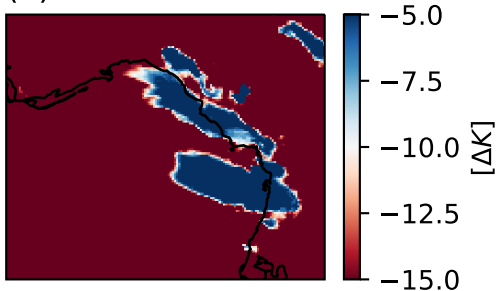


(a) WVD – SWD



(b) Edge detection

