

Structure
void setup() void loop()

Control Structures
if (x<5){ } else { }
switch (myvar) {
case 1:
break;
case 2:
break;
default:
}
for (int i=0; i <= 255; i++){ }
while (x<5){ }
do { } while (x<5);
continue; //Go to next in do/for/while loop
return x; // Or "return;" for voids.
goto // considered harmful :-)

Further Syntax
// (single line comment)
/* (multi-line comment) */
#define DOZEN 12 //Not baker's!
#include <avr/pgmspace.h>

General Operators
= (assignment operator)
+ (addition) - (subtraction)
* (multiplication) / (division)
% (modulo)
== (equal to) != (not equal to)
< (less than) > (greater than)
<= (less than or equal to)
>= (greater than or equal to)
&& (and) || (or) ! (not)

Pointer Access
& reference operator
* dereference operator

Bitwise Operators
& (bitwise and) | (bitwise or)
^ (bitwise xor) ~ (bitwise not)
<< (bitshift left) >> (bitshift right)

Compound Operators
++ (increment) -- (decrement)
+= (compound addition)
-= (compound subtraction)
*= (compound multiplication)
/= (compound division)
&= (compound bitwise and)
|= (compound bitwise or)

Constants
HIGH | LOW
INPUT | OUTPUT
true | false
143 // Decimal number
0173 // Octal number
B11011111 // Binary (8-bits only)
0x7B // Hex number
7U // Force unsigned
10L // Force long
15UL // Force long unsigned
10.0 // Forces floating point
2.4e5 // 245,000

Data Types
void
boolean (0, 1, false, true)
char (e.g. 'a' -128 to 127)
unsigned char (0 to 255)
byte (0 to 255)
int (-32,768 to 32,767)
unsigned int (0 to 65535)
word (0 to 65535)
long (-2,147,483,648 to 2,147,483,647)
unsigned long (0 to 4,294,967,295)
float (-3.4028235E+38 to 3.4028235E+38)
double (currently same as float)
sizeof(myint) // returns 2 bytes

Strings
char S1[15];
char S2[8]='a','r','d','u','i','n','o';
char S3[8]='a','r','d','u','i','n','o','\0';
//Included \0 null termination
char S4[] = "arduino";
char S5[8] = "arduino";
char S6[15] = "arduino";

Arrays
int myInts[6];
int myPins[] = {2, 4, 8, 3, 6};
int mySensVals[6] = {2, 4, -8, 3, 2};

Conversion
char() byte()
int() word()
long() float()

ARDUINO CHEAT SHEET V.02B

Mostly taken from the extended reference:

<http://arduino.cc/en/Reference/Extended>

Gavin Smith – Robots and Dinosaurs, The Sydney Hackspace



Qualifiers
static // persists between calls
volatile // use RAM (nice for ISR)
const // make read-only
PROGMEM // use flash

Digital I/O
pinMode(pin, [INPUT, OUTPUT])
digitalWrite(pin, value)
int digitalRead(pin)
//Write High to inputs to use pull-up res

Analog I/O
analogReference([DEFAULT, INTERNAL, EXTERNAL])
int analogRead(pin) //Call twice if switching pins from high Z source.
analogWrite(pin, value) // PWM

PWM – ESP32
ledcAttachPin(pin, port);
ledcSetup(port, 4000, 8);
ledcWrite(port, wert);
(wichtig für die PWM-Programmierung mit dem ESP32)

Time
unsigned long millis() // 50 days overflow.
unsigned long micros() // 70 min overflow
delay(ms)
delayMicroseconds(us)

Math
min(x, y) max(x, y) abs(x)
constrain(x, minval, maxval)
map(val, fromL, fromH, toL, toH)
pow(base, exponent) sqrt(x)
sin(rad) cos(rad) tan(rad)

Random Numbers
randomSeed(seed) // Long or int
long random(max)
long random(min, max)

Bits and Bytes
lowByte() highByte()
bitRead(x, bitn) bitWrite(x, bitn, bit)
bitSet(x, bitn) bitClear(x, bitn)
bit(bitn) //bitn: 0-LSB 7-MSB

External Interrupts
attachInterrupt(interrupt, function, [LOW, CHANGE, RISING, FALLING])
detachInterrupt(interrupt)
interrupts()
noInterrupts()

Libraries:

Serial.
begin([300, 1200, 2400, 4800, 9600, 14400, 19200, 28800, 38400, 57600, 115200])
end()
int available()
int read()
flush()
print()
println()
write()

EEPROM (#include <EEPROM.h>)
byte read(intAddr)
write(intAddr, myByte)

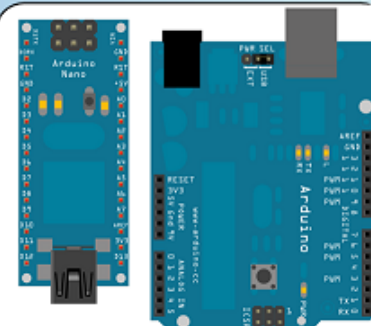
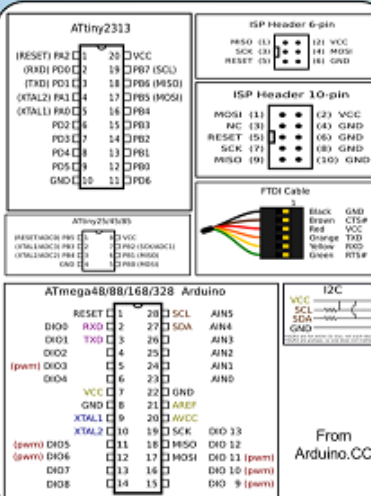
Servo (#include <Servo.h>)
attach(pin, [min_uS, max_uS])
write(angle) // 0-180
writeMicroseconds(uS) //1000-2000, 1500 is midpoint
read() // 0-180
attached() //Returns boolean
detach()

SoftwareSerial(RxPin, TxPin)
// #include <SoftwareSerial.h>
begin(longSpeed) // up to 9600
char read() // blocks till data
print(myData) or println(myData)

Wire (#include <Wire.h>) // For I2C
begin() // Join as master
begin(addr) // Join as slave @ addr
requestFrom(address, count)
beginTransmission(addr) // Step 1
send(mybyte) // Step 2
send(char * mystring)
send(byte * data, size)
endTransmission() // Step 3
byte available() // Num of bytes
byte receive() //Return next byte
onReceive(handler)
onRequest(handler)

	ATmega168	ATmega328	ATmega1280
Flash (2k for bootloader)	16kB	32kB	128kB
SRAM	1kB	2kB	8kB
EEPROM	512B	1kB	4kB

	Duemilanove / Nano / Pro / ProMini	Mega
# of IO	14 + 6 analog (Nano has 14+8)	54 + 16 analog
Serial Pins	0 - RX 1 - TX	0 - RX1 1 - TX1 19 - RX2 18 - TX2 17 - RX3 16 - TX3 15 - RX4 14 - TX4
Ext Interrupts	2 - (Int 0) 3 - (Int 1)	2, 3, 21, 20, 19, 18 (IRQ0 - IRQ5)
PWM pins	5, 6 - Timer 0 9, 10 - Timer 1 3, 11 - Timer 2	0-13 53 - SS 51 - MOSI 50 - MISO 52 - SCK
SPI	10 - SS 11 - MOSI 12 - MISO 13 - SCK	53 - SS 51 - MOSI 50 - MISO 52 - SCK
I2C	Analog4 - SDA Analog5 - SCL	20 - SDA 21 - SCL



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