### WALEED AHMED

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#### **SKILLS**



#### **EXPERIENCE**

## Software Developer Christie Digital

**CHKISTIE**®

May 2019 - Present

**♀** Kitchener, ON

- Worked closely with QA and UI/UX designers for user interface development and maintenance to meet release deadlines across a wide variety of platforms using the Qt framework in C++ and QML
- User interface and backend development for a high-profile application that will enable seamless and efficient control of up to 256 projectors to deliver a world-class visual experience at Expo 2020 in Dubai
- Refactored software architecture to be more modular and wrote extensive unit tests using Google Test for continuous integration purposes setup on a Jenkins build server, significantly reducing the effort needed to maintain code health for developers and QA

#### Video Software Developer

#### **Synaptive Medical**

♥ Toronto, ON



- Reverse engineered third party camera colour settings to improve visibility of biological tissue during surgical procedures
- Used **C#** for design and integration of image processing algorithms with existing software architecture in a Windows environment
- Post-processed image data in Python using data libraries such as Pandas. Numpy, and Matplotlib to analyze colour manipulation
- Utilized OpenCV in C++ to model and apply colour transformations
- Created a desktop application using the .**NET** framework to serve as a frontend interface for a serial communication protocol that allowed reading/writing of camera settings, enabling quicker debugging
- Built a web interface using **JavaScript**, **HTML**, and **CSS** for convenient and intuitive usage of a colour manipulation algorithm

# Industrial Imaging Software Developer P&P Optica



**#** Jan 2018 - Apr 2018

♥ Waterloo, ON

- Developed software for industrial imaging applications on **Linux** machines with **Git** version control in an **Agile** environment
- Implemented image correction algorithms and post-processing for industrial cameras in **Python** using **Numpy**, **OpenCV**, and **Matplotlib**
- Refactored data handling modules for efficient file input/output and wrote unit tests for them in **Python** using Pytest
- Restructured camera control modules in **C/C++** that use the Camera Link serial protocol to interface with the camera for control purposes
- Documented software design decisions and a troubleshooting guide to efficiently debug issues pertaining to image acquisition

#### **ACTIVITIES**

## Software Team Lead **UW Robotics**



Apr 2018 - Present

github.com/uwrobotics/RR2019

- Led the software team for a mobile racing robot and competed in the International Autonomous Robot Racing Competition
- Developed software architecture using a Linux based framework; ROS (Robot Operating System), for efficient package management and communication in C++
- Planned and managed software development for an autonomous robot capable of perception, mapping, and path planning using a front-facing stereo camera along with a lidar sensor
- Implemented a lane detection algorithm using OpenCV capable of handling variable lane widths, curvature, and lighting conditions
- Implemented a lightweight traffic light detection algorithm using OpenCV that reduced overhead and false positive rate in comparison to the previous method

#### **PROJECTS**

**Agilite** 

#### DeltaHacks V



₩ Jan 2019

github.com/w29ahmed/Agilite

 Built a backend processing pipeline in Python using OpenCV and Tensorflow capable of extracting and recognizing handwritten text from an agile board

### **EDUCATION**

B.ASc Computer Engineering University of Waterloo



**#** 2022

Online Coursework

- Coursera: Machine Learning (Andrew Ng)
- Udemy: Machine Learning A-Z

### **INTERESTS**

Autonomous Vehicles Deep Learning

Computer Vision Gym Reading

Toronto Raptors Basketball