

Korea - New Zealand Joint Research Workshop

Recent works on Wearable Interaction and Usability

A Way to Enrich Physical Immersion?



Gerard J. Kim (김정현)
Digital eXPerience Laboratory
Korea University



Wearable computers (Witt, 07)

- ▶ **Limited Capabilities:** The wearable computer system is often very limited or constrained in terms of available computation power, energy consumption, and available I/O modalities (Smart phones?)
- ▶ **Portable / Mobile / (Self contained?)**
- ▶ **Physical constraints:** Enables hands-free or hand-limited use
- ▶ **Adapted Interaction:**
The wearable computer system may automatically adapt the interaction style and/or interface rendering of a application, contents, environment in order to make interaction easier and more efficient while minimizing mental effort

Some previous and on-going works

- ▶ Display
 - ▶ Readability of augmented information
 - ▶ Google glass study: Dual focus problem
 - ▶ (Richer tactile feedback)
- ▶ Arm/Hand input
 - ▶ Mid-air gestures: Performance model
 - ▶ Hand-augmented interface
- ▶ Body-based input
 - ▶ (Body based metaphors)
 - ▶ EMMI: Extreme body movements
 - ▶ Pressure based whole body interface: G-bar
 - ▶ QUI: Quadruped user interface
 - ▶ Body based robot control Sprint

Readability for see-through contents

▶ Motivation

- ▶ Dynamic background
- ▶ Eye fatigue:
 - ▶ Lack of sufficient contrast (luminance/chromatic)
 - ▶ Dual focus
 - ▶ Visual acuity (center vs. periphery)

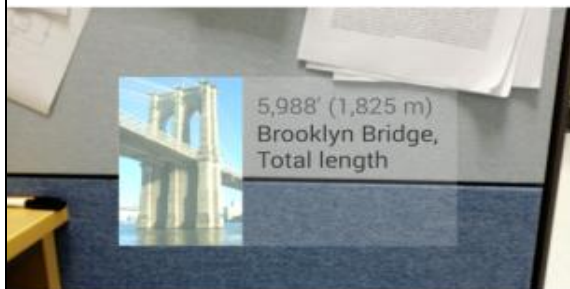
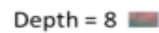
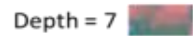
▶ Approach

- ▶ Analyze “conspicuity (or saliency)” of augmented region
- ▶ Adjust brightness of augmentation to enhance conspicuity
- ▶ Mobile implementation
 - ▶ Object level (vs. pixel level) analysis and adjustment

Input Image



CIELab Color Map



Output Image

View Objects



5,988' (1,825 m)
Brooklyn Bridge,
Total length



...



5,988' (1,825 m)

5,988' (1,825 m)

...

5,988' (1,825 m)

Brooklyn Bridge,
Total length

Brooklyn Bridge,
Total length

...

Brooklyn Bridge,
Total length

Original
Object

Decrease
Brightness
(40%)

~

Increase
Brightness
(160%)



Object Saliency

Before

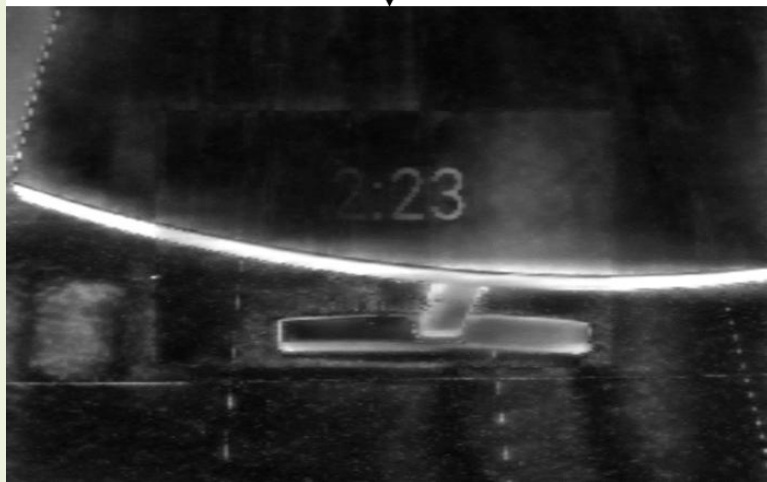


Optimize
For Contrast
By changing
the brightness

After



Saliency map



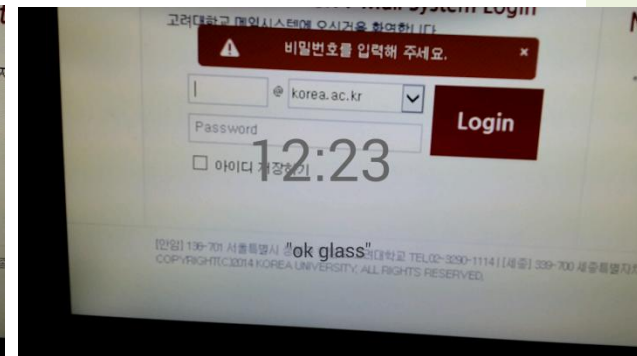
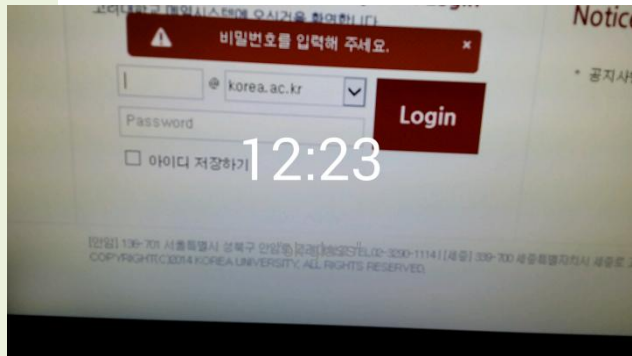
Saliency map



Without adjustment

Our approach

Ground truth



Eye fatigue assessment for see-through glasses

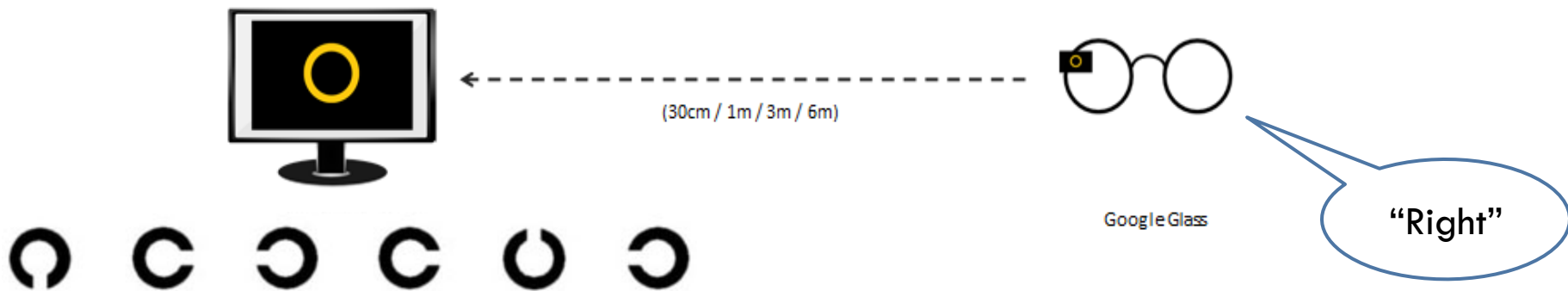


► Motivation

- Quantify and establish an eye fatigue/stress (due to refocusing)
- Later use it as a guideline in glass-based application design (or even glass design itself)
 - E.g. Object recognition and overlay

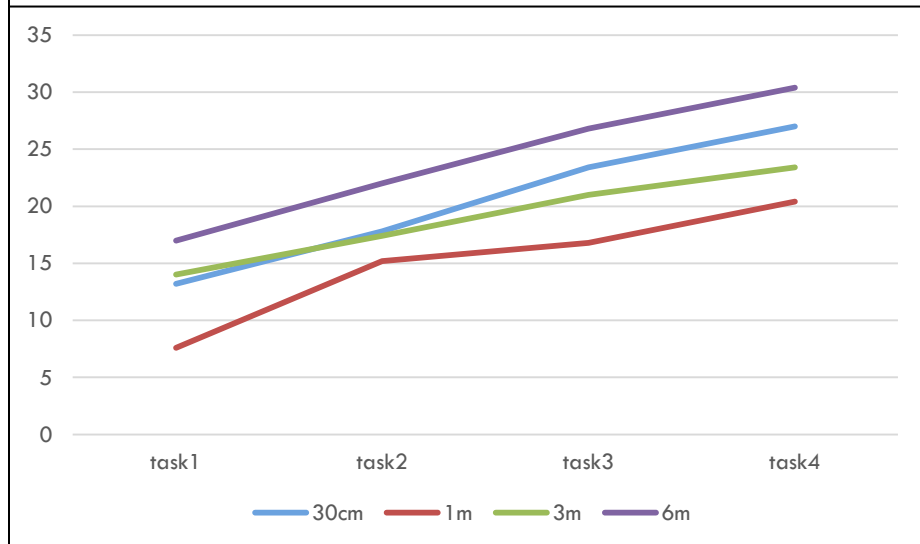
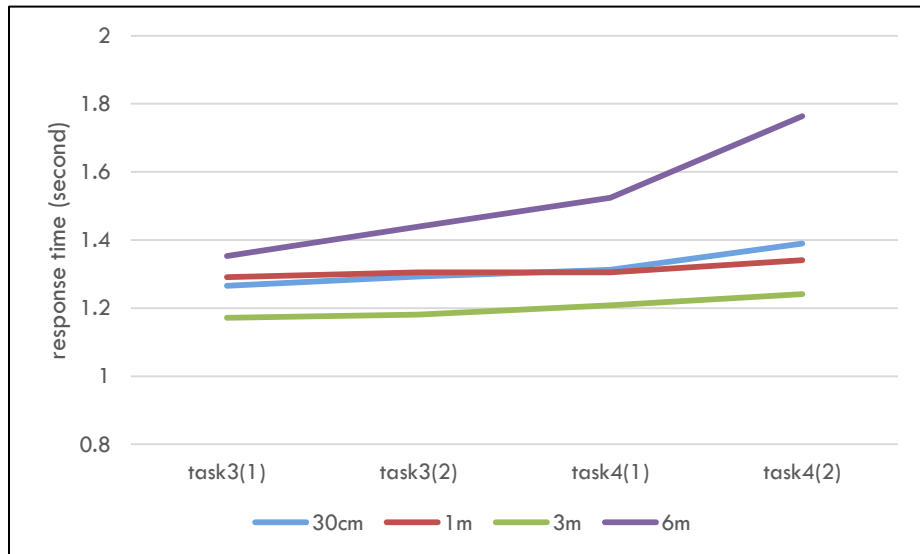
► Basic experiment

- “Refocus and identify” task at different lengths using google glass
- Measure fatigue indirectly by response time and survey

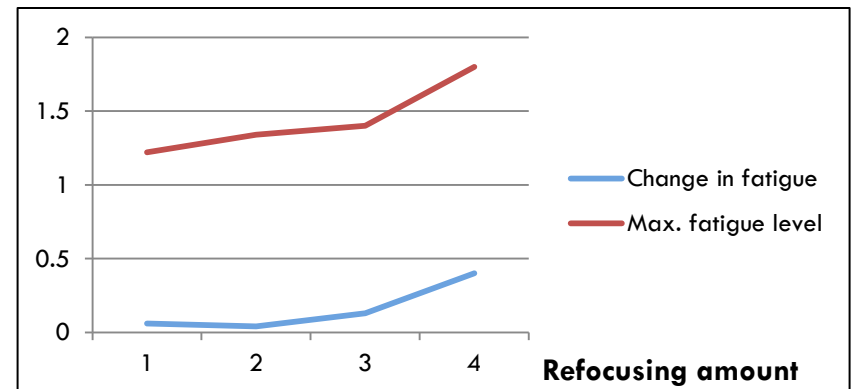


▶ Notes

- ▶ Google glass designed to focus on a 25 inch virtual screen 2.4 m away
- ▶ Obviously, longer the refocusing distance, more tired it will be
 - ▶ Interested in form of the function (linear, exponential, saturating, step, ...?)



- ▶ Response time change in time
 - ▶ $6m > 30cm > 3m \sim 1m$
- ▶ Survey on “eye/refocus” fatigue
 - ▶ $6m > 30cm > 3m \sim 1m$
 - ▶ Same as above



Extended Fitt's Law for Mid-air Gestures

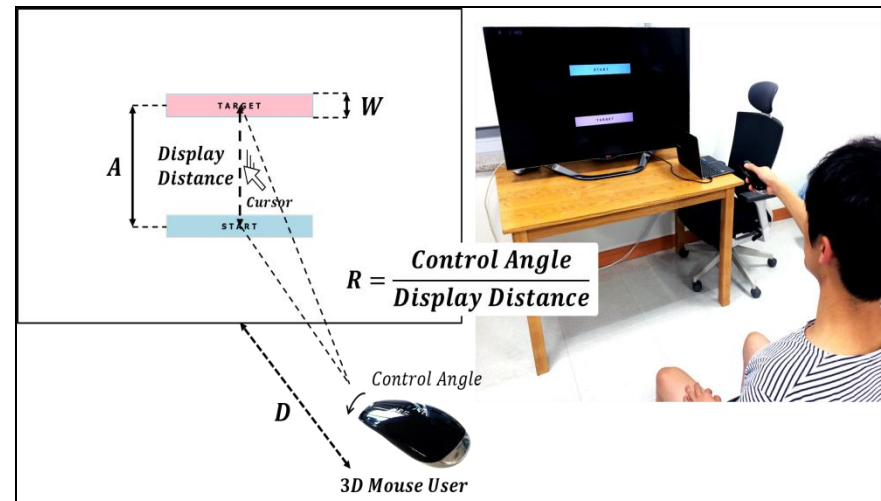
► Motivation

- Wearable/Hand-held devices will use gestures heavily in the future
- Validate if traditional Fitt's Law applies, or extend it if necessary
- Use as guideline in wearable/remote interaction design

► Basic experiment

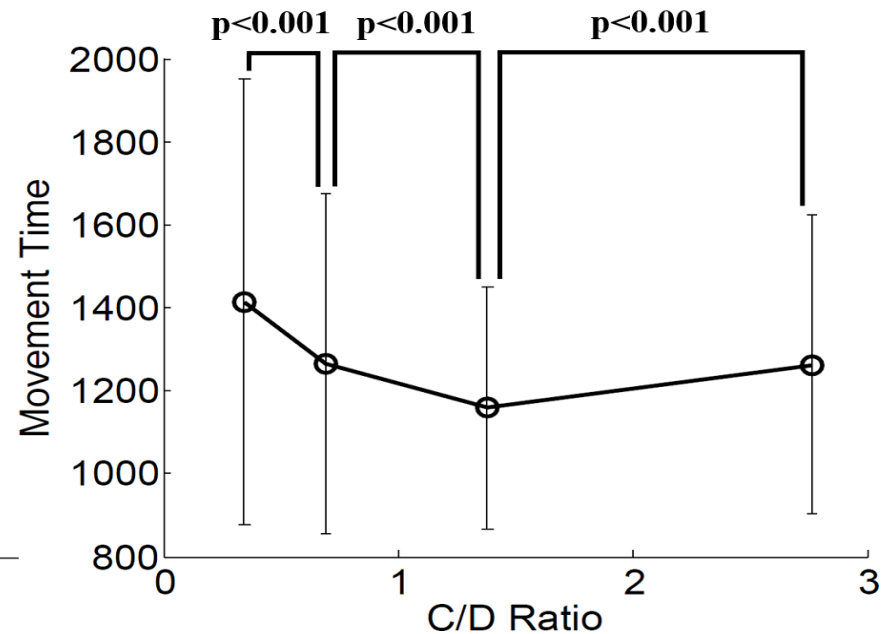
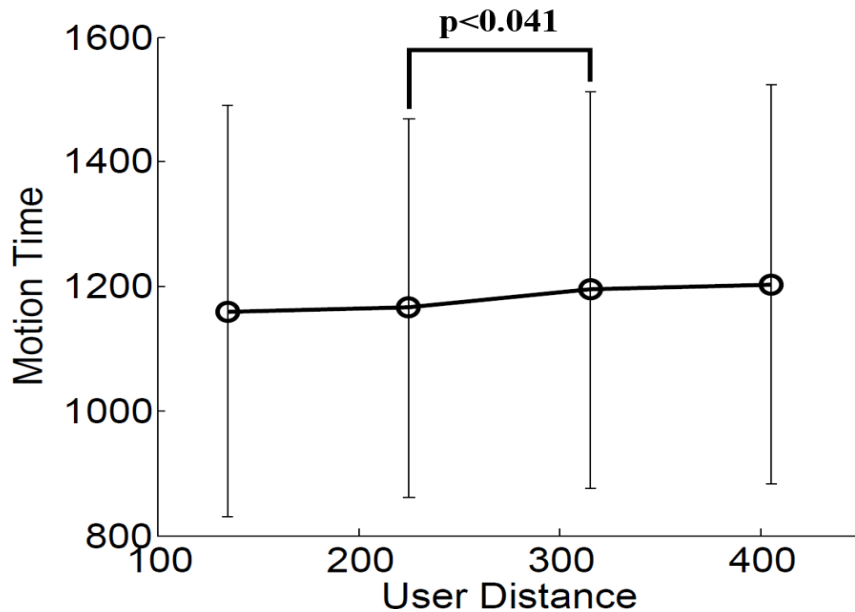
- Hypothesis: Performance will depend on:
 - Object width (W) and Movement distance (A) +
 - Viewing/distance and C/D ratio
- Logitech MX Air Mouse

Factor	Levels
Movement Distance (A)	10.41, 15.62, 23.43 cm
Object Width (W)	4.63, 6.94, 10.41 cm
User Distance (D)	135, 225, 315, 405 cm
C/D Ratio (R)	2.76, 1.38, 0.69, 0.34 °/cm



Collect performance data for different combinations and fit a function

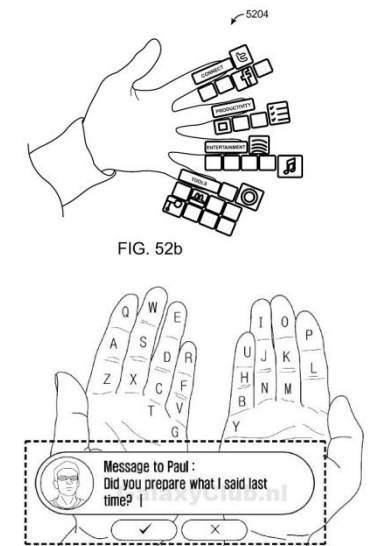
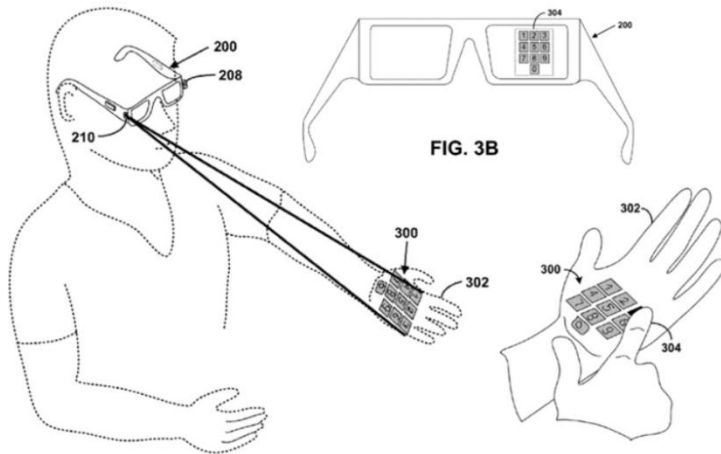
$$MT = a + b \log_2 \left(\frac{A}{W} + 1 \right) + c \tan^{-1} \left(\frac{(D - D_{ref})^2}{D_{ref}^2} \right) + d(R - R_{ref})^2$$



Model	a	b	c	D	RMS	R^2	$R^2_{(adj)}$
Fitts [5]	710	299	N/A	N/A	88.34	0.718	0.714
Welford [15]	399	232	N/A	N/A	102.3	0.621	0.616
Bi [3]	688	276	N/A	N/A	99.72	0.64	0.635
Kopper [8]	710	298	N/A	N/A	88.41	0.717	0.713
Ours	578	299	35.9	139	34.50	0.958	0.956

Hand augmented AR interface

- ▶ Depth sensor on the glass (near future?)
- ▶ Use hand/palm as a tangible surface on which interaction occurs
 - ▶ Tracking hands/palms/fingers/finger parts
 - ▶ Low end mobile platform - no learning / no IK



Skin Color Detection

HSV Color Space Conversion

HSV 색상 공간으로 변환 후 피부색에 해당하는 영역의 마스크를 생성함



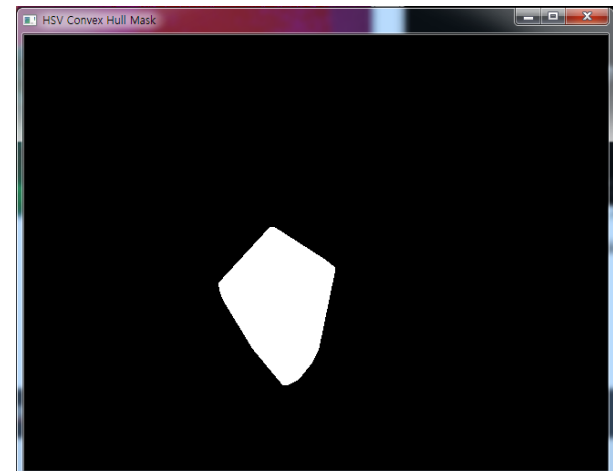
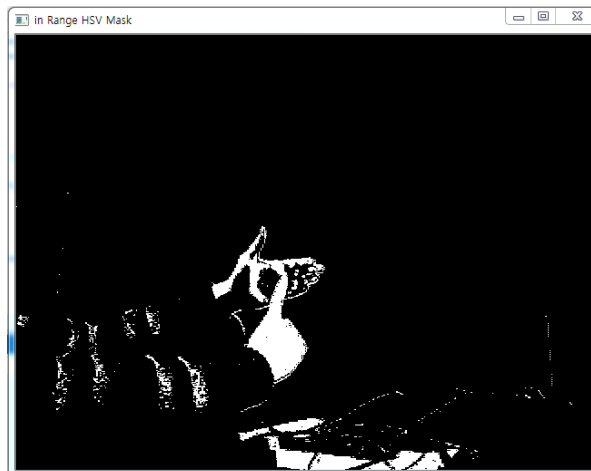
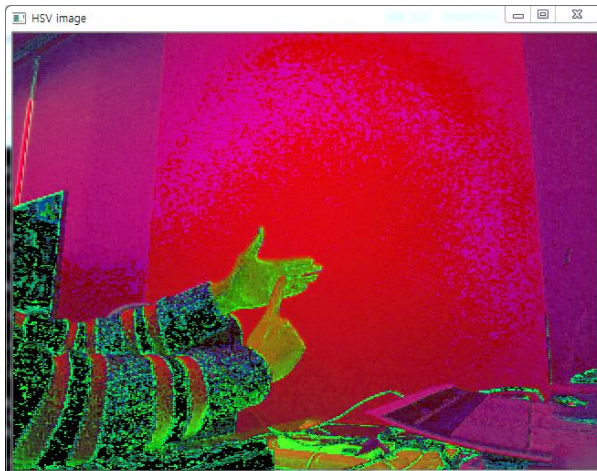
Contour

HSV 색상 공간에서 생성한 마스크에서 나타나는 영역의 Contour를 구하고 각 Contour의 크기 및 면적 등을 이용하여 필터링 함



Convex Hull

선택된 Contour를 이용하여 각 Contour를 둘러싸는 Convex Hull을 구하고 이를 이용하여 마스크를 생성함



Depth Map processing

Range Filtering

Depth 센서의
거리값을 이용하여
50cm~95cm 범위 내의
값만 사용하도록 함



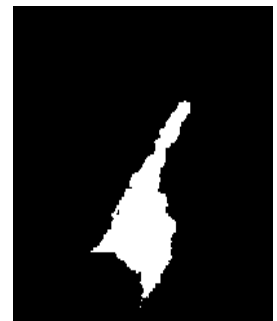
Masked Depth Map

RGB 영상을 이용한
Convex Hull 마스크와
필터링된 Depth Map을
이용하여 손 영역으로
추정되는 영역 추출



Classify Hands

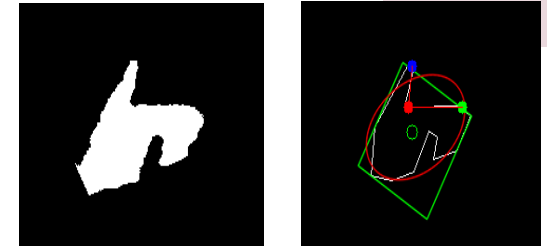
RANSAC 알고리즘을
이용하여 스크린이
되는 손과 입력하는
손을 구분함



Palm Orientation and Interaction Fingertip

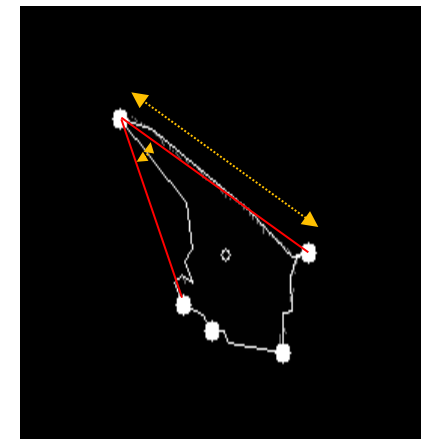
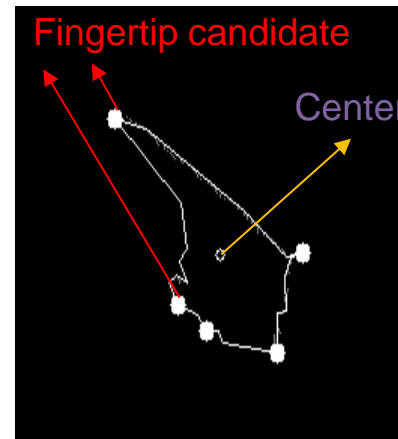
▶ Palm

- ▶ Z: normal to the palm plane
- ▶ Estimate thumb and index finger from the convex hull
- ▶ Calculate relative rotation to the reference (palm in right angle to the sensor)



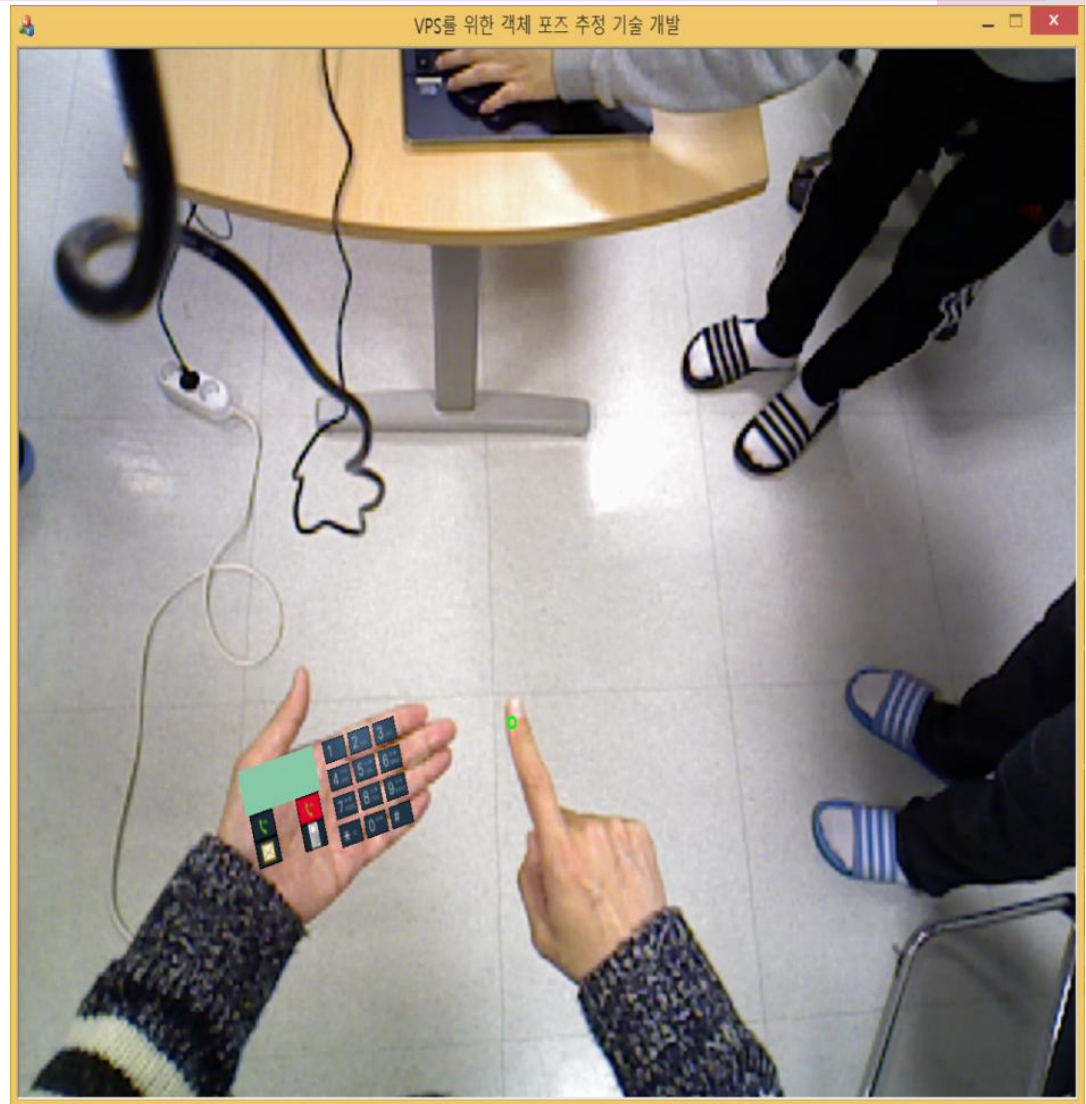
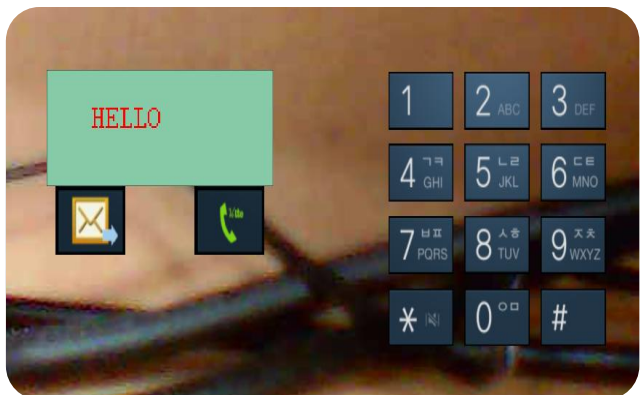
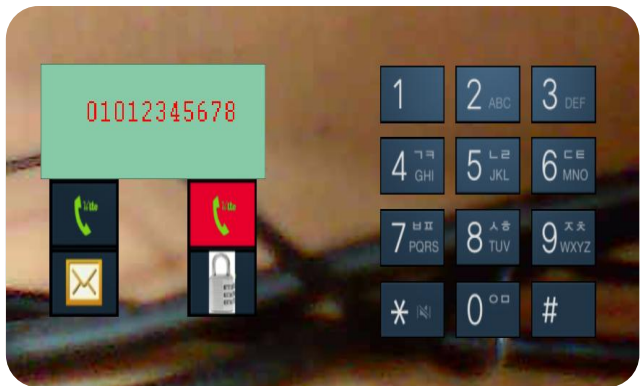
▶ Interaction fingertip

- ▶ Noise filtering + convex hull and consider relative angles among the vertices
- ▶ Event press detection
 - ▶ Threshold distance between fingertip and palm ($< 3\text{cm}$)



UI Application

movie



Body based interfaces (circa 2004)

Q: How can we interact using our body parts (other than just hands) ?



Body as interaction surface
(ergonomic)

Body inspired metaphors
(easy to remember)



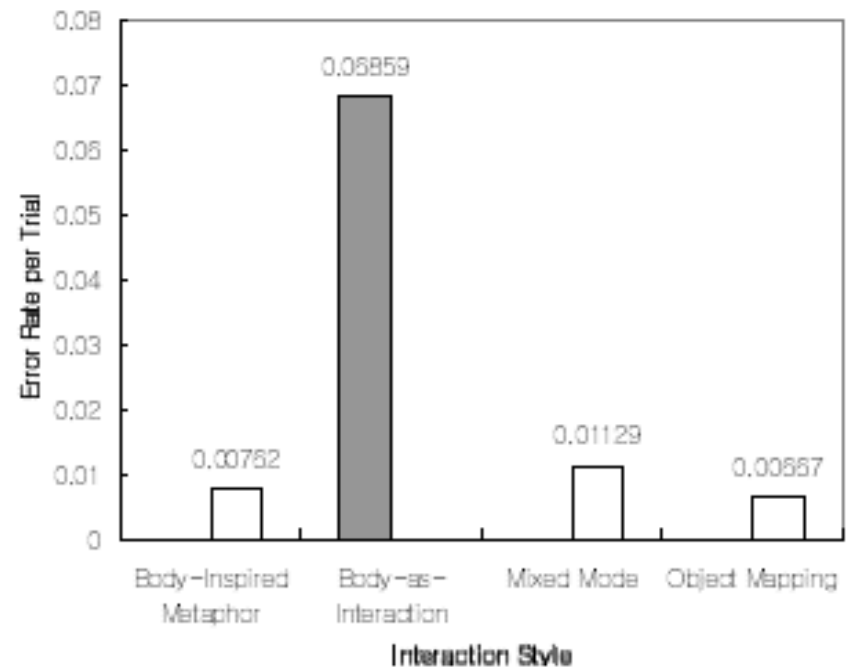
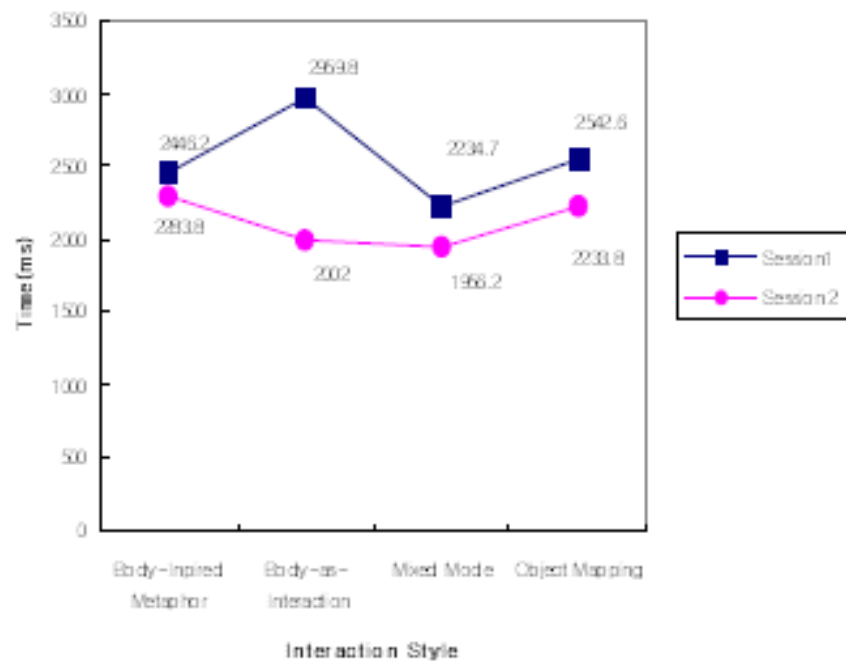
Proprioceptive



Body based metaphor (circa 2004)

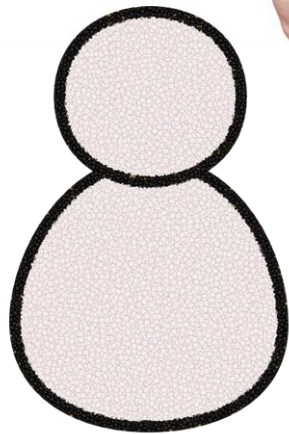
Body Parts / Clothing	Original Semantics	Applicable Tasks
Eye(s) / Eye Glass	Seeing Window	presentation, check emails, viewers, turn on TV, activate window,
Mouth	Eating Speaking Blowing	beep, take items (in games), coloring (by blowing)
Ear(s) / Ear Rings	Hearing Collect Info	play sound, increase volume, join in mail list
Head	Importance Thought	homing, bring out notepad
Hand(s) / Fingers	Hold	temporary storage,
Leg(s)	Locomotion Support	navigation, constraining
Skeleton	Hierarchy Structure	avatar control, data traversal
Buttons	Switch / Key Open/Close	activation
Pockets	Containment Safe	folders, trash can, file transfer

Application	Tasks	Body-Inspired Metaphor
Powerpoint	Start/End	Touch the Eye
	Next Slide	Right Shoulder
	Prev. Slide	Left Shoulder
MP3 Player	Start/End	Touch the Ear
	Play	Touch the Mouth
	Stop	Touch the Chest
	Next Song	Right Shoulder
	Prev. Song	Left Shoulder
Desktop Manager	Open Folder	Touch a Pocket
	Log in	Touch the Back Pocket

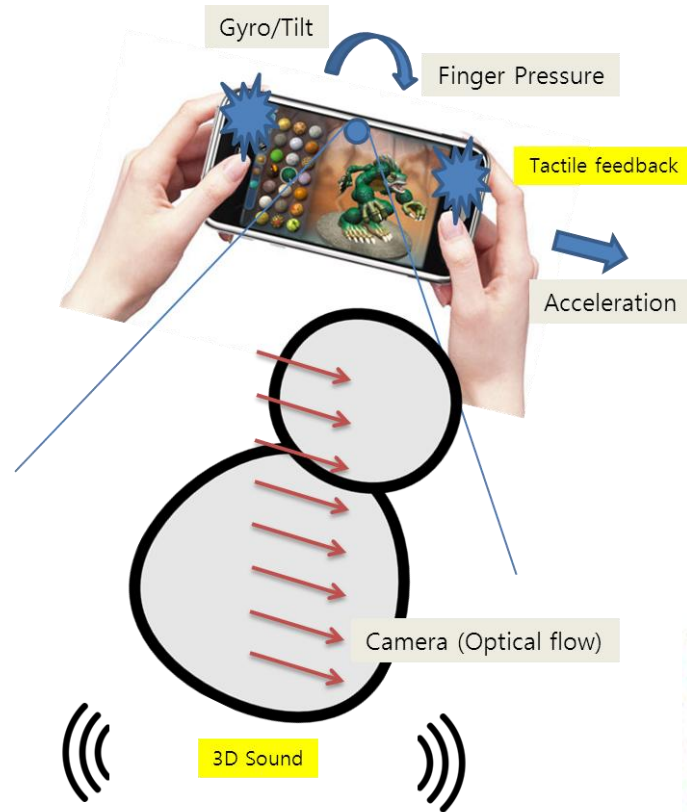


	Folder	Control Panel	Power point	MP3 Player	Wallet
Eye	1		13 (87%)	1	
Ear				12 (80%)	
Mouth			1	2	
Head	1	14 (93%)			
Pocket	13 (87%)			1	1
Back Pocket	1				14 (93%)

EMMI: Extreme Motion Mobile Interface



(a)

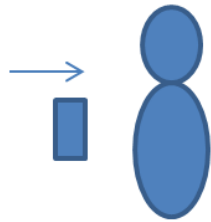


(b)

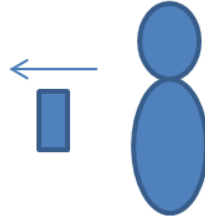
movie



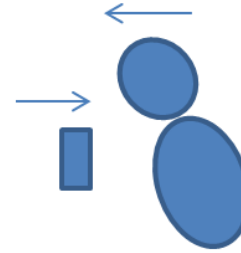
side view



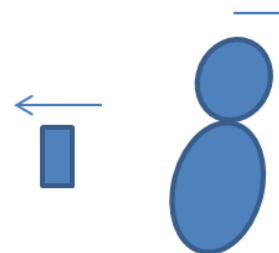
Zoom in



Zoom out

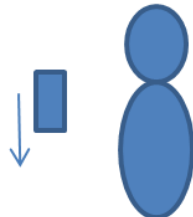


Microscope

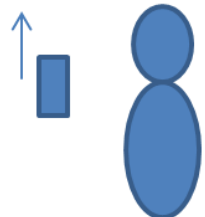


Telescope

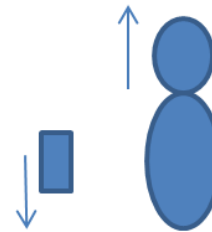
side view



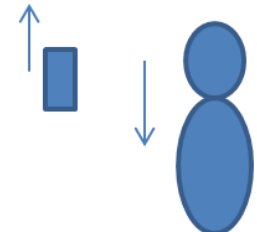
Jump up



Duck down

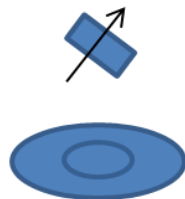


Quantum jump

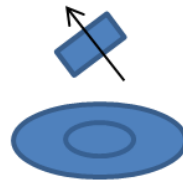


Quantum drop

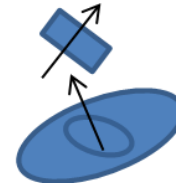
top view



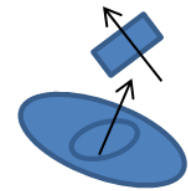
Step aside left



Step aside right



Avoid to left



Avoid to right

front view



Steer left



Steer right

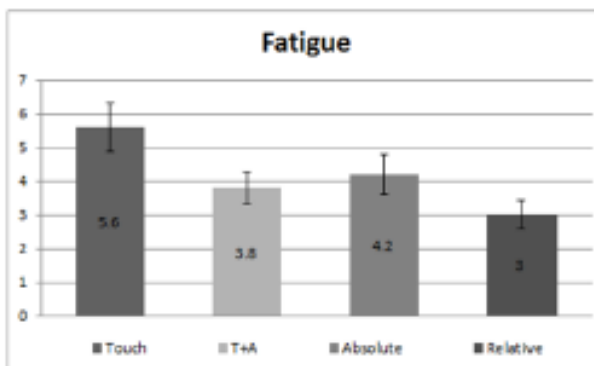
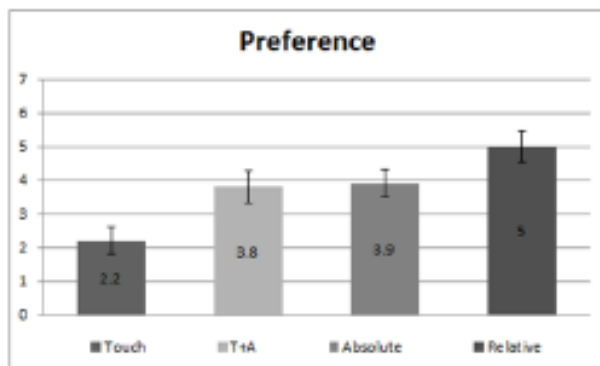
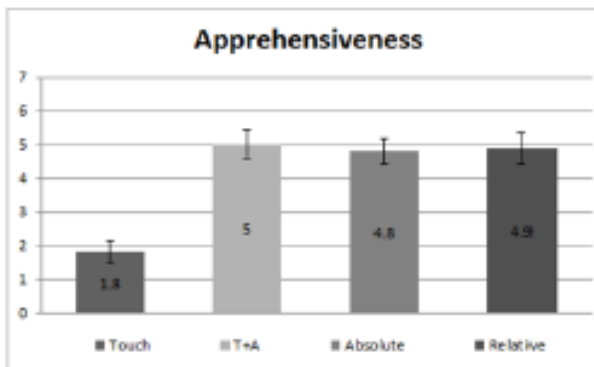
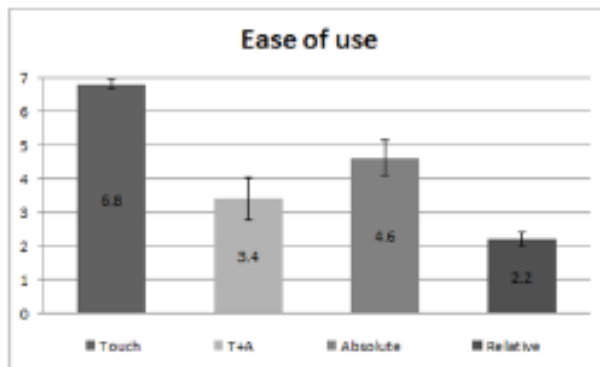


U turn to left



U turn to right

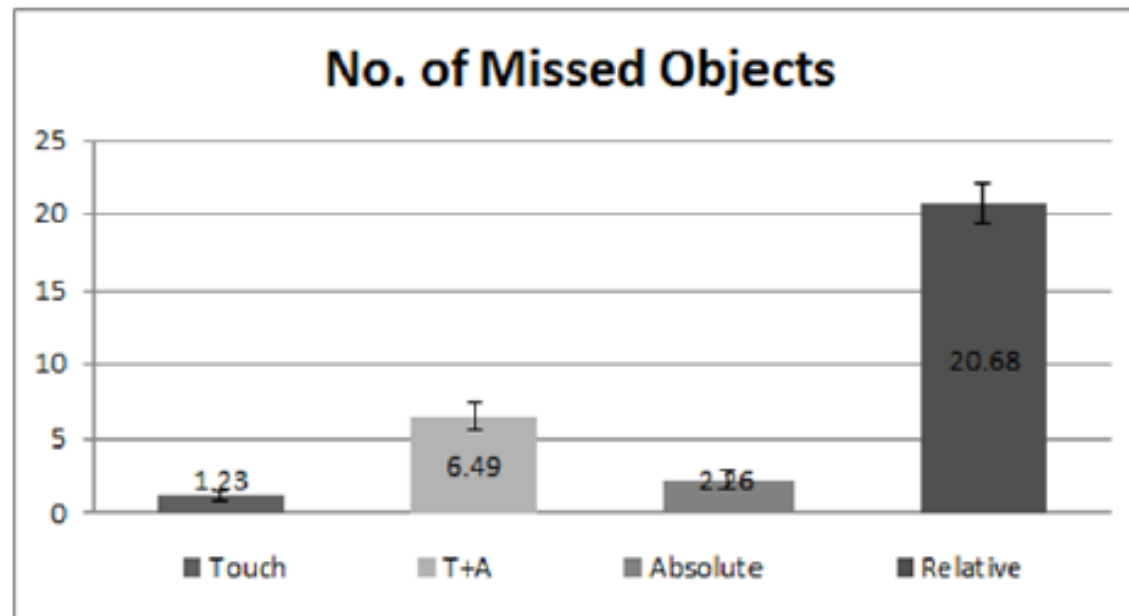
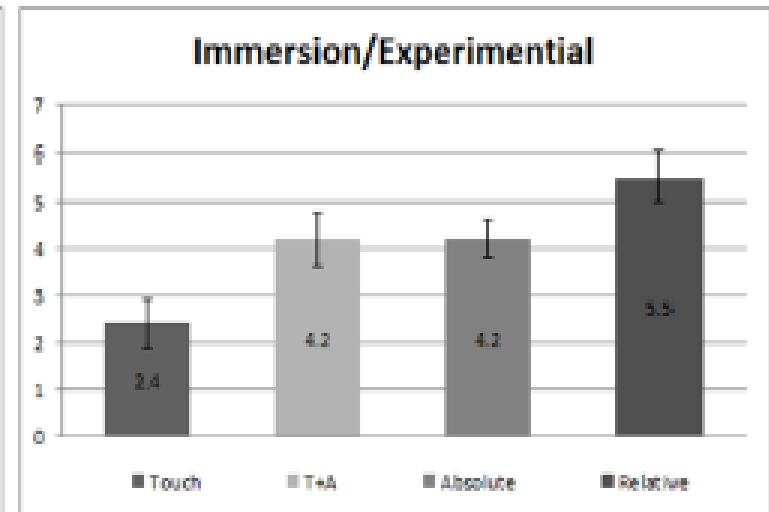
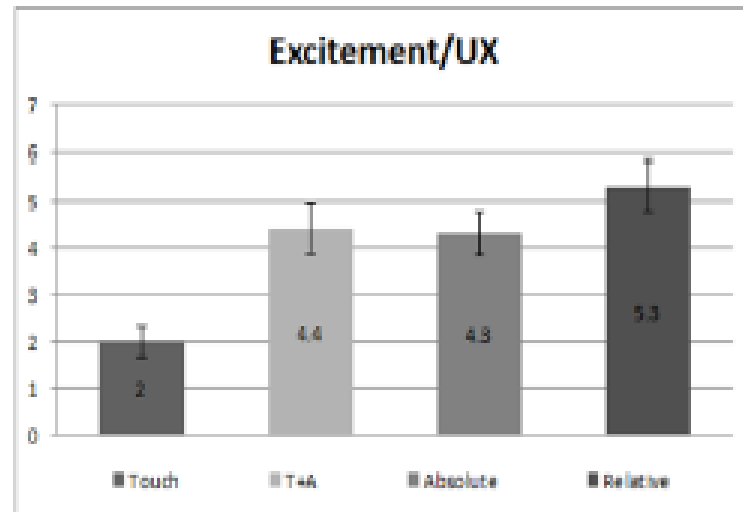
Interface type	Symbol	Explanation
Touch based	Touch	Touch the respective lane (e.g. lanes 1 and 5) to directly place the basket
Touch + Acceleration	T+M	Use direct touch and motion (detected by an acceleration threshold) simultaneously to move into lanes 1 and 5
Absolute motion by hand	Absolute	Use only hand motion (approximated by an acceleration threshold ¹)
Relative motion by hand/head	Relative	Use hand motion (approximated by an acceleration ¹ threshold) and head movement (approximated by the face detection / optical flow measurement from the phone camera)



Generally low usability



Q: Should mobile game be really experiential?



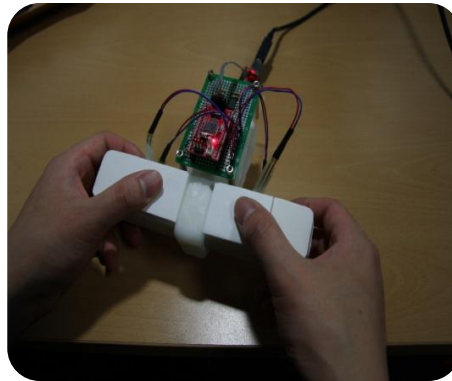
G-Bar: Revisited

[movie](#)

<div>Input Scheme</div> <div>Grounded</div>	Isometric		Isotonic
YES	G-bar	-	-
NO	-	NG-bar	Wiimote



G-bar



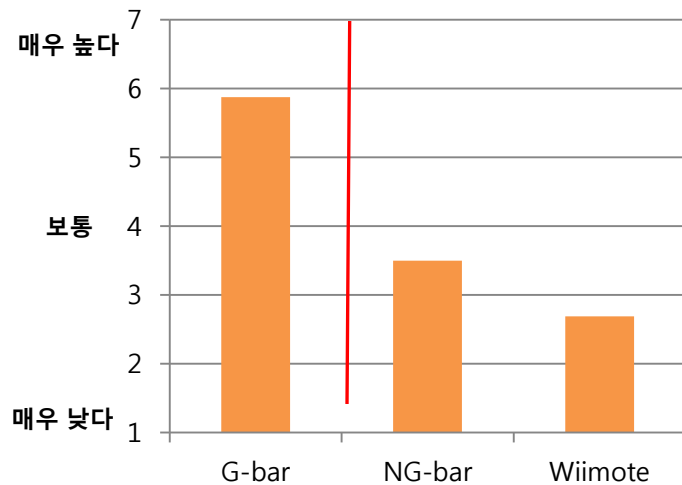
NG-bar



Wii-mote

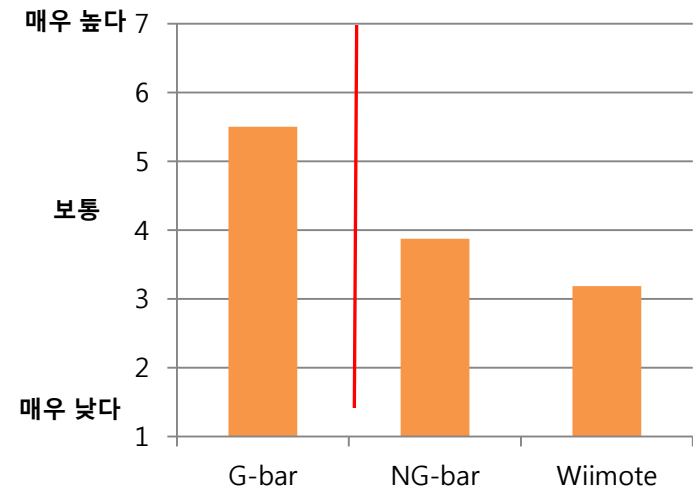
Results (1)

Whole body interaction



G-bar , NG-bar : $p = 0.000$
G-bar , Wiimote : $p = 0.000$
NG-bar , Wiimote : $p = 0.131$

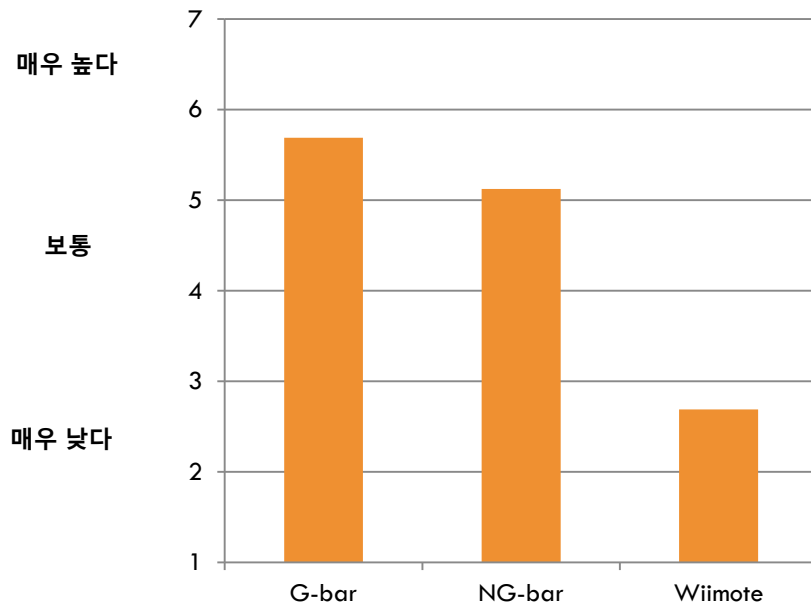
Presence by WBI



G-bar , NG-bar : $p = 0.001$
G-bar , Wiimote : $p = 0.000$
NG-bar , Wiimote : $p = 0.223$

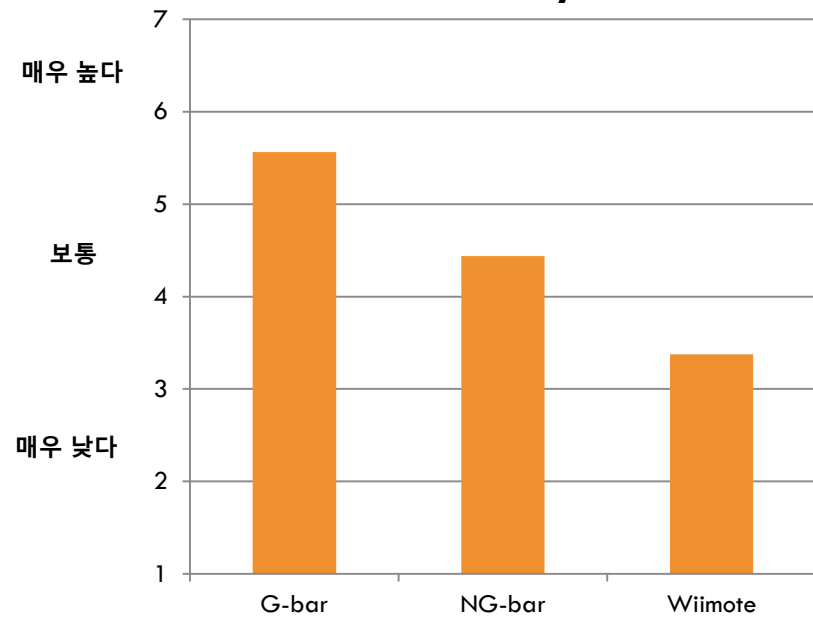
Results (2)

Force feedback



G-bar , NG-bar : $p = 0.091$

Presence by Force



G-bar , NG-bar : $p = 0.027$

QUI: Quadruped interface



QUI: Quadruiped interface

- ▶ Use both hands and feet
- ▶ Fast and simultaneous input
- ▶ Tasks

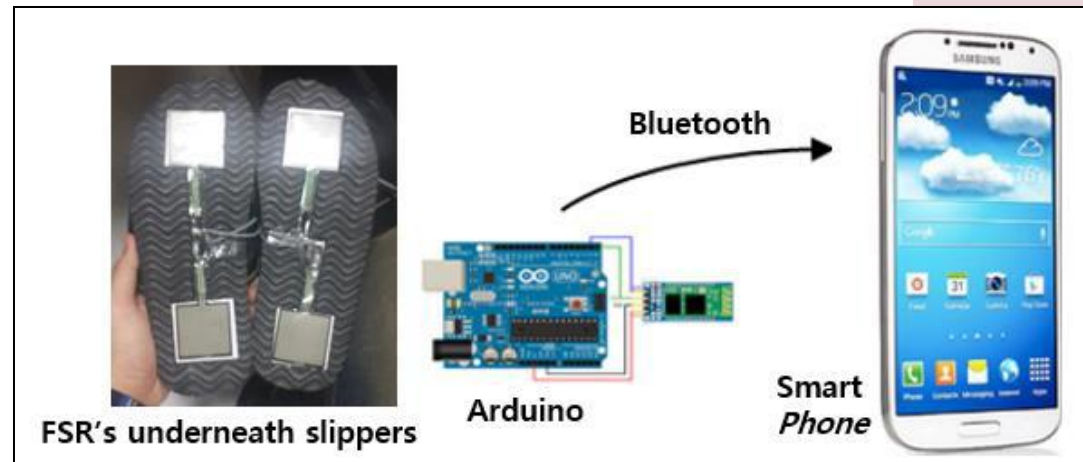
- ▶ Typing

- ▶ Mode change (Shift, Special characters)

- ▶ Special keys (Backspace, Space bar)

- ▶ Gaming

- ▶ Shoot with hands/fingers and navigate with feet



Typing/Chat

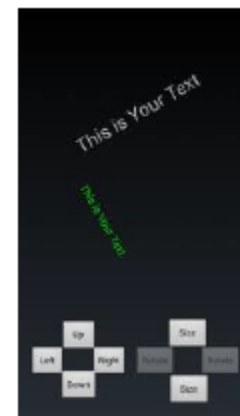
	Task 1 (Korean National Anthem)	Task 2 (Conversational Chat)
Task Characteristics	Memorized phrases (relatively easy)	Reactive / Involve special characters (more difficult)
Fingers (mapped to)	All keys in the virtual keyboard	All keys in the virtual keyboard
Left foot (mapped to)	Backspace	Switch to special character layout (like a function key)
Right foot (mapped to)	Space bar	Space bar

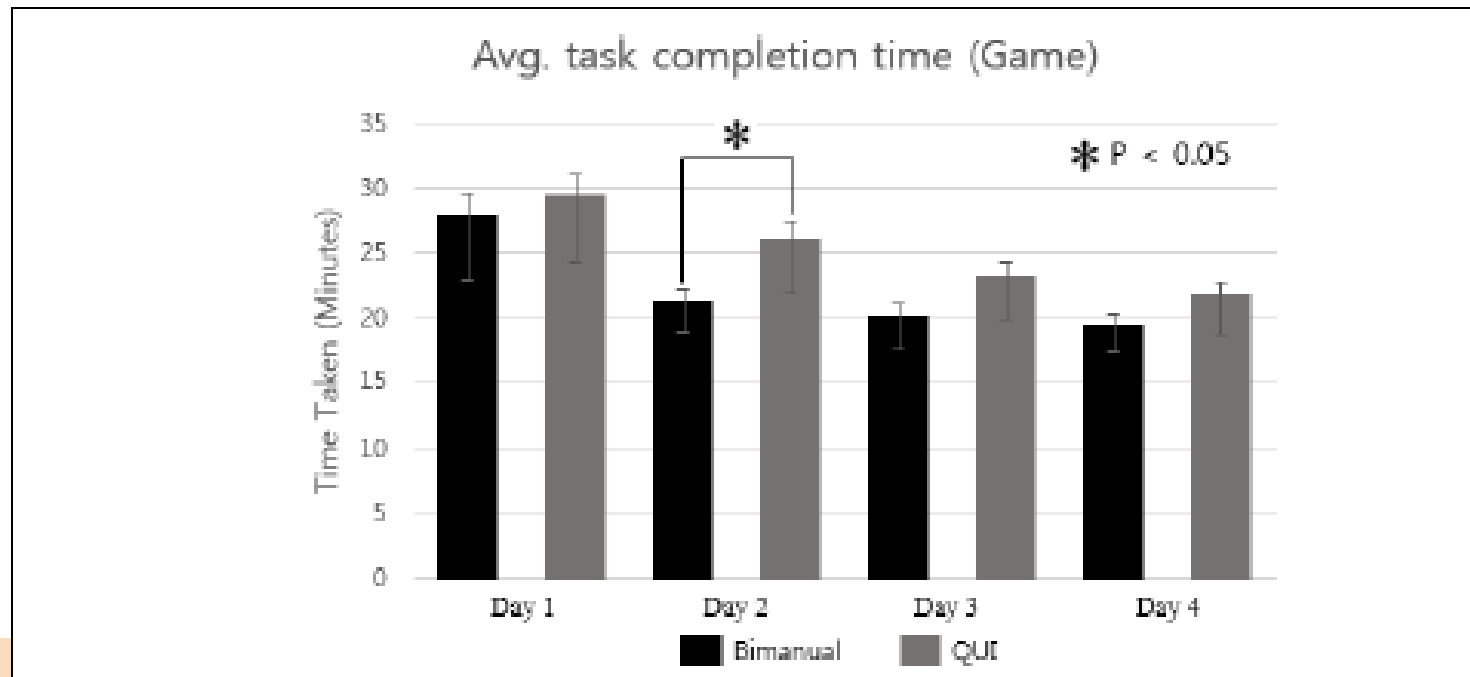
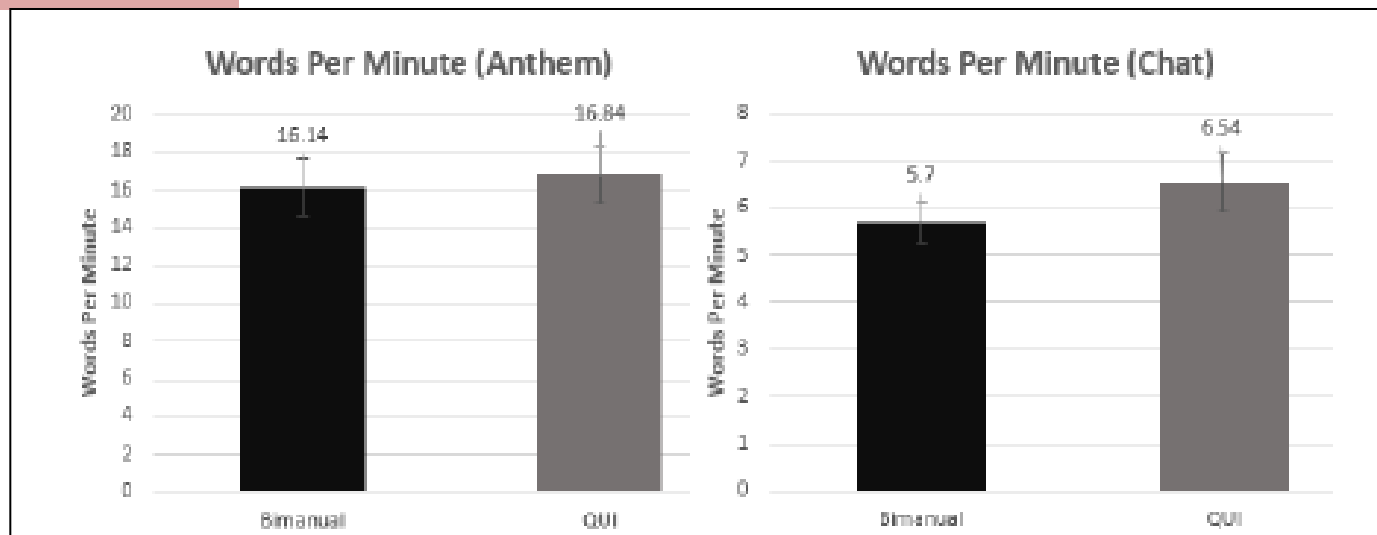


[movie](#)

Object manipulation

	Degrees of freedom / Control amount	Finger touch input	QUI
Position	2 / ± 800 pixels (left/right and up/down)	Fingers of left hand	Fingers of left hand
Scale	1 / $\pm 0.2\%$ (bigger or smaller)	Fingers of right hand	Fingers of right hand
Orientation	1 / ± 30 degrees (rotate left/right)	Fingers of right hand	Left and right foot





Sprint: Body based robot control

[movie](#)

The header features a row of three colored squares (light red, dark red, and light orange) on the left. A wide, light purple horizontal bar spans the width of the slide, containing the title text. A thin dark purple line is positioned directly below the text. On the right side, a light red square is partially visible, overlapping the purple bar.

Summary and Collective Conclusion



gjkim@korea.ac.kr

Thank you