

List of commands (public functions) of the INA226_WE library		
Function	Parameters	what it does
<code>void Init()</code>	none	initiates the INA226 with some default register values
<code>void reset_INA226()</code>	none	reset of the device
<code>void getI2cErrorCode()</code>	none	returns the current error code from endTransmission(); 0 = success.
<code>void setCorrectionFactor(<i>factor</i>)</code>	<i>factor</i> (float)	if INA226 current values differ from currents measured with calibrated equipment, you can apply a factor
<code>void setAverage( <i>mode</i> )</code>	INA226_AVERAGE_X  <i>X</i> = 1, 4, 16, 64, 128, 256, 512, 1024	sets the number of samples that are averaged for one measurement
<code>void setConversionTime( <i>time</i> )</code>	INA226_CONV_TIME_X  <i>X</i> = 140, 204, 332, 588, 1100, 2116, 4156, 8244	sets time for conversion for shunt and bus voltage in microseconds
<code>void setMeasureMode( <i>mode</i> )</code>	INA226_CONTINUOUS, INA226_TRIGGERED, INA226_POWER_DOWN + current only or bus voltage only versions	sets the mode; for POWER_DOWN please use the powerDown function since it remembers the mode before power-down; see also the examples.
<code>void setResistorRange( <i>resistorValue</i>,                         (<i>range</i>) )</code>	<i>resistorValue</i> in ohms (float), range in Ampere (float)	Sets resistor value in case you don't use an INA226 module with 0.1 ohms shunt. The secon parameter ( <i>range</i> ) is optional (see example).
<code>float getShuntVoltage_mV()</code>	none	delivers shunt voltage in mV
<code>float getBusVoltage()</code>	none	delivers bus voltage in V
<code>float getCurrent_mA()</code>	none	delivers current in mA
<code>float getBusPower_mW()</code>	none	delivers the power in mW
<code>void startSingleMeasurement()</code>	none	starts single shot measurement and waits until data is available
<code>void startSingleMeasurementnoWait()</code>	none	starts single shot measurement and does not wait (non-blocking)
<code>void powerDown()</code>	none	switches the module off and saves the configuration before
<code>void powerUp()</code>	none	switches the module on after Power Down and writes back the configuration (modes, gains, etc)
<code>void waitUntilConversionCompleted()</code>	none	waits until the current conversions and calculations are completed.
<code>void setAlertPinActiveHigh()</code>	none	by default the the alert pin is active-low; this function changes this
<code>void enableAlertLatch()</code>	none	the alert flag is set and the alert pin is active, when the limit in the alert register is exceeded; by default it will be deleted with the next measurement in limit; with enableAlertLatch the flag will have to be cleared manually, which gives better control
<code>void setAlertType( <i>type</i>, <i>limit</i> )</code>	types: INA226_SHUNT_UNDER, INA226_SHUNT_OVER, INA226_BUS_UNDER, INA226_BUS_OVER, INA226_CURRENT_UNDER, INA226_CURRENT_OVER, INA226_POWER_OVER <i>limit</i> : float	sets the alert type and the limit:  SHUNT_OVER/_UNDER: limit in mV BUS_OVER / _UNDER: limit in V CURRENT_OVER / _UNDER: limit in mA POWER_OVER: limit in mW
<code>void readAndClearFlags()</code>	none	reads the Mask/Enable register; this clears the overflow, conversion ready and limit alert flags; the status of the flags are saved in the following bool variables: - overflow - convAlert - limitAlert