

A Algorithms

Algorithm 1: Caching a skill in an abstract domain.

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1 Algorithm cachSkill
   Inputs:
   | A state trace from the skill execution  $\mathfrak{S}(\mathbf{E})$ 
   | A public abstraction key  $PubKey = (\text{project}_p, \text{reconst}_p, \mathcal{P}_s)$ 
   Output:
   | Caching success flag

2  $validPrivateKeys \leftarrow \bigcap_{s \in \mathfrak{S}(\mathbf{E})} \mathcal{P}_s$ 
3 if  $validPrivateKeys \neq \emptyset$  then
4   | Select a key  $p$  from  $validPrivateKeys$ 
5   |  $abstractTrace \leftarrow \text{project}_p(\mathfrak{S}(\mathbf{E}))$ 
6   |  $DataBase.add(abstractTrace, PubKey)$ 
7   | return True // caching succeeded
8 end
9 return False // caching failed, try another public key

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Algorithm 3: Reconstruction of a cached abstract skill.

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1 Algorithm reconstructSkill
  Inputs:
  | An abstract skill's state trace  $(\xi_0, \dots, \xi_n)$ 
  | A public key  $PubKey = (\text{project}_p, \text{reconst}_p, \mathcal{P}_s)$ 
  | A "classical" task planning problem  $P \doteq (D, \mathbf{S}_{\text{start}}, \mathbf{S}_{\text{goal}})$ 
  Output:
  | A plan that solves the given problem, if reconstruction
  | succeeded; otherwise, returns False

2  $p \leftarrow \text{getPrivateKey}(\xi_0, \xi_n, \mathbf{S}_{\text{start}}, \mathbf{S}_{\text{goal}}, PubKey)$ 
3 if  $p \neq \mathbf{False}$  then                                     // skill is applicable
4    $states \leftarrow \text{reconst}_p(\xi_0, \dots, \xi_n)$  // reconstruct state trace
5    $actions \leftarrow \text{recoverActions}(states, D)$  // recover actions
6   if  $actions \neq \mathbf{False}$  then
7     return  $actions$ 
8   end
9 end
10 return False

1 Procedure recoverActions
  Inputs:
  | A state trace  $(S_0, \dots, S_n)$ 
  | A planning domain  $D$ 
  Output:
  | If feasible, returns a sequence of actions that follows the states in
  | the trace; otherwise, returns False

2 for  $i \in \{1, \dots, n\}$  do
3   if  $\exists$  an action  $a \in \mathcal{A}$  between  $S_{i-1}$  and  $S_i$  then
4      $a_i \leftarrow a$ 
5   end
6   else
7     return False                                     // unfeasible
8   end
9 end
10 return  $(a_1, \dots, a_n)$                              // feasible

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