

Non Linear Programming: Homework 8

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1 Total variation image interpolation

1.1 Code

```
% tv_img_interp.m
% Total variation image interpolation.
% EE364a
% Defines m, n, Uorig, Known.

% Load original image.
Uorig = double(imread('flowgray.png'));

[m, n] = size(Uorig);

% Create 50% mask of known pixels.
rand('state', 1029);
Known = rand(m,n) > 0.5;

%%%% Put your solution code here
cvx_begin
variable U12(m, n);
variable T(m-1, n-1);
minimize sum(sum((U12(2:end, 2:end) - U12(1:end-1,2:end))
    .^2 + (U12(2:end, 2:end) - U12(2:end,1:end-1)).^2))
subject to
U12 .* Known == Uorig .* Known;
cvx_end

cvx_begin
variable U1v(m, n);
variable T(m-1, n-1);
minimize sum(sum(abs(U1v(2:end, 2:end) - U1v(1:end-1,2:
    end)) + abs(U1v(2:end, 2:end) - U1v(2:end,1:end-1))))
subject to
```

```

Utv .* Known == Uorig .* Known;
cvx_end

% Calculate and define Ul2 and Utv.

%%%%%%%%

% Graph everything.
figureHandle = figure(1); cla;
colormap gray;

subplot(221);
imagesc(Uorig)
title('Original_image');
axis image;

subplot(222);
imagesc(Known.*Uorig + 256-150*Known);
title('Obscured_image');
axis image;

subplot(223);
imagesc(Ul2);
title('l_2_reconstructed_image');
axis image;

subplot(224);
imagesc(Utv);
title('Total_variation_reconstructed_image');
axis image;

saveas(figureHandle, ['/u/vvasuki/vishvas/work/
    optimization/hw/hw8/code/imageInterpolation.jpg'], '
    jpg');
% close all;

```

1.2 Results

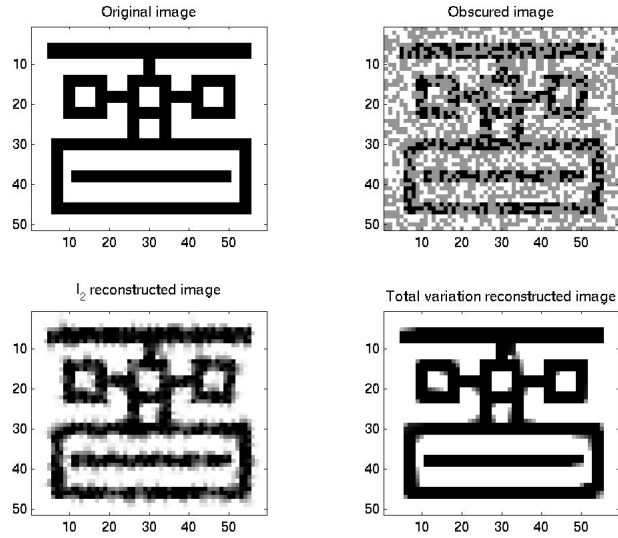
2 Sparse linear separation

2.1 Code

```

function sparseLinearSeparationExperiment
threshold = 10^-2;
hw8_sparse;

```



```

[thicknessMax, sparsityMin] = getSlabThicknessSparsity(X,
    Y, 0, threshold);
fprintf(1, 'Max thickness: %d min sparsity: %d\n',
    thicknessMax, sparsityMin);
% return

thicknesses = [];
sparsities = [];
a_10ftr = [];
a = [];
for l = 0:5:100
    % for lPow = -50:50:100
    % l = 10^lPow;
    l
    [thicknesses(end+1), sparsities(end+1), a] =
        getSlabThicknessSparsity(X, Y, l, threshold);
    if(sparsities(end) > 39/50 && numel(a_10ftr) == 0)
        a_10ftr = a;
    end
    a',
% keyboard
end

plotFigure(thicknesses, sparsities);

```

```

importantFeatureIndices = find(abs(a_10ftr) >= max(abs(
    a_10ftr))*threshold);
importantFeatureIndices
[thickness_10ftr , sparsities_10ftr , a] =
    getSlabThicknessSparsity(X(importantFeatureIndices , :)
    , Y(importantFeatureIndices , :) , 0, threshold);

display( 'All done , ready for inspection ');
keyboard
end

function plotFigure(thicknesses , sparsities)
figureHandle = figure();
figureHandle = plot(sparsities , thicknesses);
xlabel( 'sparsity ');
ylabel( 'slab_thickness ');
% close all;
saveas(figureHandle , [ '/u/vvasuki/vishvas/work/
    optimization/hw/hw8/code/sparseSeparation.jpg '], 'jpg'
);
end

function [thickness , sparsity , a] =
    getSlabThicknessSparsity(X, Y, l, threshold)
[n, N] = size(X);
M = size(Y, 2);
cvx_begin
variable a(n);
variable b;
minimize norm(a, 2) + l*norm(a, 1)
subject to
X'*a + b*ones(N,1) >= ones(N,1);
Y'*a + b*ones(M,1) <= -ones(M,1);
cvx_end
thickness = 2/norm(a,2);
sparsity = sum(abs(a) < max(abs(a))*threshold)/n;
end

```

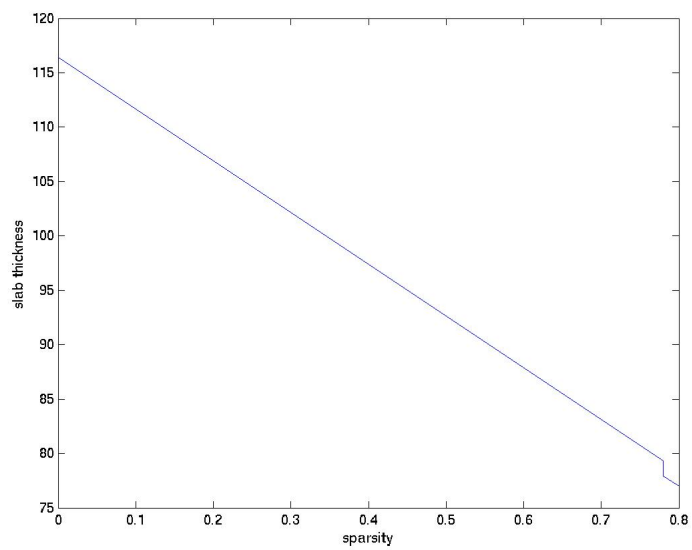
2.2 Max slab thickness

Max thickness: 1.164244e+02 min sparsity: 0

Maximizing slab width ($\frac{2}{\|a\|}$) is equivalent to minimizing $\|a\|$.

2.3 Tradeoff curve

2.4 Solution after identifying important features



```
importantFeatureIndices =  
  1.0000e+000  
  7.0000e+000  
  8.0000e+000  
 18.0000e+000  
 19.0000e+000  
 21.0000e+000  
 23.0000e+000  
 26.0000e+000  
 27.0000e+000  
 46.0000e+000
```

```
thickness_10ftr =  
  
  78.4697e+000
```