

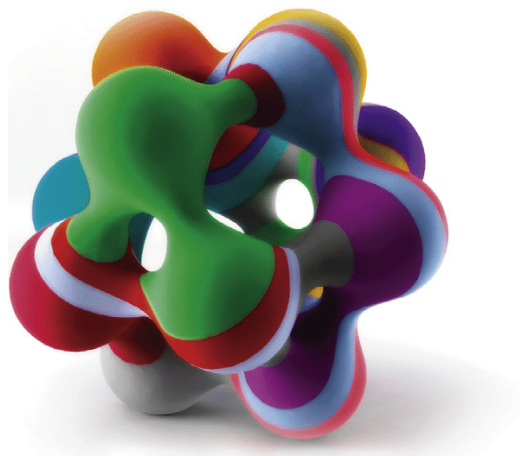
# Morse Theory

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November 25, 2020



## Contents

# 1 Introduction

**Ex.** Show that the function  $f : S^2 \rightarrow \mathbb{R}, f(x, y, z) = z$  is a Morse function.

$f$  is smooth on  $S^2$  since it extends to a smooth map on all of  $\mathbb{R}^3$ . We can map  $R^3$  to  $S^2$  with the stereographic projection two functions:

$$\phi_1(x_1, x_2, x_3) = \left( \frac{x_1}{1-x_3}, \frac{x_2}{1-x_3} \right) \text{ and } \phi_2(y_1, y_2, y_3) = \left( \frac{y_1}{1+y_3}, \frac{y_2}{1+y_3} \right)$$

Therefore, to get  $S^2 \rightarrow R^3$  we can take  $\phi_1^{-1}$  and  $\phi_2^{-1}$

$$\phi_1^{-1}(x_1, x_2, x_3) = \left( \frac{2x_1}{x_1^2+x_2^2+1}, \frac{2x_2}{x_1^2+x_2^2+1}, \frac{x_1^2+x_2^2-1}{x_1^2+x_2^2+1} \right)$$

$$\phi_2^{-1}(y_1, y_2, y_3) = \left( \frac{2y_1}{y_1^2+y_2^2+1}, \frac{2y_2}{y_1^2+y_2^2+1}, \frac{1-y_1^2-y_2^2}{y_1^2+y_2^2+1} \right)$$

Then, we take  $g_1 = f \circ \phi_1^{-1}$  and  $g_2 = f \circ \phi_2^{-1}$

$$g_1(x, y) = \frac{x^2+y^2-1}{x^2+y^2+1} \text{ and } g_2(x, y) = \frac{1-x^2-y^2}{x^2+y^2+1}$$

Now, we can compute jacobian of  $g_1$  and  $g_2$ , find critical points, and check that determinant of hessian matrix is non-zero.

$$\nabla g_1(x, y, z) = 0 \text{ iff } (x, y, z) = (0, 0, -1)$$

$$\nabla g_2(x, y, z) = 0 \text{ iff } (x, y, z) = (0, 0, 1) \text{ We have two critical points, and now}$$

we compute the hessian at them.

$$H(g_1) = \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} \implies \det(H(g_1)) = 16$$

$$H(g_2) = \begin{bmatrix} -4 & 0 \\ 0 & -4 \end{bmatrix} \implies \det(H(g_2)) = 16$$

Both critical points are non-degenerate, therefore  $f$  is a Morse function. ■