

1 *Equações de Navier-Stokes Aplicadas em Escoamentos Monofásicos*

1.1 Descrição do Problema

Escrever Texto sobre o problema.

Serão utilizadas as seguintes hipóteses:

1. Escoamento monofásico;
2. Fluido monocomponente;
3. Não há trocas de calor entre o meio e a tubulação;
4. Escoamento isotérmico;
5. Sem atrito com as paredes do tubo (Equação de Euler);

1.2 Equações Governantes

A equação de Navier-Stokes unidimensional pode ser escrita como:

$$\frac{\partial}{\partial t}(\rho) + \nabla \cdot (\rho \vec{v}) = S_m \quad (1.1)$$

$$\frac{\partial}{\partial t}(\rho \vec{v}) + \nabla \cdot (\rho \vec{v} \vec{v}) = -\nabla p + \rho g \sin(\theta) \quad (1.2)$$

A Eq. 1.1 representa a equação da conservação da massa sendo uma equação puramente convectiva. A eq. 1.2 é a conservação da quantidade de movimento sendo

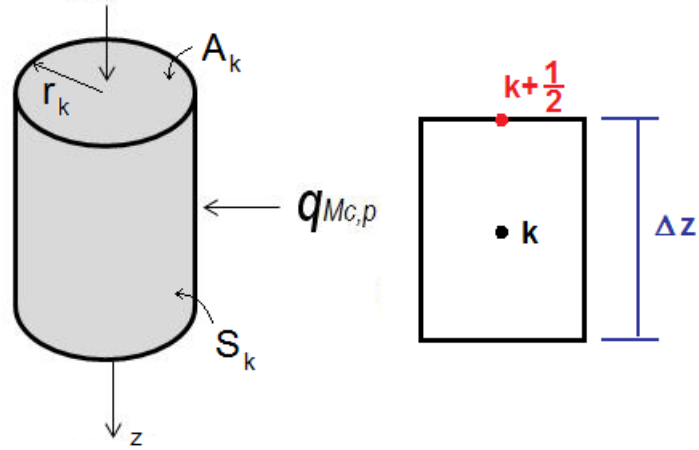


Figura 1: Volume de Controle Unidimensional.

uma equação difusiva e convectiva. Observa-se dois fatos que tornam a solução numérica desse conjunto de equações difícil:

1. A Eq. da quantidade de movimento é não linear pois apresenta o produto de velocidades na derivada.
2. As equações estão acopladas entre si, o que torna inviável a solução delas de forma separada.

1.3 Volume de Controle

A Fig. 1, ilustra o volume de controle que será adotado para a discretização das equações médias de transporte. O subíndice k representa o elemento discreto de uma tubulação na direção z . As variáveis A_k , S_k e r_k representam, respectivamente, a área transversal ao escoamento, a superfície lateral e o raio do elemento discreto. O termo $q_{m_{c,p}}$ representa a vazão mássica do componente c na fase p por unidade de volume.

De acordo com a Fig. 1, é possível definir os seguintes termos:

$$dV_k = \pi r_k^2 \Delta z_k \quad (1.3)$$

$$A_k = \pi r_k^2 \quad (1.4)$$

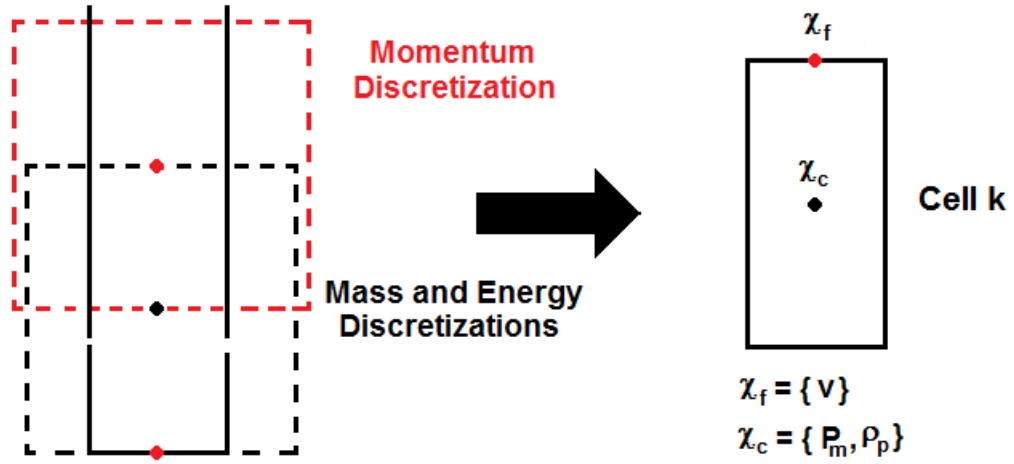


Figura 2: Malha deslocada para solução das equações de Navier-Stokes unidimensionais.

$$dS_k = 2\pi r_k \Delta z_k \quad (1.5)$$

Para facilitar a solução das equações, será adotado o esquema de malhas deslocadas, mostrado na Figura 2. Nesse esquema a pressão é armazenada no centro da célula e a velocidade na face da mesma.

1.4 Equações de Navier-Stokes discretizadas

Será aplicado o método dos volumes finitos na equação da difusão como descrito no capítulo 4 e 8 de ??) .

1.4.1 Conservação da Massa

Utilizando o método dos volumes finitos, a equação da conservação da massa pode ser escrita como:

$$\int_t^{t+\Delta t} \iiint_{V.C.} \frac{\partial}{\partial t} (\rho) dV dt + \int_t^{t+\Delta t} \iiint_{V.C.} \nabla \cdot (\rho \vec{v}) dV dt = \int_t^{t+\Delta t} \iiint_{V.C.} S_m dV dt \quad (1.6)$$

Aplicando a regra de Leibiniz no primeiro termo:

$$\iiint_{V.C.} \int_t^{t+\Delta t} \left[\frac{\partial}{\partial t} (\rho) \right] dt dV + \int_t^{t+\Delta t} \iiint_{V.C.} \nabla \cdot (\rho \vec{v}) dV dt = \int_t^{t+\Delta t} \iiint_{V.C.} S_m dV dt \quad (1.7)$$

Aplicando o teorema de Gauss:

$$\iiint_{V.C.} \int_t^{t+\Delta t} \left[\frac{\partial}{\partial t} (\rho) \right] dt dV + \int_t^{t+\Delta t} \iiint_{S.C.} (\rho \vec{v}) \cdot \vec{n} dS dt = \int_t^{t+\Delta t} \iiint_{V.C.} S_m dV dt \quad (1.8)$$

Avaliando a integral no tempo do primeiro termo da equação:

$$\int_t^{t+\Delta t} \left[\frac{\partial}{\partial t} (\rho) \right] dt = \rho^{n+1} - \rho^n \quad (1.9)$$

Para se avaliar as integrais no tempo das outras variáveis, será utilizado um parâmetro θ que pondera quanta informação deve ser utilizada do passo de tempo anterior, assim:

$$\int_t^{t+\Delta t} f(x, t) dt = [\theta f^{n+1} + (1 - \theta) f^n] \Delta t \quad (1.10)$$

Como será utilizado um esquema totalmente implícito, $\theta = 1$, assim:

$$\int_t^{t+\Delta t} f(x, t) dt = f^{n+1} \Delta t \quad (1.11)$$

Substituindo na Equação 1.8 e utilizando o volume de controle unidimensional (Figura 1):

$$(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} = (AS_m\Delta x)_k^{n+1} \quad (1.12)$$

1.4.2 Conservação da Quantidade de Movimento

A equação da quantidade de movimento pode ser escrita como:

$$\int_t^{t+\Delta t} \iiint_{V.C.} \frac{\partial}{\partial t} (\rho \vec{v}) dV dt + \int_t^{t+\Delta t} \iiint_{V.C.} \nabla \cdot (\rho \vec{v} \vec{v}) dV dt = - \int_t^{t+\Delta t} \iiint_{V.C.} \nabla p dV dt + \int_t^{t+\Delta t} \iiint_{V.C.} \rho g_{sen}(\theta) dV dt \quad (1.13)$$

Aplicando o teorema de Gauss e a regra de Leibiniz:

$$\iiint_{V.C.} \int_t^{t+\Delta t} \left[\frac{\partial}{\partial t} (\rho \vec{v}) \right] dt dV + \int_t^{t+\Delta t} \iint_{S.C.} (\rho \vec{v} \vec{v}) \cdot \vec{n} dS dt = - \int_t^{t+\Delta t} \iiint_{V.C.} \nabla p dV dt + \int_t^{t+\Delta t} \iiint_{V.C.} \rho g_{sen}(\theta) dV dt \quad (1.14)$$

Discretizando implicitamente no tempo, e utilizando o volume de controle unidimensional:

$$\iiint_{V.C.} [(\rho \vec{v})^{n+1} - (\rho \vec{v})^n] dV + \iint_{S.C.} (\rho \vec{v} \vec{v})^{n+1} \cdot \vec{n} dS \Delta t = - \iiint_{V.C.} \nabla p^{n+1} dV \Delta t + \iiint_{V.C.} \rho^{n+1} g_{sen}(\theta) dV \Delta t \quad (1.15)$$

$$(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] = - \left(A\Delta x \frac{\partial p}{\partial x} \right)_{k+\frac{1}{2}}^{n+1} + (A\Delta x \rho g_{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \quad (1.16)$$

Utilizando diferenças finitas para aproximar a derivada da pressão:

$$(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] = - (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} + (A\Delta x \rho g_{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \quad (1.17)$$

Será utilizado o esquema de interpolação Donor-Cell para se avaliar a velocidade no centro das células.

1.5 Algoritmo COUPLE com formulação Full-Implicit

1.5.1 Método de Newton-Rapson

A formulação implícita do problema será realizada utilizando-se o método de Newton-Raphson, descrito por:

$$R_k^\nu + \sum_j^{N \text{ Equations}} \frac{\partial R_k^\nu}{\partial x_j} \left(x_j^{(\nu+1)} - x_j^{(\nu)} \right) = 0 \quad (1.18)$$

ou em notação matricial:

$$J^\nu \delta x^{\nu+1} = -R^\nu \quad (1.19)$$

onde J é a matriz Jacobiano do problema, R é o vetor de resíduos e δx é a variação da solução do problema. Observa-se que todas as propriedades serão avaliadas no tempo $n + 1$.

Os resíduos para a equação da conservação da massa são dados por:

$$R_k^m = (A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m\Delta x)_k^{n+1} \quad (1.20)$$

Os resíduos para a equação da quantidade de movimento desprezando termos fonte, são dados por:

$$R_k^p = (A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho g \sin(\theta))_{k+\frac{1}{2}}^{n+1} \quad (1.21)$$

Dessa forma a Equação 1.19 pode ser escrita como:

$$\begin{bmatrix} \frac{\partial R_1^p}{\partial p_1} & \frac{\partial R_1^p}{\partial v_1} & \frac{\partial R_1^p}{\partial p_2} & \frac{\partial R_1^p}{\partial v_2} & \frac{\partial R_1^p}{\partial p_3} & \frac{\partial R_1^p}{\partial v_3} & \dots & \frac{\partial R_1^p}{\partial p_n} & \frac{\partial R_1^p}{\partial v_n} \\ \frac{\partial R_1^m}{\partial p_1} & \frac{\partial R_1^m}{\partial v_1} & \frac{\partial R_1^m}{\partial p_2} & \frac{\partial R_1^m}{\partial v_2} & \frac{\partial R_1^m}{\partial p_3} & \frac{\partial R_1^m}{\partial v_3} & \dots & \frac{\partial R_1^m}{\partial p_n} & \frac{\partial R_1^m}{\partial v_n} \\ \frac{\partial R_2^p}{\partial p_1} & \frac{\partial R_2^p}{\partial v_1} & \frac{\partial R_2^p}{\partial p_2} & \frac{\partial R_2^p}{\partial v_2} & \frac{\partial R_2^p}{\partial p_3} & \frac{\partial R_2^p}{\partial v_3} & \dots & \frac{\partial R_2^p}{\partial p_n} & \frac{\partial R_2^p}{\partial v_n} \\ \frac{\partial R_2^m}{\partial p_1} & \frac{\partial R_2^m}{\partial v_1} & \frac{\partial R_2^m}{\partial p_2} & \frac{\partial R_2^m}{\partial v_2} & \frac{\partial R_2^m}{\partial p_3} & \frac{\partial R_2^m}{\partial v_3} & \dots & \frac{\partial R_2^m}{\partial p_n} & \frac{\partial R_2^m}{\partial v_n} \\ \frac{\partial R_3^p}{\partial p_1} & \frac{\partial R_3^p}{\partial v_1} & \frac{\partial R_3^p}{\partial p_2} & \frac{\partial R_3^p}{\partial v_2} & \frac{\partial R_3^p}{\partial p_3} & \frac{\partial R_3^p}{\partial v_3} & \dots & \frac{\partial R_3^p}{\partial p_n} & \frac{\partial R_3^p}{\partial v_n} \\ \frac{\partial R_3^m}{\partial p_1} & \frac{\partial R_3^m}{\partial v_1} & \frac{\partial R_3^m}{\partial p_2} & \frac{\partial R_3^m}{\partial v_2} & \frac{\partial R_3^m}{\partial p_3} & \frac{\partial R_3^m}{\partial v_3} & \dots & \frac{\partial R_3^m}{\partial p_n} & \frac{\partial R_3^m}{\partial v_n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \frac{\partial R_n^p}{\partial p_1} & \frac{\partial R_n^p}{\partial v_1} & \frac{\partial R_n^p}{\partial p_2} & \frac{\partial R_n^p}{\partial v_2} & \frac{\partial R_n^p}{\partial p_3} & \frac{\partial R_n^p}{\partial v_3} & \dots & \frac{\partial R_n^p}{\partial p_n} & \frac{\partial R_n^p}{\partial v_n} \\ \frac{\partial R_n^m}{\partial p_1} & \frac{\partial R_n^m}{\partial v_1} & \frac{\partial R_n^m}{\partial p_2} & \frac{\partial R_n^m}{\partial v_2} & \frac{\partial R_n^m}{\partial p_3} & \frac{\partial R_n^m}{\partial v_3} & \dots & \frac{\partial R_n^m}{\partial p_n} & \frac{\partial R_n^m}{\partial v_n} \end{bmatrix} \begin{bmatrix} \delta p_1 \\ \delta v_1 \\ \delta p_2 \\ \delta v_2 \\ \delta p_3 \\ \delta v_3 \\ \vdots \\ \delta p_n \\ \delta v_n \end{bmatrix} = - \begin{bmatrix} R_1^p \\ R_1^m \\ R_2^p \\ R_2^m \\ R_3^p \\ R_3^m \\ \vdots \\ R_n^p \\ R_n^m \end{bmatrix} \quad (1.22)$$

Observa-se que as funções de resíduo (Equações 1.20 e 1.21) para a célula k só dependem dos vizinhos a esquerda e a direita. Logo:

$$\begin{bmatrix} \frac{\partial R_1^p}{\partial p_1} & \frac{\partial R_1^p}{\partial v_1} & \frac{\partial R_1^p}{\partial p_2} & \frac{\partial R_1^p}{\partial v_2} & 0 & 0 & \dots & 0 & 0 \\ \frac{\partial R_1^m}{\partial p_1} & \frac{\partial R_1^m}{\partial v_1} & \frac{\partial R_1^m}{\partial p_2} & \frac{\partial R_1^m}{\partial v_2} & 0 & 0 & \dots & 0 & 0 \\ \frac{\partial R_2^p}{\partial p_1} & \frac{\partial R_2^p}{\partial v_1} & \frac{\partial R_2^p}{\partial p_2} & \frac{\partial R_2^p}{\partial v_2} & \frac{\partial R_2^p}{\partial p_3} & \frac{\partial R_2^p}{\partial v_3} & \dots & 0 & 0 \\ \frac{\partial R_2^m}{\partial p_1} & \frac{\partial R_2^m}{\partial v_1} & \frac{\partial R_2^m}{\partial p_2} & \frac{\partial R_2^m}{\partial v_2} & \frac{\partial R_2^m}{\partial p_3} & \frac{\partial R_2^m}{\partial v_3} & \dots & 0 & 0 \\ 0 & 0 & \frac{\partial R_3^p}{\partial p_2} & \frac{\partial R_3^p}{\partial v_2} & \frac{\partial R_3^p}{\partial p_3} & \frac{\partial R_3^p}{\partial v_3} & \dots & 0 & 0 \\ 0 & 0 & \frac{\partial R_3^m}{\partial p_2} & \frac{\partial R_3^m}{\partial v_2} & \frac{\partial R_3^m}{\partial p_3} & \frac{\partial R_3^m}{\partial v_3} & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & 0 & 0 & \dots & \frac{\partial R_n^p}{\partial p_n} & \frac{\partial R_n^p}{\partial v_n} \\ 0 & 0 & 0 & 0 & 0 & 0 & \dots & \frac{\partial R_n^m}{\partial p_n} & \frac{\partial R_n^m}{\partial v_n} \end{bmatrix} \begin{bmatrix} \delta p_1 \\ \delta v_1 \\ \delta p_2 \\ \delta v_2 \\ \delta p_3 \\ \delta v_3 \\ \vdots \\ \delta p_n \\ \delta v_n \end{bmatrix} = - \begin{bmatrix} R_1^p \\ R_1^m \\ R_2^p \\ R_2^m \\ R_3^p \\ R_3^m \\ \vdots \\ R_n^p \\ R_n^m \end{bmatrix} \quad (1.23)$$

1.6 Derivadas Parciais

1.6.1 Derivada do resíduo da massa em relação a pressão

1.6.1.1 Bloco à esquerda:

$$\frac{\partial R_k^m}{\partial p_{k-1}} = \frac{\partial}{\partial p_{k-1}} \left[(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m\Delta x)_k^{n+1} \right] \quad (1.24)$$

$$\frac{\partial R_k^m}{\partial p_{k-1}} = \frac{\partial}{\partial p_{k-1}} \left((A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} \right) + \frac{\partial}{\partial p_{k-1}} (A\rho v)_{k+\frac{1}{2}}^{n+1} - \frac{\partial}{\partial p_{k-1}} (A\rho v)_{k-\frac{1}{2}}^{n+1} - \frac{\partial}{\partial p_{k-1}} (AS_m \Delta x)_k^{n+1} \quad (1.25)$$

$$\frac{\partial R_k^m}{\partial p_{k-1}} = - (Av)_{k-\frac{1}{2}}^{n+1} \frac{\partial}{\partial p_{k-1}} (\rho)_{k-\frac{1}{2}}^{n+1} \quad (1.26)$$

como

$$\rho_{k-\frac{1}{2}}^{n+1} = \frac{\rho_{k-1}^{n+1} + \rho_k^{n+1}}{2}$$

então:

$$\frac{\partial R_k^m}{\partial p_{k-1}} = - \frac{(Av)_{k-\frac{1}{2}}^{n+1}}{2} \frac{\partial (\rho_{k-1}^{n+1})}{\partial p_{k-1}} \quad (1.27)$$

1.6.1.2 Bloco central:

$$\frac{\partial R_k^m}{\partial p_k} = \frac{\partial}{\partial p_k} \left[(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m \Delta x)_k^{n+1} \right] \quad (1.28)$$

$$\frac{\partial R_k^m}{\partial p_k} = \frac{\partial}{\partial p_k} \left((A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} \right) + \frac{\partial}{\partial p_k} (A\rho v)_{k+\frac{1}{2}}^{n+1} - \frac{\partial}{\partial p_k} (A\rho v)_{k-\frac{1}{2}}^{n+1} - \frac{\partial}{\partial p_k} (AS_m \Delta x)_k^{n+1} \quad (1.29)$$

$$\frac{\partial R_k^m}{\partial p_k} = \frac{(A\Delta x)_k}{\Delta t} \frac{\partial (\rho_k^{n+1})}{\partial p_k} + (Av)_{k+\frac{1}{2}}^{n+1} \frac{\partial \rho_{k+\frac{1}{2}}^{n+1}}{\partial p_k} - (Av)_{k-\frac{1}{2}}^{n+1} \frac{\partial \rho_{k-\frac{1}{2}}^{n+1}}{\partial p_k} - (A\Delta x)_k^{n+1} \frac{\partial S_{mk}^{n+1}}{\partial p_k} \quad (1.30)$$

como

$$\rho_{k-\frac{1}{2}}^{n+1} = \frac{\rho_{k-1}^{n+1} + \rho_k^{n+1}}{2}$$

$$\rho_{k+\frac{1}{2}}^{n+1} = \frac{\rho_k^{n+1} + \rho_{k+1}^{n+1}}{2}$$

então:

$$\frac{\partial R_k^m}{\partial p_k} = \frac{(A\Delta x)_k}{\Delta t} \frac{\partial (\rho_k^{n+1})}{\partial p_k} + \frac{(Av)_{k+\frac{1}{2}}^{n+1}}{2} \frac{\partial (\rho_k^{n+1})}{\partial p_k} - \frac{(Av)_{k-\frac{1}{2}}^{n+1}}{2} \frac{\partial (\rho_k^{n+1})}{\partial p_k} - (A\Delta x)_k^{n+1} \frac{\partial (S_{m_k}^{n+1})}{\partial p_k} \quad (1.31)$$

$$\frac{\partial R_k^m}{\partial p_k} = \left[\frac{(A\Delta x)_k}{\Delta t} + \frac{(Av)_{k+\frac{1}{2}}^{n+1}}{2} - \frac{(Av)_{k-\frac{1}{2}}^{n+1}}{2} \right] \frac{\partial (\rho_k^{n+1})}{\partial p_k} - (A\Delta x)_k^{n+1} \frac{\partial (S_{m_k}^{n+1})}{\partial p_k} \quad (1.32)$$

1.6.1.3 Bloco à direita:

$$\frac{\partial R_k^m}{\partial p_{k+1}} = \frac{\partial}{\partial p_{k+1}} \left[(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m\Delta x)_k^{n+1} \right] \quad (1.33)$$

$$\frac{\partial R_k^m}{\partial p_{k+1}} = \frac{\partial}{\partial p_{k+1}} \left((A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} \right) + \frac{\partial}{\partial p_{k+1}} (A\rho v)_{k+\frac{1}{2}}^{n+1} - \frac{\partial}{\partial p_{k+1}} (A\rho v)_{k-\frac{1}{2}}^{n+1} - \frac{\partial}{\partial p_{k+1}} (AS_m\Delta x)_k^{n+1} \quad (1.34)$$

$$\frac{\partial R_k^m}{\partial p_{k+1}} = \frac{\partial}{\partial p_{k+1}} (A\rho v)_{k+\frac{1}{2}}^{n+1} \quad (1.35)$$

como

$$\rho_{k+\frac{1}{2}}^{n+1} = \frac{\rho_k^{n+1} + \rho_{k+1}^{n+1}}{2}$$

então:

$$\frac{\partial R_k^m}{\partial p_{k+1}} = \frac{(Av)_{k+\frac{1}{2}}^{n+1}}{2} \frac{\partial (\rho_{k+1}^{n+1})}{\partial p_{k+1}} \quad (1.36)$$

1.6.2 Derivada do resíduo da massa em relação a velocidade

1.6.2.1 Bloco à esquerda:

$$\frac{\partial R_k^m}{\partial v_{k-\frac{1}{2}}} = \frac{\partial}{\partial v_{k-\frac{1}{2}}} \left[(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m\Delta x)_k^{n+1} \right] \quad (1.37)$$

$$\frac{\partial R_k^m}{\partial v_{k-\frac{1}{2}}} = \frac{\partial}{\partial v_{k-\frac{1}{2}}} \left((A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} \right) + \frac{\partial}{\partial v_{k-\frac{1}{2}}} (A\rho v)_{k+\frac{1}{2}}^{n+1} - \frac{\partial}{\partial v_{k-\frac{1}{2}}} (A\rho v)_{k-\frac{1}{2}}^{n+1} - \frac{\partial}{\partial v_{k-\frac{1}{2}}} (AS_m \Delta x)_k^{n+1} \quad (1.38)$$

$$\frac{\partial R_k^m}{\partial v_{k-\frac{1}{2}}} = -\frac{\partial}{\partial v_{k-\frac{1}{2}}} (A\rho v)_{k-\frac{1}{2}}^{n+1} \quad (1.39)$$

$$\frac{\partial R_k^m}{\partial v_{k-\frac{1}{2}}} = -(A\rho)_{k-\frac{1}{2}}^{n+1} \quad (1.40)$$

1.6.2.2 Bloco central:

$$\frac{\partial R_k^m}{\partial v_{k+\frac{1}{2}}} = \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left[(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m \Delta x)_k^{n+1} \right] \quad (1.41)$$

$$\frac{\partial R_k^m}{\partial v_{k+\frac{1}{2}}} = \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left((A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} \right) + \frac{\partial}{\partial v_{k+\frac{1}{2}}} (A\rho v)_{k+\frac{1}{2}}^{n+1} - \frac{\partial}{\partial v_{k+\frac{1}{2}}} (A\rho v)_{k-\frac{1}{2}}^{n+1} - \frac{\partial}{\partial v_{k+\frac{1}{2}}} (AS_m \Delta x)_k^{n+1} \quad (1.42)$$

$$\frac{\partial R_k^m}{\partial v_{k+\frac{1}{2}}} = \frac{\partial}{\partial v_{k+\frac{1}{2}}} (A\rho v)_{k+\frac{1}{2}}^{n+1} \quad (1.43)$$

$$\frac{\partial R_k^m}{\partial v_{k+\frac{1}{2}}} = (A\rho)_{k+\frac{1}{2}}^{n+1} \quad (1.44)$$

1.6.2.3 Bloco à direita:

$$\frac{\partial R_k^m}{\partial v_{k+\frac{3}{2}}} = \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left[(A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} + (A\rho v)_{k+\frac{1}{2}}^{n+1} - (A\rho v)_{k-\frac{1}{2}}^{n+1} - (AS_m \Delta x)_k^{n+1} \right] \quad (1.45)$$

$$\frac{\partial R_k^m}{\partial v_{k+\frac{3}{2}}} = \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left((A\Delta x)_k \frac{(\rho^{n+1} - \rho^n)_k}{\Delta t} \right) + \frac{\partial}{\partial v_{k+\frac{3}{2}}} (A\rho v)_{k+\frac{1}{2}}^{n+1} - \frac{\partial}{\partial v_{k+\frac{3}{2}}} (A\rho v)_{k-\frac{1}{2}}^{n+1} - \frac{\partial}{\partial v_{k+\frac{3}{2}}} (AS_m \Delta x)_k^{n+1} \quad (1.46)$$

$$\frac{\partial R_k^m}{\partial v_{k+\frac{3}{2}}} = 0 \quad (1.47)$$

1.6.3 Derivada do resíduo do momentum em relação a pressão

1.6.3.1 Bloco à esquerda:

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_{k-1}} = \frac{\partial}{\partial p_{k-1}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] \right. \\ & \left. + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho g \sin(\theta))_{k+\frac{1}{2}}^{n+1} \right] \end{aligned} \quad (1.48)$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_{k-1}} = \frac{\partial}{\partial p_{k-1}} & \left((A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} \right) + \frac{\partial}{\partial p_{k-1}} (A\rho v v)_{k+1}^{n+1} - \frac{\partial}{\partial p_{k-1}} (A\rho v v)_k^{n+1} \\ & + \frac{\partial}{\partial p_{k-1}} \left[(A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} \right] - \frac{\partial}{\partial p_{k-1}} (A\Delta x \rho g \sin(\theta))_{k+\frac{1}{2}}^{n+1} \end{aligned} \quad (1.49)$$

$$\frac{\partial R_k^p}{\partial p_{k-1}} = 0 \quad (1.50)$$

1.6.3.2 Bloco central:

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_k} = \frac{\partial}{\partial p_k} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] \right. \\ & \left. + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho g \sin(\theta))_{k+\frac{1}{2}}^{n+1} \right] \end{aligned} \quad (1.51)$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_k} = & \frac{\partial}{\partial p_k} \left((A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} \right) + \frac{\partial}{\partial p_k} (A\rho v v)_{k+1}^{n+1} - \frac{\partial}{\partial p_k} (A\rho v v)_k^{n+1} \\ & + \frac{\partial}{\partial p_k} \left[(A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} \right] - \frac{\partial}{\partial p_k} (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \end{aligned} \quad (1.52)$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_k} = & \frac{(A\Delta x)_{k+\frac{1}{2}}}{\Delta t} v_{k+\frac{1}{2}}^{n+1} \frac{\partial}{\partial p_k} \left(\rho_{k+\frac{1}{2}}^{n+1} \right) - (A v v)_k^{n+1} \frac{\partial (\rho_k^{n+1})}{\partial p_k} \\ & - A_{k+\frac{1}{2}} - (g \text{sen}(\theta) A\Delta x)_{k+\frac{1}{2}}^{n+1} \frac{\partial}{\partial p_k} \left(\rho_{k+\frac{1}{2}}^{n+1} \right) \end{aligned} \quad (1.53)$$

como

$$\rho_{k+\frac{1}{2}}^{n+1} = \frac{\rho_k^{n+1} + \rho_{k+1}^{n+1}}{2}$$

então:

$$\frac{\partial R_k^p}{\partial p_k} = \left[\frac{(A\Delta x)_{k+\frac{1}{2}}}{2\Delta t} v_{k+\frac{1}{2}}^{n+1} - (A v v)_k^{n+1} - \frac{(g \text{sen}(\theta) A\Delta x)_{k+\frac{1}{2}}^{n+1}}{2} \right] \frac{\partial (\rho_k^{n+1})}{\partial p_k} - A_{k+\frac{1}{2}} \quad (1.54)$$

1.6.3.3 Bloco à direita:

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_{k+1}} = & \frac{\partial}{\partial p_{k+1}} \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] \right. \\ & \left. + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \right] \end{aligned} \quad (1.55)$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial p_{k+1}} = & \frac{\partial}{\partial p_{k+1}} \left((A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} \right) + \frac{\partial}{\partial p_{k+1}} (A\rho v v)_{k+1}^{n+1} - \frac{\partial}{\partial p_{k+1}} (A\rho v v)_k^{n+1} \\ & + \frac{\partial}{\partial p_{k+1}} \left[(A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} \right] - \frac{\partial}{\partial p_{k+1}} (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \end{aligned} \quad (1.56)$$

$$\frac{\partial R_k^p}{\partial p_{k+1}} = \frac{(A\Delta x)_{k+\frac{1}{2}}}{\Delta t} v_{k+\frac{1}{2}}^{n+1} \frac{\partial}{\partial p_{k+1}} \left(\rho_{k+\frac{1}{2}}^{n+1} \right) + (Avv)_{k+1}^{n+1} \frac{\partial (\rho_{k+1}^{n+1})}{\partial p_{k+1}} + A_{k+\frac{1}{2}} - (gsen(\theta) A\Delta x)_{k+\frac{1}{2}}^{n+1} \frac{\partial}{\partial p_{k+1}} \left(\rho_{k+\frac{1}{2}}^{n+1} \right) \quad (1.57)$$

como

$$\rho_{k+\frac{1}{2}}^{n+1} = \frac{\rho_k^{n+1} + \rho_{k+1}^{n+1}}{2}$$

então:

$$\frac{\partial R_k^p}{\partial p_{k+1}} = \left[\frac{(A\Delta x)_{k+\frac{1}{2}}}{2\Delta t} v_{k+\frac{1}{2}}^{n+1} + (Avv)_{k+1}^{n+1} - \frac{(gsen(\theta) A\Delta x)_{k+\frac{1}{2}}^{n+1}}{2} \right] \frac{\partial (\rho_{k+1}^{n+1})}{\partial p_{k+1}} + A_{k+\frac{1}{2}} \quad (1.58)$$

1.6.4 Derivada do resíduo do momentum em relação a velocidade

1.6.4.1 Bloco à esquerda:

$$\begin{aligned} \frac{\partial R_k^p}{\partial v_{k-\frac{1}{2}}} = \frac{\partial}{\partial v_{k-\frac{1}{2}}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho vv)_{k+1}^{n+1} - (A\rho vv)_k^{n+1}] \right. \\ & \left. + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho gsen(\theta))_{k+\frac{1}{2}}^{n+1} \right] \quad (1.59) \end{aligned}$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial v_{k-\frac{1}{2}}} = \frac{\partial}{\partial v_{k-\frac{1}{2}}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} \right] + \frac{\partial}{\partial v_{k-\frac{1}{2}}} (A\rho vv)_{k+1}^{n+1} - \frac{\partial}{\partial v_{k-\frac{1}{2}}} (A\rho vv)_k^{n+1} \\ & + \frac{\partial}{\partial v_{k-\frac{1}{2}}} \left[(A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} \right] - \frac{\partial}{\partial v_{k-\frac{1}{2}}} (A\Delta x \rho gsen(\theta))_{k+\frac{1}{2}}^{n+1} \quad (1.60) \end{aligned}$$

$$\frac{\partial R_k^p}{\partial v_{k-\frac{1}{2}}} = - (A\rho)_k^{n+1} \frac{\partial (vv)_k^{n+1}}{\partial v_{k-\frac{1}{2}}} \quad (1.61)$$

1.6.4.2 Bloco central:

$$\begin{aligned} \frac{\partial R_k^p}{\partial v_{k+\frac{1}{2}}} = \frac{\partial}{\partial v_{k+\frac{1}{2}}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] \right. \\ & \left. + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \right] \end{aligned} \quad (1.62)$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial v_{k+\frac{1}{2}}} = \frac{\partial}{\partial v_{k+\frac{1}{2}}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} \right] + \frac{\partial}{\partial v_{k+\frac{1}{2}}} (A\rho v v)_{k+1}^{n+1} - \frac{\partial}{\partial v_{k+\frac{1}{2}}} (A\rho v v)_k^{n+1} \\ & + \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left[(A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} \right] - \frac{\partial}{\partial v_{k+\frac{1}{2}}} (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \end{aligned} \quad (1.63)$$

$$\frac{\partial R_k^p}{\partial v_{k+\frac{1}{2}}} = \frac{(A\Delta x \rho)_{k+\frac{1}{2}}^{n+1}}{\Delta t} + (A\rho)_{k+1}^{n+1} \frac{\partial (v v)_{k+1}^{n+1}}{\partial v_{k+\frac{1}{2}}} - (A\rho)_k^{n+1} \frac{\partial (v v)_k^{n+1}}{\partial v_{k+\frac{1}{2}}} \quad (1.64)$$

1.6.4.3 Bloco à direita:

$$\begin{aligned} \frac{\partial R_k^p}{\partial v_{k+\frac{3}{2}}} = \frac{\partial}{\partial v_{k+\frac{3}{2}}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} + [(A\rho v v)_{k+1}^{n+1} - (A\rho v v)_k^{n+1}] \right. \\ & \left. + (A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} - (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \right] \end{aligned} \quad (1.65)$$

$$\begin{aligned} \frac{\partial R_k^p}{\partial v_{k+\frac{3}{2}}} = \frac{\partial}{\partial v_{k+\frac{3}{2}}} & \left[(A\Delta x)_{k+\frac{1}{2}} \frac{[(\rho v)^{n+1} - (\rho v)^n]_{k+\frac{1}{2}}}{\Delta t} \right] + \frac{\partial}{\partial v_{k+\frac{3}{2}}} (A\rho v v)_{k+1}^{n+1} - \frac{\partial}{\partial v_{k+\frac{3}{2}}} (A\rho v v)_k^{n+1} \\ & + \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left[(A\Delta x)_{k+\frac{1}{2}} \left(\frac{p_{k+1} - p_k}{\frac{1}{2}(\Delta x_{k+1} + \Delta x_k)} \right)^{n+1} \right] - \frac{\partial}{\partial v_{k+\frac{3}{2}}} (A\Delta x \rho g \text{sen}(\theta))_{k+\frac{1}{2}}^{n+1} \end{aligned} \quad (1.66)$$

$$\frac{\partial R_k^p}{\partial v_{k+\frac{3}{2}}} = (A\rho)_{k+1}^{n+1} \frac{\partial (v v)_{k+1}^{n+1}}{\partial v_{k+\frac{3}{2}}} - (A\rho)_k^{n+1} \frac{\partial (v v)_k^{n+1}}{\partial v_{k+\frac{3}{2}}} \quad (1.67)$$

1.7 Interpolação Donor-Cell

As derivadas dos termos $(vv)_k^{n+1}$ não podem ser calculadas pois esses termos não são armazenados na geometria, dessa forma será utilizado o método Donor-Cell (UDS) para realizar essa interpolação. O método Donor-Cell é recomendado para escoamentos com altos valores do número de Peclet, onde utiliza-se a interpolação pos diferenças centradas para \vec{v} e a interpolação pelo esquema Upwind de primeira ordem (UDS) para a propriedade transportada, ϕ . O termo $\phi_{k+\frac{1}{2}}$ pode ser expresso como:

$$\phi_{k+\frac{1}{2}} = \phi_k, \quad v_k \geq 0 \quad (1.68)$$

$$\phi_{k+\frac{1}{2}} = \phi_{k+1}, \quad v_k < 0 \quad (1.69)$$

Já o termo $\phi_{k-\frac{1}{2}}$ pode ser expresso como:

$$\phi_{k-\frac{1}{2}} = \phi_{k-1}, \quad v_k \geq 0 \quad (1.70)$$

$$\phi_{k-\frac{1}{2}} = \phi_k, \quad v_k < 0 \quad (1.71)$$

1.7.1 Derivadas da propriedade transportada ϕ :

Como o sentido do escoamento é importante para o método Donor-Cell, as derivadas serão feitas considerando velocidades positivas e negativas, respectivamente. Assim, as derivadas parciais das velocidades são calculadas por:

1.7.1.1 $v_{k+\frac{1}{2}} \geq 0$:

$$\frac{\partial (vv)_k}{\partial v_{k-\frac{1}{2}}} = \frac{\partial (vv)_k}{\partial v_k} \frac{\partial v_k}{\partial v_{k-\frac{1}{2}}} = 2v_k \frac{\partial}{\partial v_{k-\frac{1}{2}}} \left[v_{k-\frac{1}{2}} \right] = 2v_k \quad (1.72)$$

$$\frac{\partial (vv)_k}{\partial v_{k+\frac{1}{2}}} = \frac{\partial (vv)_k}{\partial v_k} \frac{\partial v_k}{\partial v_{k+\frac{1}{2}}} = 2v_k \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left[v_{k-\frac{1}{2}} \right] = 0 \quad (1.73)$$

$$\frac{\partial (vv)_{k+1}}{\partial v_{k+\frac{1}{2}}} = \frac{\partial (vv)_{k+1}}{\partial v_{k+1}} \frac{\partial v_{k+1}}{\partial v_{k+\frac{1}{2}}} = 2v_{k+1} \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left[v_{k+\frac{1}{2}} \right] = 2v_{k+1} \quad (1.74)$$

$$\frac{\partial (vv)_k}{\partial v_{k+\frac{3}{2}}} = \frac{\partial (vv)_k}{\partial v_k} \frac{\partial v_k}{\partial v_{k+\frac{3}{2}}} = 2v_k \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left[v_{k-\frac{1}{2}} \right] = 0 \quad (1.75)$$

$$\frac{\partial (vv)_{k+1}}{\partial v_{k+\frac{3}{2}}} = \frac{\partial (vv)_{k+1}}{\partial v_{k+1}} \frac{\partial v_{k+1}}{\partial v_{k+\frac{3}{2}}} = 2v_{k+1} \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left[v_{k+\frac{1}{2}} \right] = 0 \quad (1.76)$$

1.7.1.2 $v_{k+\frac{1}{2}} < 0$:

$$\frac{\partial (vv)_k}{\partial v_{k-\frac{1}{2}}} = \frac{\partial (vv)_k}{\partial v_k} \frac{\partial v_k}{\partial v_{k-\frac{1}{2}}} = 2v_k \frac{\partial}{\partial v_{k-\frac{1}{2}}} \left[v_{k+\frac{1}{2}} \right] = 0 \quad (1.77)$$

$$\frac{\partial (vv)_k}{\partial v_{k+\frac{1}{2}}} = \frac{\partial (vv)_k}{\partial v_k} \frac{\partial v_k}{\partial v_{k+\frac{1}{2}}} = 2v_k \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left[v_{k+\frac{1}{2}} \right] = 2v_k \quad (1.78)$$

$$\frac{\partial (vv)_{k+1}}{\partial v_{k+\frac{1}{2}}} = \frac{\partial (vv)_{k+1}}{\partial v_{k+1}} \frac{\partial v_{k+1}}{\partial v_{k+\frac{1}{2}}} = 2v_{k+1} \frac{\partial}{\partial v_{k+\frac{1}{2}}} \left[v_{k+\frac{3}{2}} \right] = 0 \quad (1.79)$$

$$\frac{\partial (vv)_k}{\partial v_{k+\frac{3}{2}}} = \frac{\partial (vv)_k}{\partial v_k} \frac{\partial v_k}{\partial v_{k+\frac{3}{2}}} = 2v_k \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left[v_{k-\frac{1}{2}} \right] = 0 \quad (1.80)$$

$$\frac{\partial (vv)_{k+1}}{\partial v_{k+\frac{3}{2}}} = \frac{\partial (vv)_{k+1}}{\partial v_{k+1}} \frac{\partial v_{k+1}}{\partial v_{k+\frac{3}{2}}} = 2v_{k+1} \frac{\partial}{\partial v_{k+\frac{3}{2}}} \left[v_{k+\frac{1}{2}} \right] = 2v_{k+1} \quad (1.81)$$

1.8 Modelo de Fluido

O fluido utilizado será um gás ideal tal que a sua massa específica será dada por:

$$\rho = \frac{pM}{RT} \quad (1.82)$$

onde M representa a massa molar do gás e R a constante universal dos gases.

Assim, a derivada da massa específica com a pressão será dada por:

$$\frac{\partial \rho}{\partial p} = \frac{M}{RT} \quad (1.83)$$