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import numpy as np

# Objective function: Minimize the weight of the truss
def fitness(x):
    # Truss example: A simple 2D truss with 3 members and 2 nodes
    # Here x = [A1, A2, A3] are the cross-sectional areas of the members
    A1, A2, A3 = x

    # Define lengths of members (in meters) and material properties
    L1 = 10 # Length of member 1 (m)
    L2 = 10 # Length of member 2 (m)
    L3 = 10 # Length of member 3 (m)
    E = 200e9 # Young's Modulus (Pa) (for steel)
    rho = 7800 # Density of steel (kg/m^3)

    # Calculate the weight of the truss (total mass * gravity)
    mass = (rho * A1 * L1 + rho * A2 * L2 + rho * A3 * L3) # in kg
    weight = mass * 9.81 # in Newtons

    return weight

# Constraint functions: Stress and deflection
# For simplicity, assume simple linear elastic behavior and ideal conditions

def stress_constraint(x):
    # Example stress limit (simplified)
    sigma_max = 250e6 # Maximum allowable stress (Pa) for steel
    A1, A2, A3 = x
    F1 = 10000 # Load on member 1 (N)
    F2 = 10000 # Load on member 2 (N)
    F3 = 10000 # Load on member 3 (N)

    stress_1 = F1 / A1 # Stress in member 1
    stress_2 = F2 / A2 # Stress in member 2
    stress_3 = F3 / A3 # Stress in member 3

    # Return violation if any member exceeds allowable stress
    return max(0, stress_1 - sigma_max), max(0, stress_2 - sigma_max), max(0, stress_3 - sigma_max)

def deflection_constraint(x):
    # Example deflection limit (simplified)
    delta_max = 0.01 # Maximum allowable deflection (m)
    A1, A2, A3 = x
    F1 = 10000 # Load on member 1 (N)
    F2 = 10000 # Load on member 2 (N)
    F3 = 10000 # Load on member 3 (N)
    L1 = 10 # Length of member 1 (m)
    L2 = 10 # Length of member 2 (m)
    L3 = 10 # Length of member 3 (m)
    E = 200e9 # Young's Modulus (Pa)

    # Simplified deflection calculation (linear approximation)
    delta_1 = (F1 * L1**3) / (3 * E * A1) # Deflection in member 1
    delta_2 = (F2 * L2**3) / (3 * E * A2) # Deflection in member 2
    delta_3 = (F3 * L3**3) / (3 * E * A3) # Deflection in member 3

    # Return violation if any member exceeds allowable deflection
    return max(0, delta_1 - delta_max), max(0, delta_2 - delta_max), max(0, delta_3 - delta_max)

# Grey Wolf Optimizer class
class GreyWolfOptimizer:
    def __init__(self, fitness_func, constraints, dim, lower_bound, upper_bound, num_wolves=30, max_iter=100):
        self.fitness_func = fitness_func # Fitness function
        self.constraints = constraints # List of constraint functions
        self.dim = dim # Number of dimensions (variables to optimize)
        self.lower_bound = lower_bound # Lower bound for the design variables
        self.upper_bound = upper_bound # Upper bound for the design variables
        self.num_wolves = num_wolves # Number of wolves

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self.num_wolves = num_wolves # Number of wolves
self.max_iter = max_iter # Maximum number of iterations

# Initialize positions of wolves
self.wolves = np.random.uniform(low=self.lower_bound, high=self.upper_bound, size=(self.num_wolves, self.c
self.alpha_pos = np.zeros(self.dim) # Position of alpha wolf
self.beta_pos = np.zeros(self.dim) # Position of beta wolf
self.delta_pos = np.zeros(self.dim) # Position of delta wolf
self.alpha_score = float("inf") # Fitness of alpha wolf
self.beta_score = float("inf") # Fitness of beta wolf
self.delta_score = float("inf") # Fitness of delta wolf

def update_positions(self, a):
    # Update the positions of wolves based on alpha, beta, delta
    for i in range(self.num_wolves):
        A1 = 2 * a * np.random.rand(self.dim) - a
        C1 = 2 * np.random.rand(self.dim)
        D_alpha = np.abs(C1 * self.alpha_pos - self.wolves[i])
        X1 = self.alpha_pos - A1 * D_alpha

        A2 = 2 * a * np.random.rand(self.dim) - a
        C2 = 2 * np.random.rand(self.dim)
        D_beta = np.abs(C2 * self.beta_pos - self.wolves[i])
        X2 = self.beta_pos - A2 * D_beta

        A3 = 2 * a * np.random.rand(self.dim) - a
        C3 = 2 * np.random.rand(self.dim)
        D_delta = np.abs(C3 * self.delta_pos - self.wolves[i])
        X3 = self.delta_pos - A3 * D_delta

        # Update wolf's position
        self.wolves[i] = (X1 + X2 + X3) / 3
        # Ensure wolves stay within the search space
        self.wolves[i] = np.clip(self.wolves[i], self.lower_bound, self.upper_bound)

def optimize(self):
    for t in range(self.max_iter):
        a = 2 - t * (2 / self.max_iter)

        # Evaluate fitness for each wolf
        for i in range(self.num_wolves):
            fitness_value = self.fitness_func(self.wolves[i])

            # Check for constraint violations (penalty approach)
            stress_penalty = sum(self.constraints[0](self.wolves[i]))
            deflection_penalty = sum(self.constraints[1](self.wolves[i]))
            total_penalty = stress_penalty + deflection_penalty

            # Total fitness value with penalties
            fitness_value += total_penalty

            # Update alpha, beta, and delta wolves
            if fitness_value < self.alpha_score:
                self.alpha_score = fitness_value
                self.alpha_pos = self.wolves[i].copy()
            elif fitness_value < self.beta_score:
                self.beta_score = fitness_value
                self.beta_pos = self.wolves[i].copy()
            elif fitness_value < self.delta_score:
                self.delta_score = fitness_value
                self.delta_pos = self.wolves[i].copy()

        # Update wolves' positions
        self.update_positions(a)

        # Print the progress
        print(f"Iteration {t+1}/{self.max_iter}, Best fitness = {self.alpha_score}")

    return self.alpha_pos, self.alpha_score

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# Parameters for the optimization problem
dim = 3 # Three members in the truss
lower_bound = 1e-4 # Lower bound for the cross-sectional areas
upper_bound = 0.5 # Upper bound for the cross-sectional areas
num_wolves = 30 # Number of wolves
max_iter = 100 # Maximum number of iterations

# Initialize and run the Grey Wolf Optimizer
gwo = GreyWolfOptimizer(fitness_func=fitness, constraints=[stress_constraint, deflection_constraint], dim=dim, low
best_position, best_fitness = gwo.optimize())

# Output the result
print(f"Optimal Cross-sectional Areas: {best_position}")
print(f"Minimum Weight: {best_fitness} N")
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Iteration 1/100, Best fitness = 124608.13687813526
Iteration 2/100, Best fitness = 72804.98567007676
Iteration 3/100, Best fitness = 64316.09064478929
Iteration 4/100, Best fitness = 1914.2302890130575
Iteration 5/100, Best fitness = 230.02400000000003
Iteration 6/100, Best fitness = 230.02400000000003
Iteration 7/100, Best fitness = 230.02400000000003
Iteration 8/100, Best fitness = 230.02400000000003
Iteration 9/100, Best fitness = 230.02400000000003
Iteration 10/100, Best fitness = 230.02400000000003
Iteration 11/100, Best fitness = 230.02400000000003
Iteration 12/100, Best fitness = 230.02400000000003
Iteration 13/100, Best fitness = 230.02400000000003
Iteration 14/100, Best fitness = 230.02400000000003
Iteration 15/100, Best fitness = 230.02400000000003
Iteration 16/100, Best fitness = 230.02400000000003
Iteration 17/100, Best fitness = 230.02400000000003
Iteration 18/100, Best fitness = 230.02400000000003
Iteration 19/100, Best fitness = 230.02400000000003
Iteration 20/100, Best fitness = 230.02400000000003
Iteration 21/100, Best fitness = 230.02400000000003
Iteration 22/100, Best fitness = 230.02400000000003
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Iteration 24/100, Best fitness = 230.02400000000003
Iteration 25/100, Best fitness = 230.02400000000003
Iteration 26/100, Best fitness = 230.02400000000003
Iteration 27/100, Best fitness = 230.02400000000003
Iteration 28/100, Best fitness = 230.02400000000003
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Iteration 56/100, Best fitness = 230.02400000000003
Iteration 57/100, Best fitness = 230.02400000000003
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