# WALEED AHMED

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### **SKILLS**



### **EXPERIENCE**

# Software Developer Christie Digital



May 2019 - Present

**♥** Kitchener, ON

- Worked closely with QA and UI/UX designers for user interface development and maintenance across a wide variety of platforms using the Qt framework in C++ and QML
- Involved with the software development of a high-profile application to be used to control up to 256 projectors at Dubai Expo in 2020
- Refactored the software architecture of a desktop application to be more modular and wrote extensive unit tests using Google Test for continuous integration purposes setup on a Jenkins build server

### Video Software Developer

#### **Synaptive Medical**



♥ Toronto, ON



- Reverse engineered third party camera color settings to improve visibility of biological tissue during surgical procedures
- Used **C#** for design and integration of image processing algorithms with existing software architecture in a Windows environment
- Post-processed image data in **Python** using data libraries such as **Pandas**, **Numpy**, and **Matplotlib** to analyze colour manipulation
- Utilized OpenCV in C++ to model and apply colour transformations
- Created a Windows desktop application using the .NET framework to serve as a front-end interface for a serial communication protocol that allowed reading/writing of camera settings
- Built a web interface using **JavaScript**, **HTML**, and **CSS** for convenient and intuitive usage of a colour manipulation algorithm

# Industrial Imaging Software Developer P&P Optica



- m Jan 2018 Apr 2018
- ♥ Waterloo, ON
- Developed software for industrial imaging applications on **Linux** machines with **Git** version control in an **Agile** environment
- Implemented image correction algorithms and post-processing for industrial cameras in **Python** using **Numpy**, **OpenCV**, and **Matplotlib**
- Refactored data handling modules for efficient file input/output and wrote unit tests for them in Python using Pytest
- Restructured camera control modules in C/C++ that use the Camera Link serial protocol to interface with the camera for control purposes
- Documented software design decisions and a troubleshooting guide to efficiently debug issues pertaining to image acquisition

# **ACTIVITIES**

# Software Team Lead UW Robotics



Apr 2018 - Present

#### github.com/uwrobotics/RR2019

- Led software team for a mobile racing robot and competed in the International Autonomous Robot Racing Competition
- Developed software architecture using a Linux based framework; ROS (Robot Operating System), for efficient package management and communication between software modules in C++
- Planned and managed software development for an autonomous robot capable of perception, mapping, and path planning using a front-facing stereo camera along with a lidar sensor
- Implemented a lane detection algorithm using OpenCV capable of handling variable lane widths, curvature, and lighting conditions
- Implemented a lightweight traffic light detection algorithm using OpenCV that reduced overhead and false positive rate in comparison to the previous method

## **PROJECTS**

#### **Agilite**

### DeltaHacks V



### github.com/w29ahmed/Agilite

 Built a backend processing pipeline in Python using OpenCV and Tensorflow capable of extracting and recognizing handwritten text from an agile board

### **EDUCATION**

B.ASc Computer Engineering University of Waterloo



**∰** 2022

# **INTERESTS**

Autonomous Vehicles

Computer Vision Image Processing

Deep Learning Gym Reading

Basketball Toronto Raptors