Vuong Ho

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EDUCATION

University of Arkansas
M.S in Computer Science. Advisor: Prof. Susan Gauch. GPA: 4.0/4.0 (until present)

 ${\rm Arkansas,\; USA}$ Jun 2023 - May 2025 (expected)

University of Information Technology

HCMC, Vietnam

University of Information Technology B.S in Computer Science. GPA: 3.4/4.0

Agu 2016 - Nov 2020

RESEARCH INTERESTS

- Autonomous Driving Perception: Surround View Monitor (SVM), Auto Parking, Free-space segmentation, 2D/3D Object Detection, Driving Monitoring System, Calibration
- 3D Scene Understanding: 3D Point Cloud Object Detection and Segmentation, Depth estimation, Path Planning, VSLAM
- 3D Generation: 3D Reconstruction, text-to-3D, images-to-3D, NeRF, 3D Gaussian Splatting, Diffusion model, LLMs

EXPERIENCE

• VinAI

HCMC, Vietnam

Research Engineer Mar 2021 - Jun 2023 • Implemented a 360 surround view monitoring system from four cameras around a car and perspective projection from fisheye

- o Implemented a 360 surround view monitoring system from four cameras around a car and perspective projection from fisheye image (front/rear/left/right views, wheel views) which deployed success on VinFast E34. Technical based on camera intrinsic, extrinsic calibration, 3D object model, blending image
- o Implemented calibration algorithms: Intrinsic camera, Extrinsic fisheye cameras-vehicle coordinate system(Ego), LiDAR-Camera, auto-calibration
- \circ Implemented algorithms for mapping pixel index between Fisheye \leftrightarrow Perspective image. Estimate distance between vehicle coordinate system(Ego) to object based on calibration
- Implemented algorithms free-space segmentation/detection based on cameras (BEV)
- o Auto Parking: Support build Occupancy Grid Map (OGM) from four cameras, researched path planning method
- o Researched and applied CV, ML/DL techniques to develop 3DOD from LiDAR Point Cloud

AI Research Resident Apr 2020 - Mar 2021

- o Mentors: Dr. Binh-Son Hua
- Research topic: 3D Point Cloud Segmentation, 3D Medical Image Segmentation. Proposed a 3D Point Cloud method for 3D voxel medical image segmentation dataset

• VCCorp
AI Engineer

HCMC, Vietnam
Jun 2019 - Apr 2020

- \circ Implemented a classification system using RNN/LSTM model that can predict the category, detect depraved content/violence in videos on social media
- o Implemented a VIP (very important person) detection system on videos

• FPT Software

AI Intern

HCMC, Vietnam

Mar 2017 - May 2018

- o Implemented a 3D medical Image Segmentation model, analysis, processing, and visualization of 3D image data
- o Implemented a object detection model for broken products when passing on conveyor belts in industrial plants
- Personal project: Self-driving car

HCMC, Vietnam

∘ Implemented of mini-self-driving cars, running in real environment Using machine learning to detect lanes, traffic signs, and obstructions, thereby making decisions about speed, and steering angle ▶

PUBLICATIONS

- FG-CXR: A Radiologist-Aligned Gaze Dataset for Enhancing Interpretability in Chest X-Ray Report Generation Trong-Thang Pham, Ngoc-Vuong Ho, Nhat-Tan Bui, Thinh Phan, Hien Nguyen, Brijesh Patel, Donald Adjeroh, Gianfranco Doretto, Anh Nguyen, Carol Wu, and Ngan Le. ACCV 2024
- Surround view monitoring system and method

Dai Thanh Phan, Phuc Thien Nguyen, Chi Thanh Nguyen, Duc Chan Vu, Truong Trung Tin, Nguyen Van Thang, Dang Quang Nguyen, **Ngoc-Vuong Ho**, Hai Hung Bui. Patent WO2024057060A1, WIPO (PCT) 2022

• Point-Unet: A Context aware Point-based Neural Network for Volumetric Segmentation Ngoc-Vuong Ho, Tan Nguyen, Gia-Han Diep, Ngan Le, Binh-Son Hua. MICCAI 2021

Honors & Awards

• CVPR Registration Award

• MICCAI 2021 Student Travel Award

2024

2021

• HackerRank Certificates Problem Solving (Basic)

2020 2019

• Southeast Asia Machine Learning School in Indonesia

2019
• The Mini-course "Statistical learning: bagging, boosting, SVM, introduction to neural network"

2019
2019

• Top 8/876 in the Digital race Driverless in 2017 -2018 by FPT Corporation

2018

TECHNICAL SKILLS

Programming: C/C++, Python, MATLAB, CUDA(basic), Parallel computing

Frameworks & Tools: Pytorch, TensorFlow, Unix/Linux, OpenCV, OpenGL(Basic), LATEX, Docker, ROS, Blender, Git

Database: SQL, ETL Data Modeling, Kafka Coding/Algorithm: Checkout my LeetCode