Homework 8

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Exercise 4.3

(a)

Deterministic noise will go up because f becomes more complex for \mathcal{H} to model.

There's a higher tendency to overfit because overfitting increases as target comlexity increases.

(b)

Deterministic noise will go up because h^* from a simpler \mathcal{H} performs at most as well as h^* from a more complex \mathcal{H} since the simpler \mathcal{H} is a subset of the more complex \mathcal{H} .

There's a lower tendency to overfit because a simpler \mathcal{H} is less likely to be led astray by noise.

Exercise 4.5

(a)

Guess $\Gamma = I$

Verify:

$$\begin{aligned} \mathbf{w}^T \Gamma^T \Gamma \mathbf{w} &= \mathbf{w}^T I^T I \mathbf{w} \\ &= \mathbf{w}^T I I \mathbf{w} \\ &= \mathbf{w}^T \mathbf{w} \\ &= \sum_{q=0}^Q w_q^2 \end{aligned}$$

(b)

$$\begin{split} \mathbf{w}^T \Gamma^T \Gamma \mathbf{w} &= (\sum_{q=0}^Q w_q)^2 \\ &= \sum_{i=0}^Q w_i \sum_{j=0}^Q w_j \\ &= (\sum_{j=0}^Q w_j, ..., \sum_{j=0}^Q w_j) \mathbf{w} \\ \mathbf{w}^T \Gamma^T \Gamma &= (\sum_{j=0}^Q w_j, ..., \sum_{j=0}^Q w_j) \\ \forall \text{ column index } i : \mathbf{w}^T (\Gamma^T \Gamma)_i &= \sum_{j=0}^Q w_j \\ &= \mathbf{w}^T \mathbf{1} \text{ where } \mathbf{1} \text{ is the vector of all 1's} \\ \Gamma^T \Gamma &= \begin{pmatrix} 1 & 1 & ... & 1 \\ 1 & 1 & ... & 1 \\ ... & ... & ... & ... \\ 1 & 1 & ... & 1 \end{pmatrix} \text{ of dimeision } (Q+1) \times (Q+1) \end{split}$$

The inner product of any 2 columns of Γ is 1.

$$\Gamma = \begin{pmatrix} \frac{1}{\sqrt{Q+1}} & \frac{1}{\sqrt{Q+1}} & \cdots & \frac{1}{\sqrt{Q+1}} \\ \frac{1}{\sqrt{Q+1}} & \frac{1}{\sqrt{Q+1}} & \cdots & \frac{1}{\sqrt{Q+1}} \\ \cdots & \cdots & \cdots & \cdots \\ \frac{1}{\sqrt{Q+1}} & \frac{1}{\sqrt{Q+1}} & \cdots & \frac{1}{\sqrt{Q+1}} \end{pmatrix}$$

Exercise 4.6

The hard-order constraint is more useful because as the hint says, the norm of \mathbf{w} is irrelevant. If we use the soft-order constraint, then for any \mathbf{w} with $\mathbf{w}^T\mathbf{w} > C$, we can just multiply \mathbf{w} by some positive number α that's small enough to satisfy the constraint but the still perform the same classification because $sign(\mathbf{w}^T\mathbf{x}) = sign(\alpha \mathbf{w}^T\mathbf{x})$ for all \mathbf{x} .

Exercise 4.7

(a)

Given that the validation error $E_{\text{val}}(g^-) = \frac{1}{K} \sum_{(\mathbf{x},y) \in \mathcal{D}_{\text{val}}} e(g^-(\mathbf{x}), y)$, we have

$$\begin{split} \sigma_{\mathrm{val}}^2 &= \mathrm{Var}_{\mathcal{D}_{\mathrm{val}}}[E_{\mathrm{val}}(g^-)] \\ &= \mathrm{Var}_{\mathcal{D}_{\mathrm{val}}}[\frac{1}{K} \sum_{(\mathbf{x},y) \in \mathcal{D}_{\mathrm{val}}} e(g^-(\mathbf{x}),y)] \\ &= \frac{1}{K^2} \mathrm{Var}_{\mathcal{D}_{\mathrm{val}}}[\sum_{(\mathbf{x},y) \in \mathcal{D}_{\mathrm{val}}} e(g^-(\mathbf{x}),y)] \\ &= \frac{1}{K^2} \sum_{i=1}^K \mathrm{Var}_{\mathbf{x}}[e(g^-(\mathbf{x}),y] \qquad (\mathbf{x},y) \in \mathcal{D} \text{ are IID} \\ &= \frac{1}{K} \mathrm{Var}_{\mathbf{x}}[e(g^-(\mathbf{x}),y] \\ &= \frac{1}{K} \sigma^2(g^-) \end{split}$$

(b)

$$\begin{split} \sigma_{\text{val}}^2 &= \frac{1}{K} \text{Var}_{\mathbf{x}}[e(g^-(\mathbf{x}), y)] \\ &= \frac{1}{K} \text{Var}_{\mathbf{x}}[[g^-(\mathbf{x}) \neq y]] \\ &= \boxed{\frac{1}{K} \mathbb{P}[g^-(\mathbf{x}) \neq y](1 - \mathbb{P}[g^-(\mathbf{x}) \neq y])} \end{split}$$

(c)

Lemma: f(x) = x(1-x) has global maximum $\frac{1}{4}$ Proof:

$$\frac{df}{dx} = -2x + 1 = 0$$

$$dxx = \frac{1}{2} \text{ is a critical point}$$

$$\frac{d^2f}{dx^2} = -2 < 0 \implies \text{global max}$$

$$\sigma_{\text{val}}^2 = \frac{1}{K} \mathbb{P}[g^-(\mathbf{x}) \neq y] (1 - \mathbb{P}[g^-(\mathbf{x}) \neq y])$$

$$\leq \frac{1}{K} (\frac{1}{4})$$

$$= \frac{1}{4K}$$

(d)

As the hint says, the squared error is unbounded. y can be as far from $g^{-}(\mathbf{x})$ as possible so there's no uniform upper bound.

(e)

Training with fewer points results in a higher error bar, which results in a higher upper bound for $E_{\text{out}(g^-)}$, which is the mean of $e(g^-(\mathbf{x}), y)$. As the hint says, the variance also increases.

(f)

Given that $E_{\text{out}} \leq E_{\text{val}} + O(\frac{1}{\sqrt{K}})$. As we increase K, $O(\frac{1}{\sqrt{K}})$ will get smaller but E_{val} , whose expected value is E_{out} , will get larger since we train using fewer points, resulting in a larger error bar.

4.8

Yes because it only depends on the model, the training data, and the testing data. No other intervention is done in computing E_m .