

Vincent W. Hill

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EDUCATION

The University of Alabama
Doctor of Philosophy

Tuscaloosa, Alabama
Expected December 2022

The University of Alabama
Master of Science in Aerospace Engineering and Mechanics

Tuscaloosa, Alabama
May 2020

The University of Alabama
Bachelor of Science in Mechanical Engineering

Tuscaloosa, Alabama
December 2017

EXPERIENCE

Guidance, Navigation, and Control Engineer
Raytheon Technologies

August 2021—Present
Tucson, AZ

- Developed and tested GNC algorithms for classified missile programs

Guidance, Navigation, and Control Engineer
AeroVironment, Inc.

May 2020—July 2021
Simi Valley, CA

- Developed and tested GNC algorithms for large high-altitude long-endurance (HALE) UAS
- Conducted Monte Carlo simulations to analyze uncertainty & failure mode effects on control system performance
- Wrote flight test cards to evaluate control law performance
- Designed a control law to govern flexible wing shape through only control surface deflections
- Developed a Kalman Filter data fusion algorithm to improve aircraft height above ground level estimates
- Designed a control law for autonomous landing with minimal instrumentation
- Designed a control law to stabilize a system mode predicted to become unstable in stratospheric flight
- Primary flight test crew member for 13 flight hours to date
- Participated in 60 hours of flight test crew simulator training to date

Dissertation Research

June 2020—Present

- Implemented a Python simulation testbed for multi-agent, multi-target GNC algorithm development
- Developed a probabilistic, measurement-based autonomous mission planning algorithm for UAS swarm operations using a random finite set multi-object tracking framework

Graduate Coursework Projects

August 2018—May 2021

- Designed an H_∞ robust control law for active gust rejection of a flexible aircraft
- Developed Python code for UAV navigation with loose INS/GPS integration
- Estimated the position of a mobile rover using differential GNSS
- Designed and tested a coupled guidance-control algorithm for a lateral aircraft model
- Derived the equations of motion and designed a control system for an inverted pendulum with cart

Research Technician

March 2018—July 2018
Tuscaloosa, Alabama

The University of Alabama – Remote Sensing Center

- Technician on climate change research program
- Led a team of undergraduate and graduate students to manufacture a ground-penetrating radar system
- System was completed and deployed to Greenland's EastGRIP research station in July 2018

Co-Op (Four Terms)

January 2015—August 2017
Atlanta, Georgia

Delta Air Lines – Operations Support Engineering

- Served as a first responder for a 24/7 operations support engineering hotline
- Authored over 100 unique aircraft repair technique substantiations which are subject to FAA audit
- Directed Delta maintenance technicians during on-site disposition of severe aircraft damages

LEADERSHIP

Professional Development Committee Chair

August 2019—May 2020

The University of Alabama – Graduate Student Association

- Organized and moderated two professional development events, a research grant writing experts' panel and a life as a new professor discussion panel

Alumni Mentor

August 2019—May 2020

MentorUPP

- Partnered with two mechanical engineering upperclassmen to develop concrete plans to achieve realistic goals
- Provided advice on resume building, study habits, grad school admissions, and job searches
- Under my direction, senior mentee received fully funded offer to his first-choice MS program
- Junior mentee received offer from his first-choice company for a summer 2020 internship

TEACHING

Graduate Teaching Assistant

August 2018—May 2020

The University of Alabama

- Grader for two classes per semester
- Gave a total of 15 lectures on elementary glider design, technical writing, dynamics, and fluid mechanics

AWARDS

Graduate Student of the Year

April 2020

The University of Alabama – Graduate Student Association

PEER-REVIEWED JOURNAL PUBLICATIONS

1. **Vincent W. Hill**, Ryan W. Thomas, and Jordan D. Larson, "Autonomous Situational Awareness for Robotic Swarms in High-Risk Environments," in *IEEE Transactions on Control of Network Systems*, in review

REFEREED CONFERENCE PROCEEDINGS

1. **Vincent W. Hill**, Ryan W. Thomas, and Jordan D. Larson. "Autonomous Situational Awareness for UAS Swarms", IEEE Aerospace 2021 Forum, IEEE Aerospace Forum, to be published
2. **Vincent W. Hill**, Jason Mukherjee, Derek Lisoski, Oliver Chiang, Brian P. Danowsky, and Stephen Haviland. "In-Flight Stability Analysis and Envelope Clearance of a Solar-Powered HALE UAS with CIPHER", AIAA Aviation 2021 Forum, AIAA Aviation Forum, to be published