

# Vincent W. Hill

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## EDUCATION

<b>The University of Alabama</b> <b>Doctor of Philosophy</b>	Tuscaloosa, Alabama Expected August 2022
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<b>The University of Alabama</b> <b>Master of Science in Aerospace Engineering and Mechanics</b>	Tuscaloosa, Alabama May 2020
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<b>The University of Alabama</b> <b>Bachelor of Science in Mechanical Engineering</b>	Tuscaloosa, Alabama December 2017
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## EXPERIENCE

<b>Guidance, Navigation, and Control Engineer</b> <b>AeroVironment, Inc.</b>	<i>May 2020—Present</i> <i>Simi Valley, CA</i>
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- Developed and tested GNC algorithms for large high-altitude long-endurance (HALE) UAS
- Conducted Monte Carlo simulations to analyze uncertainty & failure mode effects on control system performance
- Wrote flight test cards to evaluate control law performance
- Designed a control law to govern flexible wing shape through only control surface deflections
- Developed a Kalman Filter data fusion algorithm to improve aircraft height above ground level estimates
- Designed a control law for autonomous landing with minimal instrumentation
- Designed a control law to stabilize a system mode predicted to become unstable in stratospheric flight
- Primary flight test crew member for 13 flight hours to date
- Participated in 60 hours of flight test crew simulator training to date

<b>Dissertation Research</b>	<i>June 2020—Present</i>
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- Implemented a Python simulation testbed for multi-agent, multi-target GNC algorithm development
- Developed a probabilistic, measurement-based autonomous mission planning algorithm for UAS swarm operations using a random finite set multi-object tracking framework

<b>Graduate Coursework Projects</b>	<i>August 2018—May 2021</i>
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- Designed an  $H_\infty$  robust control law for active gust rejection of a flexible aircraft
- Developed Python code for UAV navigation with loose INS/GPS integration
- Estimated the position of a mobile rover using differential GNSS
- Designed and tested a coupled guidance-control algorithm for a lateral aircraft model
- Derived the equations of motion and designed a control system for an inverted pendulum with cart

<b>Research Technician</b>	<i>March 2018—July 2018</i>
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<b>The University of Alabama – Remote Sensing Center</b>	<i>Tuscaloosa, Alabama</i>
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- Technician on climate change research program
- Led a team of undergraduate and graduate students to manufacture a ground-penetrating radar system
- System was completed and deployed to Greenland's EastGRIP research station in July 2018

<b>Co-Op (Four Terms)</b>	<i>January 2015—August 2017</i>
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<b>Delta Air Lines – Operations Support Engineering</b>	<i>Atlanta, Georgia</i>
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- Served as a first responder for a 24/7 operations support engineering hotline
- Authored over 100 unique aircraft repair technique substantiations which are subject to FAA audit
- Directed Delta maintenance technicians during on-site disposition of severe aircraft damages

## LEADERSHIP

<b>Professional Development Committee Chair</b>	<i>August 2019—May 2020</i>
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<b>The University of Alabama – Graduate Student Association</b>	
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- Organized and moderated two professional development events, a research grant writing experts' panel and a life as a new professor discussion panel

## **Alumni Mentor**

*August 2019—May 2020*

### **MentorUPP**

- Partnered with two mechanical engineering upperclassmen to develop concrete plans to achieve realistic goals
- Provided advice on resume building, study habits, grad school admissions, and job searches
- Under my direction, senior mentee received fully funded offer to his first-choice MS program
- Junior mentee received offer from his first-choice company for a summer 2020 internship

## **TEACHING**

### **Graduate Teaching Assistant**

*August 2018—May 2020*

#### **The University of Alabama**

- Grader for two classes per semester
- Gave a total of 15 lectures on elementary glider design, technical writing, dynamics, and fluid mechanics

## **AWARDS**

### **Graduate Student of the Year**

*April 2020*

#### **The University of Alabama – Graduate Student Association**

## **PUBLICATIONS**

1. **Vincent W. Hill**, Ryan W. Thomas, and Jordan D. Larson. "Autonomous Situational Awareness for UAS Swarms", IEEE Aerospace 2021 Forum, IEEE Aerospace Forum, to be published
2. **Vincent W. Hill**, Jason Mukherjee, Derek Lisoski, Oliver Chiang, Brian P. Danowsky, and Stephen Haviland. "In-Flight Stability Analysis and Envelope Clearance of a Solar-Powered HALE UAS with CIPHER", AIAA Aviation 2021 Forum, AIAA Aviation Forum, to be published