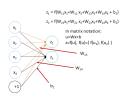
Chapter 3: Introduction to Machine Learning – Linear and Logistic Regression

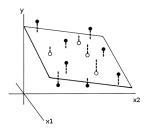


Christian Heumann (credits go to Nina Poerner, Benjamin Roth, Marina Speranskaya)

CIS LMU München, Department of Statistics LMU München

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Linear Regression



• In linear regression, the prediction \hat{y} of a label y is a linear function:

$$\hat{y} = \boldsymbol{w}^T \boldsymbol{x} = \boldsymbol{x}^T \boldsymbol{w} = \sum_{j=1}^n w_j x_j$$

- Note, that in this notation, the parameter vector $\mathbf{w} \in \mathbb{R}^n$ stands already for the *estimated* parameter vector.
- Weight w_j decides if the value of feature x_j increases or decreases the prediction \hat{y} .

Matrix notation I

- m samples
- Prediction for one sample:

$$\hat{y}_i = \mathbf{w}^T \mathbf{x}_i = \mathbf{x}_i^T \mathbf{w}$$

• Error for one sample (residual):

$$e_i = (y_i - \hat{y}_i)$$

Squared error for one sample:

$$e_i^2 = (y_i - \hat{y}_i)^2 = (\hat{y}_i - y_i)^2$$

Matrix notation:

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \hat{\mathbf{y}} = \begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_m \end{bmatrix} \mathbf{X} = \begin{bmatrix} \mathbf{x}_1^T \\ \mathbf{x}_2^T \\ \vdots \\ \mathbf{x}_m^T \end{bmatrix} \hat{\mathbf{y}} = \mathbf{X} \mathbf{w}$$

Matrix notation II

• X in detail: typically, the first column contains all 1 for the intercept (bias, shift) term.

$$\mathbf{X} = \begin{bmatrix} 1 & x_{12} & x_{13} & \dots & x_{1,n} \\ 1 & x_{22} & x_{23} & \dots & x_{2,n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{m2} & x_{m3} & \dots & x_{m,n} \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

- Estimate parameters using $\mathbf{X}^{(train)}$ and $\mathbf{y}^{(train)}$.
- ullet Make high-level decisions (which features...) using $oldsymbol{X}^{(dev)}$ and $oldsymbol{y}^{(dev)}$.
- Evaluate resulting model using $X^{(test)}$ and $y^{(test)}$.

Simple Example: Housing Prices

 Predict property prices (in 1K Euros) from just one feature: Square feet of property.

$$\mathbf{X} = \begin{bmatrix} 1 & 450 \\ 1 & 900 \\ 1 & 1350 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 730 \\ 1300 \\ 1700 \end{bmatrix}$$

• Prediction is:

$$\hat{\mathbf{y}} = \begin{bmatrix} w_1 + 450w_2 \\ w_1 + 900w_2 \\ w_1 + 1350w_2 \end{bmatrix} = \begin{bmatrix} 1 & 450 \\ 1 & 900 \\ 1 & 1350 \end{bmatrix} \cdot \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \mathbf{X} \, \mathbf{w}$$

- w₁ will contain costs incurred in any property acquisition
- w_2 will contain remaining average price per square feet.
- Optimal parameters are for the above case:

$$\mathbf{w} = \begin{bmatrix} 273.3 \\ 1.08 \end{bmatrix} \quad \hat{\mathbf{y}} = \begin{bmatrix} 759.1 \\ 1245.1 \\ 1731.1 \end{bmatrix}$$

Linear Regression: Mean Squared Error

• Mean squared error of training (or test) data set is the sum of squared differences between the labels and the predictions of all *m* instances.

$$MSE := \frac{1}{m} \sum_{i=1}^{m} e_i^2 = \frac{1}{m} \sum_{i=1}^{m} (y_i - \hat{y}_i)^2$$

• In matrix notation:

$$MSE := rac{1}{m}||oldsymbol{y} - oldsymbol{\hat{y}}||_2^2$$

$$= rac{1}{m}||oldsymbol{y} - oldsymbol{X}oldsymbol{w}||_2^2$$

Learning: Improving on MSE

• Gradient of a function f: Vector whose components are the n partial derivatives of f wrt to the parameters, here \mathbf{w} .

$$\nabla_{\mathbf{w}} f(\mathbf{w}) = \begin{bmatrix} \frac{\partial f(\mathbf{w})}{\partial w_1} \\ \frac{\partial f(\mathbf{w})}{\partial w_2} \\ \vdots \\ \frac{\partial f(\mathbf{w})}{\partial w_n} \end{bmatrix}$$

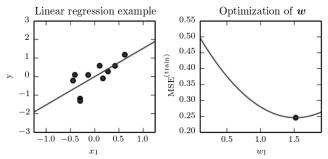
- View MSE as a function f(w) of w
- Minimum is where gradient is 0:

$$\nabla_{\mathbf{w}} MSE \stackrel{!}{=} \mathbf{0}$$

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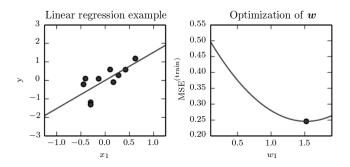
Learning: Improving on MSE

View MSE as a function of w



- Why minimum and and not maximum or saddle point?
 - Because it is a quadratic function...
 - ▶ Check convexity for a 1-dimensional function: Second derivative > 0.
 - ▶ Check for a vector valued function: Hessian is positive definite.

Second Derivative Test



Second derivative of Mean Squared Error for Linear model with only one feature:

$$\frac{d^2}{dw^2} \sum_{i=1}^m (y_i - x_i w)^2 = \frac{d^2}{dw^2} \sum_{i=1}^m (y_i^2 - 2y_i x_i w + x_i^2 w^2) = 2 \sum_{i=1}^m x_i^2 > 0$$

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Solving for w

• We now know that minimum is where gradient is **0**.

$$\nabla_{\mathbf{w}} MSE = \mathbf{0}$$

$$\Rightarrow \nabla_{\mathbf{w}} \frac{1}{m} ||\mathbf{X} \mathbf{w} - \mathbf{y}||_2^2 = \mathbf{0}$$

Solve for w:

$$\boldsymbol{w} = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{y}$$

(Normal Equation)

• The inverse $(\boldsymbol{X}^T\boldsymbol{X})^{-1}$ exists, if \boldsymbol{X} has full column rank (i.e. rank n).

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Deriving the Normal Equation

• Function to minimize:

$$||Xw - y||_2^2$$

$$= (Xw - y)^T (Xw - y)$$

$$= w^T X^T X w - w^T X^T y - y^T X w + y^T y$$

$$= w^T X^T X w - 2w^T X^T y + y^T y$$

• Take the gradient w.r.t. w and set equal to 0:

$$2X^{T}Xw - 2X^{T}y = 0$$

$$\Rightarrow X^{T}Xw = X^{T}y$$

$$\Rightarrow (X^{T}X)^{-1}X^{T}Xw = (X^{T}X)^{-1}X^{T}y$$

$$\nabla_{\mathbf{w}} \mathbf{w}^{\mathsf{T}} \mathbf{a} = \mathbf{a}$$

$$\nabla_{\mathbf{w}} \mathbf{w}^{\mathsf{T}} \mathbf{B} \mathbf{w} = 2 \mathbf{B} \mathbf{w}$$
 for symmetric \mathbf{B}

¹[Matrix Cookbook. Petersen and Pedersen, 2012]:

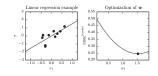
Practical Remarks

What if $\mathbf{X}^T \mathbf{X}$ does not have an inverse?

- This can happen if there are infinitely many solutions:
 - one feature is the exact multiple of another
 - there are more features than training examples
 - → a Moore-Penrose pseudoinverse picks solution with smallest Euclidean norm.
 - → adding a regularization term makes the system of equations non-singular (uniquely solvable).
 - ★ Normal Equation becomes: $\mathbf{w} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{y}$
 - ★ Also called Ridge Regression.
- In general: Avoid computing the matrix inverse when implementing least squares (slow/unstable)!
- There are usually special routines for solving linear least squares and ridge regression.



Second Derivative Test for Multi-Dimensional Case



- Second derivative test for multi-dimensional $\mathbf{w} \in \mathbb{R}^n$ Is Hessian positive definite? $(\mathbf{z}^T \mathbb{H} \mathbf{z} > 0 \text{ for } \mathbf{z} \neq \mathbf{0})$ \Leftrightarrow Function is convex.
- Hessian: Matrix of second-order partial derivatives.

$$\mathbb{H}_{j,k} = \frac{\partial^2 f(\boldsymbol{w})}{\partial w_j \partial w_k}$$

Matrix algebra² gives:

$$\mathbb{H} = 2\boldsymbol{X}^T\boldsymbol{X} = 2\sum_{i=1}^m \boldsymbol{x}_i \boldsymbol{x}_i^T; \quad \boldsymbol{z}^T \mathbb{H} \boldsymbol{z} = 2\sum_{i=1}^m (\boldsymbol{z}^T \boldsymbol{x}_i)^2 > 0$$



²[Matrix Cookbook. Petersen and Pedersen, 2012]

Linear Regression: Summary

- ullet Linear regression models simple linear relationships between $oldsymbol{\mathit{X}}$ and $oldsymbol{\mathit{y}}$
- The Mean Squared Error is a quadratic function of the parameter vector **w**, and has a unique minimum.
- Normal equations: Find the minimum by setting the gradient to zero and solving for w.
- Linear algebra packages have special routines for solving least squares linear regression.

Maximum Likelihood Estimation

- Machine learning models are often more interpretable if they are stated in a probabilistic way.
- Performance measure: what is the probability of the training data given the model parameters? Works only well for discrete data! More general: use densities instead of probabilities
- Likelihood: probability density of data as a function of model parameters. Generally, likelihood is a function proportional to the density.
- ⇒ Maximum Likelihood Estimation
- Many models can be formulated in a probabilistic way!

Probability density of a data set

- Data:
 - Set of m examples $\boldsymbol{X} = \{\boldsymbol{x}^{(1)}, \dots \boldsymbol{x}^{(m)}\}$
 - Sometimes written as design matrix:

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}^{(1)T} \\ \vdots \\ \mathbf{x}^{(m)T} \end{bmatrix}$$

• Probability density of a data set X, parametrized by θ :

$$p_{model}(\boldsymbol{X}; \boldsymbol{\theta})$$

Probability density of a data set

- Data points are assumed to be (stochastically) independent (and sometimes identically distributed) random variables (i.d. or i.i.d.)
 - Assumption made by many ML models.
 - ▶ Identically distributed: examples come from same distribution.
 - ▶ Independent: value of one example doesn't influence other example.
 - ▶ ⇒ Probability density of the data set is the product of example probability densities.

$$p_{model}(\boldsymbol{X}; \boldsymbol{\theta}) = \prod_{i=1}^{m} p_{model}(\boldsymbol{x}^{(i)}; \boldsymbol{\theta})$$

Maximum Likelihood Estimation

- ullet Likelihood: probability density of data viewed as a function of parameters ullet
- (Negative) Log-Likelihood (NLL):
 - ► Logarithm is monotonically increasing
 - ★ Maximum of function stays the same
 - ★ Easier to do arithmetic with (sums vs. products)
 - ▶ Optimization is often formulated as minimization ⇒ take negative of function.
- Maximum likelihood estimator for θ :

$$egin{aligned} heta_{\mathit{ML}} &= \operatorname{argmax}_{ heta} p_{\mathit{model}}(extbf{ extit{X}}; heta) \ &= \operatorname{argmax}_{ heta} \prod_{i=1}^{m} p_{\mathit{model}}(extbf{ extit{x}}^{(i)}; heta) \ &= \operatorname{argmax}_{ heta} \sum_{i=1}^{m} \log p_{\mathit{model}}(extbf{ extit{x}}^{(i)}; heta) \end{aligned}$$

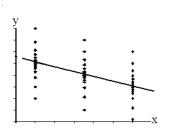
Conditional Log-Likelihood

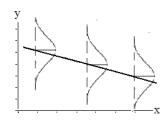
- Log-likelihood can be stated for supervised and unsupervised tasks.
- Unsupervised learning (e.g. density estimation).
 - ▶ Task: model $p_{model}(X; \theta)$ (as before)
 - $X = \{x^{(1)}, \dots x^{(m)}\}$
- Supervised learning (Predictive modeling):
 - ▶ Task: model $p_{model}(y|X;\theta)$
 - $X = \{x^{(1)}, \dots x^{(m)}\}, \quad y = \{y^{(1)}, \dots y^{(m)}\}$
- Maximum likelihood estimation for the supervised case (independent examples):

$$m{ heta}_{\mathit{ML}} = \operatorname{argmax}_{m{ heta}} P(m{y}|m{X};m{ heta})$$

$$= \operatorname{argmax}_{\boldsymbol{\theta}} \sum_{i=1}^{m} \log P(y^{(i)}|\boldsymbol{x}^{(i)}; \boldsymbol{\theta})$$

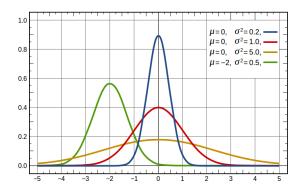
- Instead of predicting one value \hat{y} for an input x, one models the probability density p(y|x).
- For the same value of x, different values of y may occur (depending on the modeled probability density).





Gaussian Distribution

- Gaussian distribution: $N(y|\mu,\sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(y-\mu)^2}{2\sigma^2}\right]$
 - Quadratic function as negative exponent, scaled by variance
 - Normalization factor $\frac{1}{\sigma\sqrt{2\pi}}$





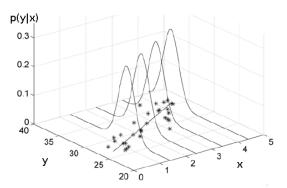
ullet Assume label y is distributed by a Gaussian, depending on features x

$$p(y|\mathbf{x}) = N(y|\mu, \sigma^2)$$

where the mean is determined by the linear transformation

$$\mu = \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}$$

and σ is a constant.



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- Gaussian distribution: $N(y|\mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(y-\mu)^2}{2\sigma^2}\right]$ Taking the log makes it a quadratic function!
- Negative log-likelihood, conditional on X (i.e., the probability distribution of X is not modeled, only that of y with X kept fixed).

$$-\log P(\mathbf{y}|\mathbf{X}; \boldsymbol{\theta})$$

$$= -\sum_{i=1}^{m} \log p(\mathbf{y}^{(i)}|\mathbf{x}^{(i)}; \boldsymbol{\theta})$$

$$= m \log \sigma + \frac{m}{2} \log(2\pi) + \sum_{i=1}^{m} \frac{(\mathbf{y}^{(i)} - \boldsymbol{\theta}^{T} \mathbf{x}^{(i)})^{2}}{2\sigma^{2}}$$

$$= \operatorname{const} + \frac{1}{2\sigma^{2}} \sum_{i=1}^{m} (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{T} \mathbf{x}^{(i)})^{2}$$

• What is the optimal value for θ ?

Conditional negative log-likelihood:

$$NLL(\boldsymbol{\theta}) = \operatorname{const} + \frac{1}{2\sigma^2} \sum_{i=1}^{m} (y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)})^2$$

Compare to previous result:

$$MSE(\mathbf{w}) = \frac{1}{m} \sum_{i=1}^{n} (y^{(i)} - \mathbf{w}^{T} \mathbf{x}^{(i)})^{2}$$

- Minimizing NLL under these assumptions is equivalent to minimizing MSE!
- The result of the minimization of the NLL is the MLE $\hat{\theta}$.

A Caveat: Maximum Likelihood is not Bayesian

- MLE is simple: identify distribution and parameters, then maximize!
- MLE accounts for (some) uncertainty: instead of predicting a single value \hat{y} , treat y as a random variable.
- However, what about the uncertainty about our parameters θ ?
- Shouldn't θ be treated as a random variable, too? (Instead of a point estimate $\hat{\theta}$?)

A Caveat: Maximum Likelihood is not Bayesian

- ullet Uncertainty about $oldsymbol{ heta}$ influenced by:
 - ightharpoonup Our assumptions what reasonable values for heta look like.
 - ▶ The amount of training data.
 - ▶ The properties (variance ...) of the training data.
- $m{eta}$ Bayesian inference is all about modelling randomness of $m{ heta}$ in a sound way.
- Why is it called Bayesian?

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\theta)p(\theta)}{\int p(\mathbf{X}|\theta)p(\theta)d\theta}$$

- The Bayesian approach is theoretically more appealing than working with point estimates.
- In practical terms: Sometimes going the Bayesian way pays off, sometimes it doesn't.

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Maximum Likelihood: Summary

- Many machine learning problems can be stated in a probabilistic way.
- Mean squared error linear regression can be stated as a probabilistic model that allows for Gaussian random noise around the predicted value \hat{y} .
- A straightforward optimization is to maximize the likelihood of the training data.
- Maximum likelihood is not Bayesian, and may give undesirable results (e.g. if there is only little training data).
- In practice, MLE and point estimates are often used to solve machine learning problems.

Linear regression and mean squared error of prediction

• The linear model is given by (Y is a random variable, y its realization)

$$Y = \boldsymbol{\theta}^\mathsf{T} \mathbf{x} + \varepsilon$$

with $\varepsilon \sim N(0, \sigma^2)$. Thus the expectation of Y is $E(Y) = \theta^T x$.

• Using the estimated parameter (Least Squares or MLE) $\hat{\theta}$, the predicted value \hat{y} is given by

$$\hat{y} = \hat{\boldsymbol{\theta}}^T \boldsymbol{x}$$

which is also the *estimated* expectation of y, $\widehat{E(Y)}$.

• The theoretical quantity, which is estimated by the introduced MSE, is the so-called MSEP (mean squared error of prediction), which is also an expectation, based on a new observation Y_{m+1} (we ignore the index in the following) and its prediction $\hat{y} = \hat{\theta}^T x_{m+1}$:

$$MSEP = E\left\{ (Y - \hat{y})^2 \right\} = E\{ (Y - E(Y) + E(Y) - \hat{y})^2 \} = Var(Y) + MSE(\hat{y}) .$$

Note, that some terms are zero, because of stochastic independence of Y_{m+1} and \hat{y} . Note, that $MSEP > Var(Y) = \sigma^2$.

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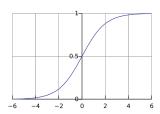
From Regression to Classification

- So far, linear regression:
 - A simple linear model.
 - Probabilistic interpretation.
 - Find optimal parameters using Maximum Likelihood Estimation.
- Can we do something similar for classification?
- ⇒ Logistic Regression (...it's not actually used for regression ...)

Logistic Regression

- Binary logistic model: Estimate the probability of a binary response $y \in \{0,1\}$ based on features x.
- Logistic Regression is a Generalized Linear Model:
 Linear model is related to the response variable via a link function.

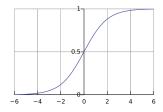
$$p(Y = 1|x; \theta) = f(\theta^T x)$$



(Note: Y denotes a random variable, whereas y, $y^{(i)}$, 0, 1 denote values that the random variable can take on. If the random variable is obvious from the context, it may be omitted.)

Logistic Regression

- Recall linear regression: $p(y|\mathbf{x}; \boldsymbol{\theta}) = N(y; \boldsymbol{\theta}^T \mathbf{x}, \sigma^2 \mathbf{I})$
 - ▶ Predicts $y \in \mathbb{R}$
- Classification: Outcome (per example) 0 or 1
 - Logistic sigmoid: $\sigma(z) = \frac{1}{1+e^{-z}}$



► Logistic Regression: Linear function + logistic sigmoid

$$p(Y = 1|x; \theta) = \sigma(\theta^T x)$$



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Binary Logistic Regression

Probability of different outcomes (for one example):

• Probability of positive outcome:

$$p(Y=1|\mathbf{x};\boldsymbol{\theta}) = \frac{1}{1+e^{-\boldsymbol{\theta}^T\mathbf{x}}}$$

Probability of negative outcome:

$$p(Y = 0|\mathbf{x}; \boldsymbol{\theta}) = 1 - p(Y = 1|\mathbf{x}; \boldsymbol{\theta})$$

Probability of a Training Example

- Probability for actual label $y^{(i)}$ given features $x^{(i)}$
- Can be written for both labels (0 and 1) without case distinction
- Label exponentiation trick: use $x^0 = 1$

$$p(Y = y^{(i)}|\mathbf{x}^{(i)}; \theta)$$

$$= \begin{cases} p(Y = 1|\mathbf{x}^{(i)}; \theta) & \text{if } y^{(i)} = 1\\ p(Y = 0|\mathbf{x}^{(i)}; \theta) & \text{if } y^{(i)} = 0 \end{cases}$$

$$= \begin{cases} p(Y = 1|\mathbf{x}^{(i)}; \theta)^{1} p(Y = 0|\mathbf{x}^{(i)}; \theta)^{0} & \text{if } y^{(i)} = 1\\ p(Y = 1|\mathbf{x}^{(i)}; \theta)^{0} p(Y = 0|\mathbf{x}^{(i)}; \theta)^{1} & \text{if } y^{(i)} = 0 \end{cases}$$

$$= p(Y = 1|\mathbf{x}^{(i)}; \theta)^{y^{(i)}} p(Y = 0|\mathbf{x}^{(i)}; \theta)^{1-y^{(i)}}$$

Binary Logistic Regression

Conditional Negative Log-Likelihood (NLL):

$$\begin{aligned} NLL(\boldsymbol{\theta}) &= -\log p(\boldsymbol{y}|\boldsymbol{X};\boldsymbol{\theta}) \\ &= -\log \prod_{i=1}^{m} p(Y = y^{(i)}|\boldsymbol{x^{(i)}};\boldsymbol{\theta}) \\ &= -\log \prod_{i=1}^{m} p(Y = 1|\boldsymbol{x^{(i)}};\boldsymbol{\theta})^{y^{(i)}} (1 - p(Y = 1|\boldsymbol{x^{(i)}};\boldsymbol{\theta}))^{1 - y^{(i)}} \\ &= -\sum_{i=1}^{m} y^{(i)} \log \sigma(\boldsymbol{\theta}^{T} \boldsymbol{x^{(i)}}) + (1 - y^{(i)}) \log(1 - \sigma(\boldsymbol{\theta}^{T} \boldsymbol{x^{(i)}})) \end{aligned}$$

- No closed form solution for minimum
- Use numerical / iterative methods.
- LBFGS, Gradient descent ...

Logistic Regression

- Logistic regression: Logistic sigmoid function applied to a weighted linear combination of feature values.
- To be interpreted as the probability that the label for a specific example equals 1.
- Applying the model on test data: Predict $y^{(i)} = 1$ if

$$p(Y = 1|x^{(i)}; \theta) > 0.5$$

 No closed form solution for maximizing NLL, iterative methods necessary.