EDUCATION

- o PhD in Informatics, Vilnius University, Lithuania, 2016.
- o MSc in Informatics, Vilnius University, Lithuania, 2011.
- o BSc in Software Engineering, Vilnius University, Lithuania, 2009.

EXPERIENCE

- o Vilnius University, Software Engineering Faculty, Assistant Professor, 2017 Present.
- o Monet Lt, UAB, Vilnius, Lithuania, Researcher, Lead Developer, 2018 Present.
- Space Science and Technology Institute, Vilnius, Lithuania, Junior Researcher, 2018 2019.
- Vilnius University, Software Engineering Faculty, Lecturer, 2011 2017.
- o Magma Solutions UAB, Vilnius, Lithuania, Engineer Developer, 2017.
- o Vilnius University, Informatics Faculty, Junior Researcher, 2013 2015.
- o VsI Inovatyvus inzineriniai projektai, Vilnius, Lithuania, Lead Developer, 2014 2015.
- o UAB Teltonika, Vilnius, Lithuania, Embedded Developer, 2009 2011.
- AB Lietuvos Energija, Vilnius, Lithuania, Developer, 2007 2008.
- o UAB Prototechnikos Iranga, Vilnius, Lithuania, Developer, 2006 2007.

LANGUAGES

- o Lithuanian, native
- English, good understanding speaking and writing.

Projects

- o Hybrid UAV Kolibris, KAM-01-08, 2016.
- High-dimensionality and small data size problems in classification of biomedical and financial data, MIP-13011, 2013 - 2015.
- o Lituanica SAT-1, 2012 2014.

Publications

- Valaitis, V. et al Minimizing Hexapod Robot Foot Deviations Using Multilayer Perceptron. International Journal of Advanced Robotic Systems. Vol. 12, 2015.
- Valaitis, V. et al Piezoelectric Force Sensors for Hexapod Transportation Platform. Transport: Special Issue on Smart and Sustainable Transport. Vol. 30, No. 3, 2015.
- Valaitis, V. et al A Price We Pay for Inexact Dimensionality Reduction. Bioinformatics and Biomedical Engineering. p. 289-300, 2015.
- Valaitis, V. Learning Inverse Kinematics Problem in Changing Task Environment. The 12th Scandinavian AI conference. Vol 257, p. 299-302, 2013.

Conferences

- Numerical Computations: Theory and Algorithms, Crotone, Italy, 2019. Learning Aerial Image Similarity using Triplet Networks.
- The 3rd IEEE Workshop on Bio-Inspired Signal and Image Processing, Vilnius, Lithuania, 2014. Multi-agent Neural Network Approach on Inverse Kinematics Problem in Changing Task Environment.
- Numerical Computations: Theory and Algorithms, Falerna, Italy, 2013. Learning Motion Patterns of Robotic Arm.
- The 12th Scandinavian AI conference, Aalborg, Denmark, 2013. Learning Inverse Kinematics Problem in Changing Task Environment.