Lab 9: Pulse Modulation

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Introduction:

The goal of this lab was to configure the clock, PWM so that input from pinouts changes the brightness of a lightbulb .

Procedure:

Download the base code from Canvas. Then configure GPIO 12 for alternate function 0. Then configure the PWM. Configure PWM0 from 0 to 100% duty cycle. Wire the pinouts to the breadboard, switches, and led.

Code:

```
.global main
main: stmfd sp!,{r4,lr}
     @@ map the devices into our address space
     @@ Load the Base Address of the GPIO device
    ldr r4.-gpiobase @ load pointer to the address of the gpio device ldr r4.[r4] @ load address of the gpio device
     60 Set the direction bits for the pins
     mov r0.#17
    bl gpio_dir_output
     mov r0.#18
    bl gpio_dir_output
     mov r0,#3
    bl gpio_dir_output
     mov r0.#27
    bl gpio_dir_output
mov r0.#22
    bl gpio_dir_input
mov r0.#23
    bl gpio_dir_input
mov r0,#24
    bl gpio_dir_input
```

pins 22,23,24 set to input for the switches

```
@@ Configure pull-up resistors for input pins
mov r0.#22
mov r1.#2
bl set_pud

mov r0.#23
mov r1.#2
bl set_pud

mov r0.#24
mov r1.#2
bl set_pud

@@ set count to 0 for button presses
mov r5. #0
```

Given Base code

```
@@ set up GPI0 12 for alternate function 0 using gpio_alt_func
mov r0. #12
mov r1. #4
bl gpio_alt_func

@ Set up PVM clock
@@ disable pvm using pvmbase
ldr r0. =pvmbase
ldr r1.[r0]
mov r2. #0
str r2. [r1. #PVM_CTL]
@@ Derive PVM clock direct from X-tal thus any system
@@ auto-slow-down-clock-to-save-power does not effect it
@@ The values below depends on the X-tal frequency!

@@ disable pvm clock using clkbase
ldr r2. =clkbase
ldr r3.[r2]
bic r4.r3, #0xffffffef
cmp r4. #0
addeq r4. r4. #0x10
str r4. [r3]
@@ wait for busy flag to clear
```

Setting up GPIO 12 for output and alternate function 0, setting up PWM

```
busywait:

@@ configure and start the clock
ldr r0. =PVMCLK_CNTL
ldr r1. =clkbase
ldr r2. [r1. r0]
bic r2. #0xffffffbf
lsr r2. #6
cmp r2. #0
bne busywait

@@ wait for busy flag to clear

@@starting clock now?
ldr r1. =clkbase
ldr r2. [r1]
ldr r3. =0x5a0c0000 @the password?
str r3. [r2. #PVMCLK_DIV]
ldr r1. =clkbase
ldr r2. [r1]
ldr r3. =0x5a0c00011
str r3. [r2. #PVMCLK_CNTL]
```

First Busy wait,

```
| busywait2:
| Idr r0, =PMMCLK_CNTL | Idr r1. =clkbase | Idr r2, [r1, r0] | Idr r2. #0xffffffbf | Isr r2. #6 | Idr r3. #6 | Idr r4. | Idr r5. #6 | I
```

Second Busy wait

```
loop:
   @@ Read GPIO Level Register O (GPLEVO) when a button is pressed
   mov r0,r4
   bl buttonpress
           r2,#0
                       @ Clear update flag
   @@ check bits 22,23,24
   80 Check input on GPIO 22
   tst r0,#(1<<22)
   moveq r2.#1
addeq r5.r5.#1
                        @ Set update flag
                      @ Increment count
   cmp r5,#7
   movgt r5.#7
    8@ Check input on GPIO 23
    tst r0.#(1<<23)
   moveq r2.#1
moveq r5,#0
                        @ Set update flag
                        @ Reset count
    @@ Check input on GPIO 24
    tst r0.#(1<<24)
   moveq r2,#1
subeq r5,r5,#1
                        @ Set update flag
                      @ Decrement count
    cmp r5,#0
   movlt r5.#0
   60 Skip printing and updating PNM if count did not change cmp r2.#1
   bne endloop
```

Setting up PWM0

```
@@ Print current count
    ldr r0.=cntfmt
    mov r1, r5
    bl printf
    @@ Update PWM duty cycle
    rsb r0, r5,#7
    ls1 r0.r0.#4
    ldr r2.-pwmbase
ldr r2.[r2]
    str r0,[r2,#PWM_DAT1]
waitrelease:
    ldr r0.[r4,#GPLEV0]
    and r0.r0.#((1<<22)|(1<<23)|(1<<24))
    cmp r0.#((1<<22)|(1<<23)|(1<<24))
    bne waitrelease
    20 Button has been released - do debounce count
    mov r2,#(1<<20)
debounc2:
    adds
            r2, r2,#-1
    bp1 debounc2
    ldr r0.[r4,#GPLEV0]
    and r0.r0.#((1<<22)|(1<<23)|(1<<24))
    cmp r0.#((1<<22)|(1<<23)|(1<<24))
    bne waitrelease
endloop:
    b loop
```

Setting up the duty cycle 0x0 = 0%, up to 0x70 = 100%

Results:

```
Successfully opened /dev/mem
Mapped GPIO device at 0x3F200000
Mapped PWM device at 0x3F100000
Mapped PPIDS device at 0x3F100000
Mapped SPIO device at 0x3F204000
Mapped BSCO device at 0x3F205000
Mapped BSCI device at 0x3F804000
Mapped ST device at 0x3F804000
Mapped ST device at 0x3F003000
register offset is 00000008 and shift is 6
register offset is 00000008 and shift is 9
register offset is 00000008 and shift is 12
register offset is 00000004 and shift is 6
```

Conclusion:

The code did not work in the end, this was due to an infinite loop in busy wait.