Floating-point Arithmetic and Stability

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Fall 2018

Representation of real numbers in the computer

▶ Real numbers differ from integers in that they have a decimal part that potentially can be infinitely long.

➤ You probably have learned from you programming class that real numbers are declared as "float", which means floating-point numbers.

In contrast to floating-point, there was once a mechanism called the "fixed-point" system.

Fixed-point system

- ▶ A position in the string is specified for the radix point.
 - ▶ E.g., a fixed-point scheme might be to use a string of 8 decimal digits with the decimal point in the middle, whereby "00012345" would represent 0001.2345.

Disadvantage

▶ The scale is fixed, and it is very easy to overflow or underflow.

Floating-point system

- Very similar to *scientific notation* $significand \times base^{exponent}$
 - ► Significand integer
 - ► Exponent integer
 - ▶ Base can be 2, 10, or 16.
- E.g.

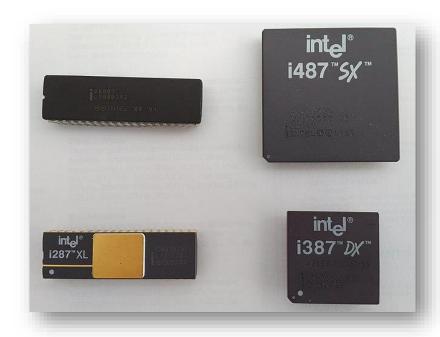
$$1.2345 = 12345 \times 10^{-4}$$

► The term floating point refers to the fact that a number's radix point can "float".

Did you know...

► Early CPUs (such as Intel 8088) could not do floating-point arithmetic, and a separate Floating-point units (FPU, such as Intel 8087) were sold as a add-on coprocessor.

➤ On the contrary, fixed-point systems were much easier to implement and could use integer arithmetic hardware.



Representable numbers

- ▶ Apparently, floating-point system can only represent rational numbers.
- ► However, not all rational number can be represented by floating-point system.
 - ► E.g., try to represent 1/5 in binary.
 - ► Extended question: how to convert decimal to binary?

Base conversion

- ▶ For whole numbers, repeatedly divide by the base and record the remainders.
 - ▶ E.g., convert decimal 500 to hexadecimal.

- ► For the fractional part, repeatedly multiply the part after the radix by the base, and record the part before the radix.
 - ► E.g., convert decimal 0.2 to binary.

Range and precision

As it turns out, even a number as simple as 0.2 may not be accurately represented as a floating-point number. There are gaps between representable numbers, and the gap scales with the exponent. Naturally, the next question would be how accurate are floating-point numbers.

▶ By the IEEE 754 Standard,

有效数字

Type	Sign	Exponent	Significand	Number of decimal digits
Half precision	1	5	10	~3.3
Single precision	1	8	23	~7.2
Double precision	1	11	52	~16.0

At a product release event, Nvidia boasted about half precision computing speed of its GPU, claiming that 3 digits of precision is enough. Is it really so?

▶ Addition and subtraction: shift and represent the smaller number with the same exponent with the larger one, then proceed with usual addition or subtraction.

▶ Use decimal and 7 digits of precision as example:

```
123456.7 + 101.7654 = (1.234567 \times 10^{5}) + (1.017654 \times 10^{2})
= (1.234567 \times 10^{5}) + (0.001017654 \times 10^{5})
= (1.234567 + 0.001017654) \times 10^{5}
= 1.235584654 \times 10^{5}
final sum: e=5; s=1.235585 (123558.5)
```

▶ Cancellation: a phenomenon called cancellation can occur when subtracting nearly equal numbers, and it is a common source of loss of significance.

▶ In this example, the result has in fact only remaining 1 significant digit.

相加事至多两倍相对误差

► Cancellation is *benign* and controlled within 2 machine epsilon when using an additional *guard digit*.

截断估计(截断近似)

► However, cancellation can be *catastrophic* when the operands involve rounding errors. E.g. the two operands were in fact 123457.1467 and 123456.659. The true result should be e = -1; s = 4.877000, which differs more than 20% from e = -1; s = 4.000000.

```
e=5; s=1.234571

- e=5; s=1.234567

e=5; s=0.000004

e=-1; s=4.000000 (after rounding and normalization)
```

▶ Multiplication and division: to multiply, the significands are multiplied while the exponents are added, and the result is rounded and normalized. Division is similar.

```
e=3; s=4.734612
x e=5; s=5.417242
------
e=8; s=25.648538980104 (true product)
e=8; s=25.64854 (after rounding)
e=9; s=2.564854 (after normalization)
```

► There are no cancellation or absorption problems with multiplication or division.

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Accuracy problem

► Cancellation is a major source of inaccuracy, and a lot of care needs to be taken.

► Consider the quadratic formula:

$$r_1 = rac{-b + \sqrt{b^2 - 4ac}}{2a}$$
 此时在电脑里做运算的时候,根号的运算已经是做过截断近似了,因此会发生像上面的rounding error

when $b^2 \gg 4ac$, $\sqrt{b^2 - 4ac} \approx |b|$. This implies $-b + \sqrt{b^2 - 4ac}$ or $-b - \sqrt{b^2 - 4ac}$ will involve catastrophic cancellation.

► How can you avoid this problem?

Accuracy problem

The expression of $x^2 - y^2$ is another formula that exhibits catastrophic cancellation.

▶ How can you avoid this problem? 使用平方差公式

Accuracy problem

▶ Evaluating the derivative numerically:

$$f'(x) = \lim_{d \to 0} \frac{f(x+d) - f(x)}{d}$$

- ▶ Intuitively one would want a *d* very close to zero, however the smallest number of *d* possible will give a more erroneous approximation of a derivative than a somewhat larger number.
 - \triangleright Because evaluating f(x) involves rounding error.
 - ▶ The computation of f(x) may already be unstable.

导致有时候取大一点的d比 小一点的d更接近真实值

 \blacktriangleright To make things worse, f(x) itself may be *ill-conditioned*.

类似于 不稳定的

Condition of a problem

Consider a problem as a function $f: X \to Y$ from a normed vector space X of data to a normed vector space Y of solutions.

A well-conditioned problem is one with the property that all small perturbations of x lead to only small changes in f(x).

稳定性与否

An *ill-conditioned* problem is one with the property that some small perturbations of x leads to a large change in f(x).

Absolute condition number

Let δx denote a small perturbation of x, and write $\delta f = f(x + \delta x) - f(x)$. The absolute condition number $\hat{\kappa} = \hat{\kappa}(x)$ of the problem f at x is defined as

$$\hat{\kappa} = \lim_{\delta \to 0} \sup_{\|\delta x\| \le \delta} \frac{\|\delta f\|}{\|\delta x\|} \triangleq \sup_{\delta x} \frac{\|\delta f\|}{\|\delta x\|},$$
 绝对误差的比值

with the understanding that δx is infinitesimal.

类似于某种矩阵范数/极大函数的定义

▶ If f is differentiable, let J(x) be the Jacobian at x, i.e., $J_{ij} = \partial f_i / \partial x_j$, then $\hat{\kappa} = ||J(x)||$, where ||J(x)|| is the norm of J(x) induced by the norms on X and Y.

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Relative condition number

由这个式子看出相对条件数描述的 是自变量的误差与因变量误差的相 **关程度**

与上一页相比之下, 类似于

相对误差与绝对误差

▶ The relative condition number $\kappa = \kappa(x)$ is defined by

$$\kappa = \lim_{\delta \to 0} \sup_{\|\delta x\| \le \delta} \left(\frac{\|\delta f\|/\|f(x)\|}{\|\delta x\|/\|x\|} \right) \triangleq \sup_{\delta x} \frac{\|\delta f\|/\|f(x)\|}{\|\delta x\|/\|x\|}$$

 \blacktriangleright If f is differentiable, then

$$\kappa = \frac{\|J(x)\|}{\|f(x)\|/\|x\|}.$$

► The relative condition number is arguably more useful than the absolute condition number, because floating-point arithmetic introduces relative errors rather than absolute ones.

Question

默认相对条件数

► Is a condition number of 1000 large or small? 大概相当于如果x丢失一位有效 数字那么f(x)会丢3位有效数字

 \blacktriangleright What is its implication on the accuracy of f(x)?

 \blacktriangleright What is the relative condition number of x/2?

▶ What is the relative condition number of \sqrt{x} ?



► Consider the problem of obtaining the scalar $f(x) = x_1 - x_2$ from the vector $x = (x_1, x_2)^T$, using the ∞-norm.

Consider the computation of $f(x) = \tan x$ for x near 10^{100} . A minuscule relative perturbation in x can result in arbitrarily large changes in $\tan x$, so $\tan 10^{100}$ is effectively uncomputable on most computers. We don't need to calculate the Jacobian to know the problem is ill-conditioned.

对10^100量级的浮点数其相对误差可能比较小,但是绝对误差一定特别大,远大于π,而tan周期为π,因此该问题一定是不稳定的

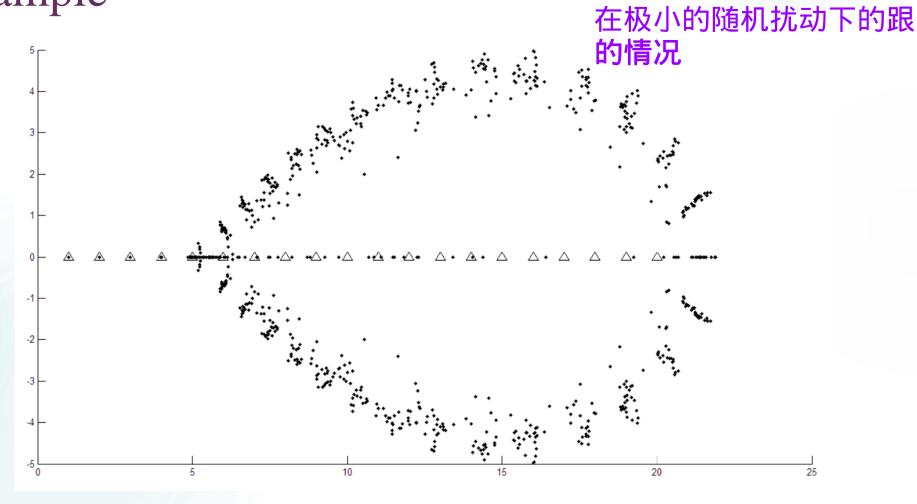
The determination of the roots of a polynomial, given the coefficients, is a classic example of an ill-conditioned problem. Consider $x^2 - 2x + 1$, with a double root at x = 1. A small perturbation in the coefficients can lead to a large change in the roots; for example, $x^2 - 2x + 0.9999 = (x + 1)$

此次计算时,方程系数为自 变量,而根为因变量

用求根公式易见条件数为∞

散点为原方程的某些系数

Example



Wilkinson's classic example of ill-conditioning: roots of $\prod_{i=1}^{20} (x-i)$

► The problem of computing the eigenvalues of a nonsymmetric matrix is often ill-conditioned. Compare the eigenvalues of the two matrices

$$\begin{pmatrix} 1 & 1000 \\ 0 & 1 \end{pmatrix}$$
, and $\begin{pmatrix} 1 & 1000 \\ 0.001 & 1 \end{pmatrix}$

▶ On the other hand, if a matrix is symmetric, then its eigenvalues are well-conditioned.

一般来讲非对称矩阵特征值不稳定

Condition of matrix-vector multiplication

Fix $A \in \mathbb{R}^{m \times m}$ and nonsingular, consider the problem of computing Ax from input x.

$$\kappa = ||A|| \frac{||x||}{||Ax||} \le ||A|| ||A^{-1}||.$$

Similarly, the problem of solving Ax = b given b has condition number $\kappa = \|A^{-1}\| \frac{\|b\|}{\|x\|} \le \|A\| \|A^{-1}\|.$

关于线性方程的解/向量的变换的条件数

Condition number of a matrix

▶ $||A|| ||A^{-1}||$ is a commonly used quantity and is thus defined as the condition number of A, denoted by $\kappa(A)$:

$$\kappa(A) = ||A|| ||A^{-1}||.$$

For L2 norm, $||A|| = \sigma_1$, $||A^{-1}|| = 1/\sigma_m$, where σ_1 and σ_m are the largest and smallest singular values of A. Thus,

$$\kappa(A) = \frac{\sigma_1}{\sigma_m}.$$

Condition of a system of equations

▶ If we hold b fixed and A is perturbed by infinitesimal δA . Show that the relative condition number is $\kappa(A)$.