

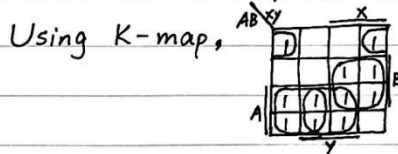
## Assignment 3

1. The state equations are

$$A(t+1) = J_A A' + K_A A$$

$$= A'(Bx + B'y') + A(B'xy')$$

$$= A'Bx + A'B'y' + AB + Ax' + Ay$$



$$A(t+1) = Ax' + Ay + Bx + A'B'y'$$

$$B(t+1) = J_B B' + K_B B$$

$$= A'B'x + (A + xy')'B$$

$$= A'B'x + A'Bx' + A'By \text{ (simplest form)}$$

$$= A'B$$

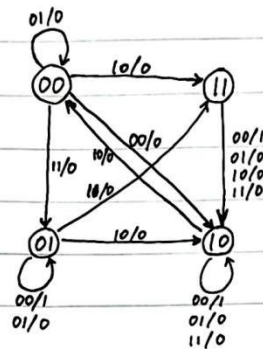
State table:

Present state		Input		Next State		Output	FF Inputs			
A	B	x	y	A	B	Z	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>
0	0	0	0	1	0	0	1	0	0	0
0	0	0	1	0	0	0	0	0	0	0
0	0	1	0	1	1	0	1	1	1	1
0	0	1	1	0	1	0	0	0	1	0
0	1	0	0	0	1	1	0	0	0	0
0	1	0	1	0	1	0	0	0	0	0
0	1	1	0	1	0	0	1	0	1	1
0	1	1	1	1	1	0	1	0	1	0
1	0	0	0	1	0	1	1	0	0	1
1	0	0	1	1	0	0	0	0	0	1
1	0	1	0	0	0	0	1	1	0	1
1	0	1	1	1	0	0	0	0	0	1
1	1	0	0	1	0	1	0	0	0	1
1	1	0	1	1	0	0	0	0	0	1
1	1	1	0	1	0	0	1	0	0	1
1	1	1	1	1	0	0	1	0	0	1

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FSM next page

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So we can get the FSM.



2. From the diagram, we can get input equations

$$T_A = A + B$$

$$T_B = A' + B$$

Then, state equation:

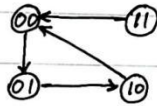
$$\begin{aligned}
 A(t+1) &= T_A \oplus A = T_A' A + T_A A' \\
 &= AA'B' + AA' + A'B \\
 &= 0 + 0 + A'B \\
 &= A'B
 \end{aligned}$$

$$\begin{aligned}
 B(t+1) &= T_B \oplus B = T_B' B + T_B B' \\
 &= AB'B + A'B' + BB' \\
 &= 0 + A'B' + 0 \\
 &= A'B'
 \end{aligned}$$

Since there aren't any input, so the truth table only has 4 lines. (next page)

Present State		Next State	
A	B	A	B
0	0	0	1
0	1	1	0
1	0	0	0
1	1	0	0

At last, we can draw FSM.



3. (a) Input equation:  $J_1 = X$ ,  $K_1 = \cancel{XQ_2} + \cancel{X'Q_2'} (XQ_2')' = X' + Q_2$   
 $J_2 = X$ ,  $K_2 = (XQ_1)' = X' + Q_1'$

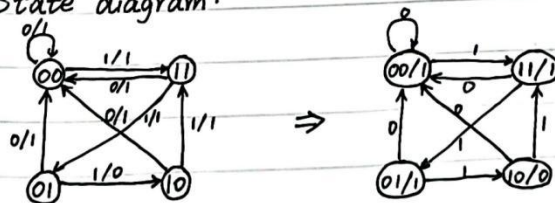
State equation:  $Q_1(t+1) = J_1Q_1' + K_1'Q_1$   
 $= XQ_1' + XQ_2'Q_1 = X(Q_1' + Q_2')$

$Q_2(t+1) = J_2Q_2' + K_2'Q_2$   
 $= XQ_2' + XQ_1Q_2$   
 $= X(Q_1 + Q_2')$

State table:

Present State		Input	Next State		Output
$Q_1$	$Q_2$	$X$	$Q_1$	$Q_2$	$F$
0	0	0	0	0	1
0	0	1	1	1	1
0	1	0	0	0	1
0	1	1	1	0	0
1	0	0	0	0	1
1	0	1	1	1	1
1	1	0	0	0	1
1	1	1	0	1	1

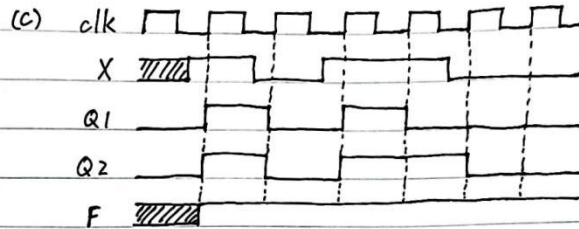
State diagram:



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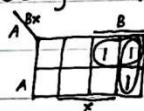
(b) Moore Machine. Because output only depend on state, output doesn't depend on input.



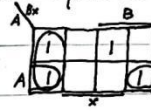
4. We first get state table.

Present State		Input	Next State		TFF Input		TFF: $\frac{Q(t)}{Q(t+1)} T$		
A	B	X	A	B	$T_A$	$T_B$	0	0	0
0	0	0	0	1	0	1	0	1	1
0	0	1	0	0	0	0	1	0	1
0	1	0	1	1	1	0	1	1	0
0	1	1	1	0	1	1			
1	0	0	1	1	0	1			
1	0	1	1	0	0	0			
1	1	0	0	0	1	1			
1	1	1	1	1	0	0			

Using K-map get input equation:



$$T_A = A'B + Bx'$$



$$T_B = B'x' + Ax' + A'Bx$$

5. When positive edge reach, the state change.

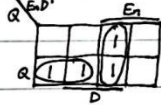
Suppose input is  $\{E_n, D\}$ , we can get state diagram.



Then list state table.

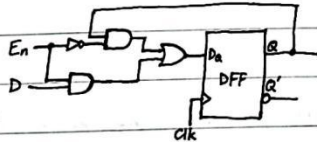
Present State	Input		Next state	DFF Input	DFF: $Q(t)$ $Q(t+1)$ D			
$Q$	$E_n$	$D$	$Q$	$D_n$	$Q(t)$	$Q(t+1)$	$D$	
0	0	0	0	0	0	0	0	0
0	0	1	0	0	1	0	0	0
0	1	0	0	0	1	0	0	0
0	1	1	1	1	1	1	1	1
1	0	0	1	1	0	1	1	1
1	0	1	1	1	0	1	1	1
1	1	0	0	0	1	0	0	0
1	1	1	1	1	1	1	1	1

K-map of  $D_n$



$$D_n = Q E_n' + D E_n$$

At last, the design is as follow.



6. (a)	A	B	$Q(t+1)$	Operation	(b) Next page
	0	0	0	Reset	
	0	1	$Q(t)$	No change	
	1	0	$Q'(t)$	Complement	
	1	1	1	Set	

(c) When  $Q(t)=0$ ,  $Q(t+1)=0$ , AB can be 00, 01, that is 0x.

When  $Q(t)=0$ ,  $Q(t+1)=1$ , AB can be 10, 11, that is 1x.

When  $Q(t)=1$ ,  $Q(t+1)=0$ , AB = 00 or 10, that is x0.

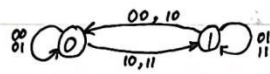
When  $Q(t)=1$ ,  $Q(t+1)=1$ , AB = 01 or 11, that is x1.

So excitation table:

$Q(t)$	$Q(t+1)$	A	B
0	0	0	x
0	1	1	x
1	0	x	0
1	1	x	1

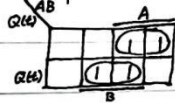
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(b) Draw state diagram and get state table.



Present State $Q(t)$	Input		Next State $Q(t+1)$
	A	B	
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

K-map of  $Q(t+1)$ :

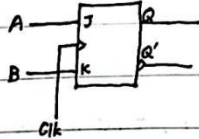


$$Q(t+1) = A\bar{Q}(t) + BQ(t)$$

(c) previous page

(d) From (c), we found the excitation table is the same as JKFF's, so this FF can be converted to JKFF.

The block diagram:





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7. Found that h, d are the same, b, e are the same, we reduce them.

Present State	Next state		Output	
	x=0	x=1	x=0	x=1
a	f	b	0	0
b	d	c	0	0
c	f	b	0	0
d	g	a	1	0
f	f	b	1	1
g	g	d	0	1

Then reduce a.c.

Present State	Next State		Output	
	x=0	x=1	x=0	x=1
a	f	b	0	0
b	d	a	0	0
d	g	a	1	0
f	f	b	1	1
g	g	d	0	1

Code the state: a: 000, b: 001, d: 010, f: 011, g: 100

~~Present State~~ We need to use 3 JKFF.

Present State			Input	Next State			Output	JKFF Inputs					
A	B	C		A	B	C		J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>	J <sub>C</sub>	K <sub>C</sub>
0	0	0	0	0	0	0	0	0	X	1	X	1	X
0	0	0	1	0	0	1	0	0	X	0	X	1	X
0	0	1	0	0	0	1	0	0	X	1	X	X	0
0	0	1	1	0	0	0	0	0	X	0	X	X	0
0	1	0	0	0	1	0	0	1	X	X	0	0	X
0	1	0	1	0	0	0	0	0	X	X	0	0	X
0	1	1	0	0	0	1	1	1	0	X	X	1	X
0	1	1	1	0	0	0	1	1	0	X	X	0	X
1	0	0	0	1	0	0	0	0	X	0	0	X	0
1	0	0	1	1	0	1	0	1	X	1	1	X	0
1	0	1	0	1	0	0	1	1	X	X	X	X	X
1	0	1	1	1	0	0	1	1	X	X	X	X	X
1	1	0	0	1	1	0	0	1	X	X	X	X	X
1	1	0	1	1	1	0	1	1	X	X	X	X	X
1	1	1	0	1	1	1	0	1	X	X	X	X	X
1	1	1	1	1	1	1	1	1	X	X	X	X	X

K-map of J<sub>A</sub>, K<sub>A</sub>

AB		C	
A	B	0	1
		0	1
0	0	0	0
0	1	0	0
1	0	X	X
1	1	X	X

AB		C	
A	B	0	1
		0	1
0	0	X	X
0	1	X	X
1	0	X	X
1	1	X	X

$$J_A = BC'x'$$

$$K_A = X$$

K-map of  $J_B, K_B$ :

	AB	Cx		
		C		

	AB	Cx		
		C		

$$J_B = A'x'$$

$$K_B = Cx'$$

K-map of  $J_C, K_C$ :

	AB	Cx		
		C		

	AB	Cx		
		C		

$$J_C = A'B'$$

$$K_C = B$$

K-map of output:

	AB	Cx		
		C		

$$y = BC + Bx' + Ax$$

8. Suppose state A: detect nothing, B: have 1, C: have 11, D: have 110, E: have 1101

And output of A to E is 0, 0, 0, 0, 1

Code the state: A: 000, B: 001, C: 010, D: 011, E: 100

We need to use 3 DFF (Suppose is L, M, N)



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The state table is as below

Present state			Input x	Next state			Output y
L	M	N		L(D <sub>L</sub> )	M(D <sub>M</sub> )	N(D <sub>N</sub> )	
0	0	0	0	0	0	0	0
0	0	0	1	0	0	1	0
0	0	1	0	0	0	0	0
0	0	1	1	0	1	0	0
0	1	0	0	0	1	1	0
0	1	0	1	0	0	0	0
0	1	1	0	0	0	0	0
0	1	1	1	1	0	0	1
1	0	0	0	0	0	0	1
1	0	0	1	0	1	0	1
1	0	1	0	x	x	x	x
1	0	1	1	x	x	x	x
1	1	0	0	x	x	x	x
1	1	0	1	x	x	x	x
1	1	1	0	x	x	x	x
1	1	1	1	x	x	x	x

K-map of D<sub>L</sub>, D<sub>M</sub>, D<sub>N</sub>, output y:

LM \ N		0	1
L	0	0	0
	1	x	x

LM \ N		0	1
L	0	0	0
	1	x	x

LM \ N		0	1
L	0	0	0
	1	x	x

$$D_L = MNx$$

$$D_M = MN' + Lx + M'Nx$$

$$D_N = L'M'N'x + MN'x'$$

And without K-map, we can easily see  $y = L$