

## Lecture 8

### 4.2 Vector spaces:

Def: An (algebraic) field  $(K, +, \cdot)$  is a set  $K$  and two maps:  $+, \cdot : K \times K \rightarrow K$ , that satisfy:

$$\underbrace{(K, +)}_{\text{CANI}} \text{ and } \underbrace{(K, \cdot)}_{\text{CANI}} \text{ with } 1 \neq 0$$

$\begin{matrix} \text{C} & \text{A} & \text{N} & \text{I} \\ \text{closure} & \text{associative} & \text{commutative} & \text{identity} \end{matrix}$

Remark: A weaker notion, to become important later, is a ring  $(R, +, \cdot)$

$$\underbrace{(R, +)}_{\text{CANI}} / \underbrace{(R, \cdot)}_{\text{CANI}}$$

Ex:  $(\mathbb{Z}, +, \cdot)$  commutative ring,  $M_{n \times m}(\mathbb{R})$  ring

$(\mathbb{R}, +, \cdot)$  field

Def: A  $K$ -vector space  $(V, \oplus, \odot)$ ,  $\oplus : V \times V \rightarrow V$   
 $\odot : K \times V \rightarrow V$

which satisfy:  $\underbrace{(V, \oplus)}_{\text{CANI}} \quad \underbrace{(K, \odot)}_{\text{ADD}} \quad \underbrace{(V, \odot)}_{\text{DISTRIBUTIVE}}$

Def:  $U \subseteq V$  is a vector subspace if,  $\forall u_1, u_2 \in U$ :

$u_1 \oplus u_2 \in U$  and  $\forall \lambda \in K, \lambda \odot u_1 \in U$ .

from now on,  $\oplus \rightarrow +$  and  $\odot \rightarrow \cdot$

Def: ~~Linear~~ linear map:  $f : V \rightarrow W$  if:

(i)  $\forall v_1, v_2 \in V : f(v_1 + v_2) = f(v_1) + f(v_2)$

(ii)  $\forall \lambda \in K, v \in V : f(\lambda \cdot v) = \lambda \cdot f(v)$

if  $f$  is a bijection,  $f$  is said a vector space isomorphism.

$$V \cong_{\text{vec}} W.$$

Def:  $\text{Hom}(V, W) := \{ f: V \xrightarrow{\sim} W \}$  can be made into a vector space by defining  $\oplus: \text{Hom}(V, W) \times \text{Hom}(V, W) \rightarrow \text{Hom}(V, W)$   
 $(f, g) \mapsto f \oplus g.$

where  $(f+g): V \rightarrow W$   
 $v \mapsto f(v) +_W g(v) =: (f \oplus g)(v)$  (linear map)

Similarly for  $\odot$ ,  $\lambda f \odot g := \lambda \cdot_W (g(v))$

For fields every thing is well defined. not linear if  $K$  is a ring.

Terminology:  $\text{End}(V) := \text{Hom}(V, V)$  "endomorphisms"  
 $\text{Aut}(V) := \{ f: V \xrightarrow{\sim} V \mid \text{invertible} \}$  "automorphisms"

$$\text{Aut}(V) \subseteq_{\text{vec}} \text{End}(V).$$

dual  $\hookrightarrow V^* := \text{Hom}(V, K)$ ;  $K$  considered as a vector space.

Def: A  $(p, q)$  tensor  $T$  is a multilinear map

$$T: \underbrace{V^* \times \dots \times V^*}_{p \text{ copies}} \times \underbrace{V \times \dots \times V}_{q \text{ copies}} \xrightarrow{\sim} K$$

Def:  $V \otimes \dots \otimes V \otimes V^* \otimes \dots \otimes V^* := \{ T \mid T \text{ is a } (p, q) \text{ tensor} \}$   
 $\underbrace{\quad \quad \quad}_{p \text{ copies}} \quad \underbrace{\quad \quad \quad}_{q \text{ copies}}$   
 $T^p_q V$

Def: Tensor product :  $\otimes : T_q^p V \times T_s^r V \rightarrow T_{q+s}^{p+r} V$

$$(T \otimes S)(v_1, \dots, v_p, v_{p+1}, \dots, v_{p+r}, w_1, \dots, w_q, w_{q+1}, \dots, w_{q+s})$$

$$= T(v_1, \dots, v_p, w_1, \dots, w_q) \cdot S(v_{p+1}, \dots, v_{p+r}, w_{q+1}, \dots, w_{q+s})$$

Example: (i)  $T_1^0 V \cong V^* := \{T: V \rightarrow K\}$

(ii)  $T_1^1 V \cong V \otimes V^* = \{T: V^* \times V \rightarrow K\} \cong_{\text{vec}} \text{End}(V^*)$

given:  $T \in V \otimes V^*$ , construct  $\hat{T} \in \text{End}(V^*)$  or:

$$\hat{T}: V^* \rightarrow V^*$$

$$w \mapsto T(\overset{w}{\otimes} \overset{\circ}{\otimes}) \quad \text{but}$$

$$T(w, v) = (\hat{T}(w))(v)$$

(iii)  $T_0^1 V \cong_{\text{vec}} V$ ? No.

(iv)  $T_1^1 V \cong_{\text{vec}} \text{End}(V)$ ? No.

(v)  $(V^*)^* \cong_{\text{vec}} V$ ? No.

only for  $\dim V < \infty$ .

Def: Given  $V$  vector space, then a subset  $B \subseteq V$  is called a (Hamel) basis if:

- Every finite subset  $\{b_1, \dots, b_n\}$  is linearly independent.  $\iff \left( \sum_{i=1}^n \lambda^i b_i = 0 \Rightarrow \lambda^1 = \dots = \lambda^n = 0 \right) \overline{B}$

(ii)  $\forall v \in V; \exists v_1^1, \dots, v_m^M \in K; \exists b_1, \dots, b_m \in B: v = \sum_{i=1}^m v_i^i b_i$

Def: Dimension of  $V$ ,  $\dim V := |B|$ .

Theorem: If  $\dim V < \infty$ , then  $(V^*)^* \cong_{\text{vec}} V$ .

$V \equiv$  vector space,  $V^* \equiv$  covector space.

Def:  $T \in T^p_q V$ ,  $\dim V < \infty$ . Let  $e_1, \dots, e_{\dim V}$  be a basis of  $V$  and  $\epsilon^1, \dots, \epsilon^{\dim V}$  be a dual basis of  $V^*$ . The components of  $T$  are:

$$T^{a_1 \dots a_p}_{b_1 \dots b_q} := T(e^{a_1}, \dots, e^{a_p}, e_{b_1}, \dots, e_{b_q})$$

Remark: Usually, one chooses on  $V^*$  a basis induced from  $e_i$ , by the condition:  $\epsilon^a(e_b) = \delta^a_b$ .

Reconstruction of  $T$  from the components:

$$T = T^{a_1 \dots a_p}_{b_1 \dots b_q} e_{a_1} \otimes \dots \otimes e_{a_p} \otimes e^{b_1} \otimes \dots \otimes e^{b_q}$$

Change of basis: Let  $\dim V = n < \infty$ .  $e_i$  basis of  $V$   
 new basis:  $\tilde{e}_j = \sum_{i=1}^n A^i_j e_i$  for this to be a basis it must be possible to:  $e_i = \sum_{j=1}^n B^j_i \tilde{e}_j$

Notation:  $T = T^{a_1 \dots a_p}_{b_1 \dots b_q} e_{a_1} \otimes \dots \otimes e_{a_p} \otimes e^{b_1} \otimes \dots \otimes e^{b_q}$   
 Implicitly summation:  $\sum_{a_1=1}^n \dots \sum_{a_p=1}^n \sum_{b_1=1}^n \dots \sum_{b_q=1}^n$

Basis of  $V$  are united if down index

Basis of  $V^*$  with up index

Remark: Having chosen basis in  $V$ , it's tempting

$$V^* \ni \omega = \omega_a \epsilon^a \longleftrightarrow \omega \hat{=} (\omega_1, \dots, \omega_n)$$

$$V \ni v = v^a e_a \longleftrightarrow v \hat{=} \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

$$\text{End}(V) \stackrel{\sim}{=} T_1^+ V \ni \phi = \phi^a_b e_a \otimes \epsilon^b \longleftrightarrow \phi \hat{=} \begin{pmatrix} \phi^1_1 & \dots & \phi^1_n \\ \vdots & \ddots & \vdots \\ \phi^n_1 & \dots & \phi^n_n \end{pmatrix}$$

Consider  $\phi, \psi \in \text{End}(V)$ , then  $\phi \circ \psi \in \text{End}(V)$ .

$$\begin{aligned}
 (\phi \circ \psi)(e_a, e_b) &= \left( \epsilon^a \left[ (\phi \circ \psi)^c{}_d e_c \otimes \epsilon^d \right] (e_b) \right) \\
 &= \epsilon^a \left( (\phi \circ \psi)^c{}_b e_c \right) = \underline{(\phi \circ \psi)^a{}_b} \\
 &= \epsilon^a \left( (\phi \circ \psi)(e_b) \right) = \epsilon^a \left( \phi(\psi(e_b)) \right) \\
 &= \epsilon^a \left( \phi(\psi^m{}_b e_m) \right) = \psi^m{}_b \epsilon^a \left( \phi(e_m) \right) \\
 &= \psi^m{}_b \epsilon^a \left( \phi^n{}_m e_n \right) \\
 &= \psi^m{}_b \phi^n{}_m \epsilon^a(e_n) \\
 &= \underline{\psi^m{}_b \phi^a{}_m}
 \end{aligned}$$

Then:  $(\phi \circ \psi)^a{}_b = \phi^a{}_m \psi^m{}_b$ , Of course.

$$\begin{aligned}
 w(v) &= w_a \epsilon^a(v^b e_b) = w_a v^b \epsilon^a(e_b) \\
 &= \underline{w_a v^a}.
 \end{aligned}$$

Change of basis:  $\tilde{e}_a = A^b{}_a e_b$  It must be so  $\exists B^j{}_i$

$e_i = B^j{}_i \tilde{e}_j$ . How vector change?

$$\begin{aligned}
 \textcircled{i} \text{ Covector } w: \quad w_a &:= w(e_a) = w(B^b{}_a \tilde{e}_b) \\
 &= B^b{}_a w(\tilde{e}_b) = B^b{}_a \tilde{w}_b
 \end{aligned}$$

(ii) vector :  $v^a = v(\epsilon^a) = \epsilon^a(v) = \epsilon^a(v^b e_b)$

$$= \epsilon^a(v^b A^m_b e_m) = v^b A^m_b \epsilon^a(e_m)$$

$$\boxed{v^a = A^a_b v^b} \text{ vector}$$

$$\boxed{\omega_a = \tilde{\omega}_b B^b_a} \text{ covector}$$

(iii) Tensor :  $T^{a\dots}_{b\dots} = A^a_m B^n_b \dots \tilde{T}^{m\dots}_{n\dots}$

Of course :  $A: V \xrightarrow{\sim} V$  and  $B = A^{-1}: V \xrightarrow{\sim} V$

$$\Downarrow A^a_m B^m_b = \delta^a_b$$

$$B^a_m A^m_b = \delta^a_b$$

Determinants : If  $\phi \in T^1_1 V$  :

$$\phi^a_b \sim \begin{pmatrix} \phi^1_1 & \dots & \phi^1_n \\ \vdots & \ddots & \vdots \\ \phi^n_1 & \dots & \phi^n_n \end{pmatrix} : g \in T^0_2 V$$

$$g_{ab} \sim \begin{pmatrix} g_{11} & \dots & g_{1n} \\ \vdots & \ddots & \vdots \\ g_{n1} & \dots & g_{nn} \end{pmatrix}$$

$$\phi \rightarrow A^{-1} \phi A$$

$$g \rightarrow A^T g A$$

Def: On  $V$ ,  $\dim V = n$ , vector space, an  $m$ -form is a  $T^0_m V$  tensor  $\omega$  ( $0 \leq m \leq n$ ) that is totally anti-symmetrical

$$\omega(v_1, \dots, v_m) = \text{sgn}(\pi) \omega(v_{\pi(1)}, \dots, v_{\pi(m)}); \pi \in S_m$$

If  $m=0$ ,  $\omega \in K$ .

If  $m > n$ ,  $\omega = 0$

Special case: Top forms  $n=m$ . If  $\omega, \omega'$  are top forms both non-vanishing,  $\exists c \in K$ ,  $\omega' = c\omega$ .

Def: Choice of one top form  $\omega$  is called a choice of Volume in  $V$ .

Def: Let  $v_1, \dots, v_n \in V$ , then the volume spanned by them is:  $\text{vol}(v_1, \dots, v_n) = \omega(v_1, \dots, v_n)$

Def: Let  $\phi \in \text{End}(V)$ , define:

$$\det \phi := \frac{\omega(\phi(e_1), \dots, \phi(e_n))}{\omega(e_1, \dots, e_n)} \quad \text{for some } \omega, \text{ and some basis } e_i$$

Is this independent of choice of  $\omega$  and  $e_i$ ? As  $\omega$  is top form,  $\frac{\omega}{\omega}$  is independent of  $\omega$ . And it is in fact basis-free.

Determinants are only defined to endomorphisms!