#### GM8136

### SD CARD CONTROLLER

**User Guide** 

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### **REVISION HISTORY**

#### **GM8136 SD Card User Guide**

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## Chapter 1

## Introduction

This chapter contains the following sections:

- 1.1 Version of the Software
- 1.2 Brief Description
- 1.3 Terminology
- 1.4 Development Environments
- 1.5 Design Assumptions



#### 1.1 Version of the Software

Software release version: 1.0.0

#### 1.2 Brief Description

FTSDC021 is a SD host controller that complies with the SD Host Controller Standard Specification, version 3.00. This document is for users to understand the Linux kernel 3.3 driver for FTSDC021. This driver provides the patch to drivers/host/mmc/sdhci.c and is mainly used for the vendor-defined register program.

Several new features in the standard specification support the SDXC card, such as the 1.8-V I/O signal voltage, and execute the tuning procedure in the SDR50 mode and SDR104 mode. In addition, because the AHB bus is used by FTSDC021, sdhci-ftsdc021.c will be used to register the driver to the platform bus so that the driver probe function can be called to complete the initialization job.

#### 1.3 Terminology

Item	Description
SD	Security Digital
MMC	Multimedia Card
SDIO	Security Digital Input/Output
SDR50	Single Data Rate (Up to 100MHz)
SDR140	Single Data Rate (Up to 208MHz)

#### 1.4 Development Environments

Table 1-1. Host Development Environments

Item	Description
Host platform	PC with Intel Pentium II or above
Host RAM	256MB or above
Host OS	Any PC Linux for cross compiler
Host cross compiler	GCC 4.4.0 cross compiler by uclibc

Table 1-2. Target Development Environments

Item	Description
Target platform	GM8136 EVB
Target RAM	512MB or above
Target OS	Linux 3.3
Host cross compiler	GCC 4.4.0-cross compiler by uclibc

#### 1.5 Design Assumptions

Users must define the transfer modes, as shown in Table 1-3, to change the way data transferred by host between the SD card and system memory.

Table 1-3. Modes for Data Transfers

Item	Description
Transfer_through_ADMA	Use the ADMA transfer mode
Transfer_through_SDMA	Use the SDMA transfer mode
Transfer_through_PIO	Use the PIO transfer mode

Since the information provided from SD may not always be correct, the additional timeout values will be required for the abnormal cards. Users can use the largest timeout value to avoid receiving the error message, "mmcblk0: error -110 transferring data". Please use sdhci-ftsdc021.c for SDHCI\_QUIRK\_BROKEN\_TIMEOUT\_VAL. SDHCI\_QUIRK\_CAP\_CLOCK\_BASE\_BROKEN should be used if FTSDC021 does not provide the base clock frequency information.



The following figures illustrate how to configure the SD/MMC driver for FTSDC021 in Linux 3.3 on the platform. Users should do it step by step and use the built-in kernel SD/MMC driver for FTSDC021.

```
.config - Linux/arm 3.3.0 Kernel Configuration
                   Linux/arm 3.3.0 Kernel Configuration
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
           CPU Power Management --->
           Floating point emulation
           Userspace binary formats --->
           Power management options --->
       [*] Networking support --->
         Device Drivers --->
           File systems --->
           Kernel hacking --->
           Security options --->
       -*- Cryptographic API --->
                     <Select>
                                 < Exit >
                                             < Help >
```

```
.config - Linux/arm 3.3.0 Kernel Configuration
                               Device Drivers
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       < > Multimedia support --->
           Graphics support --->
       < > Sound card support --->
       [*] HID Devices --->
        [*] USB support --->
       <<mark>*</mark>> MMC/SD/SDIO card support --->
       < > Sony MemoryStick card support (EXPERIMENTAL) --->
         ] LED Support --->
         ] Accessibility support
         ] Real Time Clock --->
                     <Select>
                                 < Exit >
                                             < Help >
```

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In the MMC/SD/SDIO card support option, users should choose the following item. After setting the menu configuration in kernel, users should build the kernel image and the SD/MMC driver is built in the image.

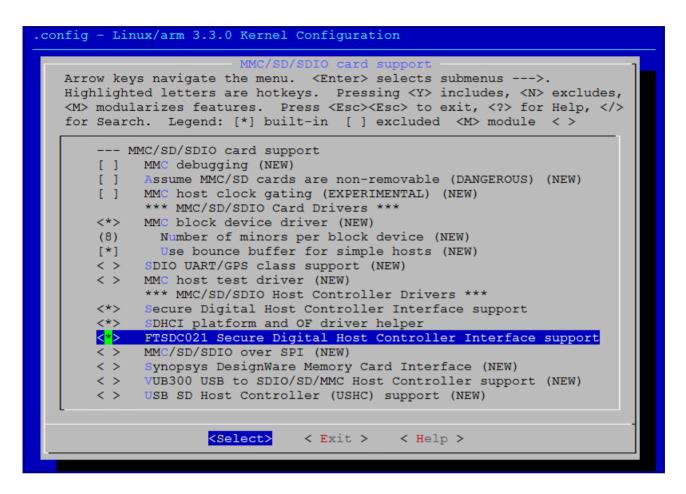


Table 1-4. Design Assumptions of Current Release

Item	Description
Related hardware	FTSDC021
Interrupt parameters	• IRQ 15 (SDC#0)
	• IRQ 17 (SDC#1)
	Level triggered
	Active high
Physical address range	• 0x92800000 ~ 0x92800FFF (SDC#0)
	• 0x93800000 ~ 0x93800FFF (SDC#1)







## Chapter 2

## **Setup and Configuration**

This chapter contains the following sections:

- 2.1 Kernel Driver Embedded
- 2.2 Build Driver as Modules
- 2.3 Using Software



#### 2.1 Kernel Driver Embedded

This is the default option of the platform and users are suggested using this option. Figure 2-1 is the booting output message of the built-in driver.

```
usbcore: registered new interface driver usb-storage
USB Mass Storage support registered.
mousedev: PS/2 mouse device common for all mice
ftiic010 ftiic010.0: irg 18, mapped at 9f86a000
sdhci: Secure Digital Host Controller Interface driver
sdhci: Copyright(c) Pierre Ossman
mmc0: SDHCI controller on ftsdc021.0 [ftsdc021.0] using ADMA
sdhci-pltfm: SDHCI platform and OF driver helper
usbcore: registered new interface driver usbhid
usbhid: USB HID core driver
TCP cubic registered
NET: Registered protocol family 17
Warning: unable to open an initial console.
Freeing init memory: 2000K
BusyBox v1.19.4 (2013-03-11 11:10:36 CST) built-in shell (ash)
Enter 'help' for a list of built-in commands.
 # mmc0: new SDHC card at address 7043
nmcblk0: mmc0:7043 SR04G 3.69 GiB
mmcblk0: p1
```

Figure 2-1. Boot Process by Using Built-in Kernel Driver



#### 2.2 Build Driver as Modules

Grain Media does not suggest using this option. It is more complicated and waste time. Figure 2-2 shows the menu configuration for building the FTSDC021 driver as a module.

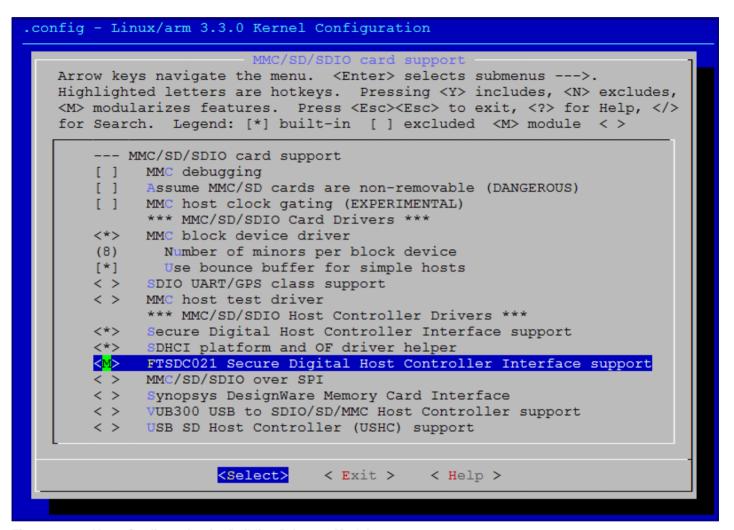


Figure 2-2. Menu Configuration for Building Driver as Module



#### 2.3 Using Software

After booting Linux, the FTSDC021 driver is also brought up. Users can insert the SD card. Then, the card detecting message will be shown on the terminal. Next, users can use "mdev -s" to generate the device node which is /dev/mmcblk0p1, as shown in Figure 2-3. Users can then use "mount -t vfat /dev/mmcblk0p1 /mnt/sd" to mount the SD card.

```
sdhci: Copyright(c) Pierre Ossman
mmc0: SDHCI controller on ftsdc021.0 [ftsdc021.0] using ADMA
sdhci-pltfm: SDHCI platform and OF driver helper
usbcore: registered new interface driver usbhid
usbhid: USB HID core driver
TCP cubic registered
NET: Registered protocol family 17
Warning: unable to open an initial console.
Freeing init memory: 2000K
mmc0: new SDHC card at address 7043
mmcblk0: mmc0:7043 SR04G 3.69 GiB
mmcblk0: p1
BusyBox v1.19.4 (2013-03-11 11:10:36 CST) built-in shell (ash)
Enter 'help' for a list of built-in commands.
 # mdev -s
 # mkdir /mnt/sd
 # mount -t vfat /dev/mmcblk0p1 /mnt/sd/
 # df
Filesystem
                     1K-blocks
                                    Used Available Use% Mounted on
/dev/mmcblk0p1
                       3861392
                                           3861388
                                                     0% /mnt/sd
```

Figure 2-3. Mount SD Card in Platform



# Chapter 3

## **Test Case**

This chapter contains the following sections:

- 3.1 Test Driver 1: mmc\_test
- 3.2 Test Driver 2: mmc\_block
- 3.3 USB Auto-mount/Auto-umount
- 3.4 Reference File



#### 3.1 Test Driver 1: mmc\_test

mmc\_test is the built-in test program in kernel 3.3. This driver provides basic raw-data read/write tests for the memory cards. Users should insert the mmc\_test driver into the kernel after the steps described in Section 2.3 are completed. The procedure is shown in Figure 3-1. It includes 18 test cases in mmc\_test. Command: echo "#" > /sys/devices/platform/ftsdc010/mmc\_host\:mmc0/mmc0\:b368/test

```
sys/class/mmc_host/mmc0/mmc0:0002/test
sys/class/mmc host/mmc0/mmc0:0002/type
/svs/class/mmc host/mmc0/mmc0:0002/uevent
 $ echo 18 > /sys/class/mmc_host/mmc0/mmc0\:0002/test
mmc test store
mmc0: Starting tests of card mmc0:0002...
mmc0: Test case 18. Correct xfer_size at read (midway failure)...
mmc0: Timeout waiting for hardware interrupt.
Timeout in DMA read/write
ret :0
mmc0: Result: OK
mmc0: Tests completed.
 $ echo 1mmc test storemmc host/mmc0/mmc0\:0002/test
> /sys/class/mmcmmc0: Starting tests of card mmc0:0002...
hmmc0: Test case 1. Basic write (no data verification)...
ost/mmc0/mmc0 : 0002/test
ret :0
mmc0: Result: OK
mmc0: Tests completed.
 $ echo 2 > /sys/class/mmc host/mmc0/mmc0\mmc test store
:0002/test
mmc0: Starting tests of card mmc0:0002...
mmc0: Test case 2. Basic read (no data verification)...
ret :0
mmc0: Result: OK
```

Figure 3-1. Insert and Execute mmc\_test in Kernel



#### 3.2 Test Driver 2: mmc\_block

mmc\_block.ko should already be inserted or built in the kernel; otherwise, the mount command will fail. Users can use the "mount" and "ls" commands to perform the block test.

Command: mount -t vfat /dev/mmcblk0 /mnt/sd

```
/ $ 1s -a1 /dev/mmc*
brw-rw---- 1 root root 179, 0 Jan 1 00:00 /dev/mmcb1k0
/ $
/ $ mount -t vfat /dev/mmcb1k0 /mnt/sd
/ $ cd /mnt/sd
/mnt/sd $ 1s
/mnt/sd $
```

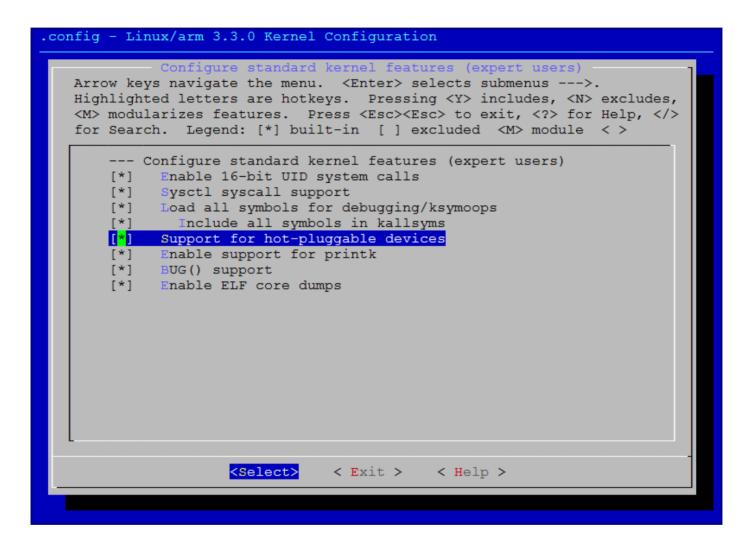
Figure 3-2. mmc\_block Test



#### 3.3 USB Auto-mount/Auto-umount

If users want to use auto-mount/auto-umount for the SD card, the following steps should be executed:

1. Open the hot-pluggable function in the kernel menu configuration. The path is General setup -> Configure standard kernel features -> Support for hot-pluggable devices. Please refer to the image below.



2. Add the commands in "arm-linux-3.3/target/rootfs-cpio/etc/init.d/rc.sysinit". Please refer to the image below.

```
1 #!/bin/sh
 2
 3 PATH=/bin:/sbin:/usr/bin:/usr/sbin
 4 export PATH
 5
6 # mount root filesystem in read-write mode
 7 /bin/busybox echo "Mounting root fs rw ..."
8 /bin/busybox mount -n -o remount,rw /
10 if [! -e /proc/mounts]; then
       /bin/busybox mount -t sysfs sysfs /sys
12
       /bin/busybox mount -t proc proc /proc
13 fi
14
15 echo "-----Starting mdev....."
16 /bin/echo /sbin/mdev > /proc/sys/kernel/hotplug
17
18 /bin/busybox mdev -s
19 /bin/busybox --install -s
20
21 # mount all other filesystems
22 /bin/busybox echo "Mounting other filesystems ...'
23 /bin/busybox mount -a
```

3. Create the "arm-linux-3.3/target/rootfs-cpio/etc/mdev.conf" file with the following content (Line 1 is used for USB and Line 2 is used for SD card.)

```
1 sd.* 0:0 660 */sbin/automount.sh $MDEV
2 mmc.* 0:0 660 */sbin/automount.sh $MDEV
```



4. Create the "arm-linux-2.6/target/rootfs-cpio/sbin/automount.sh" file with the following content (For example)

```
1 MOUNT=/bin/mount
 2 UMOUNT=/bin/umount
 3 MKDIR=/bin/mkdir
 4 RMDIR=/bin/rmdir
 5 case $1 in
            "mmcblk0")
            domount $1
 8
 9
            "mmcblk0p1")
10
            domount $1
11
12
            "sda")
13
            domount $1
14
            "sdb")
15
16
            domount $1
17
            ;;
18
            "sdc")
            domount $1
19
20
21
            "sdd")
22
            domount $1
23
            ;;
*)
24
25
            exit 1
26
            ;;
27 esac
28
29 function domount{
            M=`mount | grep $1`
if [ "$M" = "" ]; then
31
32
                     if [ ! -d /mnt/$1 ]; then
33
                             $MKDIR /mnt/$1
34
35
                     MOUNT -t vfat /dev/$1 /mnt/$1
36
            else
37
                     $UMOUNT -lf /mnt/$1
38
                     $RMDIR /mnt/$1
39
            fi
40 }
```

5. Under "arm-linux-2.6/user/busybox-1.13.4", use "make menuconfig" to enable the mdev related functions. The item is in "Linux System Utilities". Please refer to the image below.

```
BusyBox 1.13.4 Configuration
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <M> modularizes features. Press <Esc> to exit, <?> for Help, </>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       ipcs
    [*] losetup
   [<mark>*</mark>] mdev
         Support /etc/mdev.conf
            upport subdirs/symlinks
              upport regular expressions substitutions when renaming dev
            upport command execution at device addition/removal
          upport loading of firmwares
    [*] mkswap
          ersion 0 support
                                  < Exit >
                                             < Help >
```

- 6. Use "make" to generate busybox and copy busybox to the path, "arm-linux-2.6/target/rootfs-cpio/bin"
- 7. Build the Linux image and users can get the auto-mount/auto-unmount feature for the SD card

#### 3.4 Reference File

FTSDC021 Data Sheet

