

Structure Learning of Sparse Random Ising Models

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Outline

1 Graphical Models

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- ① Graphical Models
- ② Problem Definition

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- ④ Sufficient Conditions on Sample Complexity
 - Correlation Thresholding
 - Conditional Mutual Information Thresholding

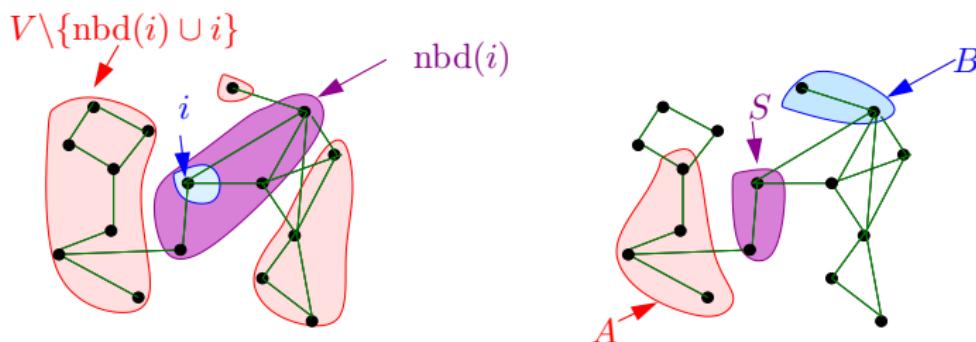
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- ⑤ Conclusion

Graphical Models: Introduction

- Graph $G = (V, E)$ represents a multivariate prob. distribution of a random vector $\mathbf{X} = (X_1, \dots, X_d)$ indexed by $V = \{1, \dots, d\}$
- Node $i \in V$ corresponds to random variable X_i
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$$X_i \perp\!\!\!\perp \mathbf{X}_{V \setminus \{\text{nbd}(i) \cup i\}} | \mathbf{X}_{\text{nbd}(i)}$$

Local Markov Property

$$\mathbf{X}_A \perp\!\!\!\perp \mathbf{X}_B | \mathbf{X}_S$$

Global Markov Property

High Dimensional Learning of Graphical Models

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- Given k training samples $\mathbf{x}^k := \{\mathbf{x}_1, \dots, \mathbf{x}_k\}$ drawn from a graphical model P , Markov on $G_n = (V, E)$ (graph with n nodes)
- Information about **model class** (e.g., Gaussian, discrete, Ising....)
- Would like an estimate $\hat{G}_n = \hat{G}_n(\mathbf{x}^k)$ that is **consistent**

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- Desideratum 2: Low computational complexity
- Motivation: High-dimensional data (microarray, social networks)

Related Work on Learning Graphical Models

Efficient Algorithms for Structure Learning

- ML for **trees**: Max-weight spanning tree (Chow & Liu 68)
 - Error exponents (T., Anandkumar, Tong, Willsky IT-'11)
 - Forest models (T., Anandkumar, Willsky JMLR-'11)
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- **Conditional independence** tests for bounded degree graphs
(Abbeel et al. '06, Bresler et al. '09)
- **Convex optimization**: ℓ_1 regularization (Dudik et al. '04, Lee et al. '06, Meinshausen & Bühlmann '06, Ravikumar et al. '10)
- **Information-theoretic** lower bounds (Santhanam & Wainwright '08)

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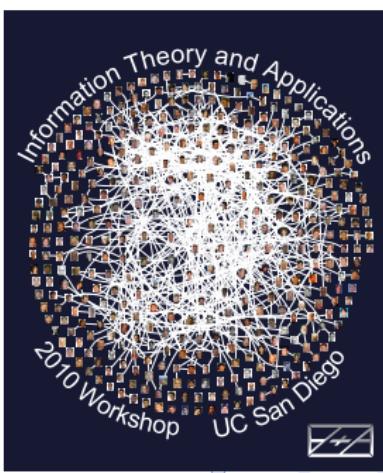
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- We consider the case where the underlying graph G is random
- Relax the assumption that graph comes from a particular set
- “Real-world” networks can be modeled by random graphs
- Our work is a first-step in understanding the fundamental limits in learning random graphical models

- Ising model
- Markov on Erdős-Rényi ensemble $G_n \sim \mathcal{G}(n, \frac{c}{n})$



Crisis = Danger + Opportunity

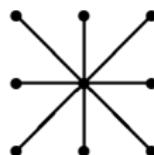
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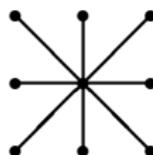


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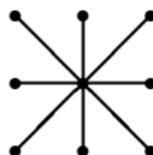
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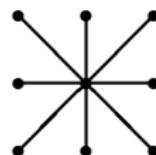
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- **Correlation decay:** Influences of “faraway” nodes on node i are negligible, model behaves locally as a tree distribution
- **Tree-based** algorithms (Chow-Liu, Thresholding) may work

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- Ising model on $G = (V, E)$:

$$P(\mathbf{x}|G) \propto \exp \left(\sum_{(i,j) \in E} J_{i,j} x_i x_j \right), \quad \mathbf{x} \in \{\pm 1\}^n$$

Assumptions:

- **Ferromagnetism:** $J_{i,j} \in [J_{\min}, J_{\max}] \subset (0, \infty)$ for all $(i,j) \in E$

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Theorem (Converse)

There exists an $\varepsilon > 0$ such that if

$$k \leq \varepsilon c \log n,$$

then,

$$\lim_{k,n \rightarrow \infty} \Pr \left(\hat{G}_n(\mathbf{x}^k) \neq G_n \right) = 1$$

for any estimator $\hat{G}_n(\cdot)$.

Proof Idea for the Strong Converse

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- Follows closely the converse technique in Bresler et al. '09.
- Main modification: Underlying graph not deterministic so counting argument needs to be modified
- Focus on graphs “with the highest likelihoods”
- Note from

$$k \leq \varepsilon c \log n,$$

that number of samples k is required to grow linearly with the average degree c

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- Set $(u, v) \in \hat{G}_n$ iff

$$\hat{C}_{u,v}^k \geq \delta(J_{\min}, J_{\max})$$

Correlation Thresholding: Theoretical Properties

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Theorem (Structural Consistency of CorrThres)

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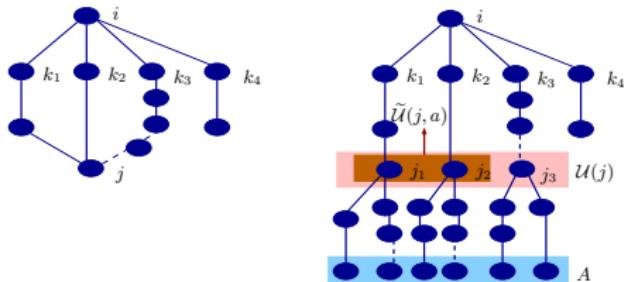
$$\lim_{\substack{k,n \rightarrow \infty \\ k = \Omega(\log n)}} \Pr \left(\text{CorrThres}(\{\hat{C}_{u,v}^k\}_{(u,v) \in V^2}; \delta); \neq G_n \right) = 0$$

Correlation Thresholding: Why / How does it work?

- Correlations are higher on edges than non-edges for **nearly homogeneous Ising models** on $\mathcal{G}(n, \frac{c}{n})$

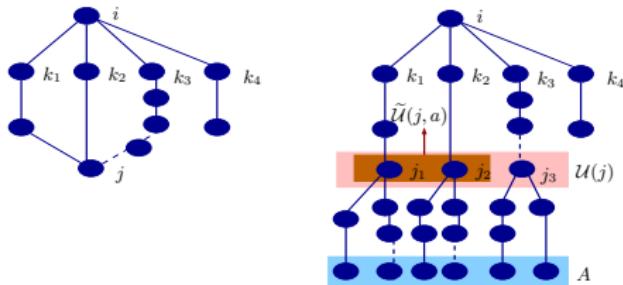
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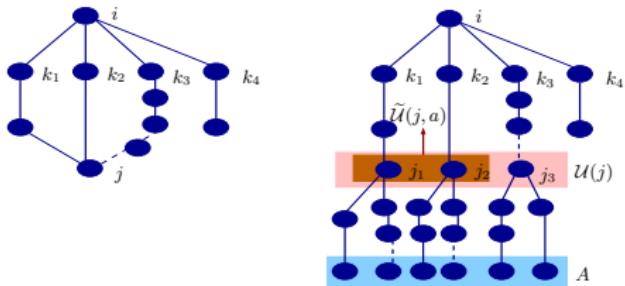
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- Prove result for **exact statistics**; generalization to sample statistics using large deviations
- Can **homogeneity** assumption be removed?

Separation Property

- Fact: For sets $A, B, S \in V$, if S separates A, B , then

$$I(X_A; X_B | X_S) = 0$$

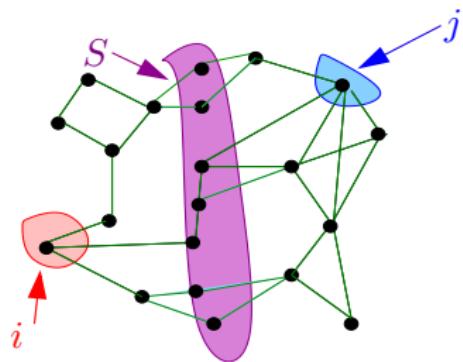
The **global Markov property**.

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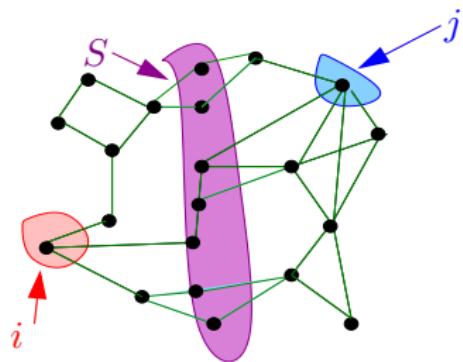
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- What should be the cardinality of the conditioning set? **Roughly 2!**
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$$\min_{S \subset V \setminus \{i,j\}, |S| \leq 2} \hat{I}(X_i, X_j | X_S) \leq \tau_{k,n}$$

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- $\tau_{k,n}$ is the threshold
- Depends on number of variables n and sample size k

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Theorem (Structural Consistency of CMIT)

For a.e. graph G_n , we have

$$\lim_{\substack{k,n \rightarrow \infty \\ k=\omega(\log n)}} \Pr(\text{CMIT}(\mathbf{x}^k; \tau_{k,n}); \neq G_n) = 0$$

Conditional MI Thresholding: Why / How does it work?

- Challenge: Separators in graphical models may be large, i.e.,

$$\hat{I}(X_i; X_j | X_S) = f(\hat{P}_{i,j,S})$$

depends on the type over many variables

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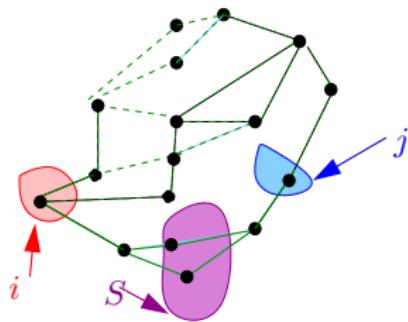
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- Approximate separation?
- In such random graphical models, the size of an approximate separator is ≤ 2 asymptotically



- Ignore effects of long paths separating i and j

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- <http://arxiv.org/abs/1011.0129>