WALEED AHMED

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SKILLS



EXPERIENCE

Autonomous Vehicles Software Engineering Intern Huawei



Sep 2020 - Present

♥ Toronto, ON

• Path planning research and development for a level 4+ system

Automotive ADAS Software Engineering Intern Qualcomm



m Jan 2020 - Apr 2020

♥ Toronto, ON

- Developed system and application software for an ADAS & autonomous driving platform in C/C++
- Accelerated performance of a computer vision SDK by an average of 20x by leveraging available hardware and software architecture in automotive focused Snapdragon SoCs

Software Engineering Intern Christie Digital



May 2019 - Aug 2019

♥ Kitchener, ON

- Worked closely with QA and UI/UX designers for user interface development and maintenance to meet release deadlines across a wide variety of platforms using the Qt framework in C++ and QML
- Significantly reduced the effort needed to maintain code health through software architecture redesign and setup of a continuous integration pipeline on a **Jenkins** build server that included unit tests with **90%** code coverage using **Google Test**

Video Software Engineering Intern Synaptive Medical



♥ Toronto, ON

- Improved visibility of biological tissue during surgical procedures through colour manipulation using C++ (OpenCV) and C#
- Post-processed image data in Python using Pandas, Numpy, and Matplotlib to analyze colour manipulation

Industrial Imaging Software Engineering Intern P&P Optica



Jan 2018 - Apr 2018

♥ Waterloo, ON

- Developed a robust image acquisition framework for rapid line scan imaging of an industrial conveyor belt in the food industry
- Implemented image correction algorithms and post-processing for industrial cameras in Python using Numpy, OpenCV, and Matplotlib

DESIGN TEAMS

Path Planning Core Member WATonomous



Sep 2019 - Dec 2019

• Simulation software development for a level 4 autonomous vehicle competing in the SAE AutoDrive Challenge

Software Team Lead **UW Robotics**



m Apr 2018 - Aug 2019

github.com/uwrobotics/RR2019

- Managed development for a robot that competed in the International Autonomous Robot Racing Competition
- Developed software architecture in ROS and C++ for perception, mapping, and path planning using a stereo camera, IMU, and LiDAR sensor

PROJECTS

Synviz

UofTHacks VII (3rd place)



₩ Jan 2020

github.com/w29ahmed/Synviz

- Built an IoT device that could decode spoken text from facial input
- Developed a backend web server in Python using Flask, Google Cloud Storage, OpenCV, and TensorFlow

Agilite

DeltaHacks V



github.com/w29ahmed/Agilite

 Built a Python backend using OpenCV and TensorFlow capable of recognizing handwritten text from an agile board

EDUCATION

B.ASc Computer Engineering, Artificial Intelligence Option



University of Waterloo

- Coursera: Self-Driving Cars Specialization
- Coursera: Machine Learning (Andrew Ng)
- Udemy: Computer Vision