


# ChickTECH

The logo for ChickTECH features the word "Chick" in a brown, cursive script and "TECH" in a bright pink, bold, sans-serif font. A horizontal teal line runs beneath the text, with the cursive tail of "Chick" looping under it.

**Robotics Workshop**

[git.io/ChickTech-Robotics](https://git.io/ChickTech-Robotics)

**WELCOME!**

# Expectations

- Be respectful of your classmates and volunteers.
  - Do not talk over each other or the volunteers.
  - Respect each others space.
- Help each other! Use each other as a resource.
  - Teaching is learning.
- Mistakes are OK. Mistakes mean you're learning.
- Have fun!

# Volunteer Introductions



- Your facilitator!
- Graduated from Louisiana Tech University
  - BA Computer Science, Minor in Mathematics
- Worked as a System Administrator, QA Analyst, Software Engineer, Full Stack Instructor and Content Creator
- Currently I live stream myself teaching how to code on Twitch and YouTube
  - <https://www.twitch.tv/codinggarden/>
  - <https://www.youtube.com/@CodingGarden>
- I like programming, skateboarding and making music

# Cass

- Graduated from University of Northern Colorado
  - Bachelor of Music Education
- Worked as an Elementary School Teacher, Software Engineer, Front-end Engineering Instructor
- Currently a Front-End Engineering Instructor at Turing School of Software and Design
- I like making art, making music and hanging out with my dog

# Agenda

# Part 1

- Ice Breaker
- What is a Robot?
- What is an Arduino?
- What is soldering?
- Solder Motors
- Assemble Robot



# Part 2

- What is code?
- Basics of programming the robot with C++
- Arduino IDE Setup
- Showcase

**ICE BREAKER**

# ICE BREAKER

- Pair up!
- Take 4 minutes to introduce yourself to your pair
  - What's your name?
  - One thing about you (hobby, favorite food, favorite color etc.)
- We will go around and YOU will introduce your partner

# What is a Robot?

- Define and Describe Robot
- List the many different types of Robots
- Explain why robots are useful

# Define and Describe Robot

- Spend 2 minutes searching the web and reading about what is a robot.
- Write down in your own words "What is a robot?"

# Define and Describe Robot

# Define and Describe Robot

A Robot is a machine designed to accomplish a task.

- ATMs
- Vending Machines
- Washing Machines

# Define and Describe Robot

A machine capable of responding to its environment to automatically carry out complex or repetitive tasks with little, if any, direction from a human being.

- An Autonomous Car - a car that drives itself
- A Washing Machine that senses the clothing to adjust the cycle
- A thermostat that learns it's users preferences and automatically adjusts
- A roomba vacuum cleaner - learns and senses the floor layout to automatically clean the floor



# List the many different types of Robots

- Medical Robots
  - Designed to mimic a surgeons precise movements/actions
- Military Robots
  - Drones
  - Bomb defusers
  - Search through debris
- Automation/Manufacturing
  - Assembly line robotic arms
  - Automated Vacuum Cleaners
  - Autonomous Cars
  - Smart Dishwashers/Dryers/Washers

# Explain Why Robots are Useful

- Spend 2 minutes thinking about "Why are robots useful?".
- Write down in your own words "Why are robots useful?"

# Explain Why Robots are Useful

# What is an Arduino?

- Define and Describe MicroController
- Define and Describe an Arduino
- Identify an Arduino as a MicroController
- List the many uses of an Arduino

# Define and Describe MicroController

- A single purpose computer
  - Similar to a desktop/laptop computer but only serves a single purpose
- Typically dedicated to a single task
  - Can only be programmed to do 1 thing at a time
- Contains:
  - CPU (Central Processing Unit)
  - Memory
  - Clock

# Define and Describe an Arduino

- A single purpose computer
- Has inputs and outputs
- Can be programmed to do many different things
  - Robots
  - Home Automation
  - Internet of Things
  - MUCH MORE!
- A rapid prototyping tool
  - An easy way to get started with electronics
    - In the past you had to source the materials and build something similar from scratch!
- Open Source hardware platform

# Identify an Arduino as a MicroController

An arduino is a MicroController! There are many other types of MicroControllers, but arduino is very popular one.

# What is soldering?

- Define Soldering
- Describe why soldering is necessary
- List the ways to stay safe while soldering



# Define Soldering

A process in which two or more items (usually metal) are joined together by melting and putting a filler metal (solder) into the joint.

# Describe Why Soldering is Necessary

- Materials used in electronics require electricity to pass through them
- When working with electronics, we typically want to connect 2 components together
  - A wire and a motor!

# List the ways to stay safe while soldering

- Always wear safety glasses.
- Grip the soldering iron by the safety grip. NEVER touch the metal.
- Solder in a well-ventilated space
  - Do not inhale the fumes! Blow them away.
- Always put your soldering iron back in its stand when not in use
- Never, ever try to catch a hot soldering iron if you drop it. Let it fall, buy a new one if you have to — just don't grab it!
- Give any soldered surface a minute or two to cool down before you touch it.
- Never leave flammable items (such as paper) near your soldering iron.

How to Solder Safely

# ROBOT TIME!!!

[1: Build an Arduino Powered Robot](#)

[2: Attach Wires](#)

[3: Solder Wires to Motors](#)

[4: Assemble Robot: Attach pivot wheel](#)

[5: Assemble Robot: Attach Motors](#)

[6: Assemble Robot: Attach Battery Pack](#)

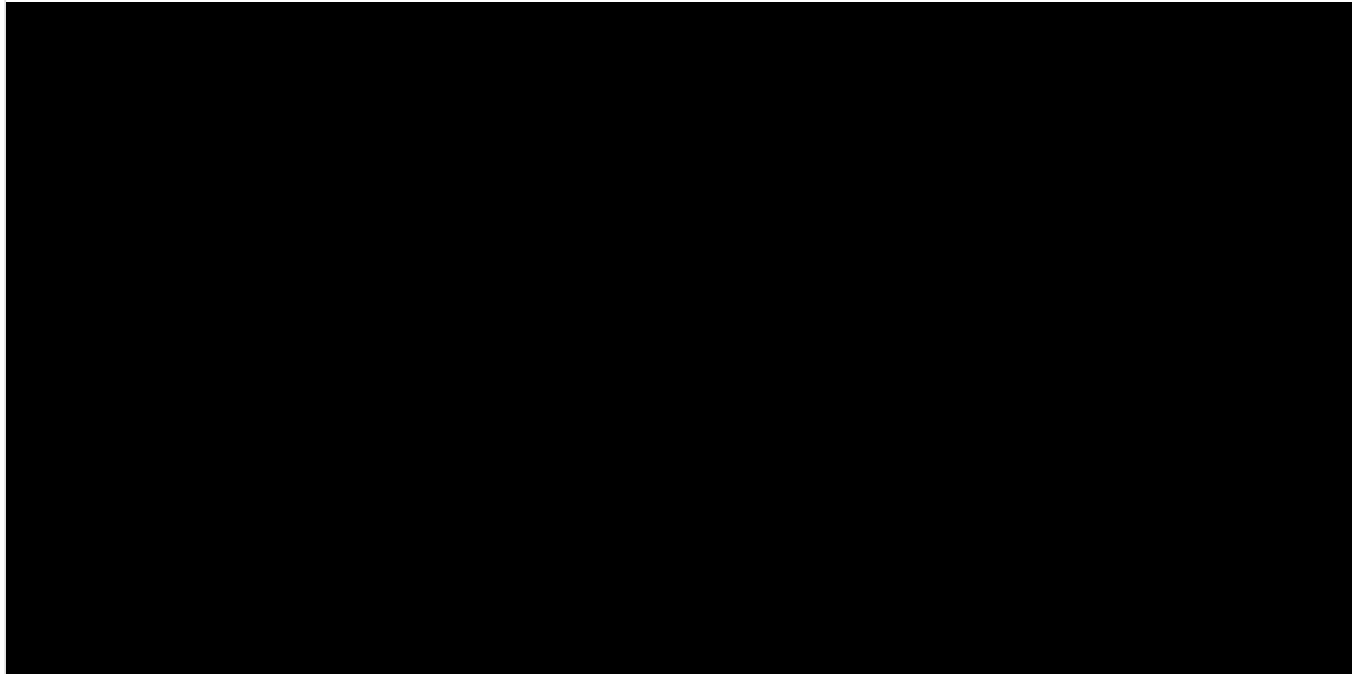
[7: Attach Motor Controller to Arduino](#)

[8: Attach Arduino to Robot](#)

[9: Connect](#)

# Step 1: Build an Arduino Powered Robot

Next Step



Next Step

[git.io/ChickTech-Robotics](https://git.io/ChickTech-Robotics)

**ROBOT  
COMPLETE!**

# Review



# What is a robot?

# What are some types of robots?

# Why are robots useful?

# What is an Arduino?

# What is soldering?

**What are the ways  
to stay safe when  
soldering?**

# Coding

- What is code?
- Basics of programming the robot with C++
- Arduino IDE Setup

# What is code?

- Define and describe computer code
- Explain why computer code is required
- List at least 3 computer coding languages
- List at least 5 things computer coding is used for



# Define and describe computer code

- Spend 2 minutes searching the web and reading about what is code.
- Write down in your own words "What is code?"

# Define and describe computer code

# Explain why computer code is required

- Computers (MicroControllers) only understand electricity
- 0s and 1s (binary)
  - 0 - no electricity (off)
  - 1 - electricity (on)
- Computer code can be written and understood by humans
  - Might look foreign, but its a lot easier to learn and code than just 1s and 0s
- The computer code that we write is translated into 0s and 1s so computers can understand it.

# List at least 3 computer coding languages (programming languages)

- Spend 2 minutes searching the web and reading about what coding (programming) languages there are.
- List at least 3 coding languages you find

**List at least 3  
computer coding  
languages**

**We will use C++ to program the  
Arduino!**

# List at least 5 things computer coding is used for

- Spend 2 minutes searching the web and reading about what coding (programming) languages are used for.
- List at least 5 things you find

**List at least 5  
things computer  
coding is used for**



# Arduino IDE Setup

1. Open the Arduino IDE
2. Go to Tools->Board and make sure "Arduino Uno" is selected.
3. Download the [CTRobotSimple](#) file
4. Go to File->Open and open the CTRobotSimple.ino file.
5. Download the [TwoMotorGearbox.zip](#) library file
6. Go to Sketch->Import Library->Add Library and select the TwoMotorGearbox.zip library file

# Basics of Programming the Robot with C++

# C++ comments

```
// This is a comment  
  
// this compiler ignores things that begin with  
  
// Programmers use these to leave themselves  
  
// and others notes about the code
```

```
/*  
  
This is also a comment.  
  
Anything between  
  
*/
```

# Control the robot

```
// move forward .5 seconds  
CCTTwoMotorControl(500, 'F', 250, 'F', 250),  
CCTTwoMotorControl(  
    500, // time in milliseconds  
    'F', // direction M1A - can be 'F' or 'R'  
    250, // speed M2A - maximum value is 255  
    'F', // direction M1B - can be 'F' or 'R'
```

Sleep 🤪 zzz



```
CCTTwoMotorControl(100) // sleep for 0.1 seconds
```

# Create a list of Commands

By changing the commands and sequence of commands, you can make the robot do anything you want!

```
CCTTwoMotorControl commandList[] = {  
    CCTTwoMotorControl(500, 'F', 250, 'F', 250),  
    CCTTwoMotorControl(500, 'R', 250, 'R', 250),  
    CCTTwoMotorControl(500, 'F', 250, 'R', 250),  
    CCTTwoMotorControl(500, 'R', 250, 'F', 250) /  
};
```

# Sending the program to the robot

1. Plug the USB cable into your Arduino and into the computer.
2. Click on the check mark  "Verify" button in the top left of the Arduino window.
3. Check to make sure it says "Done compiling" at the bottom of the window.
4. Click the arrow "Upload"  button next to the Verify button. This will load the program onto the robot.
5. If there are errors, go to Tools->Serial Port and choose a different serial port.

# CHALLENGES

- Program the robot to go in a circle
- Program the robot do a figure 8
- Setup an obstacle course (with cardboard boxes) and make the robot avoid all the obstacles
- Group up with others and perform a synchronized robot dance
- Program the robot to do anything else you can think of!



# Customize and Decorate Robot

- Use duct tape on any part of the robot
- Use foam sheets, cardboard and felt to create a different chassis shape
- Options:
  - Add eyes or antennas with pipe cleaners to make the robot look alive
  - Make the robot look like a real robot (mars rover, autonomous car, humanoid etc.)



**Showcase!**

*Chick*TECH

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**Thanks!**