

Shape Context and Shape Matching

Computer Vision
Exercise session 8

Teaching assistant:

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Assignment Tasks:

Shape Matching

Hand-out: 21-11-2019

Hand-in: 28-11-2019 23:00

Shape Matching Objectives

1. Compute shape context descriptors
2. Match a template shape to a target set of points using shape contexts



Overview of Algorithm

Given a set of template and target points:

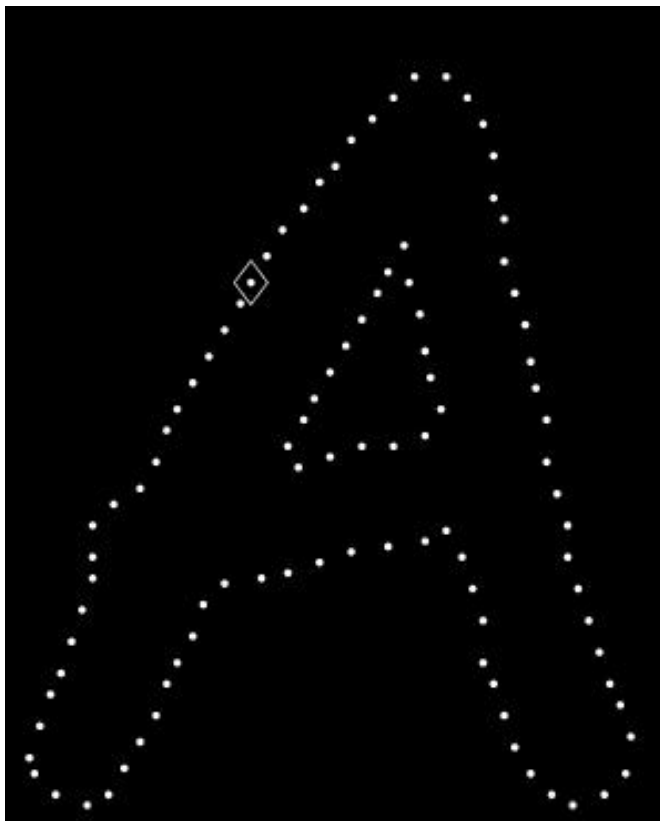
- a. Compute shape context descriptors for both sets of points
- b. Estimate cost matrix between two sets of descriptors
- c. Use cost matrix to solve the correspondence problem between two sets of descriptors (e.g. with Hungarian algorithm)
- d. From the correspondence, estimate a transformation from template to target points (e.g. with Thin Plate Splines) and perform this transformation on the template points
- e. Iterate steps a-d.

Overview of Algorithm

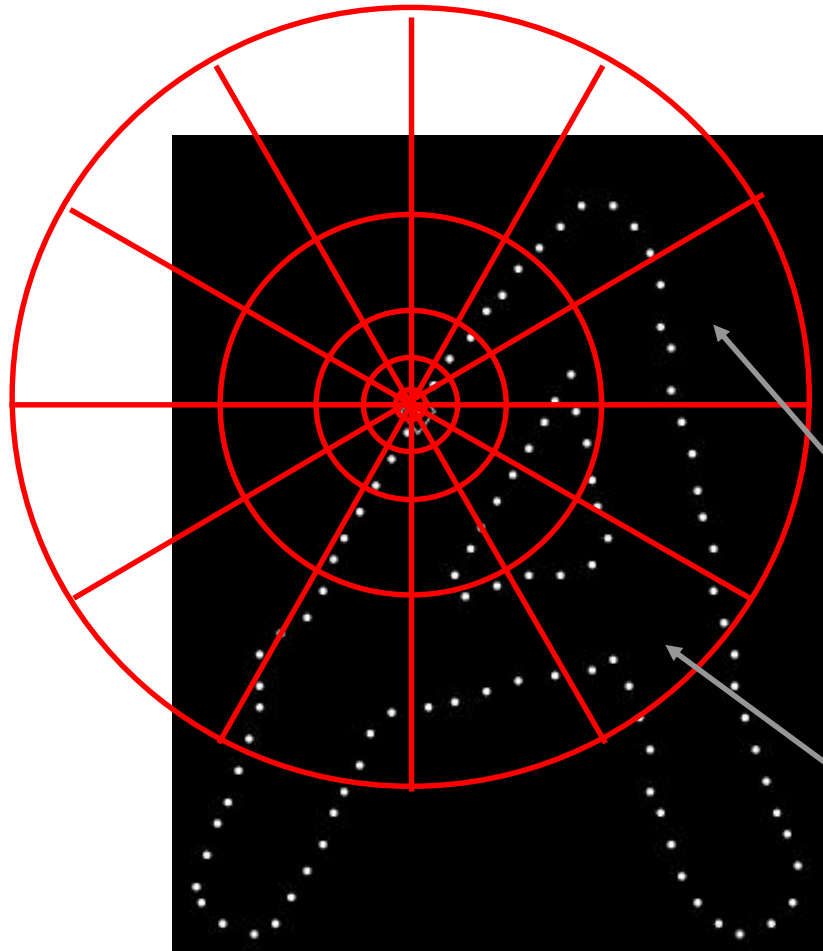
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How to Represent Shapes?



Shape Context Descriptor

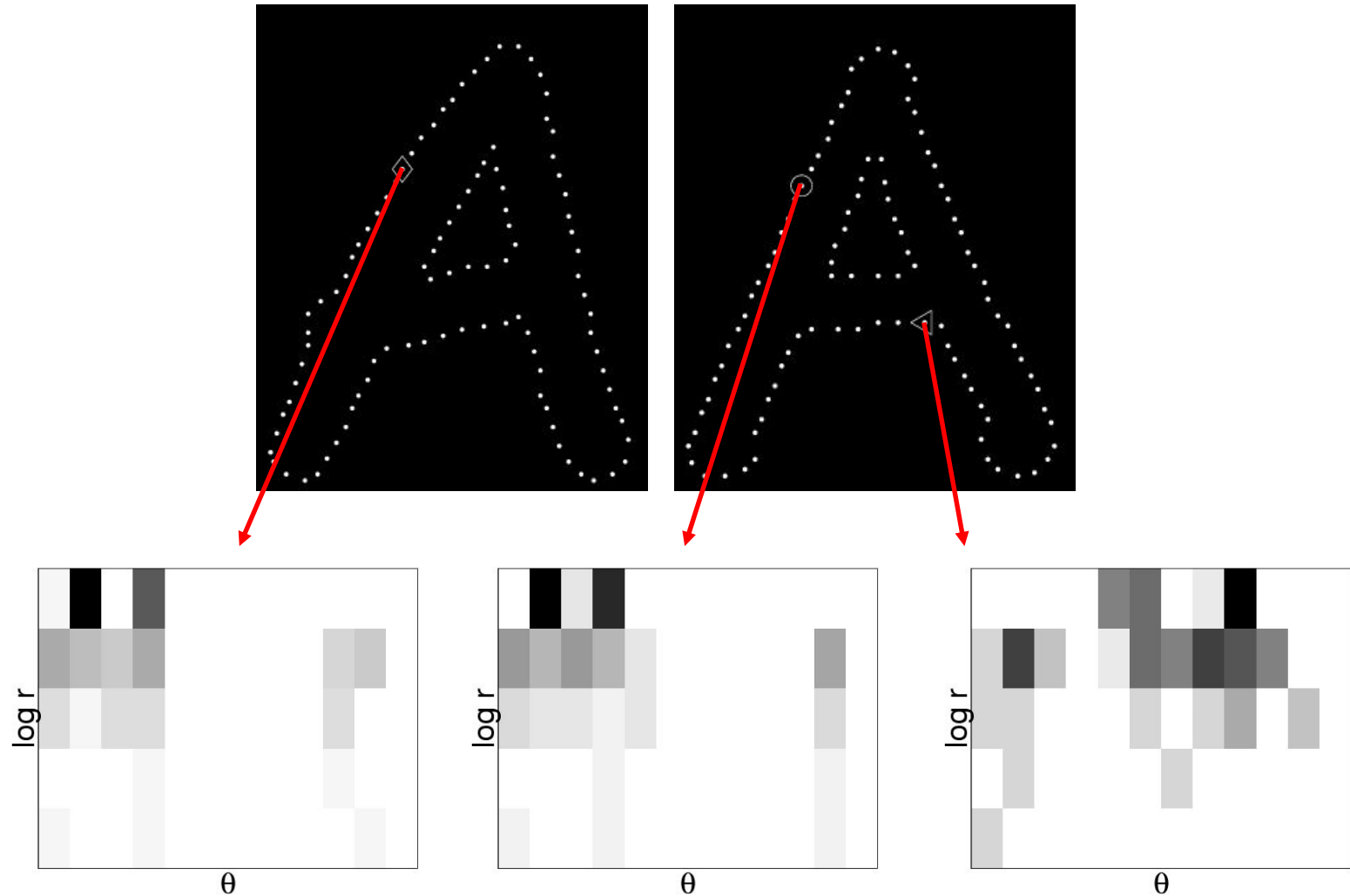


- Count number of points inside each bin
- Compact representation of distribution of points relative to each point

Count = 4

Count = 10

Shape Context Descriptor (2)



Task 1

Belongie, et al, PAMI 2002, [Shape matching and object recognition using shape contexts](#)

Overview of Algorithm

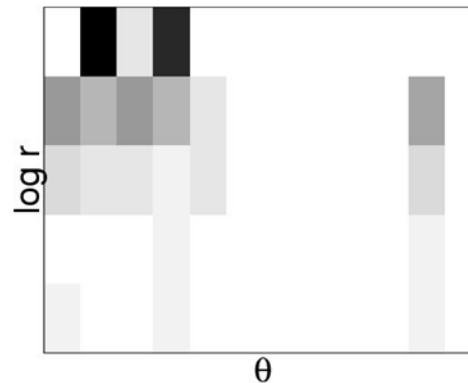
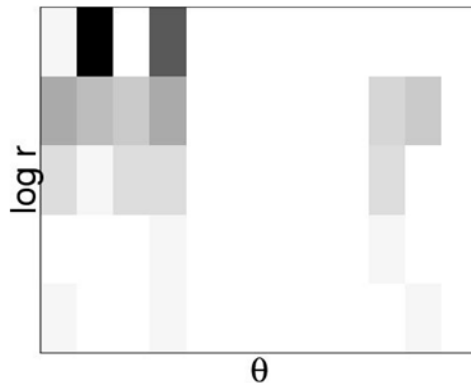
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Matching Costs

Chi-squared distance
between descriptors
 i and j .

$$C_{ij} \equiv C(p_i, p_j) = \frac{1}{2} \sum_{k=1}^K \frac{[p_i(k) - p_j(k)]^2}{p_i(k) + p_j(k)}$$

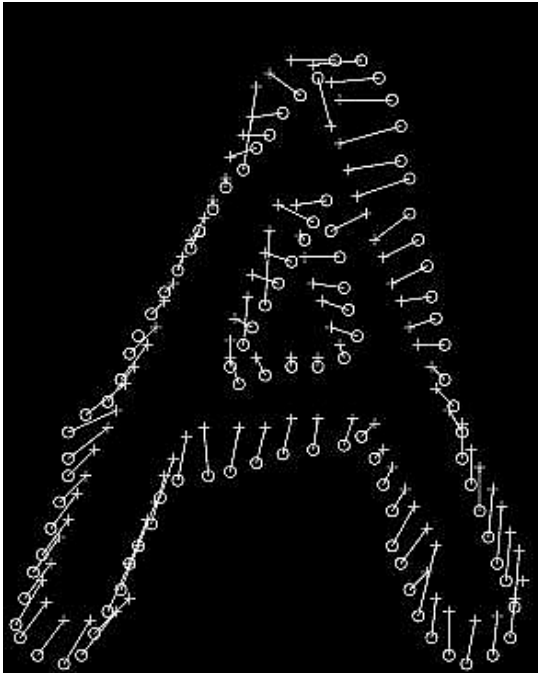
 p_i p_j 

Overview of Algorithm

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Correspondence Problem



- Minimize total cost of matching such that matching is one-to-one
- E.g. with Hungarian algorithm

Overview of Algorithm

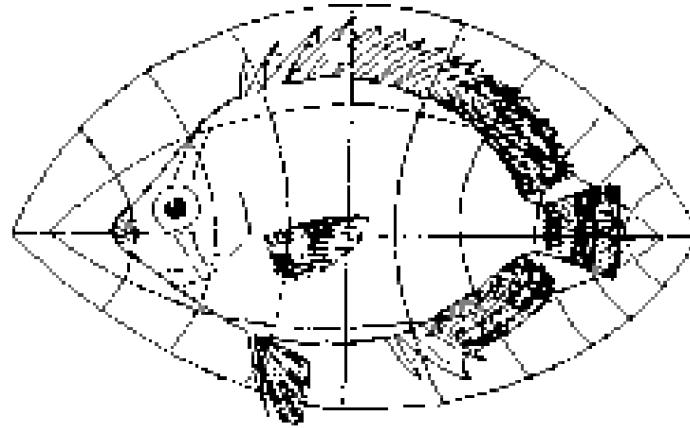
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Transformation

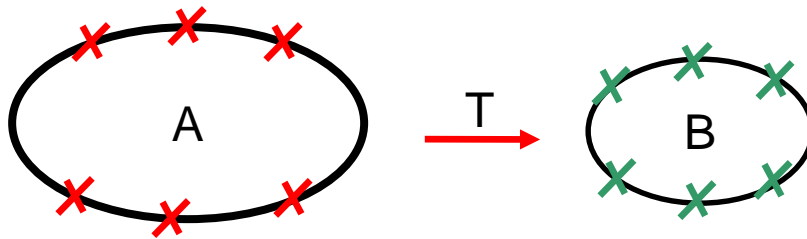


Model



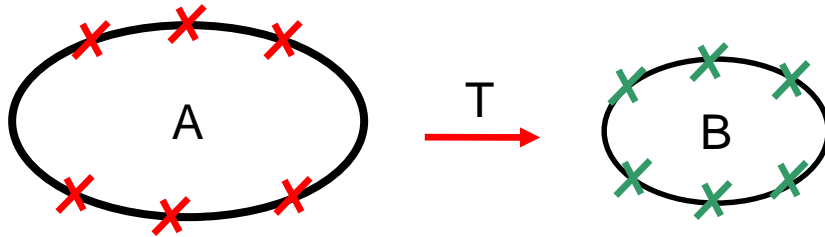
Target

Thin Plate Splines(1)

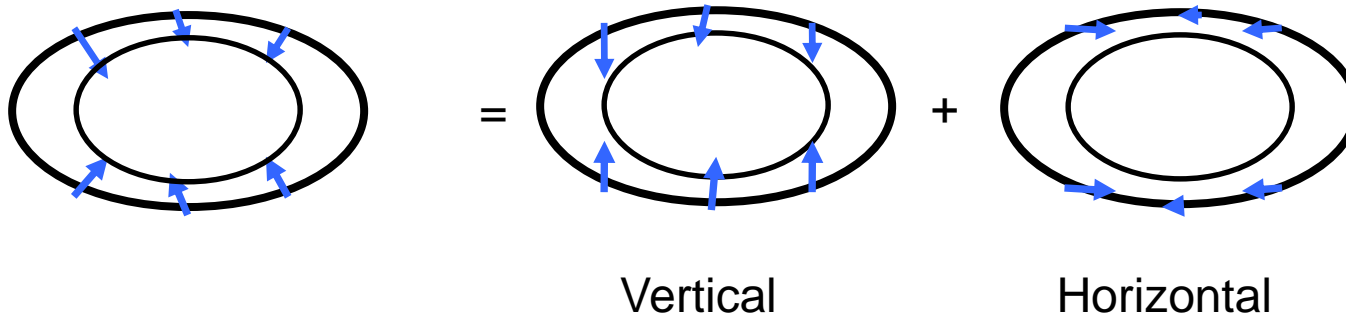


- We are given a set of correspondences
- We want to estimate the function $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that transforms A into B

Thin Plate Splines(2)

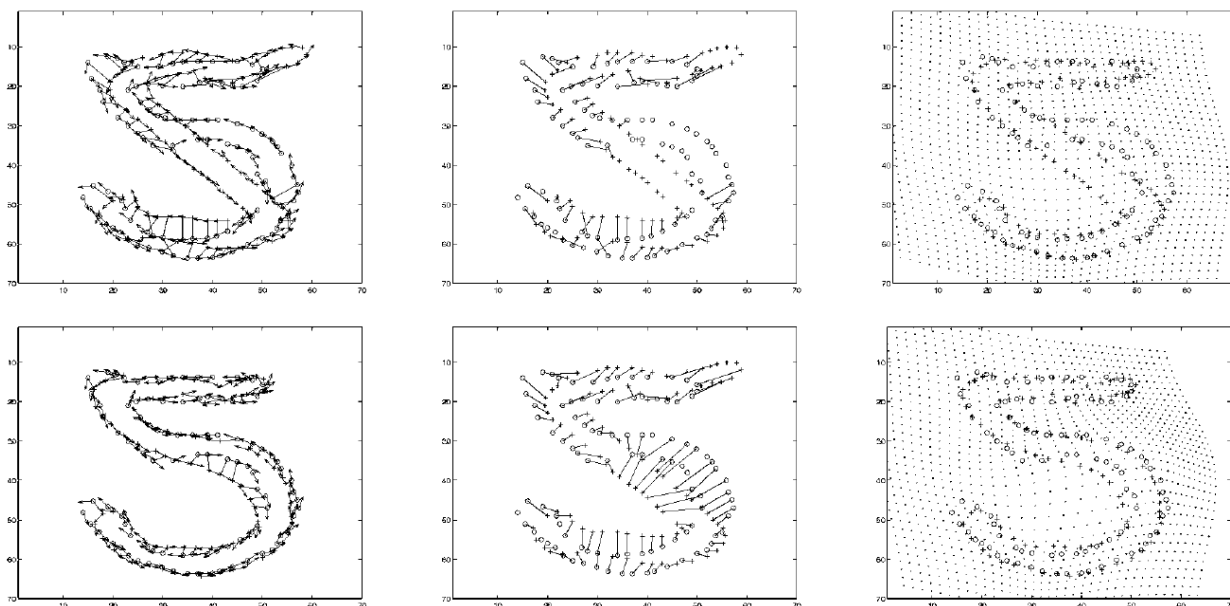


- From the correspondences, we get a displacement:



- Each component (vertical and horizontal) is a single function that we want to interpolate with a TPS.

Thin Plate Splines(3)

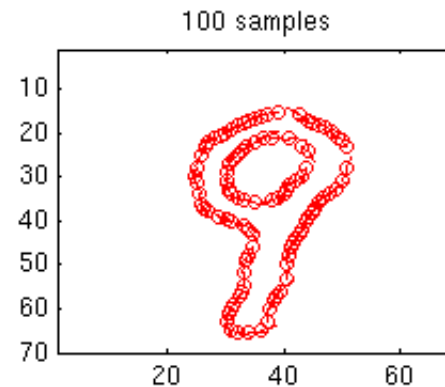
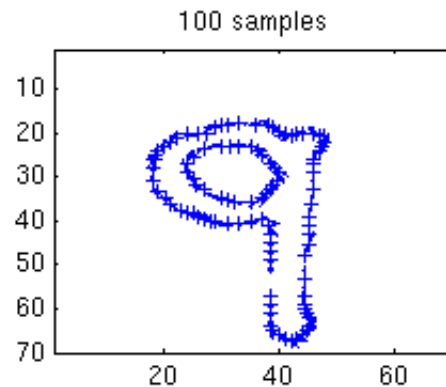
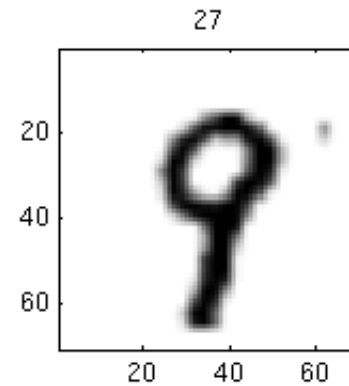
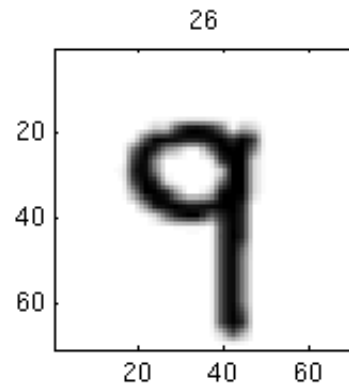


Overview of Algorithm

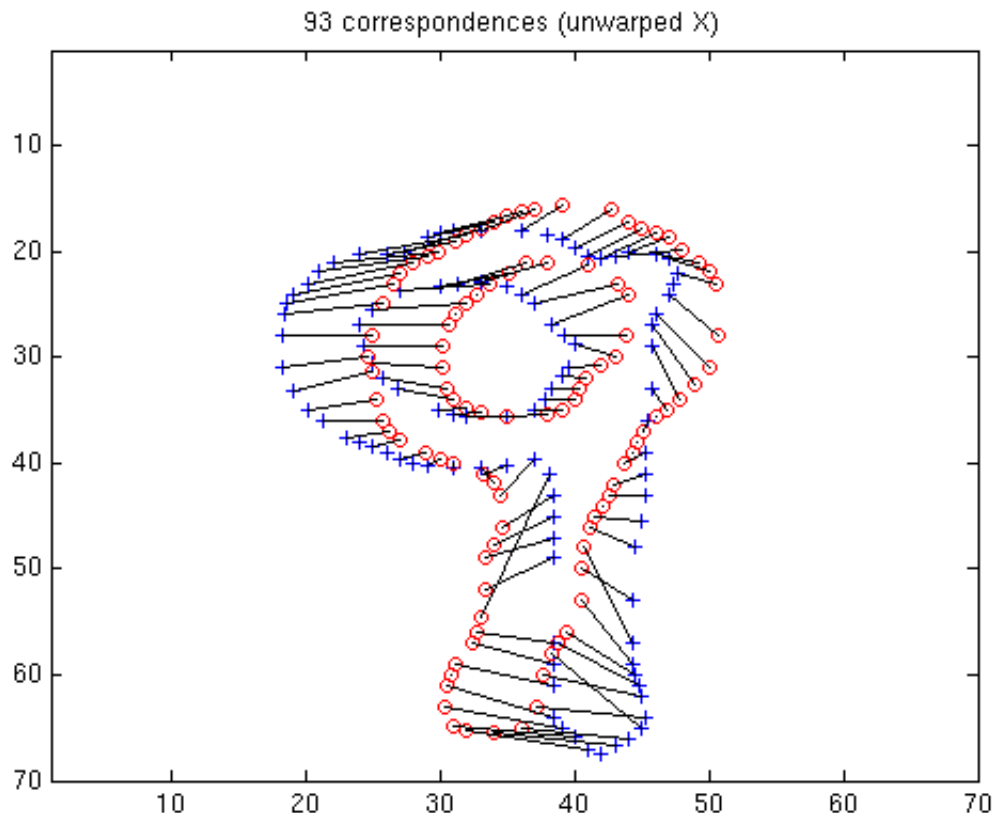
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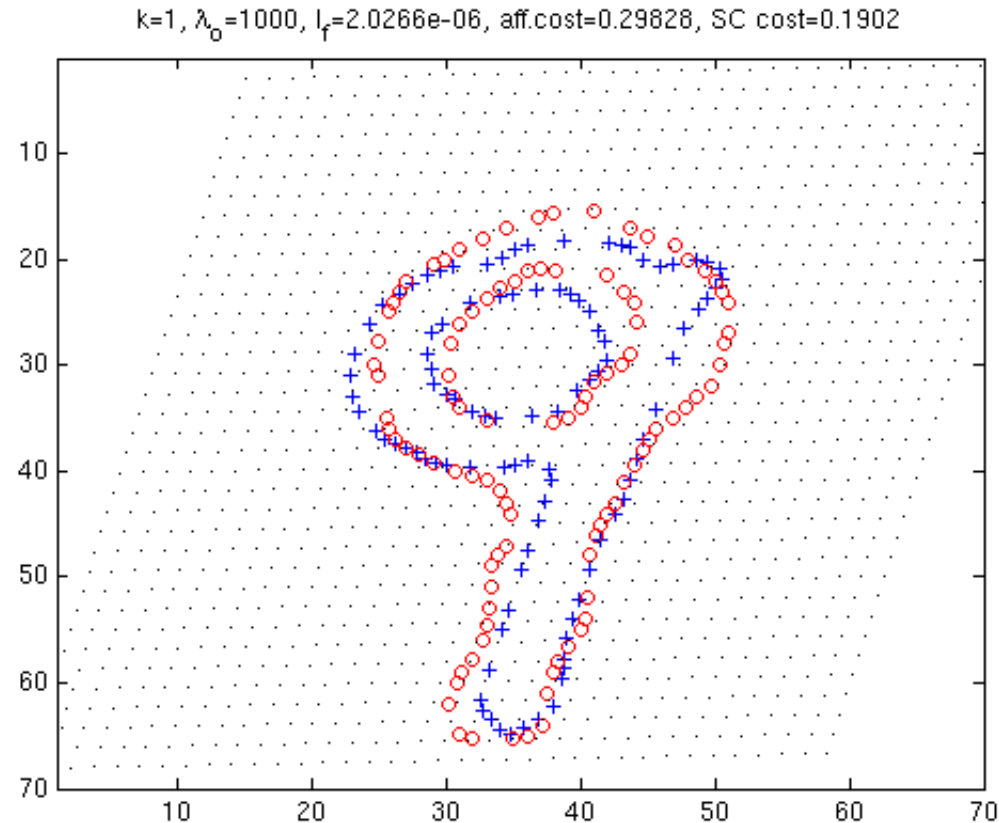
Example 1 - Numbers



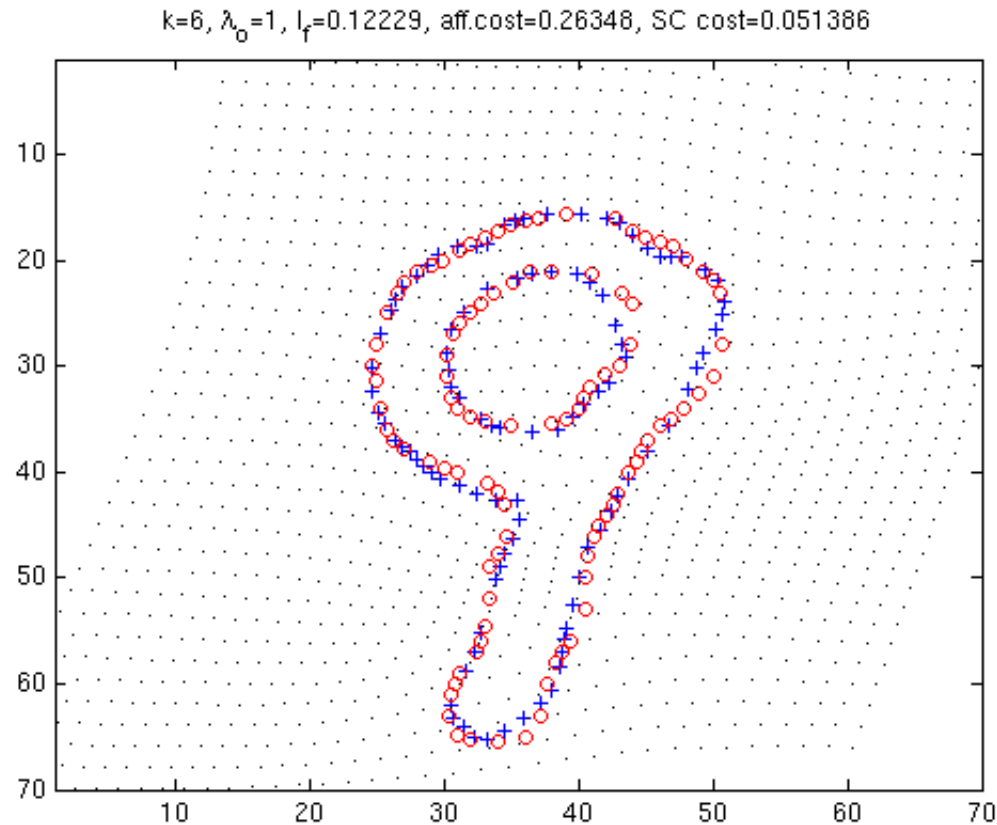
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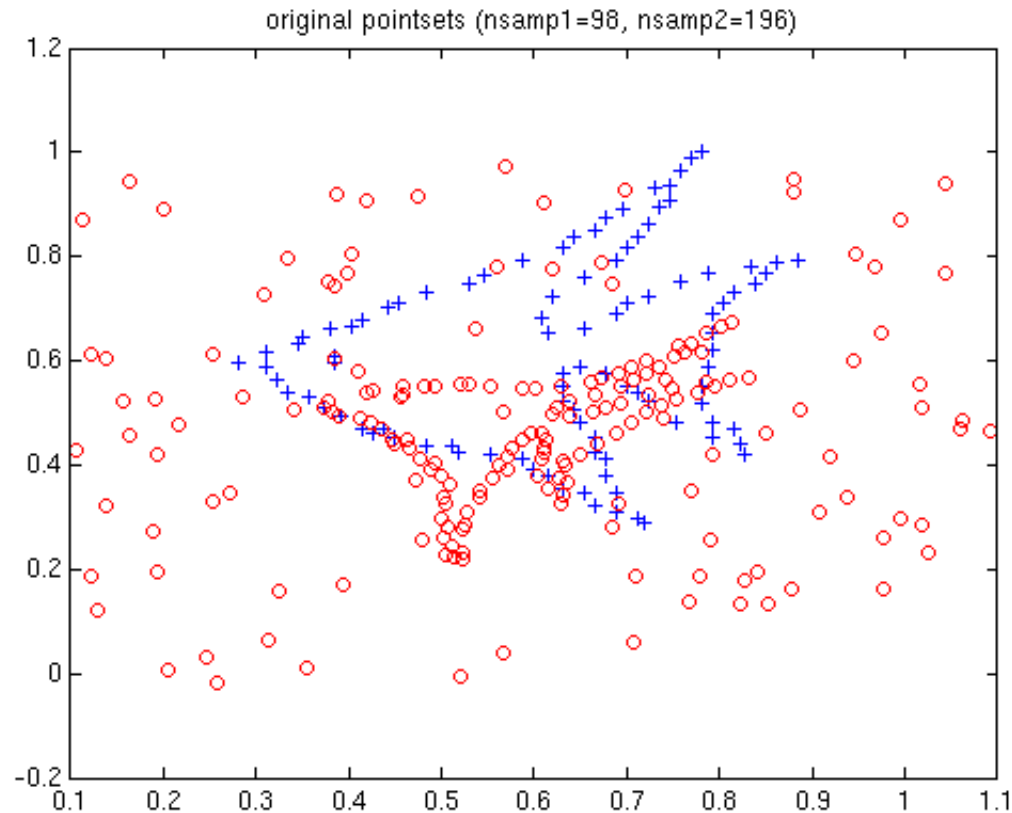
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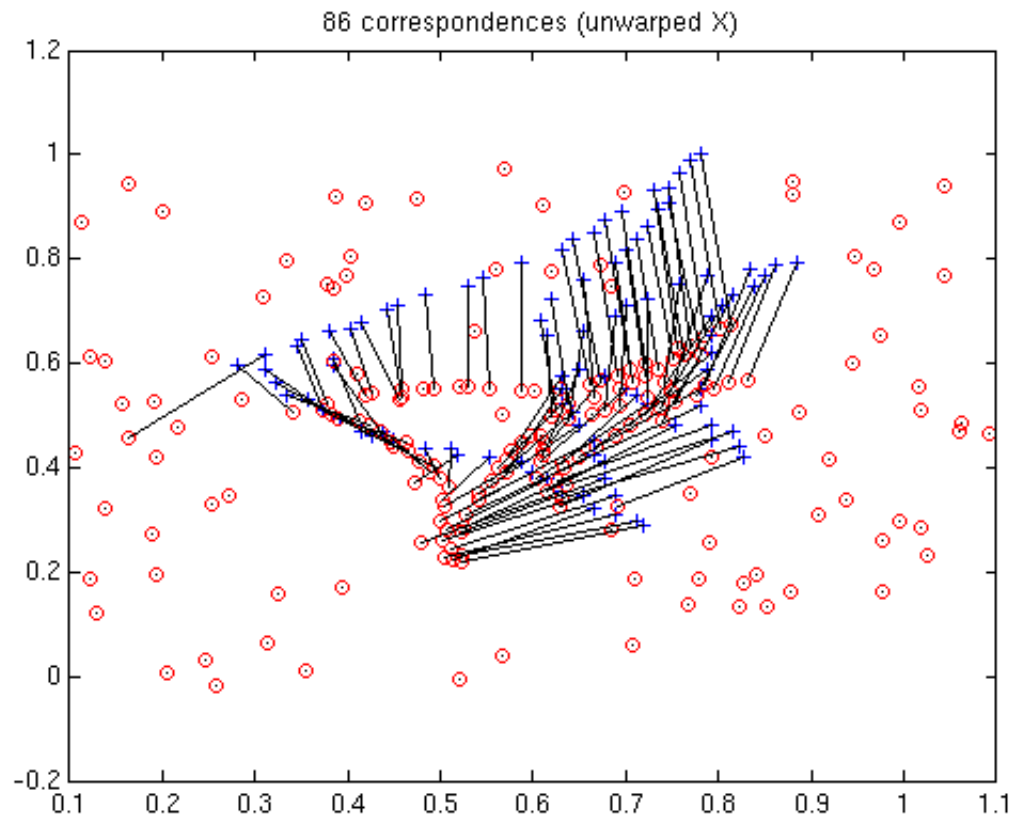
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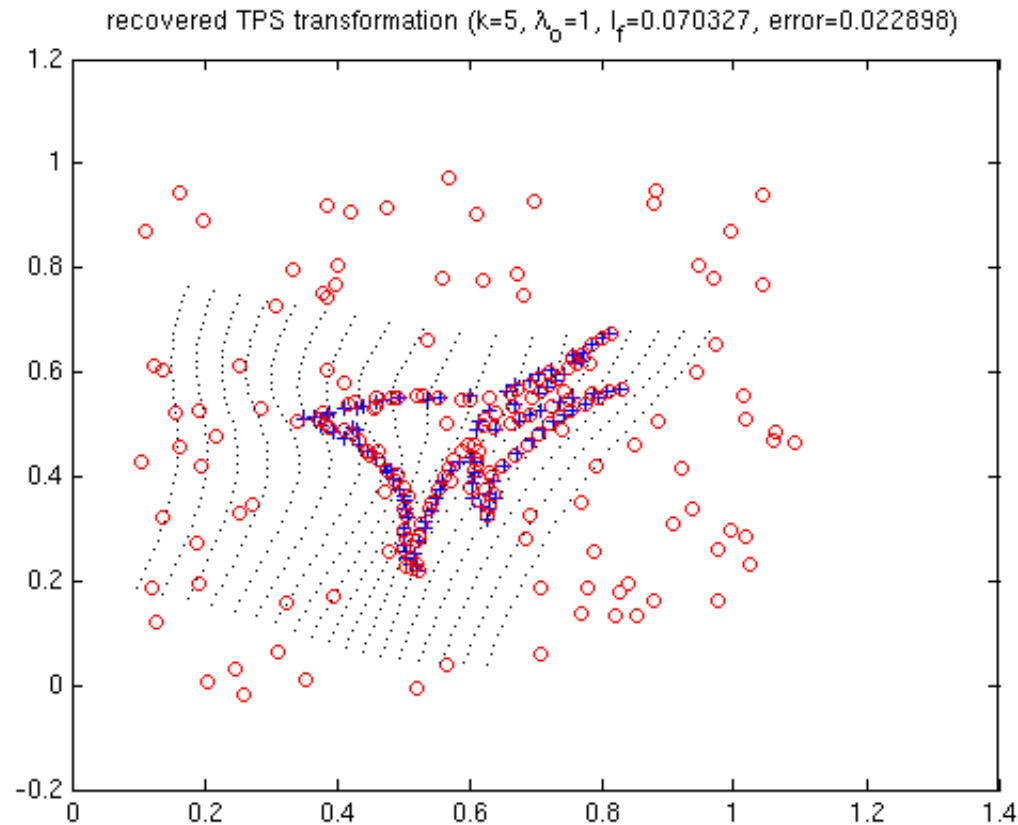
Example 2 - Fish



Example 2 - Fish



Example 2 - Fish



- Send your reports and your implementation of the required Matlab functions
 - explain main steps of your implementation
 - comment the results
 - answer the questions in the hand-out paper
- Ask questions: email to yawei.li@vision.ee.ethz.ch