



Arm

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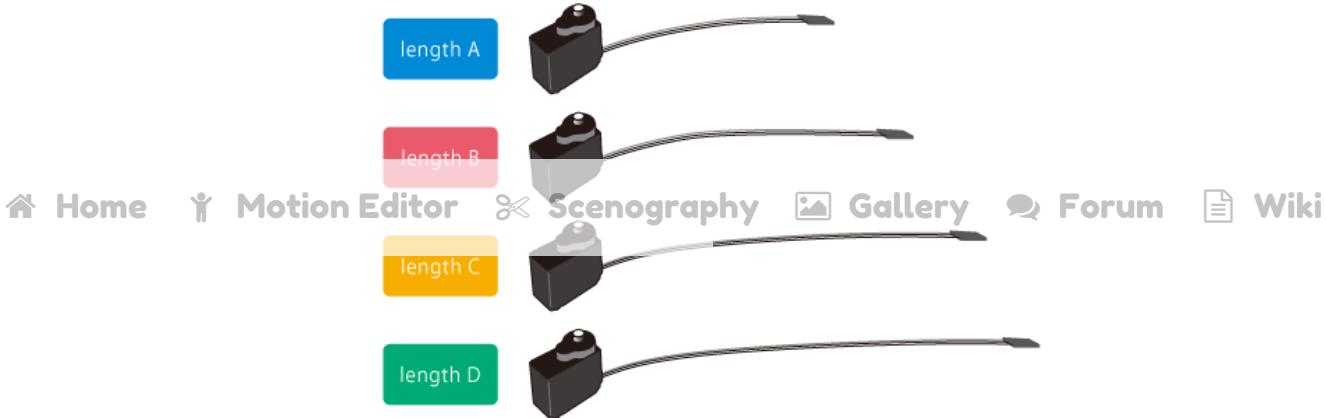
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Parts List

Parts list of the left arm is enumerated below. (Also you could use the parts to build the right arm.)

Name	Q'ty
servo_assem_type1.stl [https://github.com/plenprojectcompany/PLEN2/blob/master/stl/servo_assem_type1.stl]	1
servo_horn.stl [https://github.com/plenprojectcompany/PLEN2/blob/master/stl/servo_horn.stl]	1
servo_bracket_elbow_1.stl [https://github.com/plenprojectcompany/PLEN2/blob/master/stl/servo_bracket_elbow_1.stl]	1
servo_bracket_elbow_2.stl [https://github.com/plenprojectcompany/PLEN2/blob/master/stl/servo_bracket_elbow_2.stl]	1
hand.stl [https://github.com/plenprojectcompany/PLEN2/blob/master/stl/hand.stl]	1
Servo Motor (Length C)	1
Servo Motor (Length D)	1



Print Detail

[Arm x2](#)

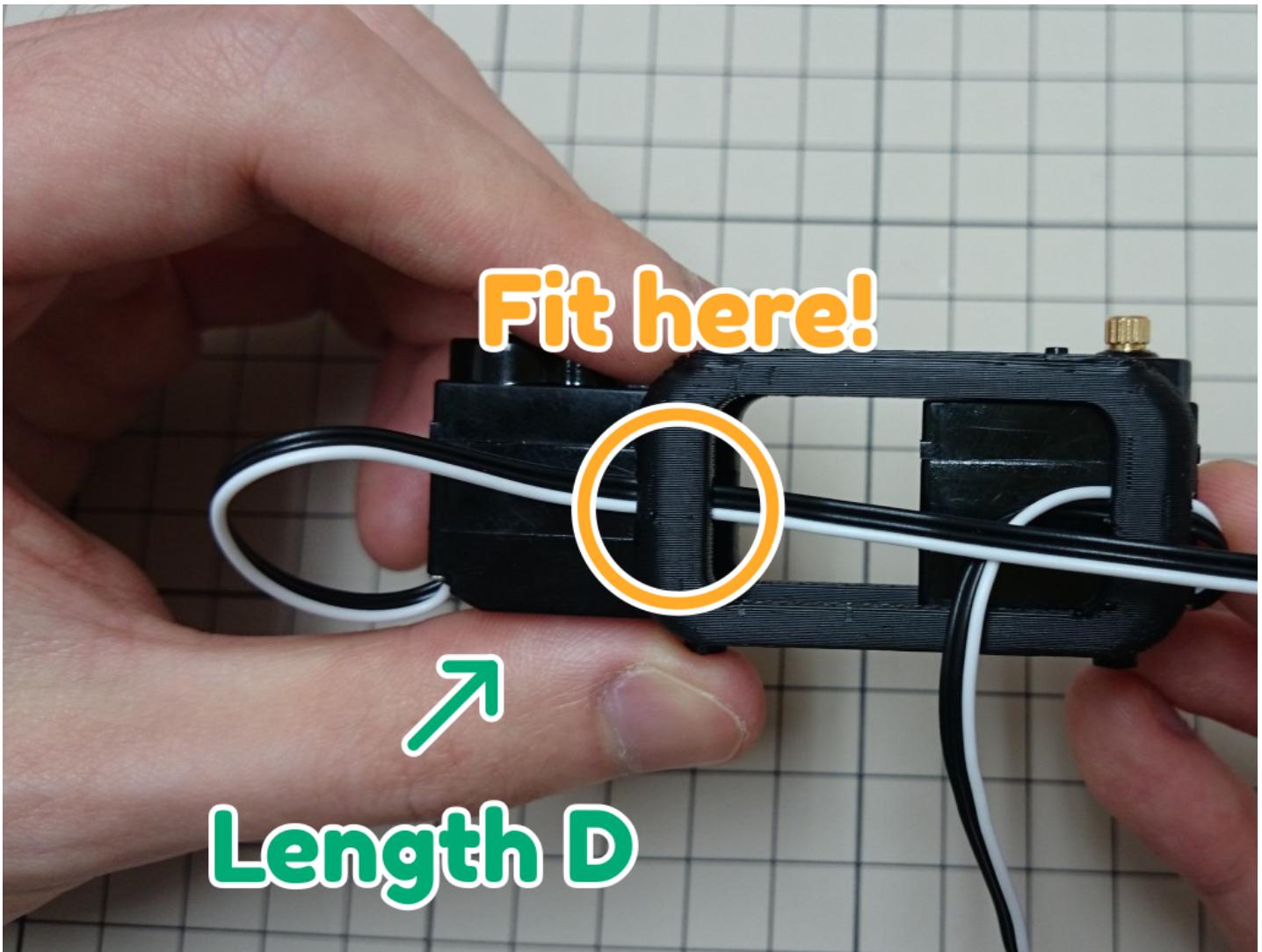
Assembling Process

Parts List



Upper Arm



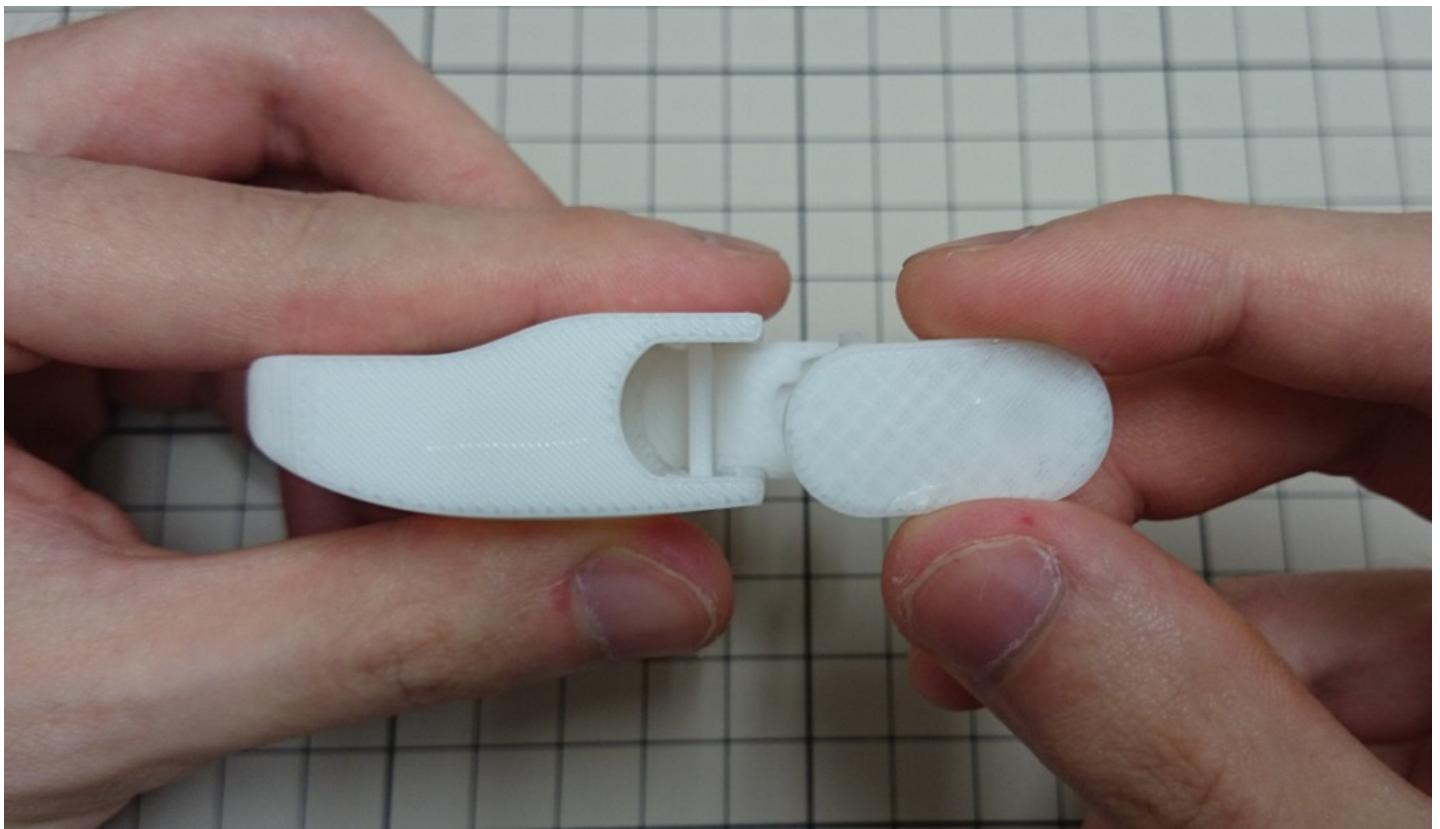
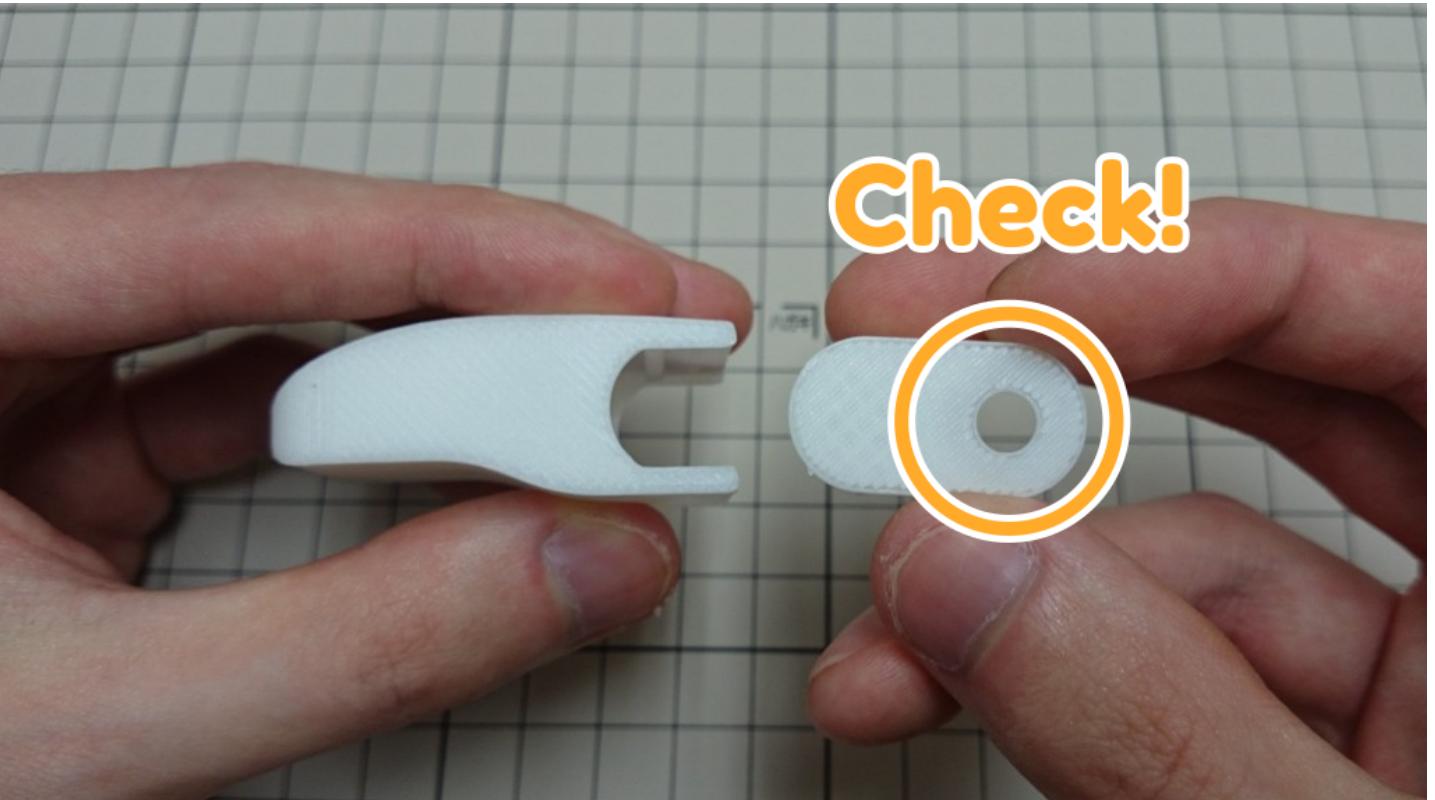


Attention! Please fit the conducting wire through inside a groove on **servo_assem_type1.stl**.



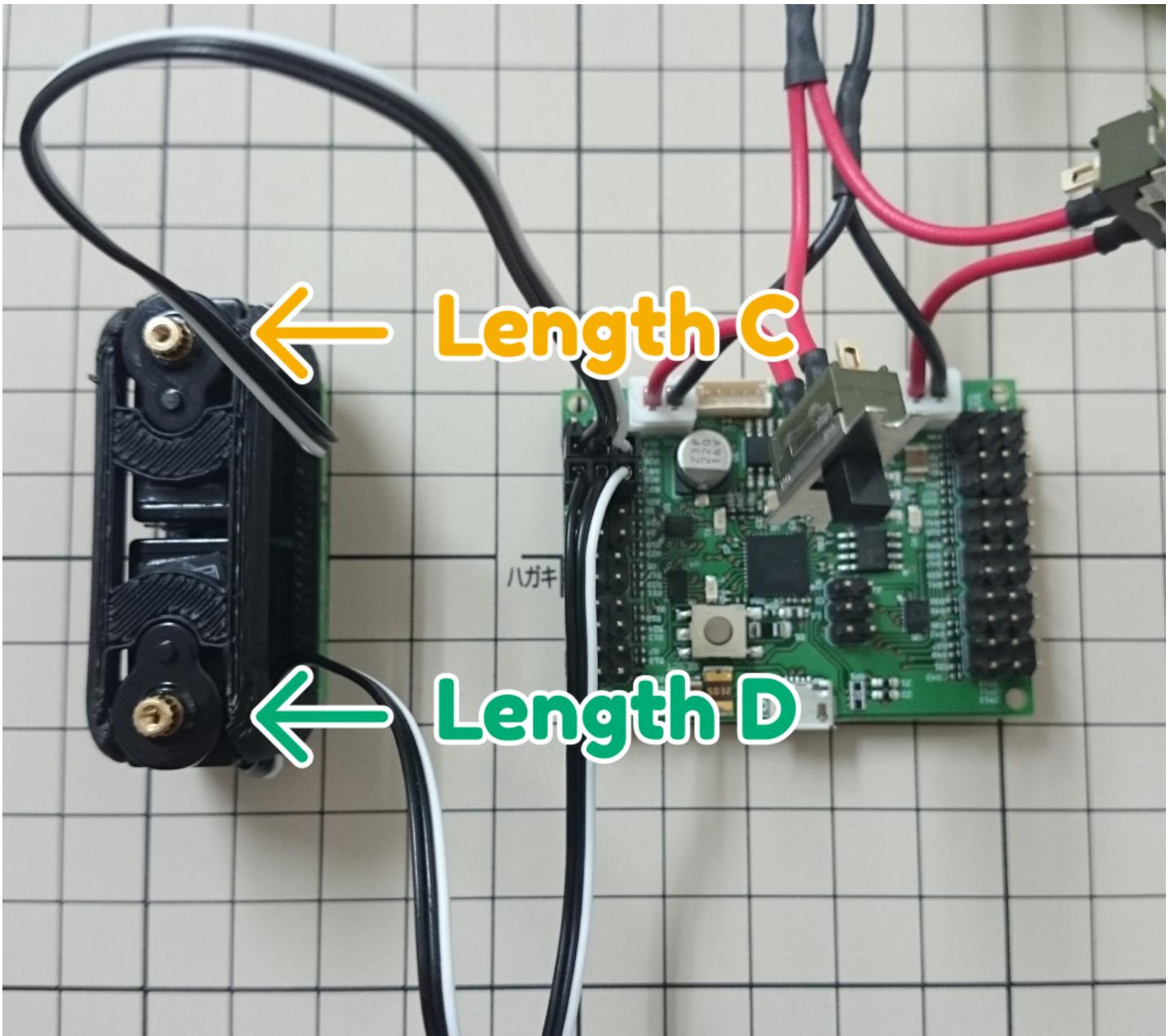
Hand

Attention! If you assemble plastic cast parts, this step has already been completed.

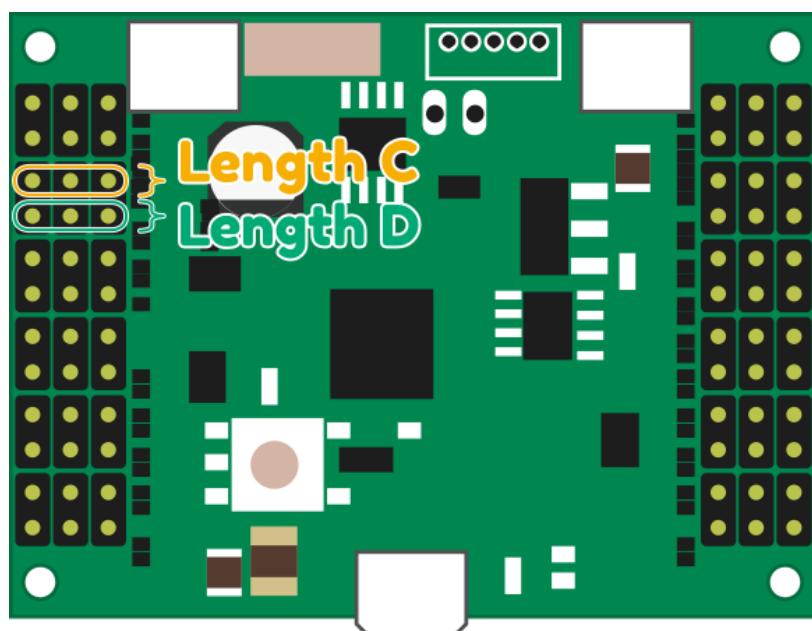


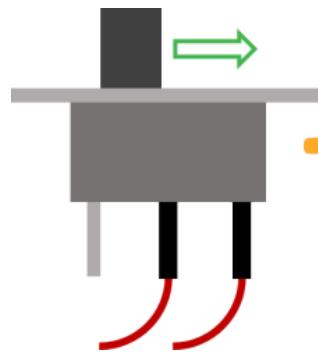
Merge Parts

Attention! Before to merge the parts, you should connect servos' cables and the control-board. When it was completed, please turn on both switches and keep the status.



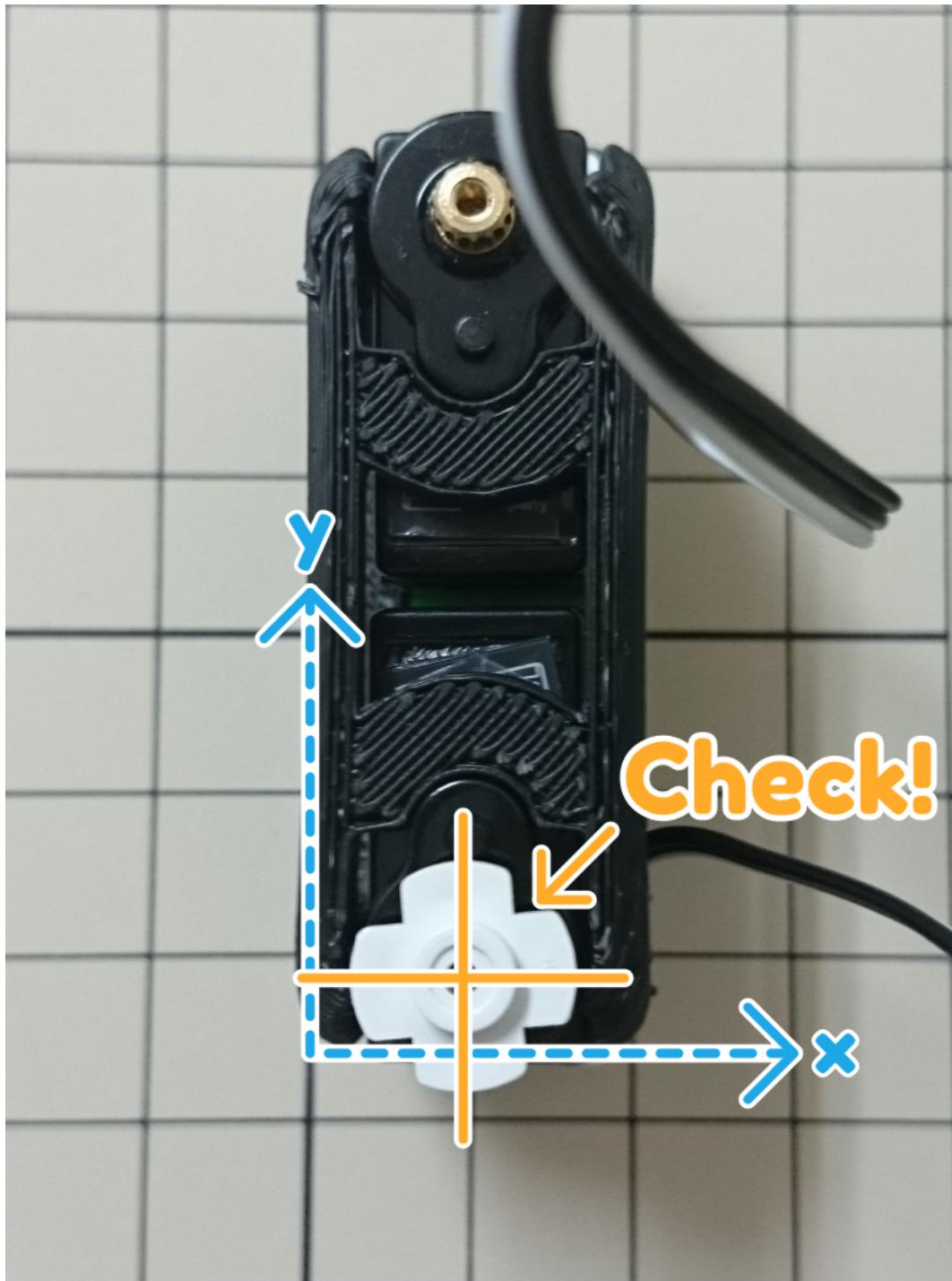
Attention! Please connect the white wire which is owned by a servo to inside of the control-board.





Turn on!

Attention! Attach a servo-horn to length D servo. At that time, please check it is placed approximately parallel to edge of the servo.





Finished Arm



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