times F(p, n)$ . i.e.  $R = \{(A, B) \in F(p, n) \times F(p, n) \mid A = Bg\}$  is closed.*

We can consider  $R$  as a set of matrices  $[AB] = [\vec{a}_1, \vec{a}_2, \dots, \vec{a}_p, \vec{b}_1, \vec{b}_2, \dots, \vec{b}_p]$  of rank  $p$ . Lemma ?? tells us that every  $(p+1) \times (p+1)$  minor of an element in  $R$  must vanish. Consider the map that assigns to  $(A, B)$  the values of all  $(p+1) \times (p+1)$  minors

$$\psi : F(p, n) \times F(p, n) \rightarrow \mathbb{R}^{\binom{n}{p+1}}$$

Since  $\phi$  is continuous ( as all of its components are polynomials ) and  $R = \psi^{-1}(0)$  , then  $R$  is closed.

**Example 0.0.1.** For example take  $G(2, 4)$ , then  $\phi : Mat_{4 \times 2} \rightarrow \mathbb{R}^{16}$



**Proposition 0.0.4.**  $G(p, n)$  is Hausdorff.

That is because  $R$  is closed in  $F(p, n) \times F(p, n)$ ,  $(F(p, n) \times F(p, n)) \setminus R = R^c$  is open.  $\implies \forall (x, y) \in R^c$  there is a basic open set  $u \times v$  containing  $(x, y)$  s.t.  $(u \times v) \cap R = \emptyset \implies \forall x, y$  s.t.  $(x, y) \notin R, \exists u$  around  $x$  and  $v$  around  $y$  s.t.  $u \cap v = \emptyset$  Thus for any two points  $[x] \neq [y] \in F(p, n)/\sim$  there exist disjoint neighborhood of  $x$  and  $y$  and  $F(2, 4)/\sim$  which is exactly the definition of Hausdorff property.

**Proposition 0.0.5.**  $G(p, n)$  is locally euclidean.

Now that we have Hausdorff property and second countable basis, we need to prove that every point lying on a manifold has a neighbourhood that is homeomorphic to an open in  $\mathbb{R}^n$ . Then we can claim that  $G(p, n)$  is a manifold.

First we define charts. Take  $A \in Mat_{n \times p}$  denote by  $A_k$ , ( $k \in$  all possible picks of  $p$  from the set  $[1, \dots, n]$ ) the  $p \times p$  minor, formed by the  $k_1$ th  $\dots$   $k_p$ th rows of  $A$ . The set

$$U_k = \{A \mid \det(A_k) \neq 0\} \subset F(p, n)$$

is open, because its complement is closed. We also have that  $\forall g \in GL(p)$  if  $A \in U_k$  then  $Ag \in U_k$ . Indeed, because  $\det(Ag) = \det(A)\det(g)$ ,  $\det((Ag)_{i,j}) \neq 0$  which means  $Ag$  will belong to a set  $U_k$  Next, define

$$V_k = U_k/\sim = \pi(U_k) \subset G(p, k)$$

The set  $V_k$  is open since the equivalence relation is open. i.e.  $\pi$  is an open map.

$U_k$  has a canonical representative  $A \sim \widehat{AA_k^{-1}}$ .  $\widehat{\cdot}$  discards all the rows whose index is in  $k$ . Similarly  $V_k$  has a canonical representative:  $[A] \sim [\widehat{AA_k^{-1}}]$

**Example 0.0.2.** Following the previous example consider  $[A] \in G(2, 4)$ . If a minor  $A_{2,4}$  is

invertible we have that  $[A] \sim [\widehat{AA_{2,4}^{-1}}] = \begin{bmatrix} * & * \\ 1 & 0 \\ * & * \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} * & * \\ * & * \end{bmatrix}$ . Since charts  $\bigcup U_k$  cover  $F(p, n)$ ,

charts  $V_k$  cover  $G(p, n)$  (because  $\pi$  is open).

Now we define homeomorphisms between charts  $V_k$  and opens in  $R^{p \times (n-p)}$  as follows:

$$\phi_k : V_k \subset G(p, n) \rightarrow Mat_{(n-p) \times p}(\mathbb{R}) \simeq \mathbb{R}^{(n-p) \times p}, \quad \phi_k([A]) = \widehat{AA_k^{-1}}$$

We can show that  $\phi$  is well defined.

Let  $A, A' \in [A]$  we will show that  $\phi$  is well defined. Equivalently  $\phi_k(A) = \phi_k(A')$  Since  $A$  and  $A'$  are in the same class, we have that  $A' = Ag$ ,  $g \in GL(p)$ ,  $\phi_k(A) = \widehat{AA_k^{-1}}$ .

$$\phi_k(A') = \phi_k(Ag) = Ag((Ag)_k)^{-1} = Ag(A_k g)^{-1} = Agg^{-1}A_k^{-1} = AIA_k^{-1} = \widehat{AA_k^{-1}} = \phi_k(A)$$

$\phi$  is continuous because matrix multiplication is continuous. Next, we can see that  $\phi$  is surjective and  $\phi^{-1}$  is continuous by explicitly defining inverse.

$$\phi_k^{-1}\left(\begin{pmatrix} - & \alpha_1 & - \\ & \vdots & \\ - & \alpha_{n-p} & - \end{pmatrix}\right) = \begin{pmatrix} 1_1 \\ \vdots \\ 1_p \\ \alpha_1 \\ \vdots \\ \alpha_{n-p} \end{pmatrix}$$

Finally, to show that  $\phi$  is a homeomorphism, we have left to shot that  $\phi$  is injective.

Assume that there  $\phi_k$  is not injective then there are  $A \in [A]$  and  $B \in [B]$  such that there is **no**  $g \in GL(p)$  for which  $Ag = B$ . i.e.  $AA_k^{-1} = BB_k^{-1} \iff AA_k^{-1}B_k = B$  but  $A_k^{-1}B_k \in GL(p)$  thus we reach contradiction. Therefore  $\phi_k$  is homeomorphism

**Example 0.0.3.** Let  $A = \begin{bmatrix} 2 & 6 \\ 1 & 3 \\ 2 & 1 \\ 4 & 3 \end{bmatrix}$ ,  $[A] \in V_{3,4}$

$$AA_{3,4}^{-1} = \begin{pmatrix} 2 & 6 \\ 1 & 3 \\ 2 & 1 \\ 4 & 3 \end{pmatrix} \begin{pmatrix} \frac{3}{2} & -\frac{1}{2} \\ -2 & 1 \end{pmatrix} = \begin{pmatrix} -9 & 5 \\ -\frac{9}{2} & \frac{5}{2} \\ 1 & 0 \\ 0 & 1 \end{pmatrix}$$

the above multiplication is continuous by ?? and we can exlcude rows 3 and 4 so that we get result in  $R^4$ . Then the restriction to  $R^4$  is also continuous.

$$\phi_{3,4}([A]) = \begin{pmatrix} -9 & 5 \\ -\frac{9}{2} & \frac{5}{2} \end{pmatrix}$$

Next the inverse map  $\phi_{3,4}(\beta)^{-1} \beta \in Mat_{2 \times 2} = \phi_{3,4}(A_{1,2}A_{3,4}^{-1}g) = [A]$  for some matrix  $A$ ,

such that  $A_{1,2} = \beta$ . But if we pick  $g = A_{3,4}$  then  $\phi_{3,4}(\beta) = \begin{bmatrix} \beta_{1,1} & \beta_{1,2} \\ \beta_{2,1} & \beta_{2,2} \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$  More generally

$$\phi_{i,j}^{-1} : \mathbb{R}^4 \rightarrow v_{i,j} \subset G(2,4) \quad \phi_{i,j}^{-1}(\beta) \rightarrow \begin{bmatrix} \beta \\ I_{2 \times 2} \end{bmatrix} = [\alpha]$$

Such that  $\alpha[i:] = \beta[1:]$ ,  $\alpha[j:] = \beta[2:]$ ,  $\alpha[(I \setminus \{i,j\})[1]] = I[1:]$  and  $\alpha[(I \setminus \{i,j\})[2]] = I[2:]$

**Example 0.0.4.**  $\phi_{3,4}^{-1}(\alpha) = [A]$  as defined in ??

$$\phi_{3,4}^{-1} \begin{pmatrix} -9 & 5 \\ -\frac{9}{2} & \frac{5}{2} \end{pmatrix} = \begin{bmatrix} -9 & 5 \\ -\frac{9}{2} & \frac{5}{2} \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

We can confirm that  $\alpha = \begin{bmatrix} -9 & 5 \\ -\frac{9}{2} & \frac{5}{2} \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$  and  $A = \begin{bmatrix} 2 & 6 \\ 1 & 3 \\ 2 & 1 \\ 4 & 3 \end{bmatrix}$  span the same subspace. Because if we

take  $g = \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}$  then  $\alpha g = A$

Since  $\bigcup U_{i,j}$  covers  $F(2, 4)$ ,  $\cup v_{i,j}$  covers  $G(2, 4)$  Finally, we check transition maps.

$$\phi_{1,2}([A])^{-1} = A_{3,4}A_{1,2}^{-1}, \quad \phi_{1,2}^{-1}(u) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ v_{1,1} & v_{1,2} \\ v_{2,1} & v_{2,2} \end{pmatrix}$$

$$\phi_{2,4}([A]) = A_{1,3}A_{2,4}^{-1}, \quad \phi_{2,4}^{-1}(v) = \begin{pmatrix} v_{1,1} & v_{1,2} \\ 1 & 0 \\ v_{2,1} & v_{2,2} \\ 0 & 1 \end{pmatrix}$$

$$\begin{aligned} \phi_{2,4} \circ \phi_{1,2}^{-1}(v) &= \begin{pmatrix} v_{1,1} & v_{1,2} \\ v_{2,1} & v_{2,2} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ v_{1,1} & v_{1,2} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ v_{2,1} & v_{2,2} \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 \\ v_{1,1} & v_{1,2} \end{pmatrix} \begin{pmatrix} v_{2,2} & -1 \\ -v_{2,1} & 0 \end{pmatrix} \frac{1}{-v_{2,1}} = \\ &= -\frac{1}{v_{2,1}} \begin{pmatrix} v_{2,2} & -1 \\ v_{1,1}v_{2,2} - v_{1,2}v_{2,1} & -v_4 \end{pmatrix} \end{aligned}$$

Now let's check the transition map  $\phi_{3,4} \circ \phi_{2,3}^{-1}$

$$\phi_{3,4} \circ \phi_{2,3}^{-1}(v) = \begin{pmatrix} v_{1,1} & v_{1,2} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ v_{2,1} & v_{2,2} \end{pmatrix} = -\frac{1}{v_{2,1}} \begin{pmatrix} v_{1,1}v_{2,2} + v_{1,2}v_{2,1} & -v_{1,1} \\ v_{2,2} & -1 \end{pmatrix}$$

Hence  $G(2, 4)$  can be equipped with the structure of a 4 dimensional smooth manifold.

However, we can also consider  $G(2, 4)$  as a quotient of Stiefel Manifold. We will define a Stiefel manifold as a set of orthonormal  $k$  frames.

$$V(n, k) \subseteq F(n, k); \quad V(n, k) = \{A \mid rkA = 2, \quad A^T A = I\}$$

$$\begin{array}{ccc} V(2, 4) & \hookrightarrow & F(2, 4) \\ & \searrow p & \downarrow \pi \\ & & G(2, 4) \end{array}$$

Map  $p$  is surjective because every subspace has an orthonormal basis. I.e. starting with any basis we can construct an orthonormal one via Gram-Schmidt algorithm. Now, if we redefine the map  $p$  such that  $p : F(2, 4)/_{O(2)} \rightarrow G(2, 4)$ , where  $O(2)$  is the orthogonal group of 2 – frames, we will have a bijection. Therefore there are two ways we can consider  $G(2, 4)$

$$G(2, 4) = F(2, 4)/_{Gl_2(\mathbb{R})} \quad G(2, 4) = V(2, 4)/_{O(2)}$$

# Chapter 1

## Tangent Spaces

Let's define tangent spaces on  $G(2, 4)$ . First consider the equivalence relation defined as:

$$(p, (U, \phi), v) \sim (p, (V, \psi), w) \text{ if } w = J(\psi \circ \phi^{-1})_{\phi(p)} v$$

Consider tangent space on  $G(2, 4)$  at  $X$ , it's given by

$$T_p X = \{(p, (U, \phi), v) \mid (U, \phi) \text{ is a chart around } p, v \in \mathbb{R}^n\} / \sim$$

Hence a tangent vector to  $G(2, 4)$  at  $p \in G(2, 4)$  is an equivalence class  $[(p; (U; \phi); v)]$ . Whenever we have fixed the chart  $(U; \phi)$ , the class is represented just by a vector  $v \in \mathbb{R}^n$ . To represent the same equivalence class in another chart, we multiply  $v \in \mathbb{R}^n$  by the respective Jacobi matrix. Jacobi matrix of transition map  $\phi_{3,4} \circ \phi_{2,3}^{-1}$  is given by:

$$J(\phi_{3,4} \circ \phi_{2,3}^{-1}) = \begin{pmatrix} -v_{2,2} & 1 & 0 & -v_{1,1} \\ \frac{1}{v_{2,1}} & 0 & -\frac{v_{1,1}}{v_{2,1}^2} & 0 \\ 0 & 0 & \frac{v_{2,2}}{v_{2,1}^2} & -\frac{1}{v_{2,1}} \\ 0 & 0 & -\frac{1}{v_{2,1}^2} & 0 \end{pmatrix}$$

**Example 1.0.1.** Consider the matrix  $a$  from the example ???. We have that  $\phi_{3,4}([A]) = \begin{pmatrix} -9 & 5 \\ -\frac{9}{2} & \frac{5}{2} \end{pmatrix}$  and  $\phi_{2,3} = \begin{pmatrix} 2 & 0 \\ 0.4 & 1.8 \end{pmatrix}$

$$J(\phi_{3,4} \circ \phi_{2,3}^{-1}) = \begin{pmatrix} -1.8 & 1 & 0 & 0 \\ 2.5 & 0 & -12.5 & 0 \\ 0 & 0 & 11.25 & -2.5 \\ 0 & 0 & -6.25 & 0 \end{pmatrix}$$

Then

$$(p, (U, \phi_{2,3}), v) \sim (p, (V, \phi_{3,4}), w) \text{ if } w = J(\phi_{3,4} \circ \phi_{2,3}^{-1})_{\phi_{2,3}(p)} v$$

**How to project on such tangent spaces ?**

## Chapter 2

### $Gr(2, 4)$ is compact

We'll endow  $R^{n \times k}$  with the norm induced by the Frobenius inner product:

$$\|A\| = \sqrt{\text{tr}(A^T A)} = \sqrt{\sum_{i,j} a_{i,j}^2}$$

$$\langle A, B \rangle = \sqrt{\text{tr}(A^T B)}$$

We define the compact Stiefel manifold as

$$St(2, 4) = \{A \in F(2, 4), \quad A^T A = I_k\}$$

It's closed because under the continuous map  $A \rightarrow A^T A$  it maps to  $I_k$ , and it's bounded by  $\sqrt{k}$  because each column of  $A$  has norm 1, so  $\|A\| = \sqrt{k}$ .

## Chapter 3

# Optimization on Grassmanian as quotient mfd

Def If the manifold  $X \in \mathbb{R}^N$  happens to be the level set  $X = f^{-1}(c)$  of a smooth function  $f : U \rightarrow \mathbb{R}^k$  over a regular value  $c \in \mathbb{R}^k$ , then

$$T_p X = \ker df_p$$

We show that defining function is  $h : \mathbb{R}^{n \times p} \rightarrow \text{Sym}(p) : X \rightarrow h(X) = X^T X - I_p$  and regular value 0. Thus tangent spaces are defined as:

$$T_x St(n, p) = \ker Dh(X) = \{V \in \mathbb{R}^n \times p : X^T V + V^T X = 0\}$$

Also, more explicitly we can arrive to:

$$T_x St(n, p) = \{X\Omega + XB_\perp : \Omega \in \text{Skew}(p), B \in \mathbb{R}^{(n-p) \times p}\}$$

$$R_X(V) = (X + V)(I_p + V^T V)^{-\frac{1}{2}}$$

$$\text{Proj}_x(U) = (I - XX^T)U + X \frac{X^T U - U^T X}{2}$$

$$\text{grad}f(X) = \text{Proj}_X(\text{grad}\bar{f}(X)) = \text{grad}\bar{f}(X) - X \text{sym}(X^T \text{grad}\bar{f}(X))$$

Wher  $\text{sym}(M) = \frac{M+M^T}{2}$

**Gradient Descent**

$$x_{k+1} = R_{x_k}(-\alpha_k \text{grad}f(x_k))$$

where  $\alpha_k$  is the step size, and  $x_1$  is some random point.



## Chapter 4

### Next Steps

Next, we need to generalize the statements above, so that we get that the dimension of grassmannian is  $G(k, n) = nk - k^2$ . We have as many charts as  $k \times k$  minors. Every  $n \times k$  matrix has  $\binom{n}{p}$   $k \times k$  minors.

## Chapter 5

# Rayleigh Quotient Newton's Method

Consider a Rayleigh quotient function  $\bar{f} = \frac{x^T M x}{x^T x}$ , if we restrict the points to lie on the sphere the function comes down to  $\bar{f} = x^T M x$ . Also we can easily calculate that the  $grad \bar{f} = 2Mx$ . Since the gradient on the manifold is given as  $grad f = P grad \bar{f}$  we can calculate that  $grad f = (I - xx^T)2Mx = 2Mx - (x^T M x)x$ . Next we find the differential of that gradient:  $D(grad f) = 2M - 2x^T M x + 4Mxx^T$ . We take the canonical dot product defined as  $g_c(\Delta, \Delta) = tr \Delta^T (I - \frac{1}{2} Y Y^T) \Delta$ . Therefore  $g_c(D(grad f), \eta) = 2M\eta - 2x^T M x \eta + 2Mxx^T \eta$ . Next to get the hessian:

$$Hess(f) = P g_c(D(grad f), \eta) = 2(PM\eta - Px^T M x \eta + PMxx^T \eta)$$

.  $P = (I - xx^T)$  is a projection operator, and notice that we can write

$$PMP\eta = PM(I - xx^T)\eta = PM\eta - PMxx^T \eta$$

Also in the term  $-Px^T M x \eta$  we can remove  $P$  and put  $\eta$  in front because  $x^T M x$  is a scalar. Therefore we get

$$Hess f = PMP\eta - \eta x^T M x$$

Finally we go to the newton iteration

$$Hess(f)\eta = -grad(f)$$

and replace and get:

$$PMP\eta - \eta x^T M x = -PMx \tag{5.1}$$

Therefore our Newton iteration is:

1. Solve ??
2. Set  $x_{new} = R(x_k)(\eta_k)$