

# Monte Carlo Methods (I)

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# Monte Carlo methods

- ▶ A broad class of computational algorithms that rely on repeated random sampling to obtain numerical results.
- ▶ Use randomness to solve problems that might be deterministic in principle, but would be difficult to solve by other approaches.
- ▶ Commonly used in three classes of problems:
  - ▶ Integration
  - ▶ Generating samples from a probability distribution
  - ▶ Optimization



# Who is Monte Carlo?

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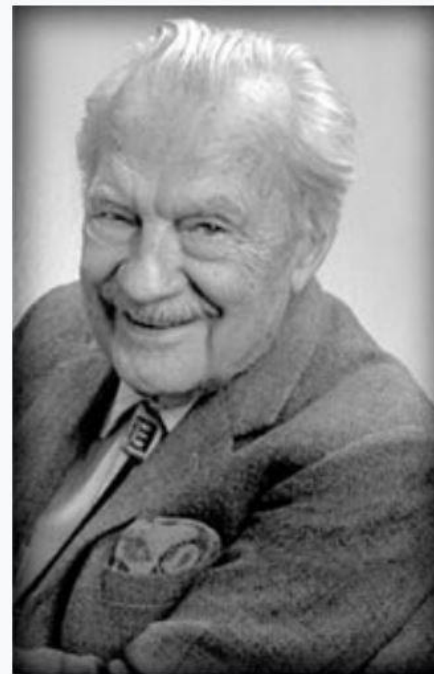
**Stanisław Ulam**



**John von Neumann**

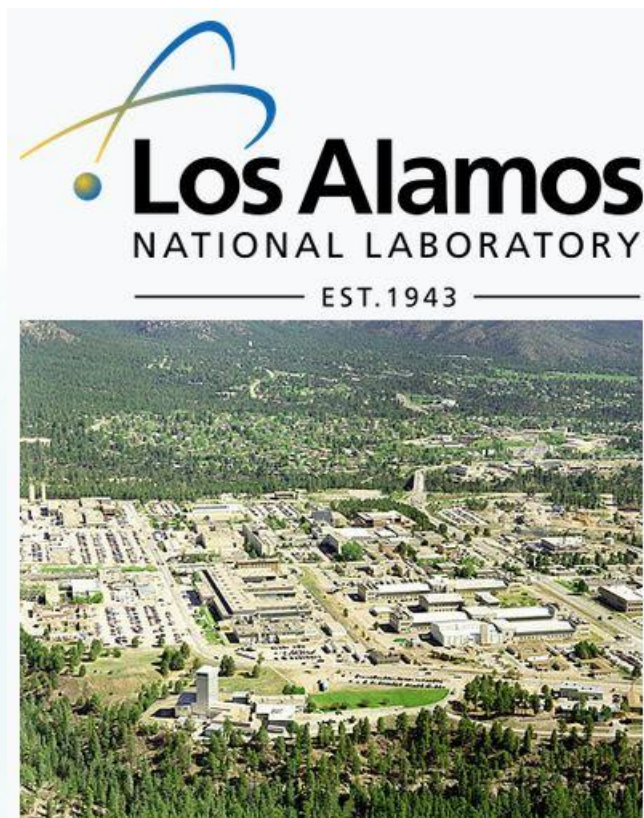


**Nicholas Metropolis**



# Who is Monte Carlo?

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The [Trinity test](#) of the Manhattan Project was the first detonation of a [nuclear weapon](#).





# Who is Monte Carlo?

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**Stanisław Ulam**



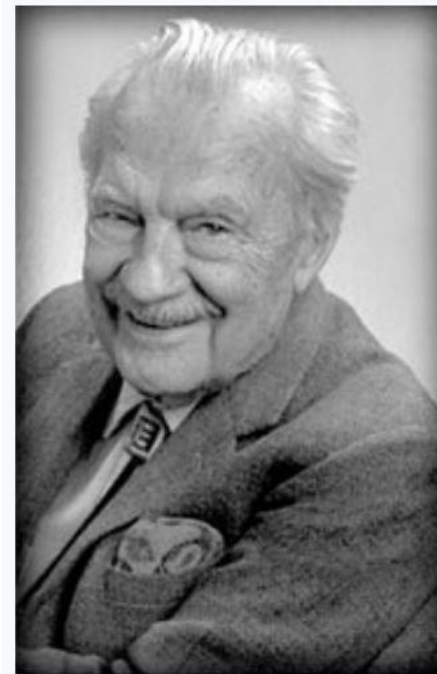
Proposed using random experiments

**John von Neumann**



Invented a way to generate pseudorandom numbers

**Nicholas Metropolis**



Invented the Metropolis sampler and gave the project the code name "Monte Carlo"

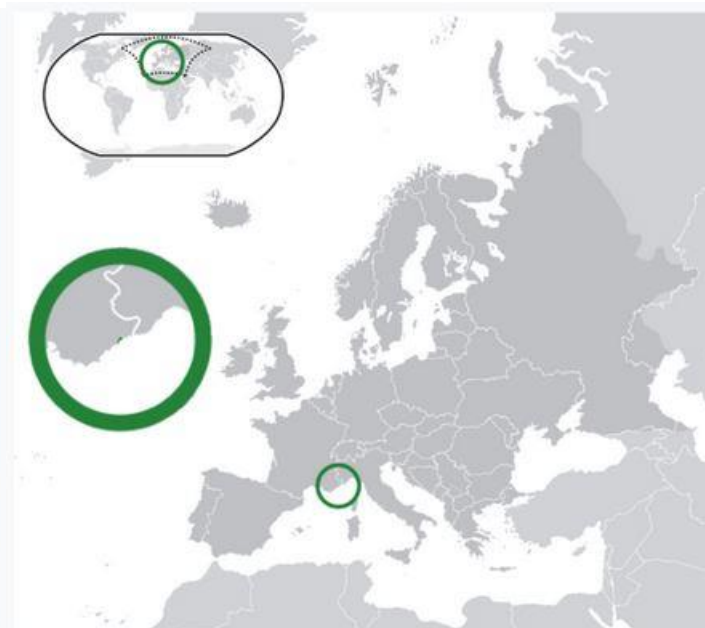


# Who is Monte Carlo?

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Casino de Monte-Carlo



Location of Monaco (green)  
in Europe (green & dark grey)

Monte Carlo (literally "Mount Charles"), is an administrative area of the Principality of Monaco.





# Who is Monte Carlo?

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Andrea Finaudi

Panoramic view of Monaco from the [Tête de Chien](#) in 2017



Area of Monaco ~ 499 acres  
Area of Tsinghua ~ 1000 acres



# Monte Carlo integration

*Integration  $\Rightarrow$  sample mean:*

Let  $g(x)$  be a function and suppose that we want to compute  $\int_a^b g(x)dx$ .

Recall that if  $X$  is a random variable with density  $f(x)$ , then the mathematical expectation of the random variable  $g(X)$  is

$$E[g(X)] = \int_{-\infty}^{\infty} g(x)f(x)dx.$$

If a random sample is available from the distribution of  $X$ , an unbiased estimator of  $E[g(X)]$  is the sample mean.





# A simple case

- ▶ Consider the problem of estimating  $\theta = \int_0^1 g(x)dx$ .

- ▶ If  $X_1, \dots, X_m$  is a random Uniform(0,1) sample, then

$$\hat{\theta} = \overline{g_m(X)} = \frac{1}{m} \sum_{i=1}^m g(X_i)$$

converges to  $E[g(X)] = \theta$  with probability 1, by the *Strong Law of Large Numbers*.

- ▶ The simple Monte Carlo estimator of  $\int_0^1 g(x)dx$  is  $\overline{g_m(X)}$ .



# Exercise

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Compute a Monte Carlo estimate of  $\int_0^1 e^{-x} dx$  and compare the estimate with the exact value.



# More general cases

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To compute  $\theta = \int_a^b g(x)dx$ , we can replace the Uniform(0,1) density with Uniform(a,b):

$$\int_a^b g(x)dx = (b - a) \int_a^b g(x) \frac{1}{b - a} dx$$

The integral is therefore  $(b - a)$  times the average value of  $g(\cdot)$  over  $(a, b)$ .





# Exercise

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Compute a Monte Carlo estimate of  $\int_2^4 e^{-x} dx$  and compare the estimate with the exact value.



# Exercise

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Use the Monte Carlo approach to estimate the standard normal cdf

$$\Phi(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt.$$

- ▶ the uniform distribution approach
- ▶ the normal distribution approach



# Importance sampling

- ▶ The estimate  $\frac{b-a}{m} \sum_{i=1}^m g(X_i)$  with uniformly distributed  $\{X_i\}$  converges to  $\int_a^b g(x)dx$  with probability 1 by the strong law of large numbers.
- ▶ One limitation of this method is that it does not apply to unbounded intervals.
- ▶ Another drawback is that it can be inefficient to draw samples uniformly across the interval if the function  $g(x)$  is not very uniform.
- ▶ It seems reasonable to consider other densities than uniform. This leads us to a general method called *importance sampling*.





# Importance sampling

- Suppose  $X$  is a random variable with density function  $f(x)$ , such that  $f(x) > 0$  on the set  $\{x : g(x) > 0\}$ . Let  $Y$  be the random variable  $g(X)/f(X)$ . Then

$$\int g(x)dx = \int \frac{g(x)}{f(x)} f(x)dx = E[Y].$$

- Estimate  $E[Y]$  by simple Monte Carlo integration. That is, compute the average

$$\frac{1}{m} \sum_{i=1}^m Y_i = \frac{1}{m} \sum_{i=1}^m \frac{g(X_i)}{f(X_i)},$$

where the random variables  $X_i$  are generated from the distribution with density  $f(x)$ . The density  $f(x)$  is called the *importance function*.



# Importance sampling

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- ▶ Question: what is the variance of the importance sampling estimate?
- ▶ Conclusion: choose  $f(x)$  to make  $g(x)/f(x)$  close to a constant.



# Bayesian inference

- ▶ From a Bayesian perspective, in a statistical model both the observables and the *parameters are random*.
- ▶ The parameters  $\theta$  has *prior* distribution  $f_{\theta}(\theta)$ .
- ▶ The distribution of  $X$  depends on  $\theta$ . The likelihood of the observed data  $x = \{x_1, \dots, x_n\}$  given  $\theta$  is  $f(x_1, \dots, x_n \mid \theta)$ .





# Bayesian inference

- Once data is observed, one can update the distribution of  $\theta$  conditional on the information in the sample  $x$ . The *posterior* distribution of  $\theta$  given  $x$  is

$$f_{\theta|x}(\theta | x) = \frac{f_{x|\theta}(x | \theta)f_{\theta}(\theta)}{f_x(x)} = \frac{f_{x|\theta}(x | \theta)f_{\theta}(\theta)}{\int f_{x|\theta}(x | \theta)f_{\theta}(\theta)d\theta}.$$

- Then a point estimate for  $g(\theta)$  could be

$$E_{\theta|x}[g(\theta)] = \int g(\theta)f_{\theta|x}(\theta | x)d\theta = \frac{\int g(\theta)f_{x|\theta}(x | \theta)f_{\theta}(\theta)d\theta}{\int f_{x|\theta}(x | \theta)f_{\theta}(\theta)d\theta}.$$



# MCMC integration

- ▶ Markov Chain Monte Carlo (MCMC) integration is a popular way to compute  $E_{\theta|x}[g(\theta)]$ .

- ▶ We have learned that we can approximate  $E_{\theta|x}[g(\theta)] = \int g(\theta)f_{\theta|x}(\theta | x)d\theta$  by generating random samples  $Y_1, \dots, Y_m$  from the distribution  $f_{\theta|x}(\theta | x)$ , then

$$\bar{g} = \frac{1}{m} \sum_{i=1}^m g(Y_i)$$

is an estimate of  $E_{\theta|x}[g(\theta)]$ . This explains the second “MC” in “MCMC” .

- ▶ The remaining problem is:  $f_{\theta|x}(\theta | x) = \frac{f_{x|\theta}(x|\theta)f_{\theta}(\theta)}{\int f_{x|\theta}(x|\theta)f_{\theta}(\theta)d\theta}$  is hard to compute.  
How do we generate samples from this distribution?



# Random sample generation

- ▶ Generating simple univariate random samples is easy:
  - ▶ Generate a uniform sample  $u = \{u_1, u_2, \dots, u_n\}$  from  $\text{Uniform}(0, 1)$ ;
  - ▶ Let  $x = F^{-1}(u)$ , where  $F$  is the cdf of the target distribution;
  - ▶ Then  $x$  is a random sample from  $F$ .





# Rejection sampling

Another method is called rejection sampling, or the acceptance-rejection method, which doesn't require calculating  $F^{-1}(x)$ .

Find a distribution with density  $g$  satisfying  $f(t) \leq c \cdot g(t)$ , for all  $t$  such that  $f(t) > 0$ .

1. Generate a random  $y$  from the distribution with density  $g$ .
2. Generate a random  $u$  from the Uniform(0, 1) distribution.
3. If  $u < \frac{f(y)}{c \cdot g(y)}$ , accept  $y$  and output  $x = y$ ; otherwise reject  $y$ . Repeat 1-3.



# Rejection sampling

- ▶ Given  $Y$ , the probability of acceptance is

$$P(\text{accept} \mid Y) = P\left(U < \frac{f(Y)}{c \cdot g(Y)} \mid Y\right) = \frac{f(Y)}{c \cdot g(Y)}.$$

- ▶ The overall probability of acceptance is

$$P(\text{accept}) = \int P(\text{accept} \mid y) g(y) dy = \int \frac{f(y)}{c \cdot g(y)} g(y) dy = \frac{1}{c}.$$

Thus  $c$  should be small.



# Rejection sampling

- To see that the accepted sample has density  $f$ , apply Bayes' Theorem.

$$pdf(x \mid \text{accepted}) = \frac{P(\text{accepted} \mid x)g(x)}{P(\text{accepted})} = \frac{\left(\frac{f(x)}{c \cdot g(x)}\right)g(x)}{1/c} = f(x)$$



# Exercise

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- ▶ Generate random samples that follows the Beta(2, 2) distribution, whose density function is  $f(x) = 6x(1 - x)$ ,  $0 < x < 1$ .
- ▶ On average, how many iterations will be required to generate 1000 samples?

