$$(i) \Rightarrow (ii)$$

suppose à is an eigenvalue et A

· let v Le the corresponding eigenvector to λ

. by defi of an eigenvalue: $A_{V} = \lambda V$ / $\cdot V^{T}$ from the left

$$\sqrt{A}V = \lambda V^{T}V$$

 $v^{T}Av = \lambda v^{T}v$ $by (i), \quad v^{T}Av \ge 0$ $v^{T}v \ge 0 \quad always \quad (even \quad v^{T}v > 0, eigenvectors \quad are nonzero)$

· let by, ..., In he eigenvalues of A and vy,..., on the corresponding eigenvectors

· linear algebra fact: eigenvalues of symmetric matrices are real

· linear algebra last: eigenvetors v,..., vn are orthonormal

Let
$$Q = \begin{pmatrix} 1 & 1 & 1 \\ v_1 & v_2 & \cdots & v_n \end{pmatrix}$$
, $\Delta = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_1 \end{pmatrix}$

=> $AQ = Q\Lambda$ $A_{\nu_2} = \lambda_2 \nu_2$

Q is ortogonal => $Q^TQ = \overline{1} = QQ^T => Q^T = Q^{-1}$

 $AQ = QA / Q^{-1}$ from the right

$$A = Q \Delta Q^{-1}$$

$$D = \begin{pmatrix} \sqrt{\lambda_1} & \sqrt{\lambda_2} & 0 \\ 0 & \sqrt{\lambda_2} & 0 \end{pmatrix}$$

- let $D = \sqrt{\Delta}$ element-wise $\Longrightarrow DD^T = DD = \Delta$

$$A = Q \Delta Q^{-1} = Q D D^{T} Q^{-1} = Q D D^{T} Q^{T} = Q D (QD)^{T}$$

· the metrix U we are looking for is QD

$$(jj_i) \Rightarrow (i)$$

$$x^{\dagger}Ax = x^{\dagger} \overrightarrow{U^{\dagger}U}x = (Ux)^{\dagger} (Ux) \ge 0$$

$$y^{\dagger} y^{\dagger} y^{\dagger} = y^{\dagger}y \ge 0 \text{ always}$$

$$\times \geq_0$$

when is this psd? Iff >11, x22 ≥0, x11x22 ≥1

then sup
$$\left\{ -x_{11} : x_{12} = 1, \left(\frac{x_{11}}{1 \times x_{22}} \right) \ge 0 \right\} = 0$$
. But x_{11} cannot be zero

3.

. hints write it as

min xn

×1 55

 $\begin{pmatrix} x_i & x_{i-1} \\ x_{i-1} & 1 \end{pmatrix} \geq 0 \qquad \text{for } i = 2, ..., n$

is this an SDP?

 $\begin{pmatrix} x_{n} x_{n-1} \\ x_{n-1} & 0 \\ & & \\ &$

yes

4.

the most intenshing care is when P is symmetric

if it is not psd, then it has a negative eigeneel & white
eigenvector v

then (v^Tv) of $v^Tv \geq 0$ is the hyperplane element-nise product

il P is not symmetric, then P:; > P; for some i,;

then yij < yii is the hyperplane or finally, some linear constraint way be violated than that egan gives the hyperplane