## WALEED AHMED

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### **SKILLS**



## **EXPERIENCE**

# Automotive ADAS Software Engineering Intern Oualcomm



math display="block" Jan 2020 - Apr 2020" | High and a second control of the cont

♥ Toronto, ON

- Developed system and application software for an ADAS & autonomous driving platform in C/C++
- Accelerated performance of a computer vision SDK by an average of 20x by leveraging available hardware and software architecture in automotive focused Snapdragon SoCs

# Software Engineering Intern Christie Digital



May 2019 - Aug 2019

- Worked closely with QA and UI/UX designers for user interface development and maintenance to meet release deadlines across a wide variety of platforms using the Qt framework in C++ and QML
- Significantly reduced the effort needed to maintain code health through software architecture redesign and setup of a continuous integration pipeline on a Jenkins build server that included unit tests with 90% code coverage using Google Test

### Video Software Engineering Intern Synaptive Medical



- **♀** Toronto, ON
- Improved visibility of biological tissue during surgical procedures through colour manipulation using **OpenCV** in **C++**
- Facilitated full control of camera settings through a .NET application that served as a frontend interface to a serial communication protocol
- Enabled intuitive usage of a colour manipulation algorithm through a web interface built with JavaScript, HTML, and CSS
- Post-processed image data in Python using Pandas, Numpy, and Matplotlib to analyze colour manipulation
- Used **C#** to integrate image processing algorithms with existing software architecture in a Windows environment

# Industrial Imaging Software Engineering Intern P&P Optica



- ₩ Jan 2018 Apr 2018
- ♥ Waterloo, ON
- Developed a robust image acquisition framework for rapid line scan imaging of an industrial conveyor belt in the food industry
- Implemented image correction algorithms and post-processing for industrial cameras in Python using Numpy, OpenCV, and Matplotlib

## **DESIGN TEAMS**

# Path Planning Core Member WATonomous



**Sep 2019 - Dec 2019** 

 Simulation software development for a level 4 autonomous vehicle competing in the SAE AutoDrive Challenge

# Software Team Lead **UW Robotics**



# Apr 2018 - Aug 2019

qithub.com/uwrobotics/RR2019

- Managed development for a robot that competed in the International Autonomous Robot Racing Competition
- Developed software architecture in ROS and C++ for perception, mapping, and path planning using a stereo camera, IMU, and LiDAR sensor

### **PROJECTS**

#### Synviz

#### **UofTHacks VII (3rd place)**



github.com/w29ahmed/Synviz

- Built an IoT device that could decode spoken text from facial input
- Developed a backend web server in Python using Flask, Google Cloud Storage, OpenCV, and TensorFlow

#### **Agilite**

#### **DeltaHacks V**



github.com/w29ahmed/Agilite

 Built a Python backend using OpenCV and TensorFlow capable of recognizing handwritten text from an agile board

### **EDUCATION**

B.ASc Computer Engineering, Artificial Intelligence Option



#### **University of Waterloo**

- Coursera: Self-Driving Cars Specialization
- Coursera: Machine Learning (Andrew Ng)
- Udemy: Computer Vision