

Automated Probabilistic Reasoning Via Variational Inference

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Bayesian Reasoning – Challenges

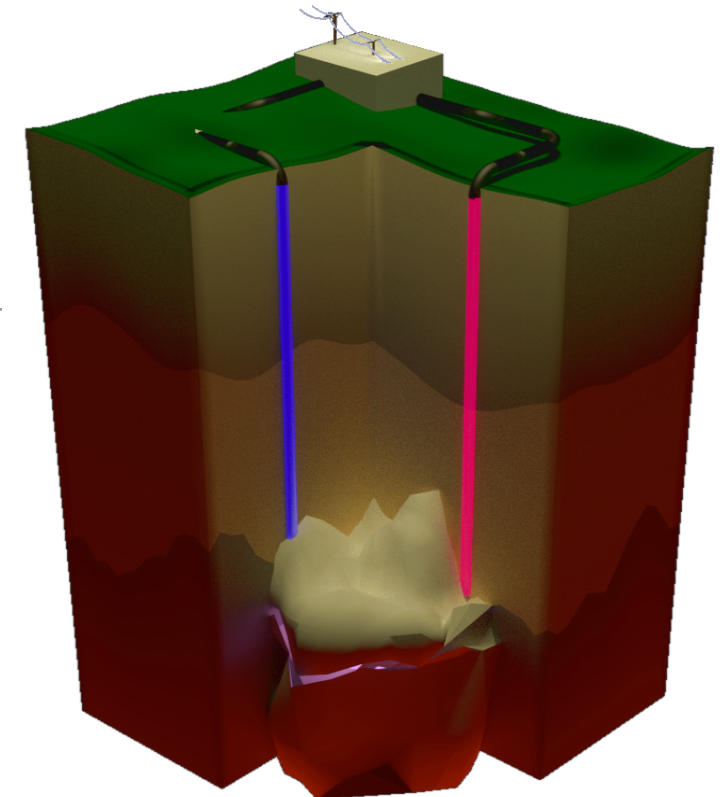
Prior over geology and
rock properties

Forward model's
likelihood

$$p(\mathbf{f}|\mathbf{y}) = \frac{p(\mathbf{f})p(\mathbf{y}|\mathbf{f})}{\int p(\mathbf{f})p(\mathbf{y}|\mathbf{f})d\mathbf{f}} \leftarrow \text{Hard bit}$$

↑
Posterior
geological model

- General likelihood models
(non-linear fwd models)
- Large datasets



\$20 Million



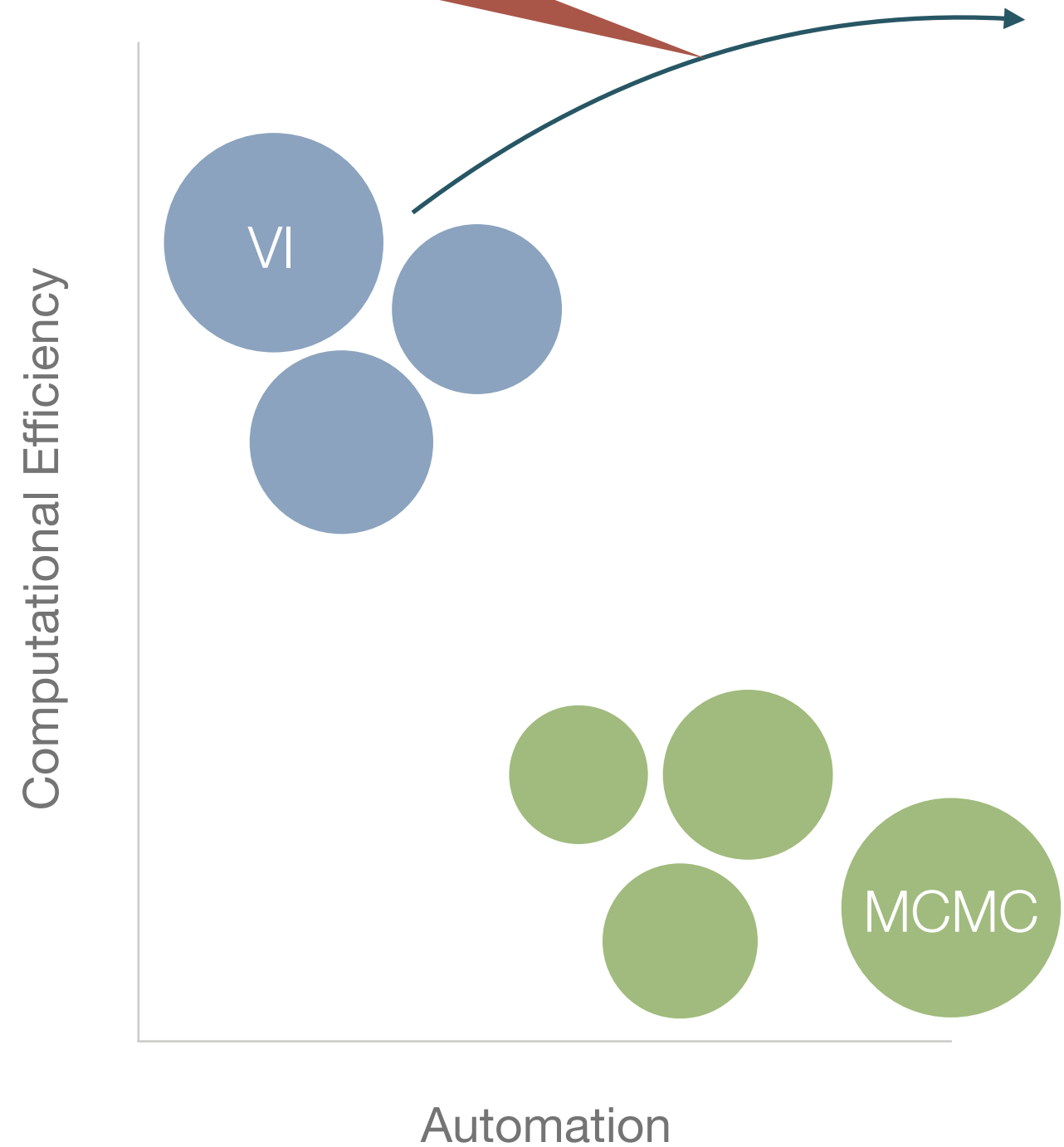
Surveys and
explorations

Goal: Build generic yet practical inference tools for practitioners and researchers

● Deterministic
● Stochastic

Automated Probabilistic Reasoning

- Other dimensions
 - Accuracy
 - Convergence



Gaussian Process Priors

Notoriously unscalable!

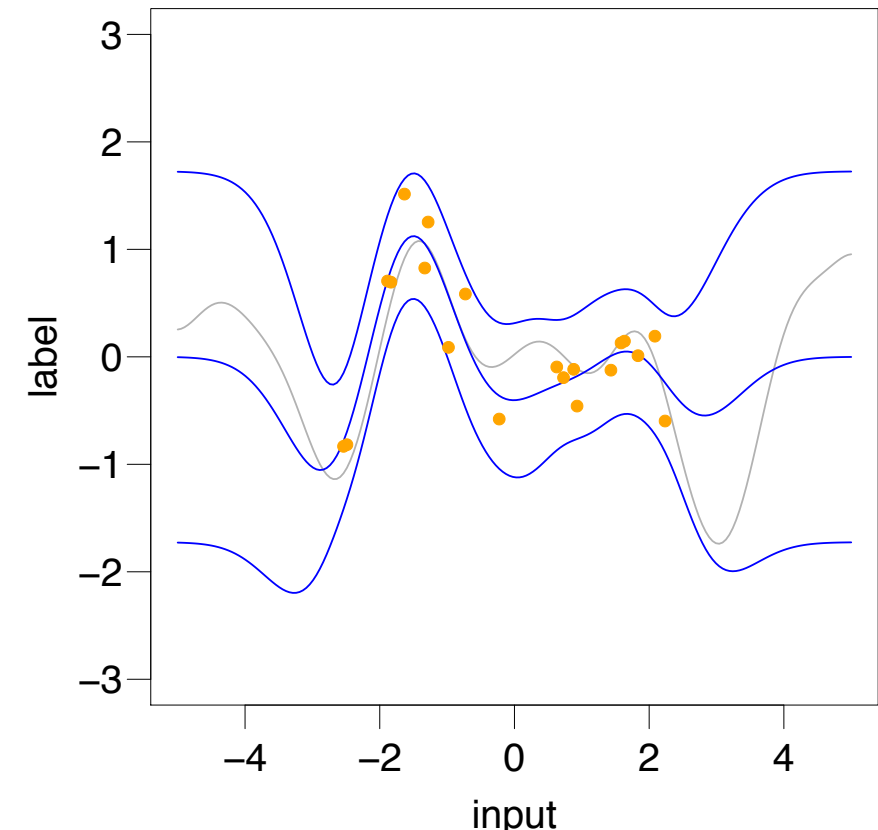
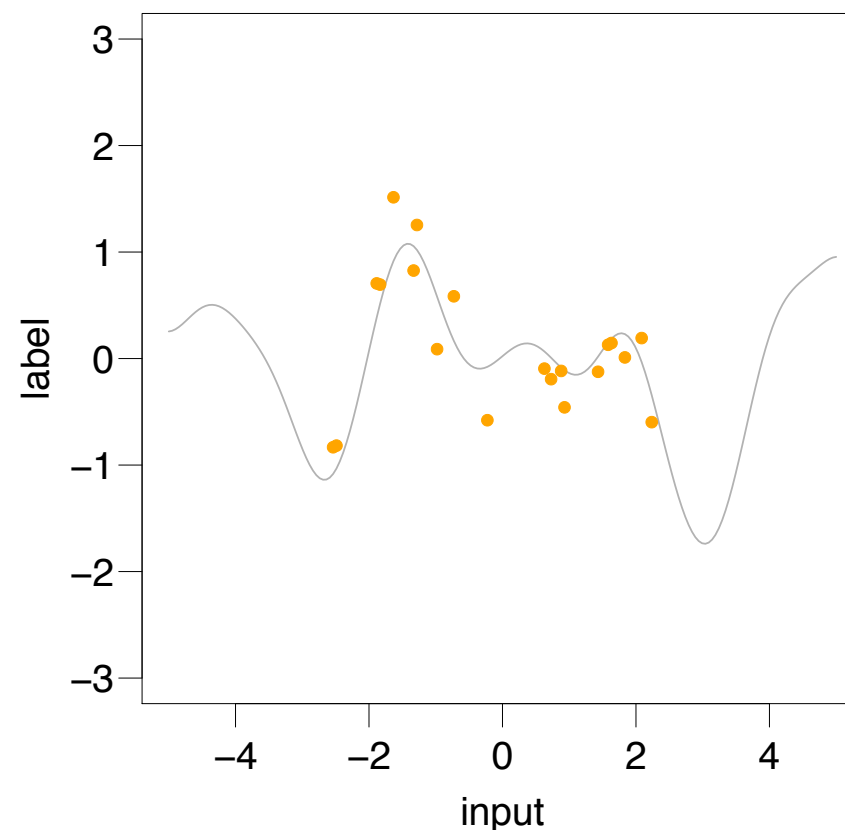
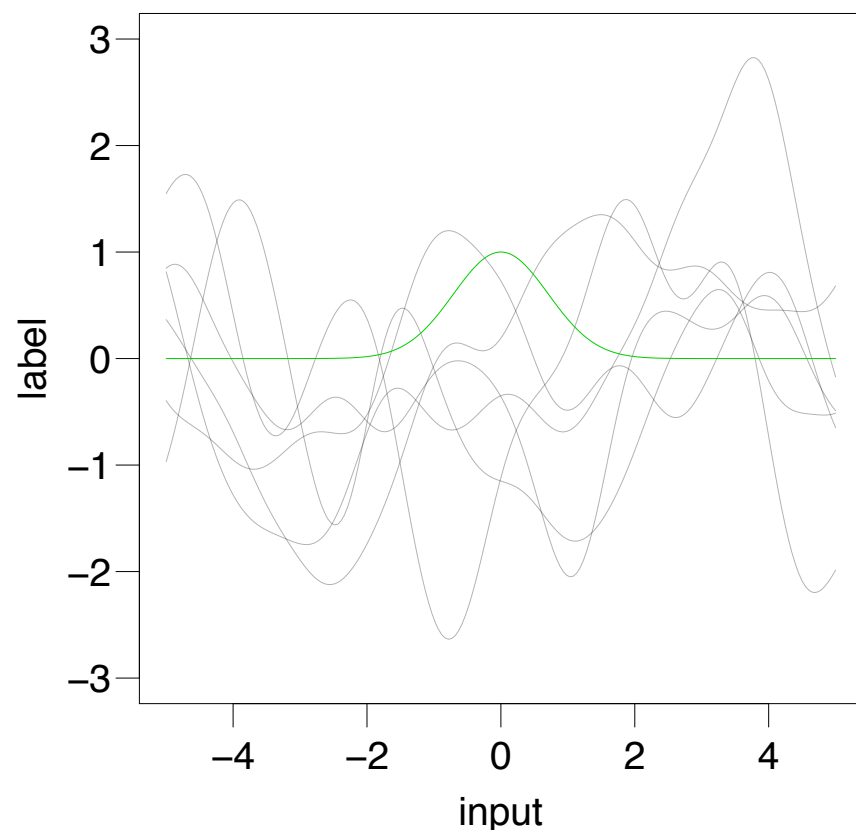
- Distribution over functions
- $f(\mathbf{x}_1), f(\mathbf{x}_2), \dots, f(\mathbf{x}_N)$ follow a joint Gaussian distribution
 - Example: density field

Mean function

Covariance function

$$f(\mathbf{x}) \sim \mathcal{GP}(\mu(\mathbf{x}), \kappa(\mathbf{x}, \mathbf{x}'; \boldsymbol{\theta}))$$

Hyper-parameters



Latent Gaussian Process Models (LGPMs)

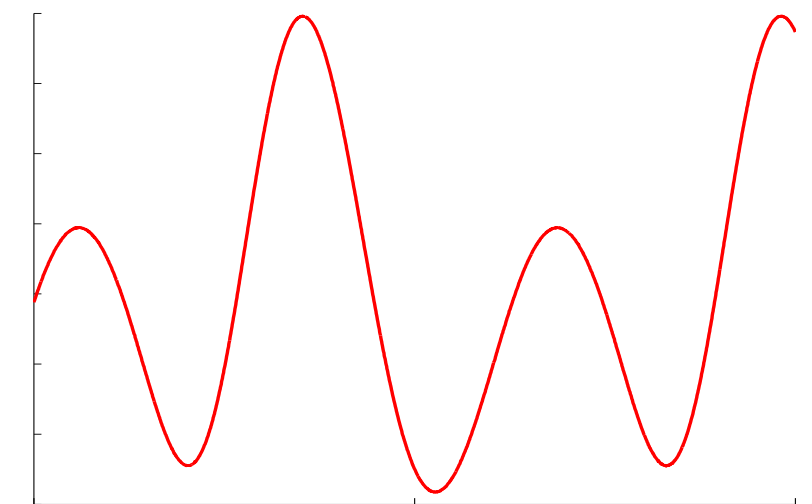
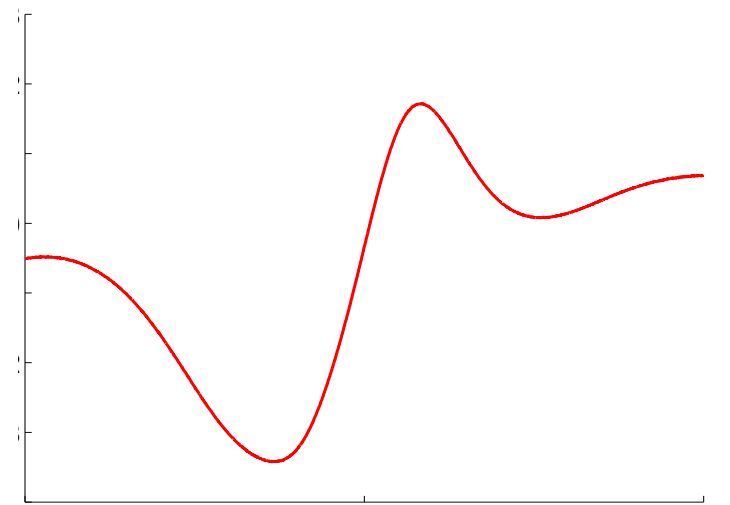
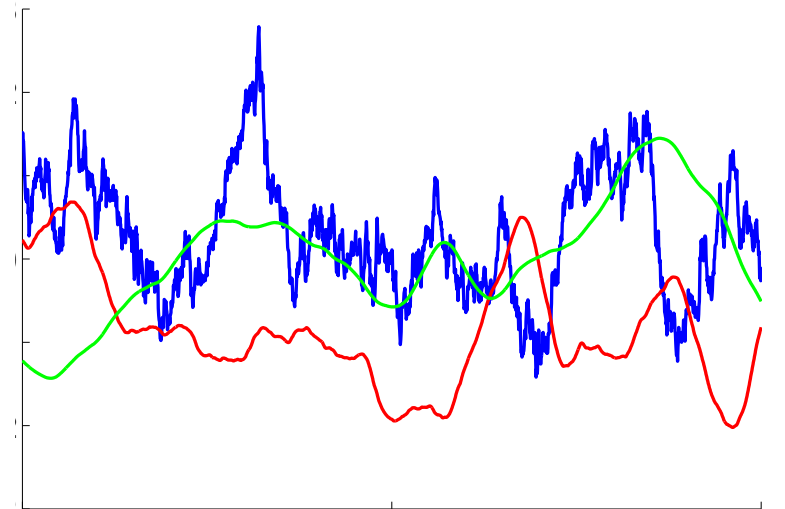
- Supervised learning: $\mathcal{D} = \{\mathbf{x}_n, \mathbf{y}_n\}_{n=1}^N$
- Factorised prior over Q latent functions

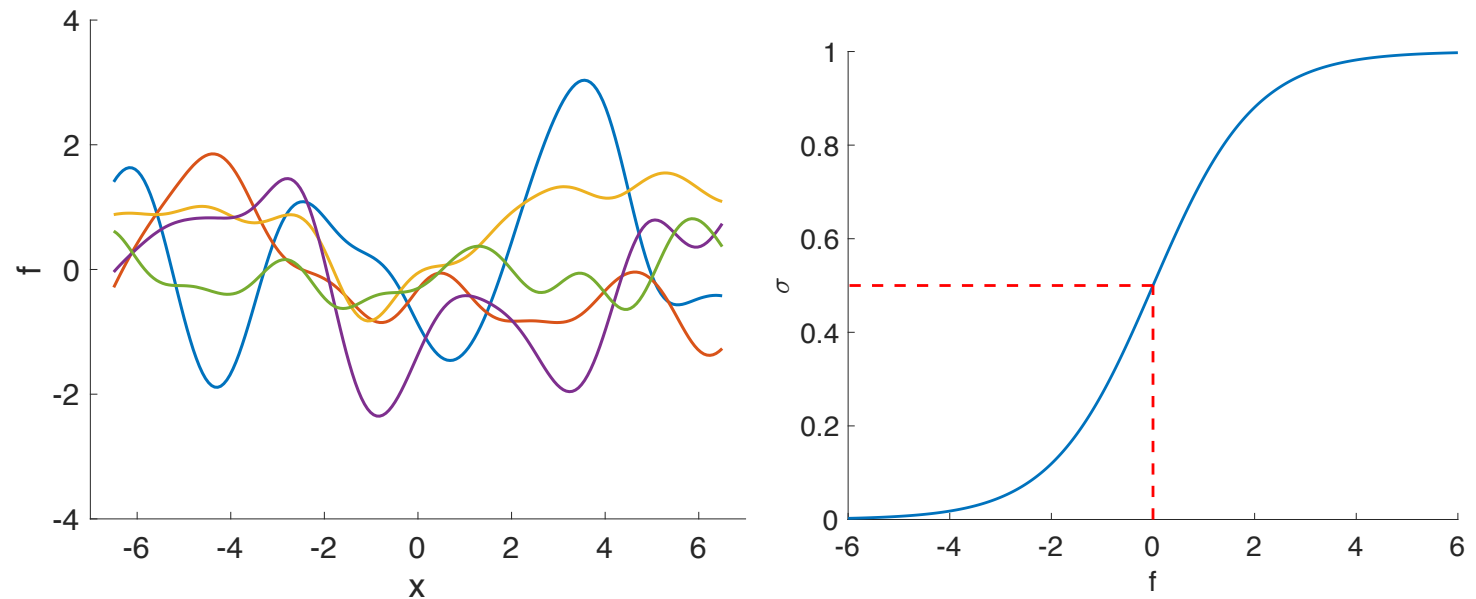
$$f_j \sim \mathcal{GP}(0, \kappa_j(\cdot, \cdot))$$

$$p(\mathbf{f}|\boldsymbol{\theta}) = \prod_{j=1}^Q \mathcal{N}(\mathbf{f}_{\cdot j}; \mathbf{0}, \mathbf{K}_j)$$

- Factorised likelihood over observations

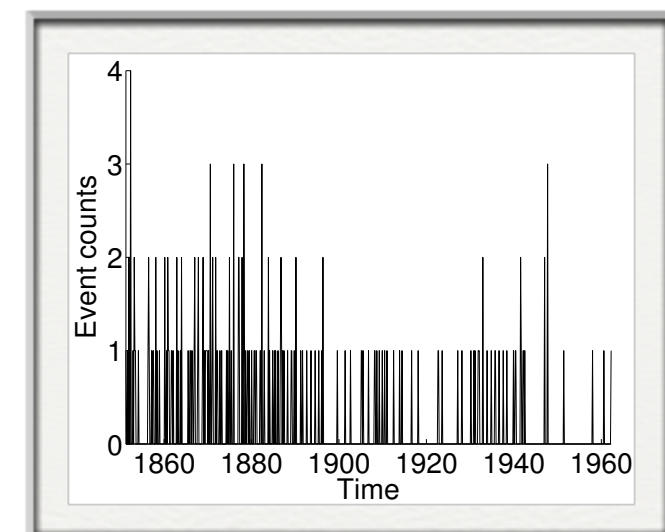
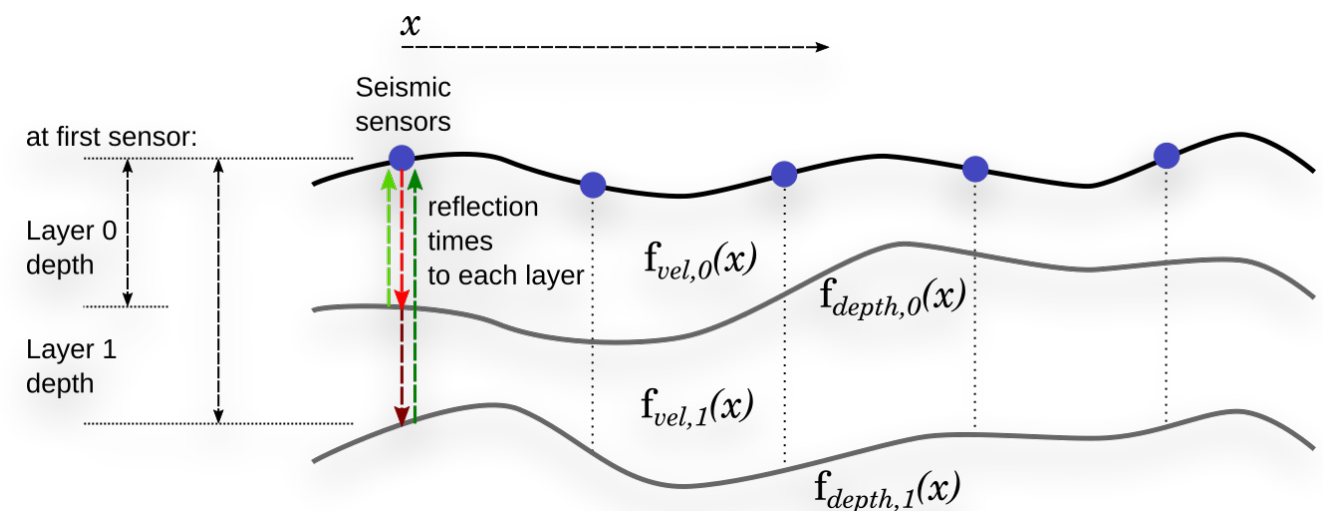
$$p(\mathbf{y}|\mathbf{f}, \boldsymbol{\phi}) = \prod_{n=1}^N p(\mathbf{y}_n|\mathbf{f}_{n\cdot}, \boldsymbol{\phi})$$





Examples of LGPMs

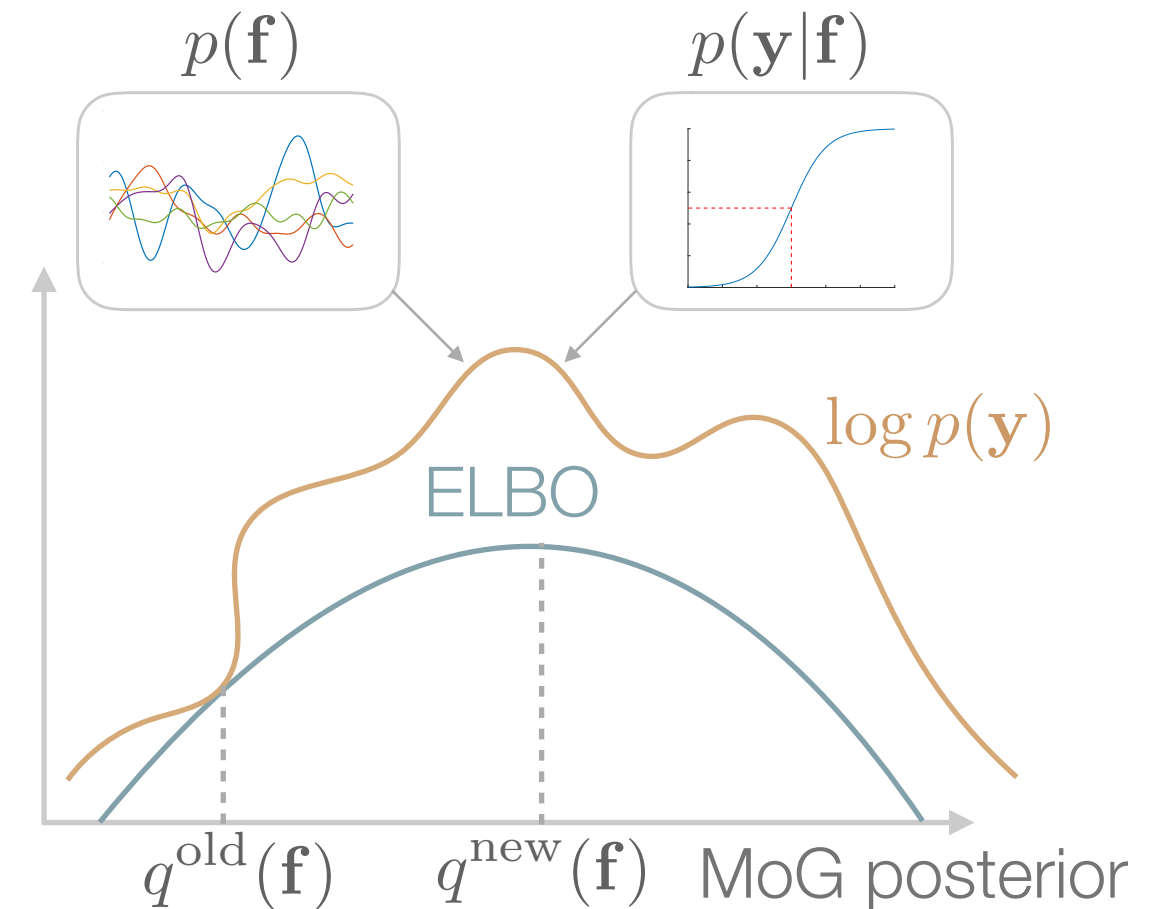
- Multi-class classification
 - Q classes, softmax likelihood
- Multi-output regression
- Inversion problems
- LGCPs for count data
- Access to 'black-box' likelihood



Solution 1.0: Automated VI for LGPMs

Nguyen and Bonilla (NIPS, 2014)

- $\text{ELBO} = -\text{KL} + \text{ELL}$
- KL
 - Analytical lower bound
 - Exact gradients
- ELL
 - Samples from univariate Gaussians
 - No explicit gradients required

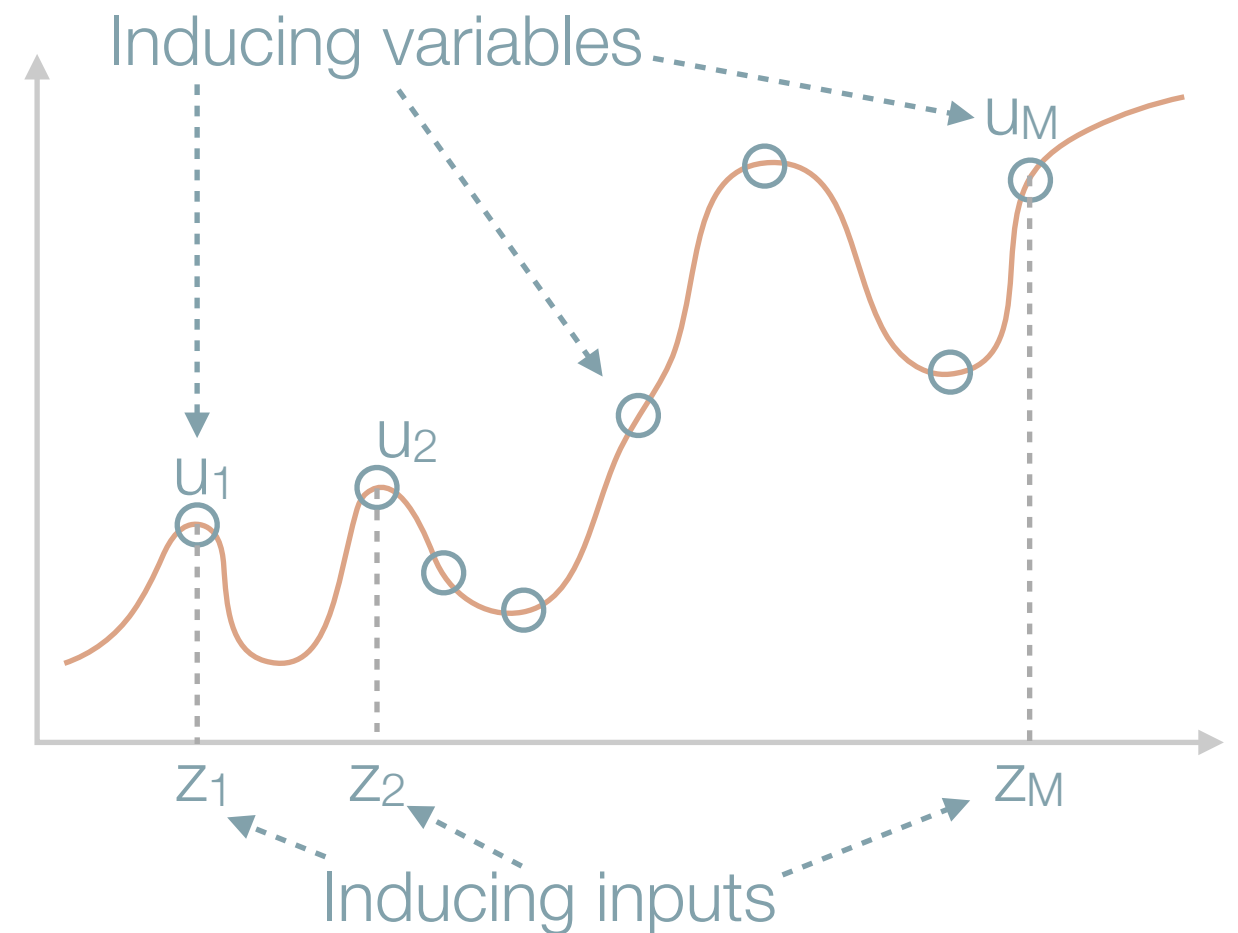


- ★ Efficient parameterisation
- ★ As good as hand-coded solutions
- ★ Orders of magnitude faster than MCMC

Solution 1.1: SAVIGP

Dezfouli and Bonilla (NIPS, 2015)

- Scalability through “sparsification”: $M \ll N$
- Statistical efficiency
- Efficient parameterisation
- Control variates

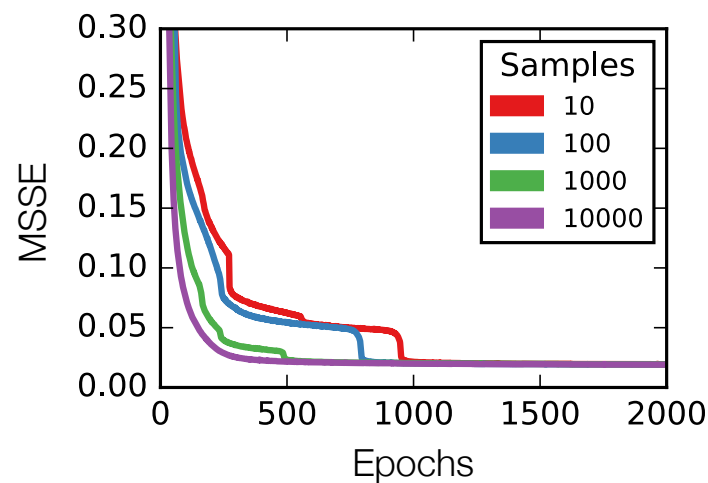


Large-scale inference for GP priors and
general black-box likelihoods

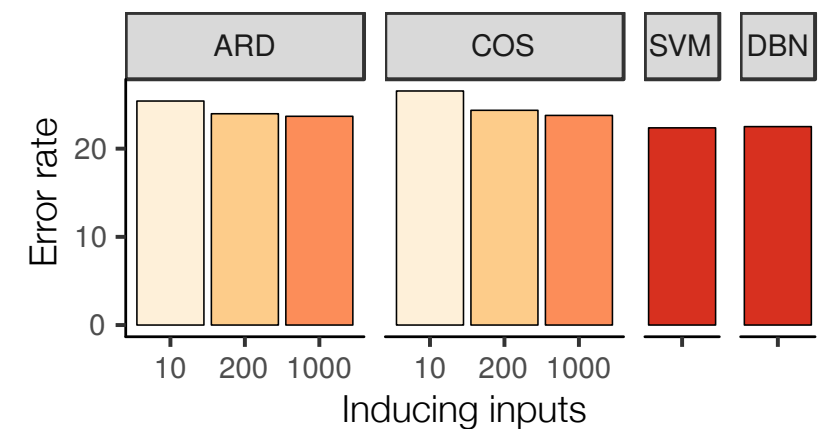
Solution 1.2: AutoGP

Krauth, Bonilla, Cutajar and Filippone (UAI, 2017)

- ★ Breaks error-barrier on MNIST for GP models
- ★ Unprecedented scale



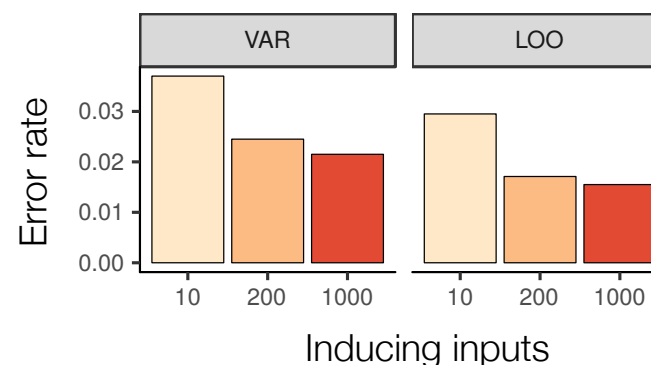
Scalability & efficient computation
Low-variance gradient estimates



Well-targeted objective functions
Leave-one-out hyper-parameter learning

The holy trinity of machine learning

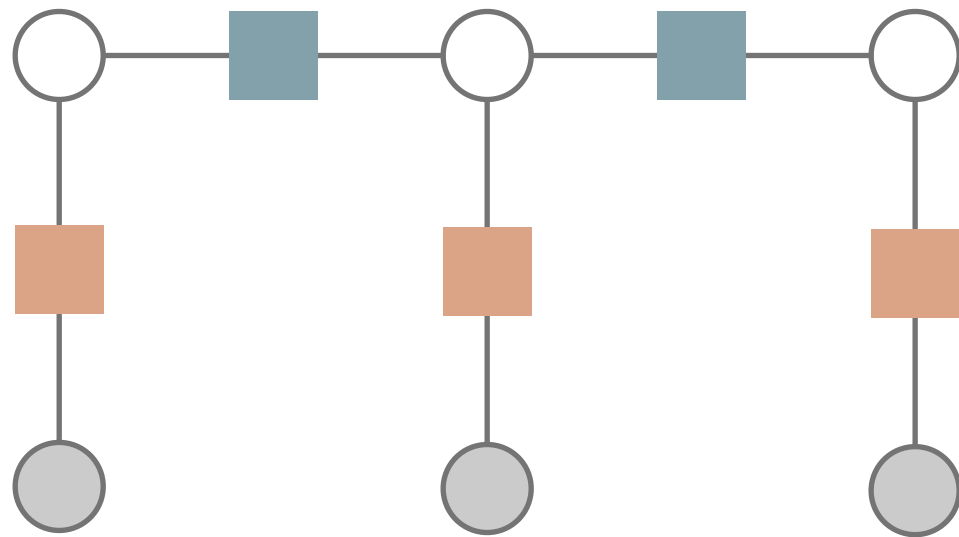
Representational power
Flexible kernels



Generalisations to More Complex Settings

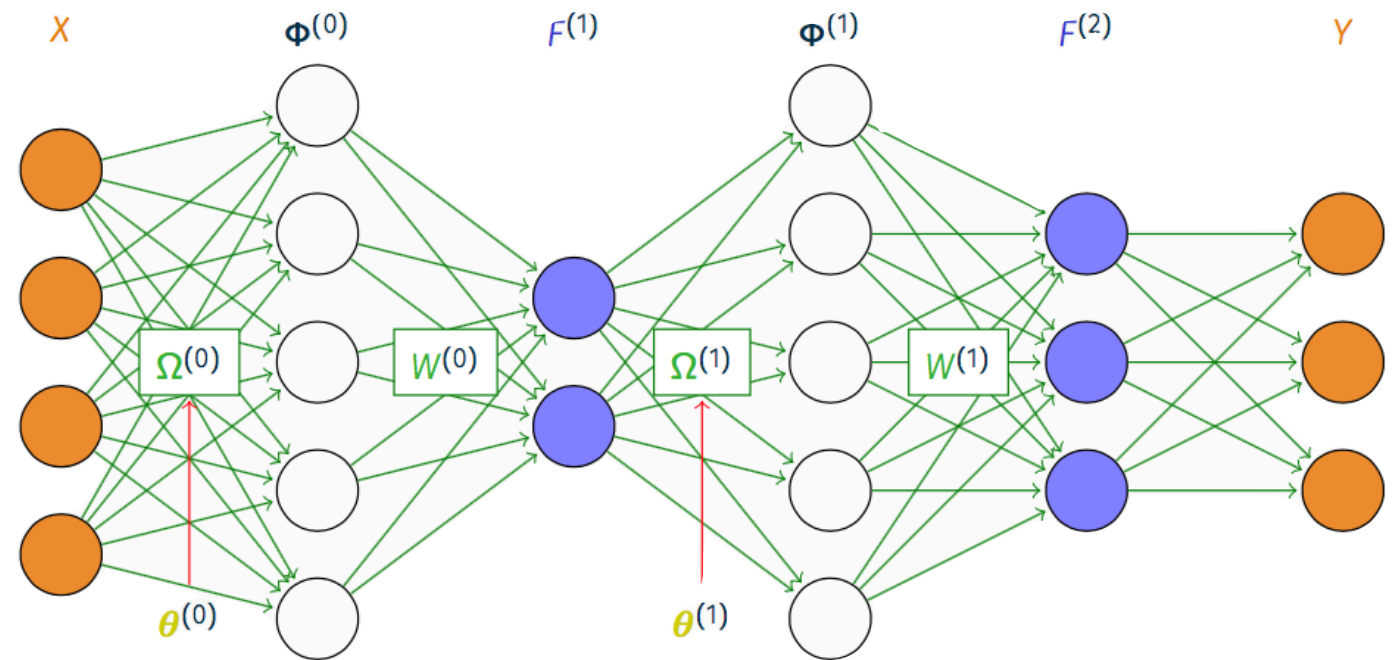
Structured prediction

(Galliani, Dezfouli, Bonilla and Quadrianto, AISTATS, 2017)

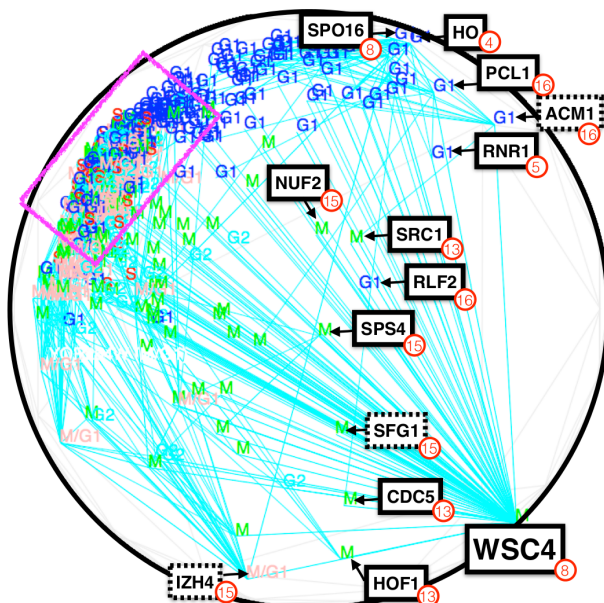


Deep Gaussian processes

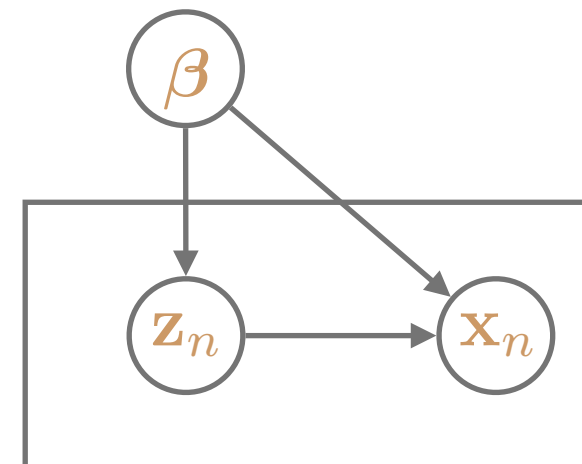
(Cutajar, Bonilla, Michardi and Filippone, ICML, 2017)



Network Structure Discovery



Implicit models



$$\mathbf{z}_n = g_z(\beta)$$

$$\mathbf{x}_n = g_x(\mathbf{z}_n; \beta)$$

$$q(\mathbf{Z}, \beta | \mathbf{X}) = g(\mathbf{Z}, \beta)$$

Summary & Conclusions

- General framework for GP priors and non-linear likelihoods
- Scalable automated variational inference
- AutoGP
- Generalisations

