WALEED AHMED

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SKILLS



EXPERIENCE

Software Developer Christie Digital

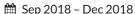


May 2019 - Present

♥ Kitchener, ON

- Worked closely with QA and UI/UX designers for user interface development and maintenance across a wide variety of platforms using the Qt framework in C++ and QML
- Involved with the software development of a high-profile application to be used to control up to 256 projectors at Dubai Expo in 2020
- Refactored the software architecture of a desktop application to be more modular and wrote extensive unit tests using Google Test for continuous integration purposes setup on a Jenkins build server

Video Software Developer Synaptive Medical



♥ Toronto, ON



- Reverse engineered third party camera color settings to improve visibility of biological tissue during surgical procedures
- Used **C#** for design and integration of image processing algorithms with existing software architecture in a Windows environment
- Post-processed image data in Python using data libraries such as Pandas, Numpy, and Matplotlib to analyze colour manipulation
- Utilized OpenCV in C++ to model and apply colour transformations
- Created a Windows desktop application using the .NET framework to serve as a front-end interface for a serial communication protocol that allowed reading/writing of camera settings
- Built a web interface using **JavaScript**, **HTML**, and **CSS** for convenient and intuitive usage of a colour manipulation algorithm

Industrial Imaging Software Developer P&P Optica



- m Jan 2018 Apr 2018
- ♥ Waterloo, ON
- Developed software for industrial imaging applications on **Linux** machines with **Git** version control in an **Agile** environment
- Implemented image correction algorithms and post-processing for industrial cameras in **Python** using **Numpy**, **OpenCV**, and **Matplotlib**
- Refactored data handling modules for efficient file input/output and wrote unit tests for them in Python using Pytest
- Restructured camera control modules in **C/C++** that use the Camera Link serial protocol to interface with the camera for control purposes
- Documented software design decisions and a troubleshooting guide to efficiently debug issues pertaining to image acquisition

ACTIVITIES

Software Team Lead UW Robotics



Apr 2018 - Present

github.com/uwrobotics/RR2019

- Led the software team for a mobile racing robot and competed in the International Autonomous Robot Racing Competition
- Developed software architecture using a Linux based framework; ROS (Robot Operating System), for efficient package management and communication between software modules in C++
- Planned and managed software development for an autonomous robot capable of perception, mapping, and path planning using a front-facing stereo camera along with a lidar sensor
- Implemented a lane detection algorithm using OpenCV capable of handling variable lane widths, curvature, and lighting conditions
- Implemented a lightweight traffic light detection algorithm using OpenCV that reduced overhead and false positive rate in comparison to the previous method

PROJECTS

Agilite

DeltaHacks V



github.com/w29ahmed/Agilite

 Built a backend processing pipeline in Python using OpenCV and Tensorflow capable of extracting and recognizing handwritten text from an agile board

EDUCATION

B.ASc Computer Engineering University of Waterloo



2022

INTERESTS

Autonomous Vehicles

Computer Vision Image Processing

Deep Learning Gym Reading

Basketball Toronto Raptors