

Numerical model investigation of Crane Glacier response to collapse of Larsen B ice shelf, Antarctic Peninsula

Adam Campbell

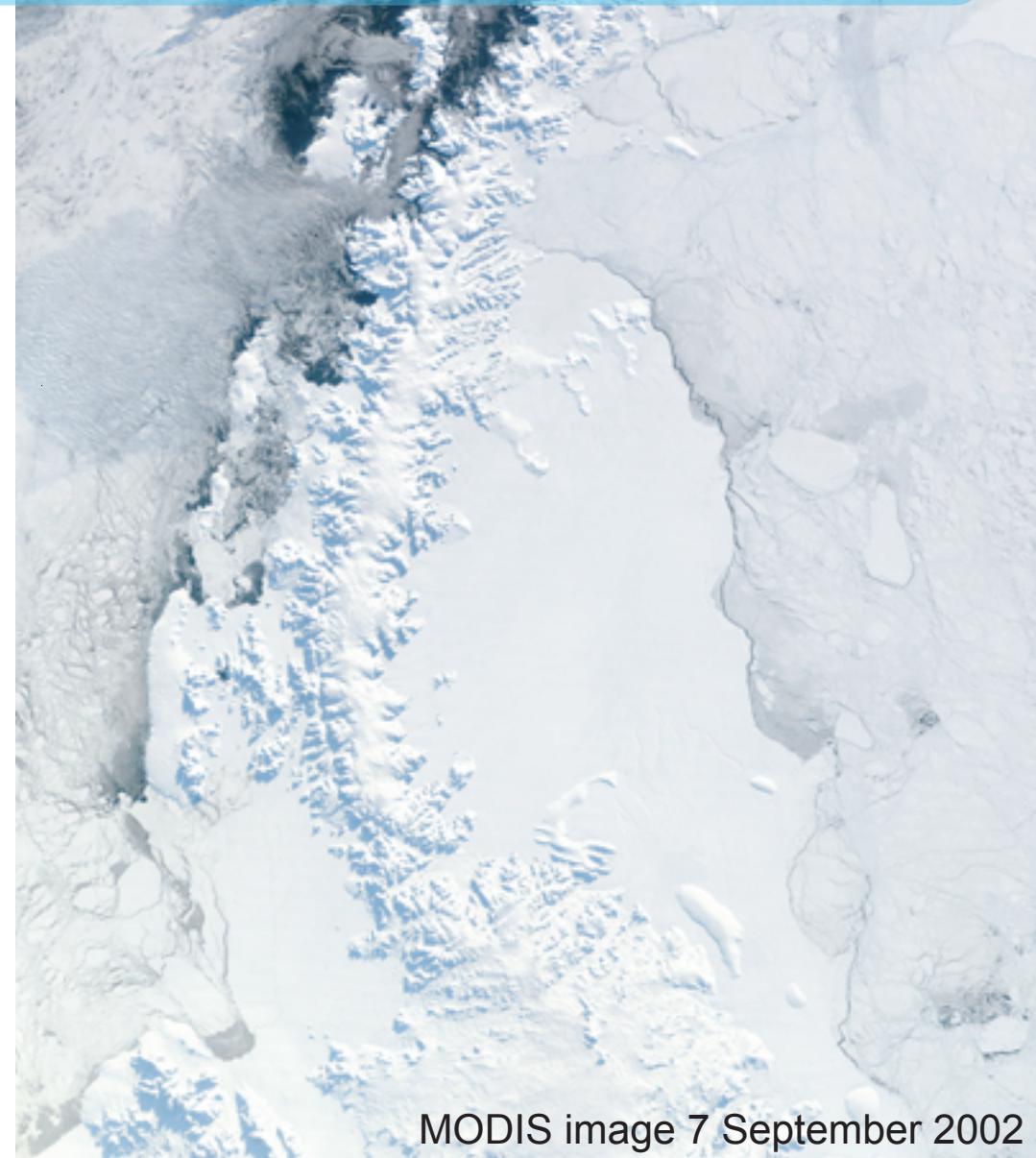
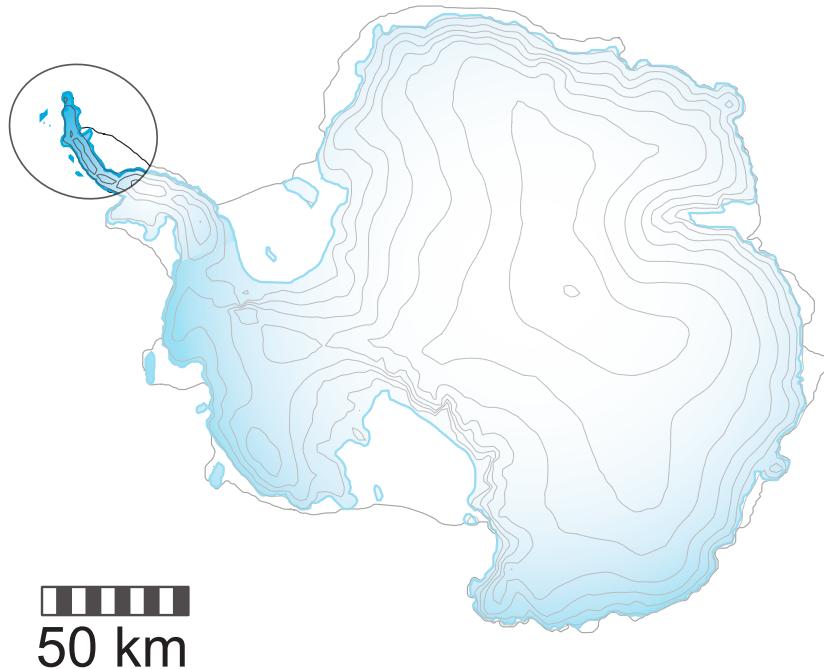
University of Washington

Christina Hulbe

Portland State University

Olga Sergienko

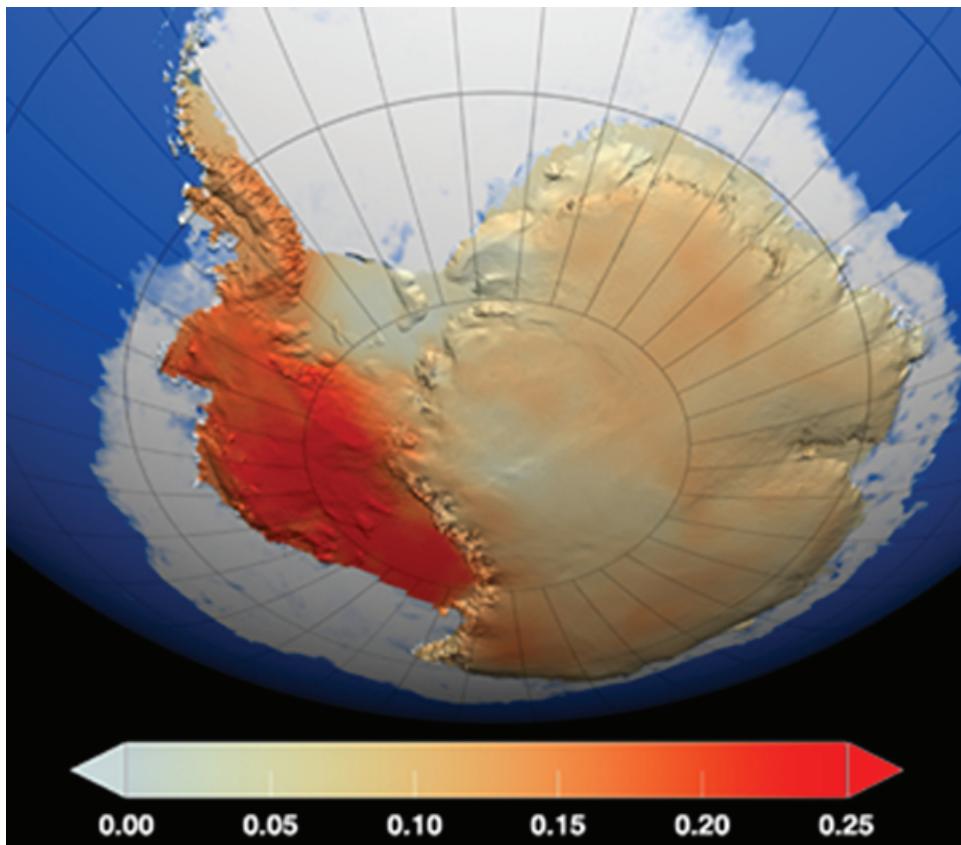
Princeton/GFDL



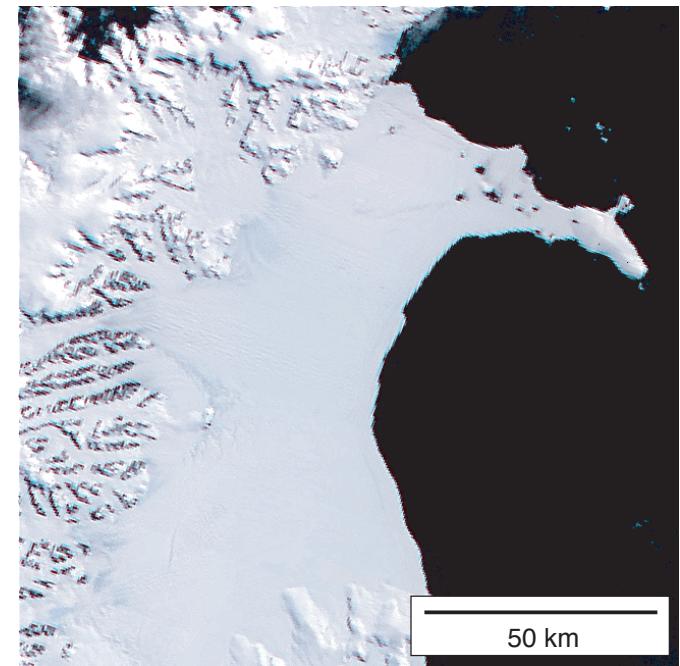
aaaaaaaaaa!

Larsen B ice shelf collapse
rapid event
tied to regional warming

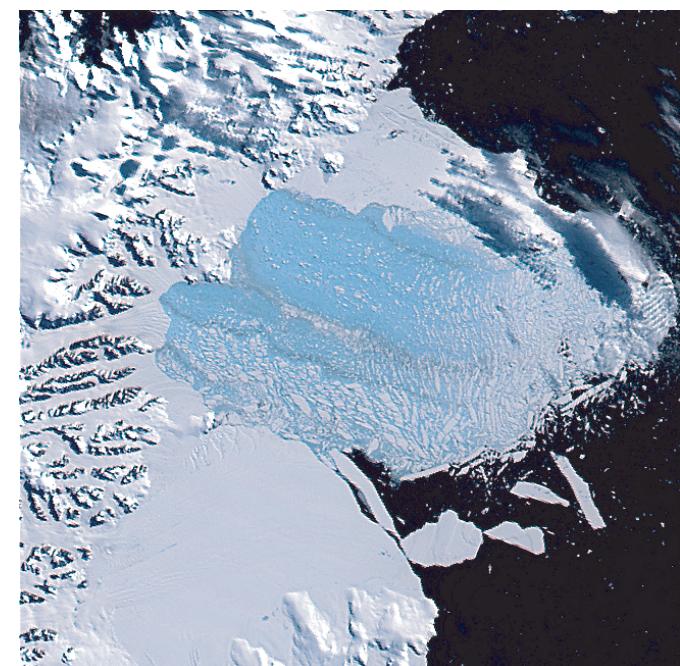
1957 to 2006 mean annual temperature trend
Steig et al., 2009, *Nature*, AWS + thermal infrared



November 22
2001



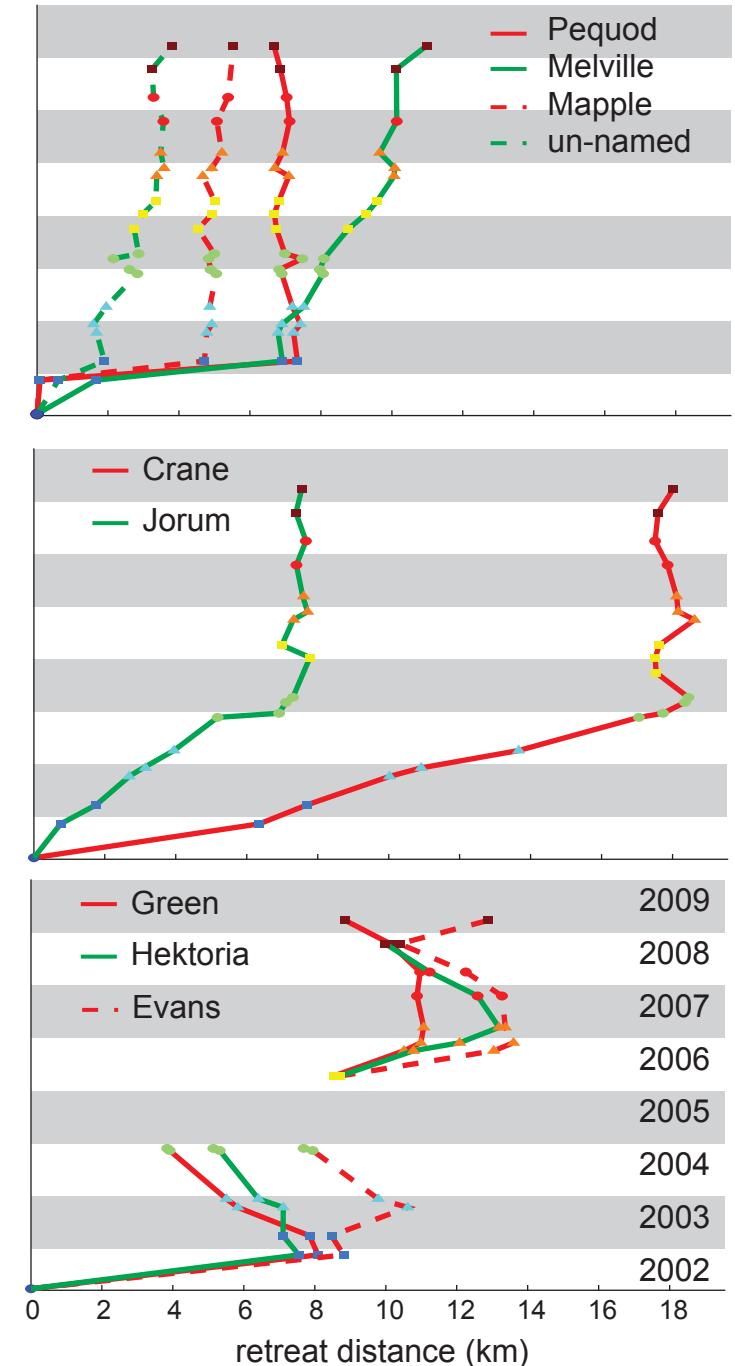
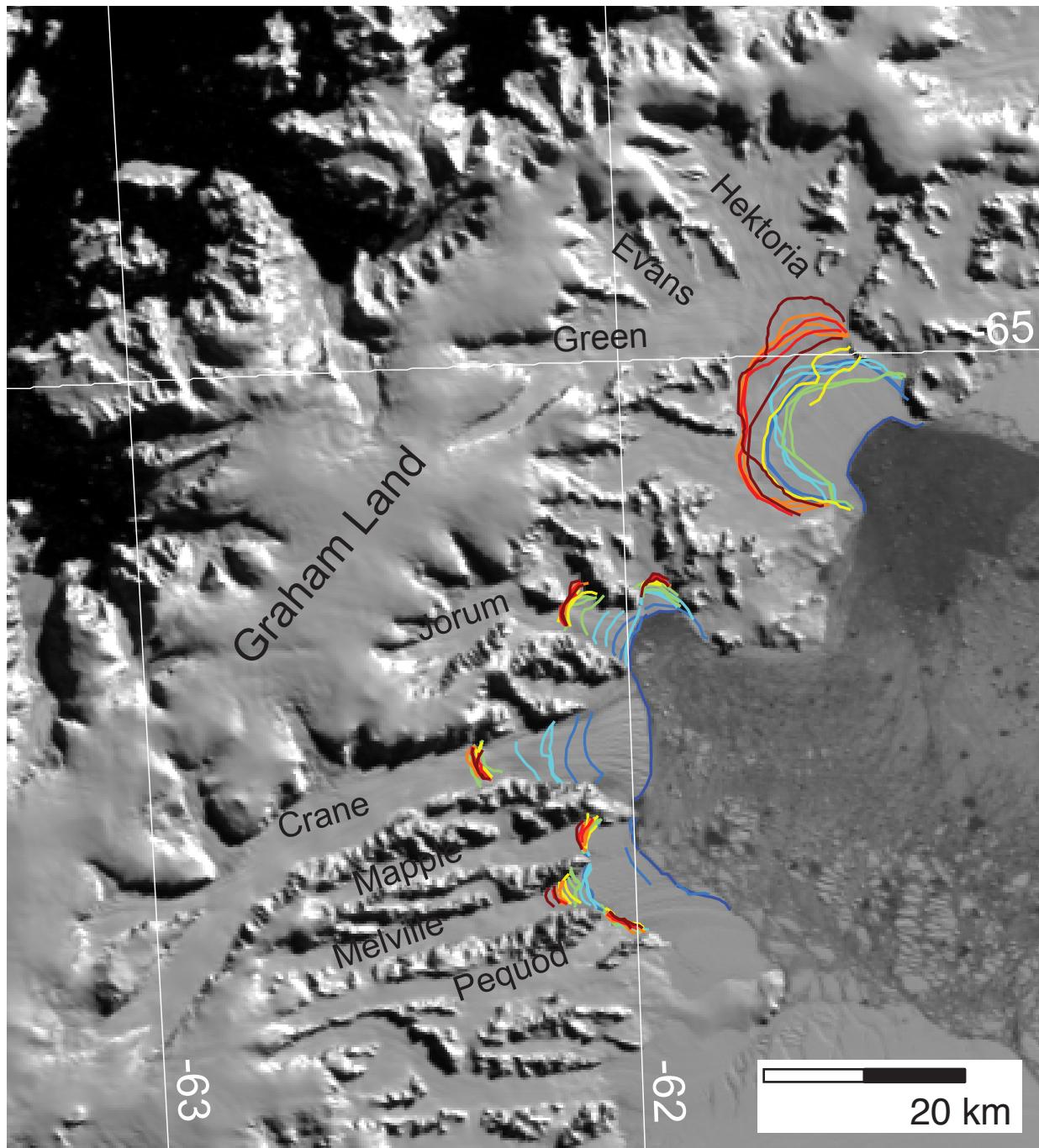
March 7
2002



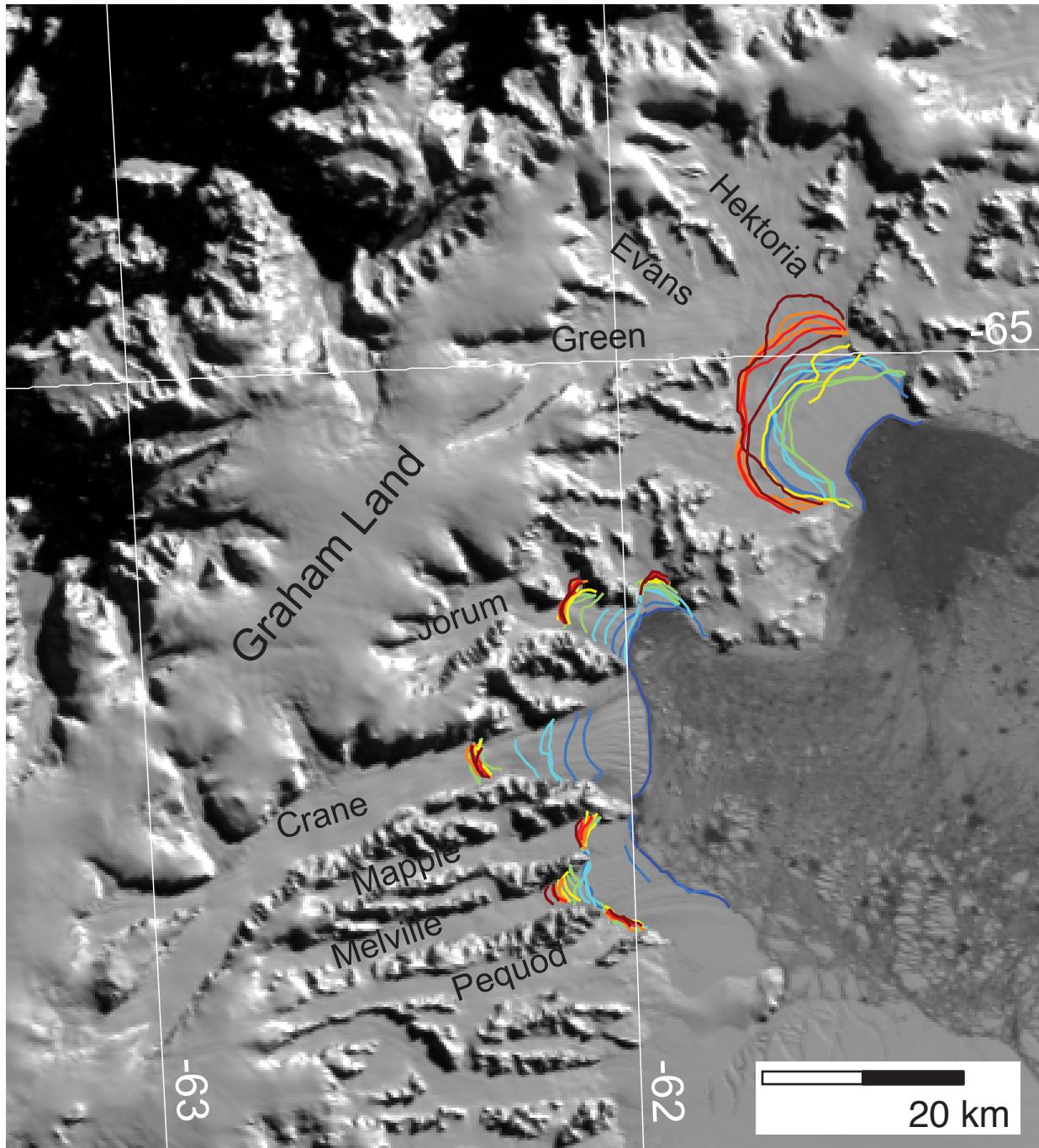
MODIS true color from NSIDC

different patterns emerge over time

front location following ice shelf disintegration



different patterns emerge over time

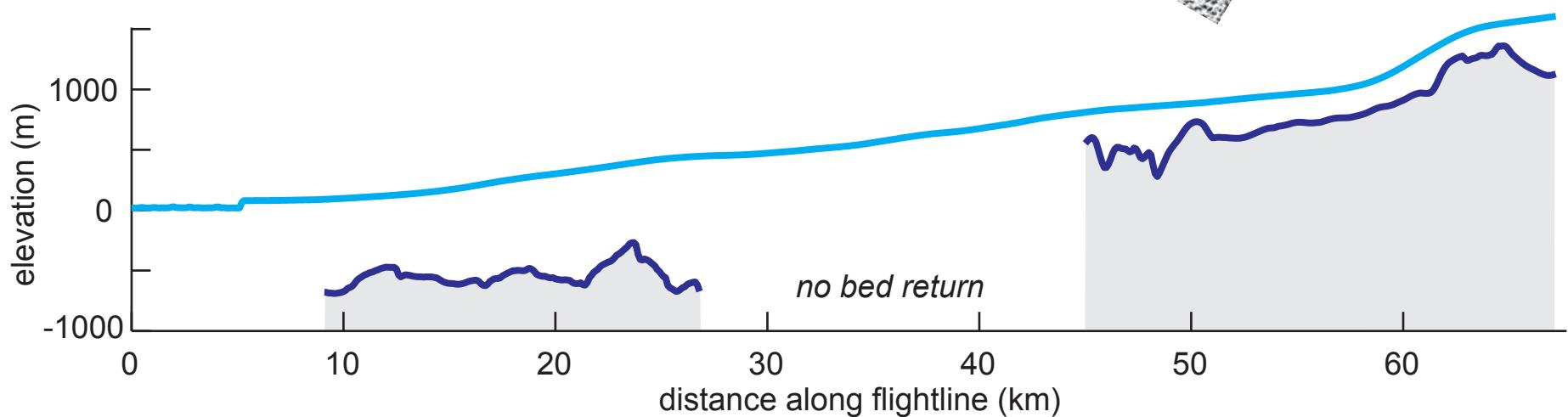
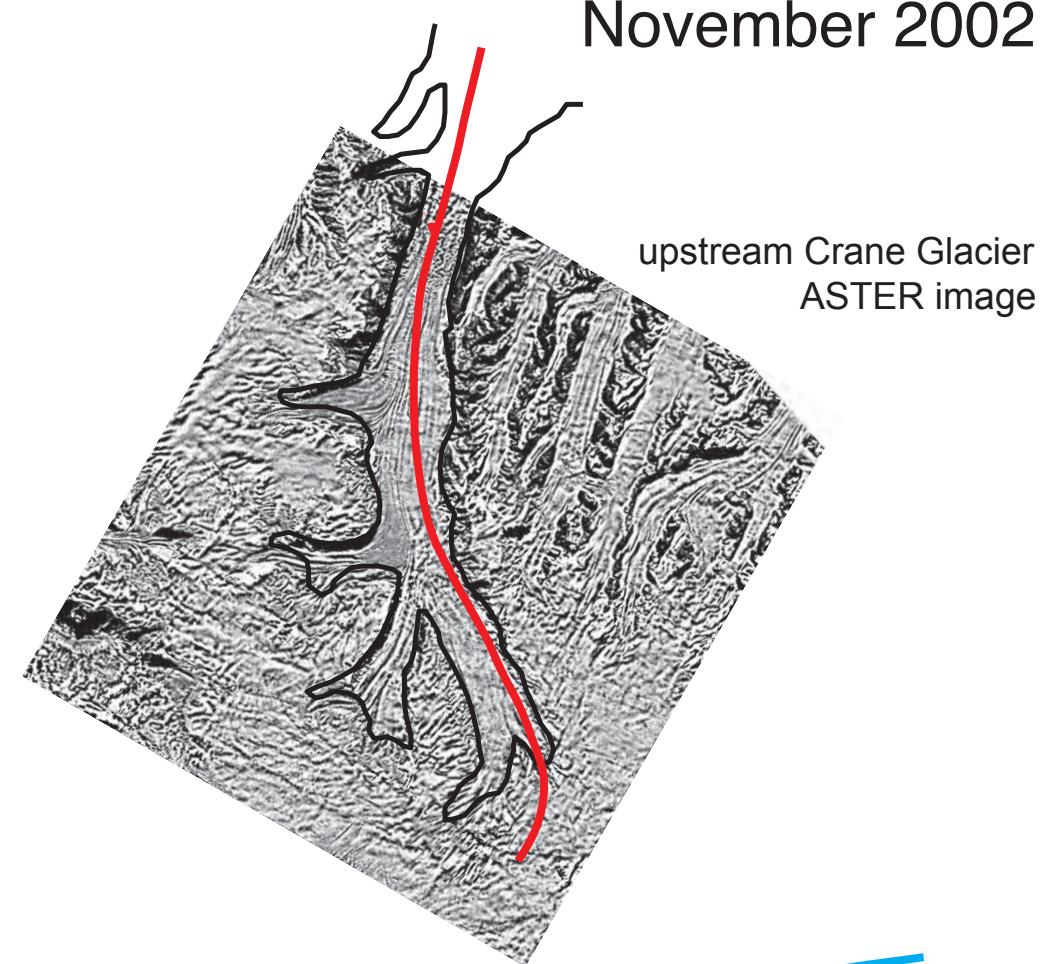
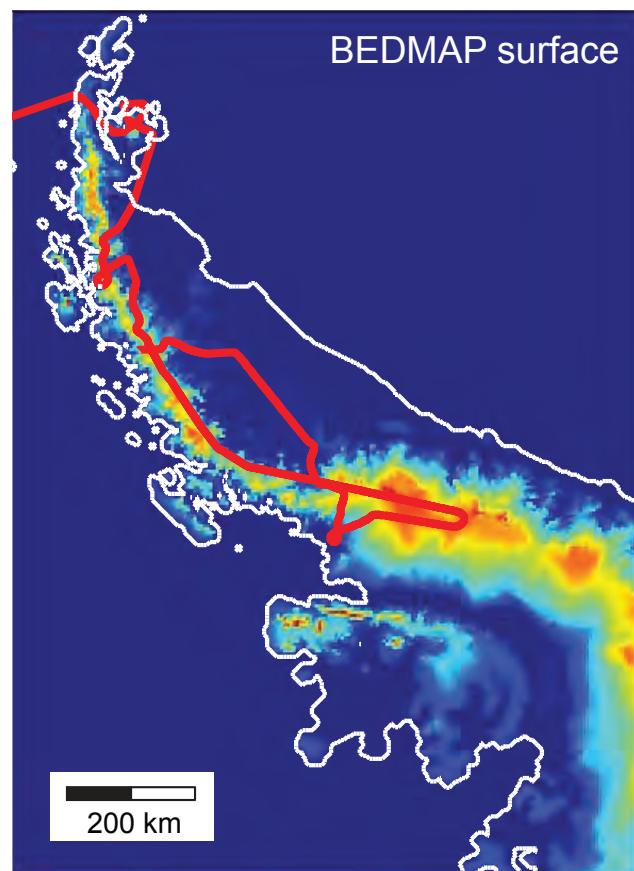


tidewater calving retreat

ice dynamics

Crane Glacier
rapid change, large glacier
and we have some data

NASA/CReSIS/CECS airborne radar & laser



tidewater calving instability

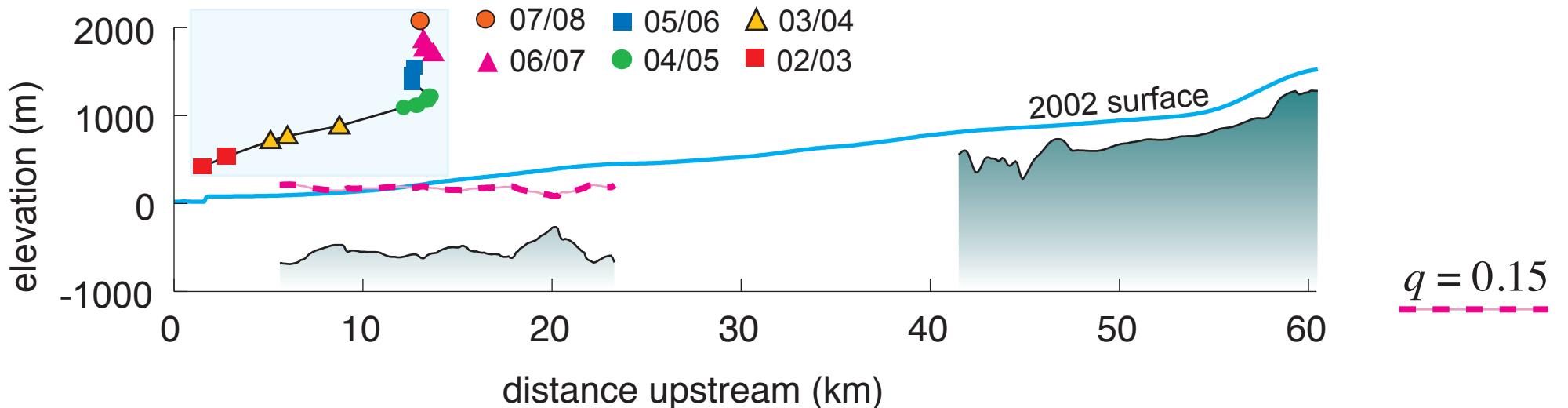
height above buoyancy (*van der Veen; Vieli*)



$$h_c = \frac{\rho_{water}}{\rho_{ice}} (1 + q) d$$

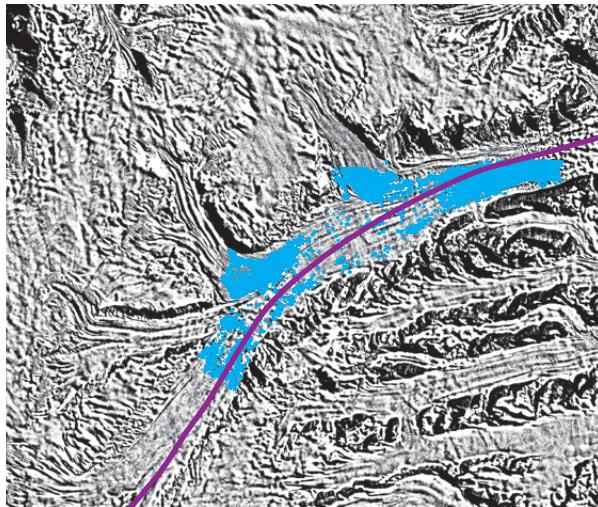
h ice thickness
 h_c critical thickness
 d water depth
 q empirical const.

$h_c / h > 1$ retreat



Crane Glacier speed

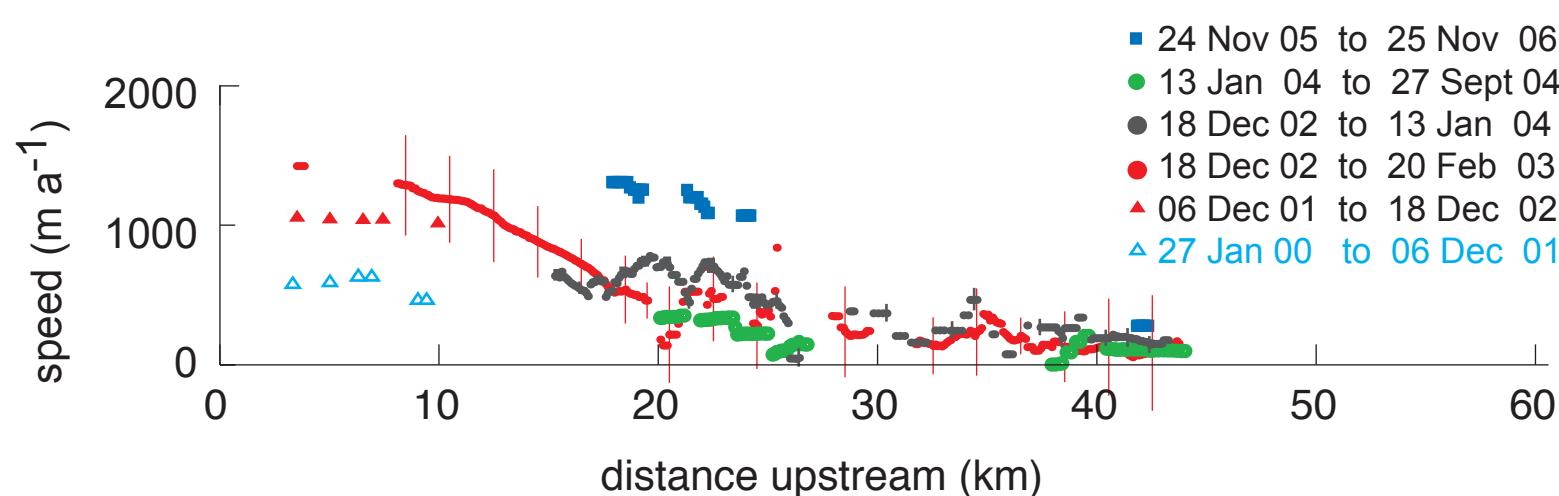
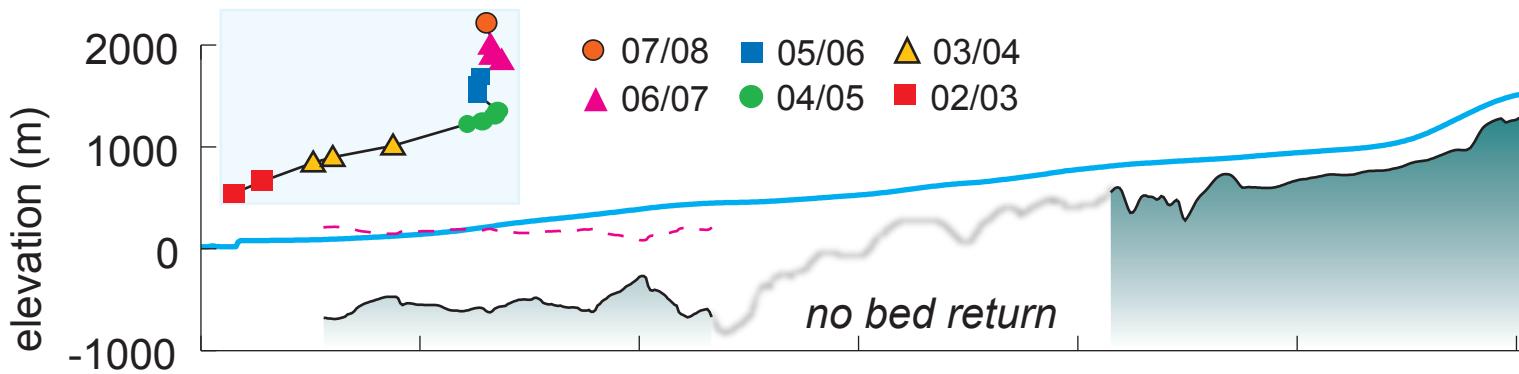
surface velocity from feature tracking
interpolated to flightline



18Dec2002
to 20Feb2003

instantaneous response

to



2002: speed up

2004: slow down

2006: speed up

numerical model

finite element solver for momentum equation along flightline

two downstream boundary conditions

- 1) pre-collapse: ice + backpressure
- 2) post-collapse: water + air

three experiments

- 1) deformation only
- 2) deformation + sliding
- 3) deformation + sliding
with steady-state
front position

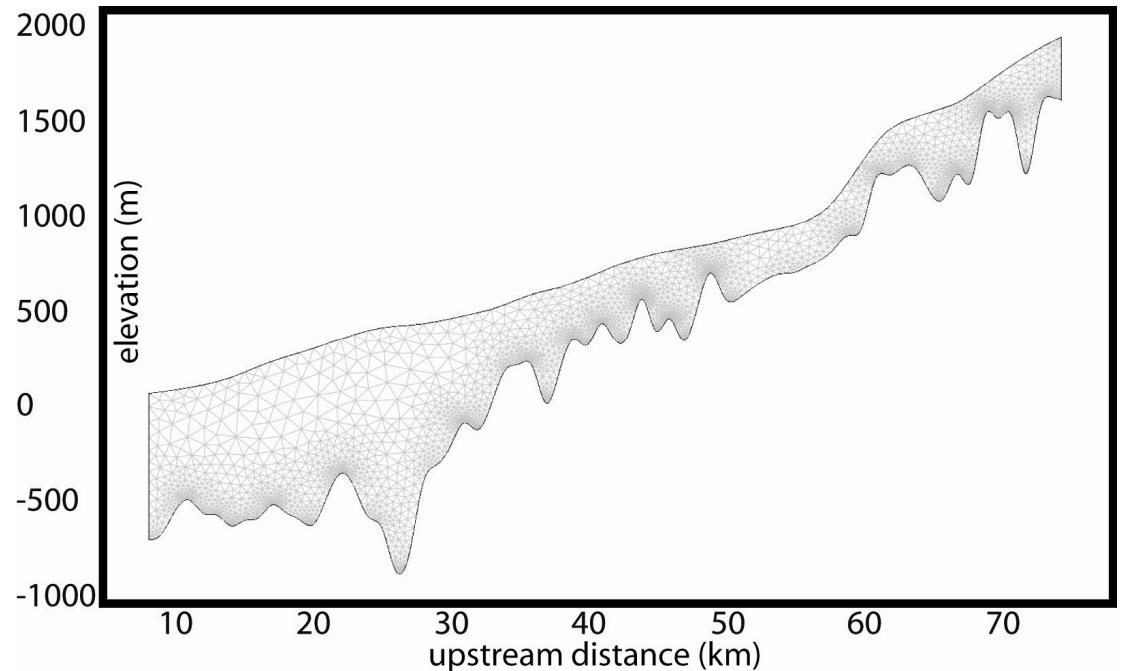


Figure 3.1 Mesh for the non-scaled models consists of 11501 nodes with an increase density near large gradients in the glacial geometry.

Table 3.1 Mesh statistics for non-scaled mesh.

Quantity	Value
Number of Elements	11501
Minimum element quality	0.0446
Element area ratio	8.85×10^{-5}

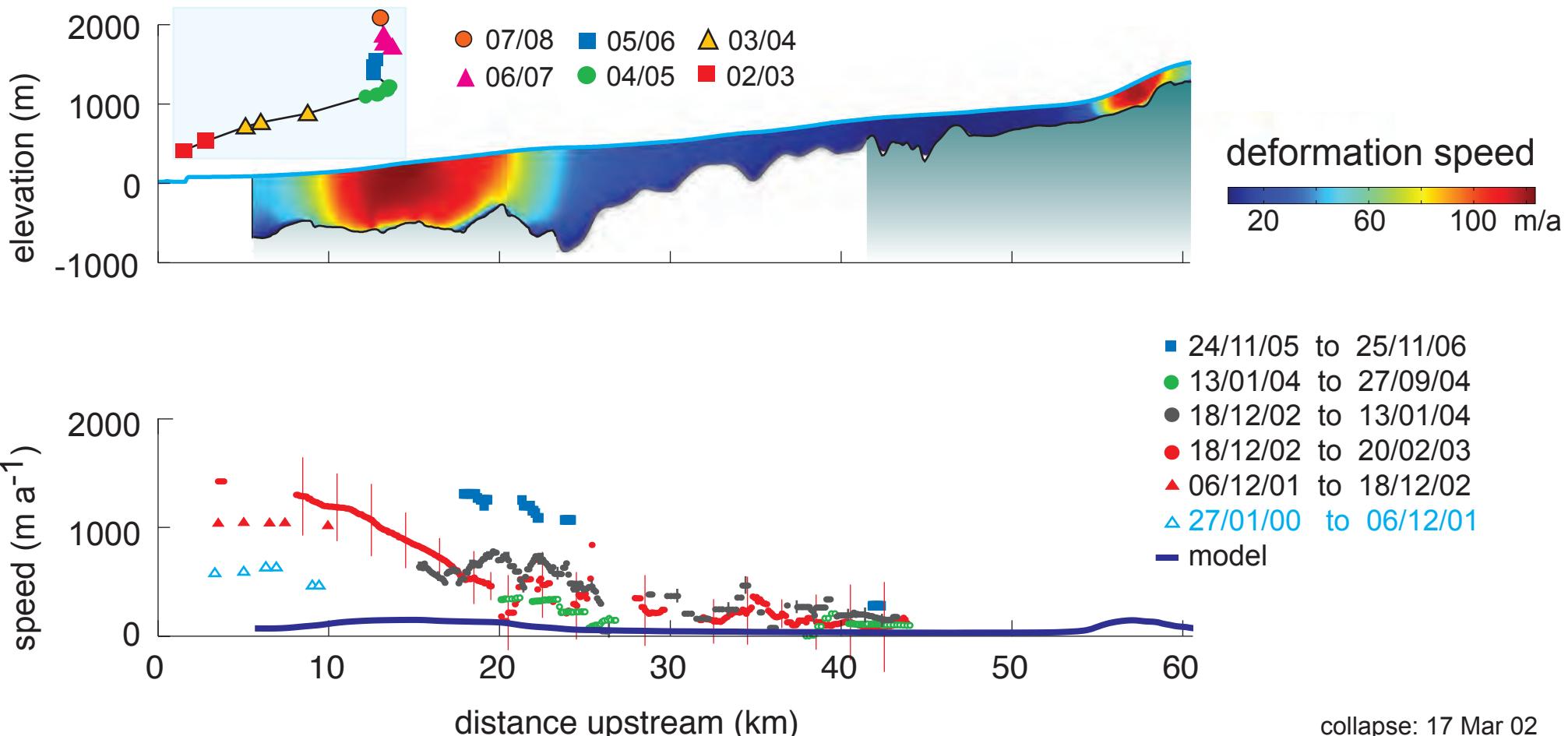
numerical model

finite element solver for momentum equation along flightline
(no lateral drag)

estimate of missing bed from surface & observed velocity

estimated ice temperature

pressure condition at downstream end *ice + backpressure*

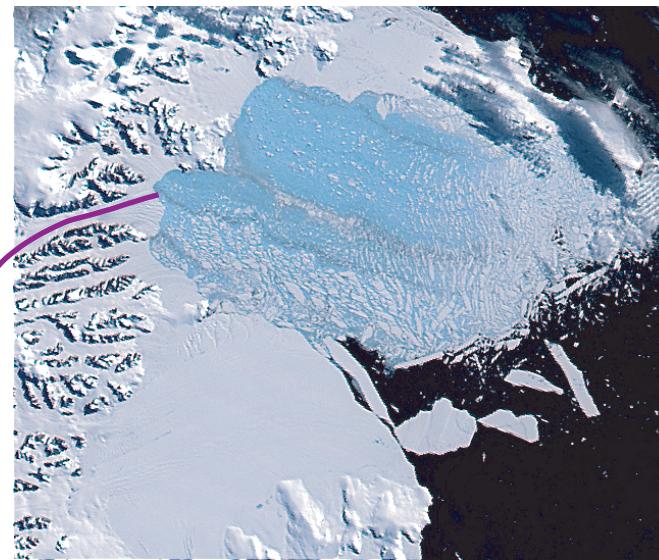
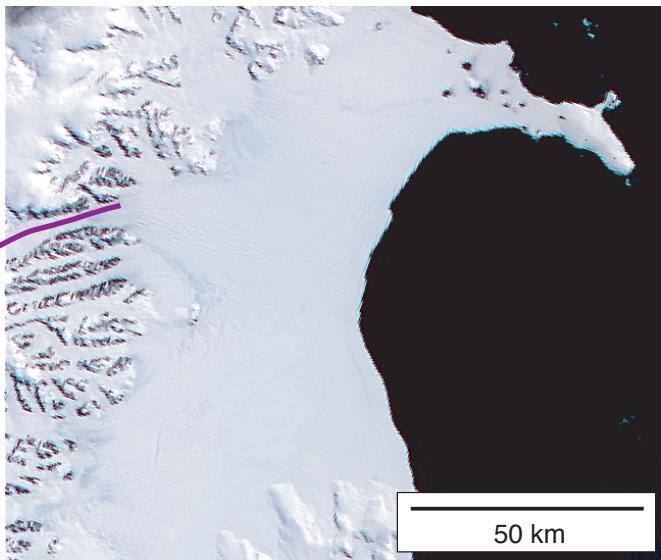


instantaneous response to ice shelf loss

FEM solves momentum equation along flightline
(no lateral drag)

pressure condition at downstream end
ice + backpressure

or
air & water

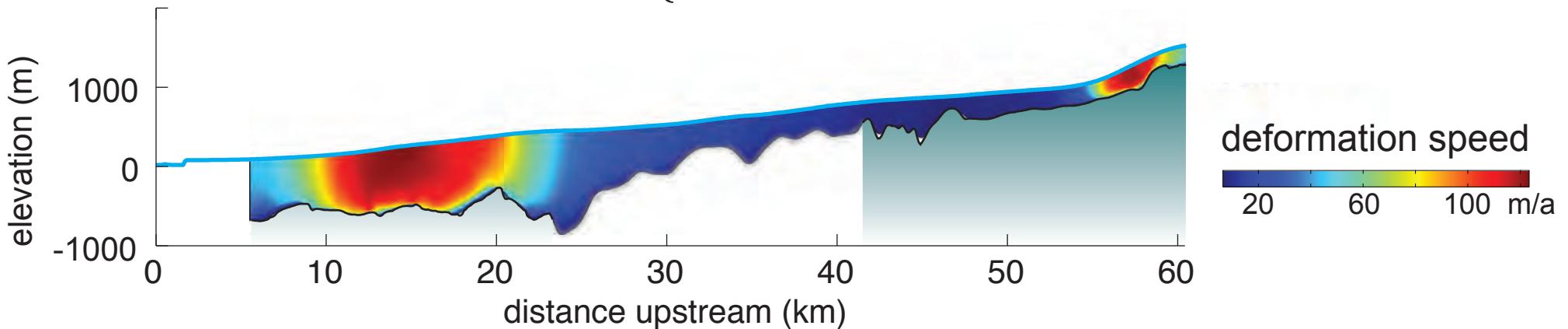


with ice shelf

$$\tau_{xx} = \rho_{ice} \cdot g \cdot (S-z) + \tau_{back}$$

air & water

$$\tau_{xx} = \begin{cases} 0 & z > sealevel \\ \rho_{water} \cdot g \cdot (sealevel-z) & z \leq sealevel \end{cases}$$

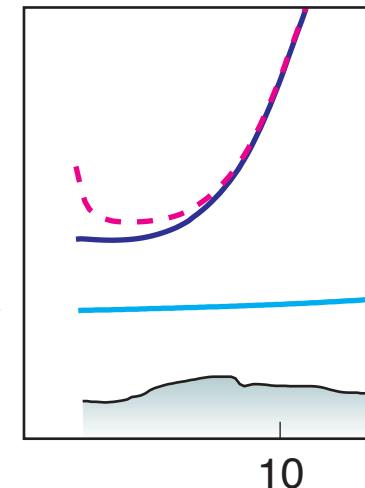
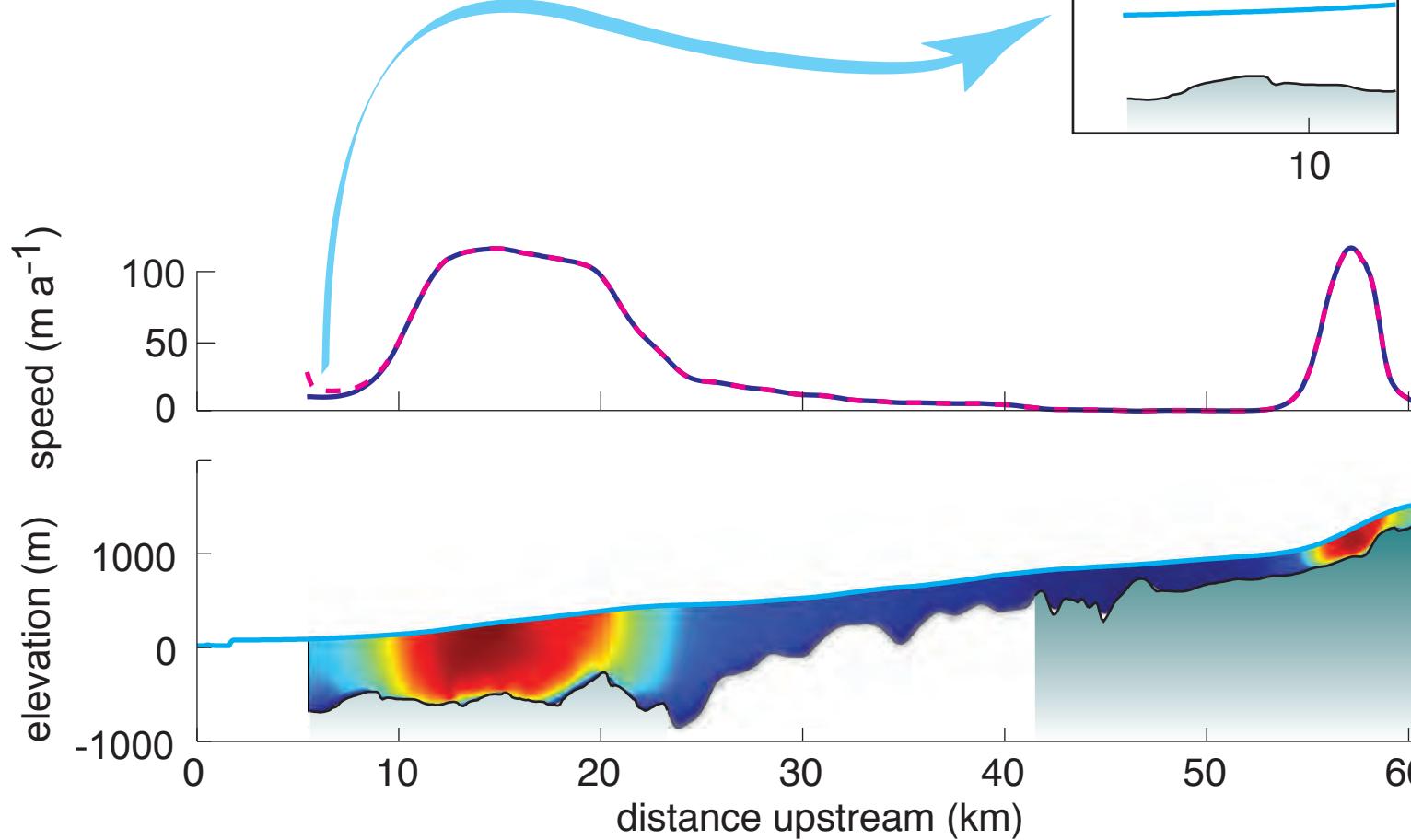


instantaneous response to ice shelf loss

ice deformation only
along flightline

$$\tau_{xx} = \rho_{ice} \cdot g \cdot (S-z) + \tau_{back}$$

$$\tau_{xx} = \begin{cases} 0 & z > sealevel \\ \rho_{water} \cdot g \cdot (sealevel-z) & z \leq sealevel \end{cases}$$



— pre-collapse
- - - post-collapse

numerical model

deformation + sliding relation

tuned to observed “pre-collapse” speed

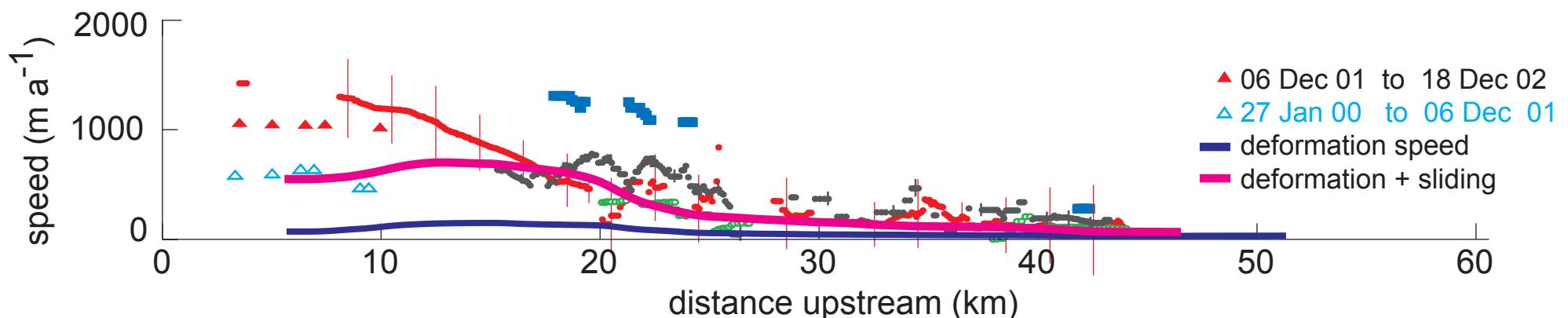
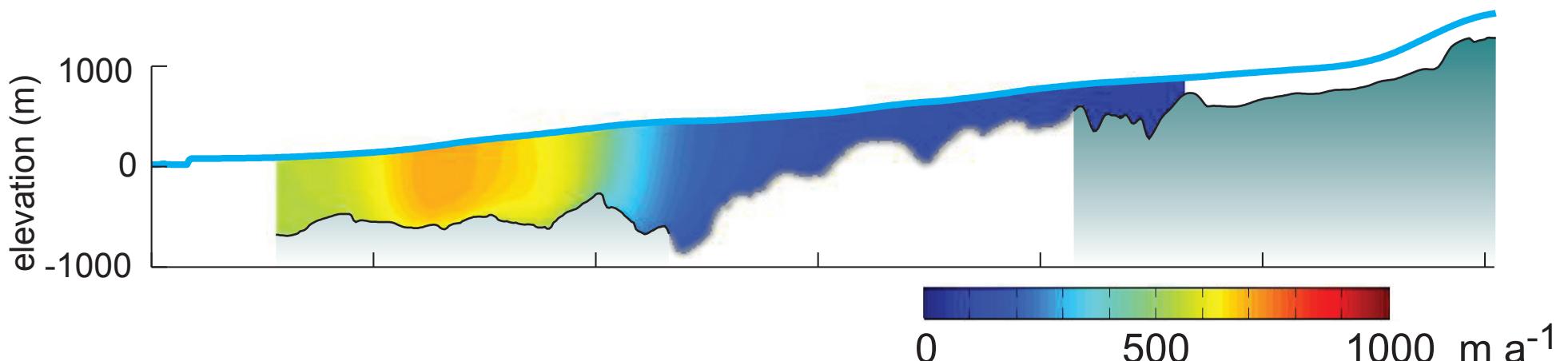
$$u_b = k \tau_b^q p_e^{-1}$$

speed at the bed depends on

basal shear stress τ_b

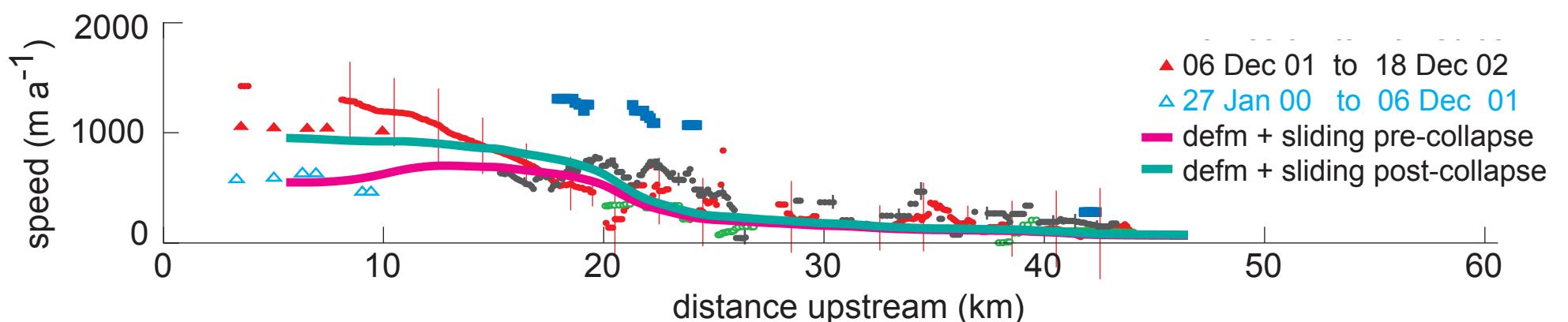
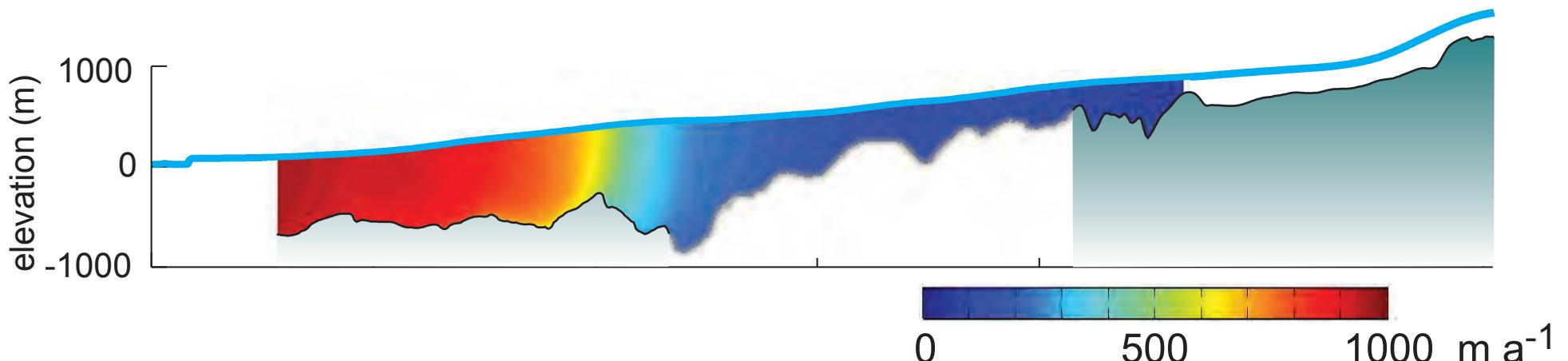
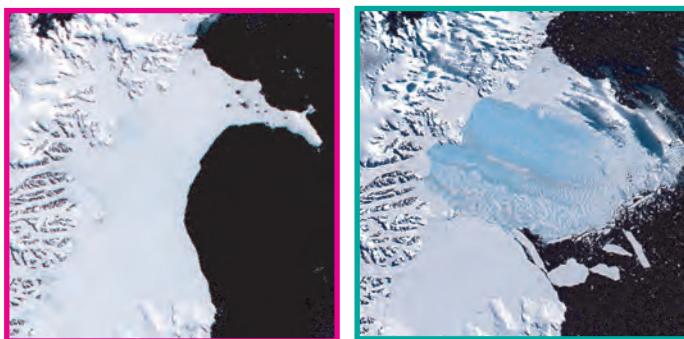
effective pressure p_e (overburden - water)

tunable parameters k, q , water level in p_e



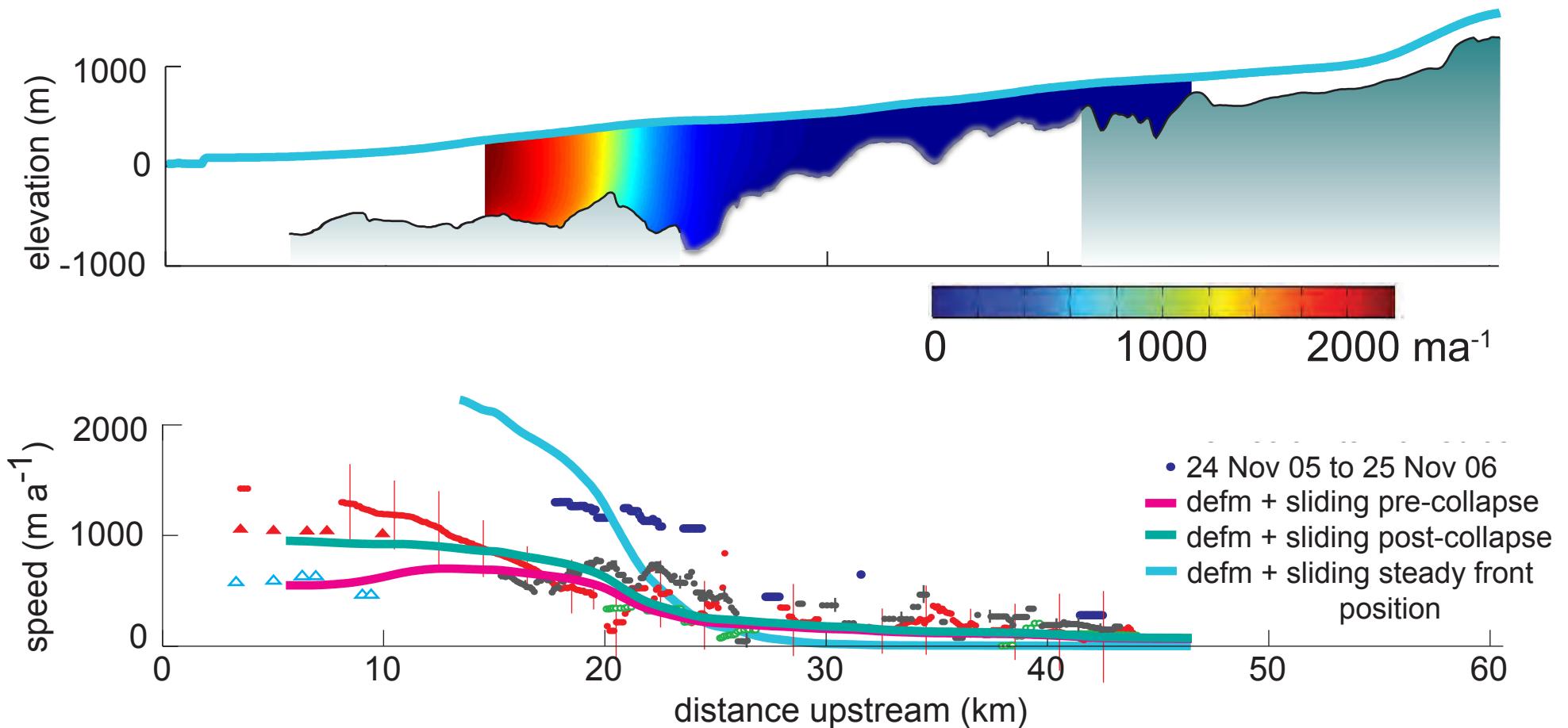
instantaneous response to ice shelf loss

deformation + sliding along flightline
replace ice+backpressure with water+air

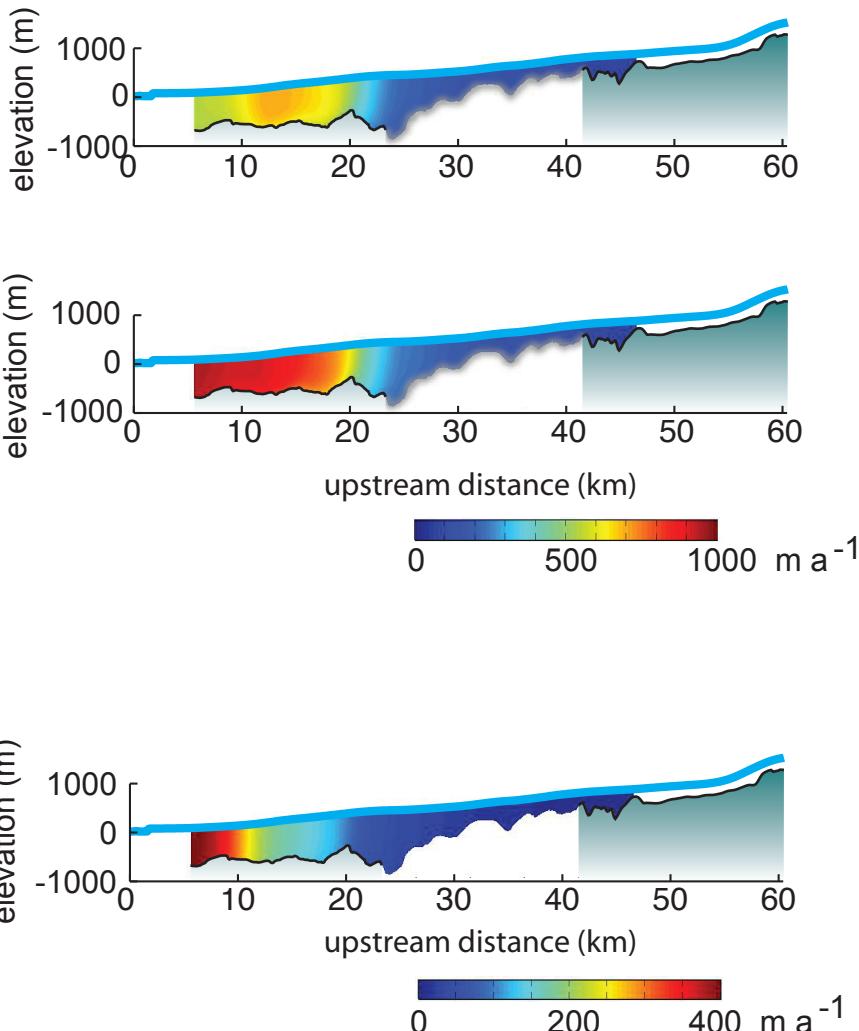


model velocity with steady front location

deformation + sliding along flightline



conclusion



tidewater calving

front retreat matches prediction

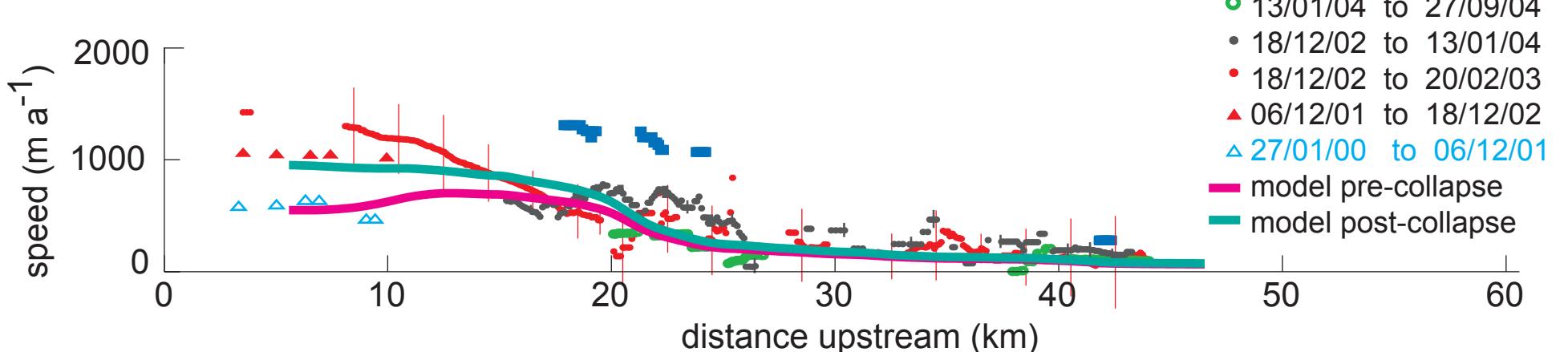
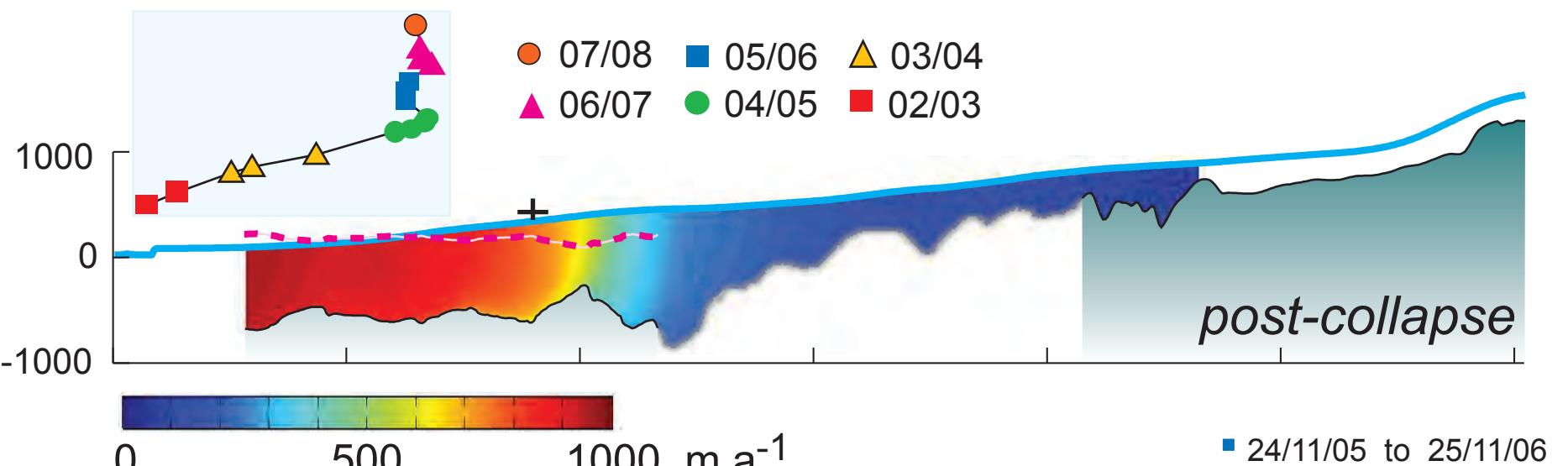
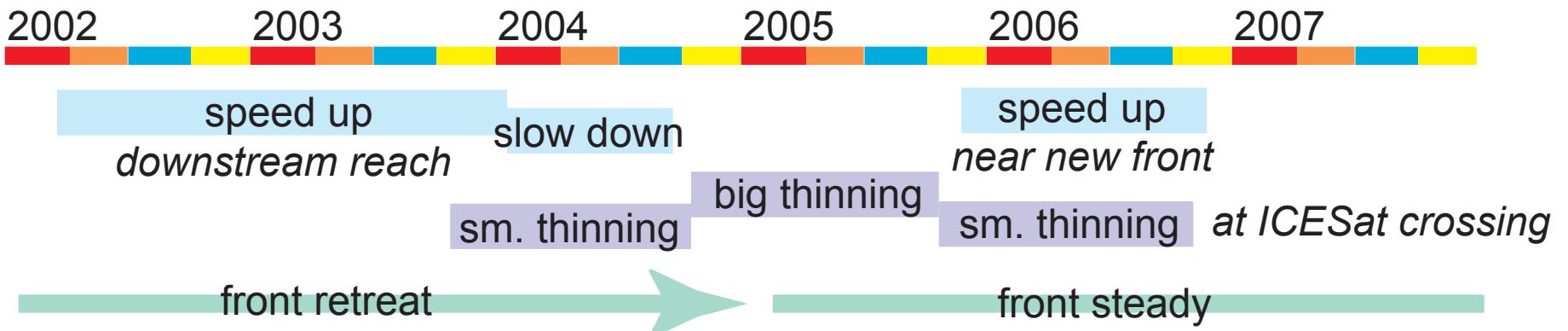
instantaneous response

dominated by sliding
amplification of stress perturbation

$$u_b = k \tau_b^q p_e^{-l}$$

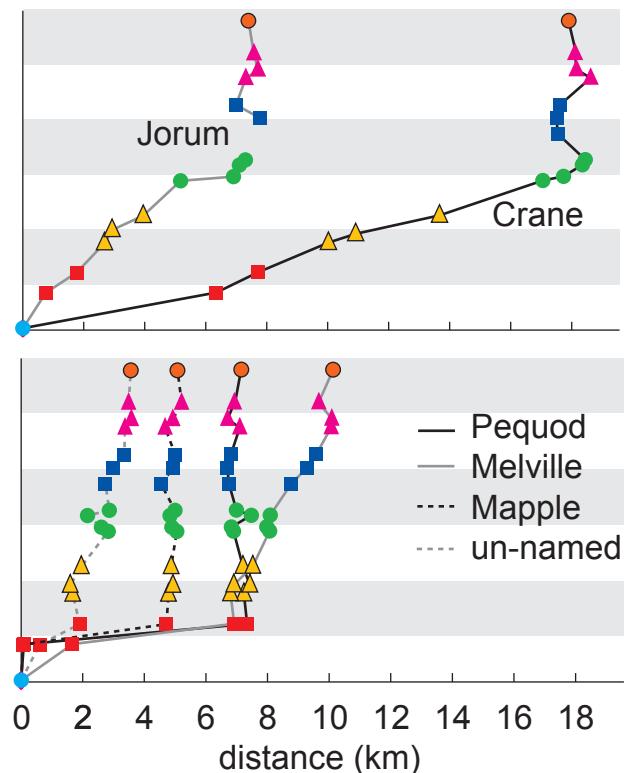
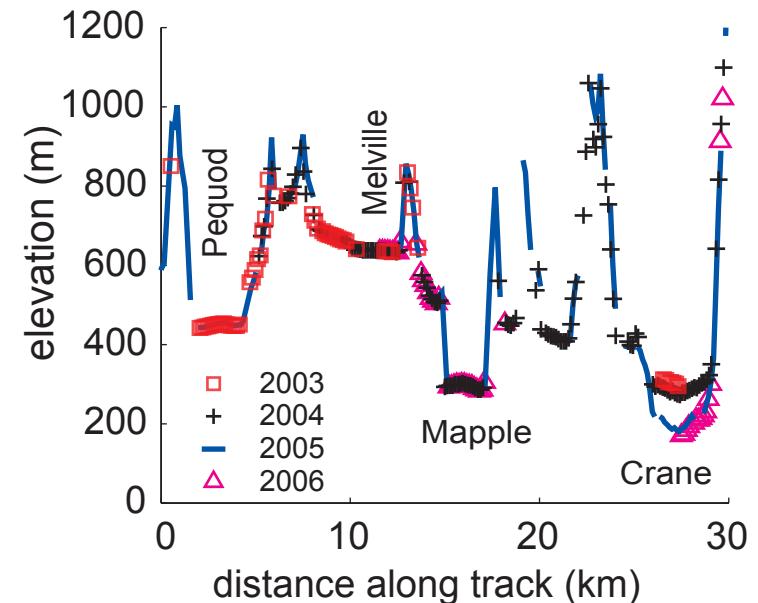
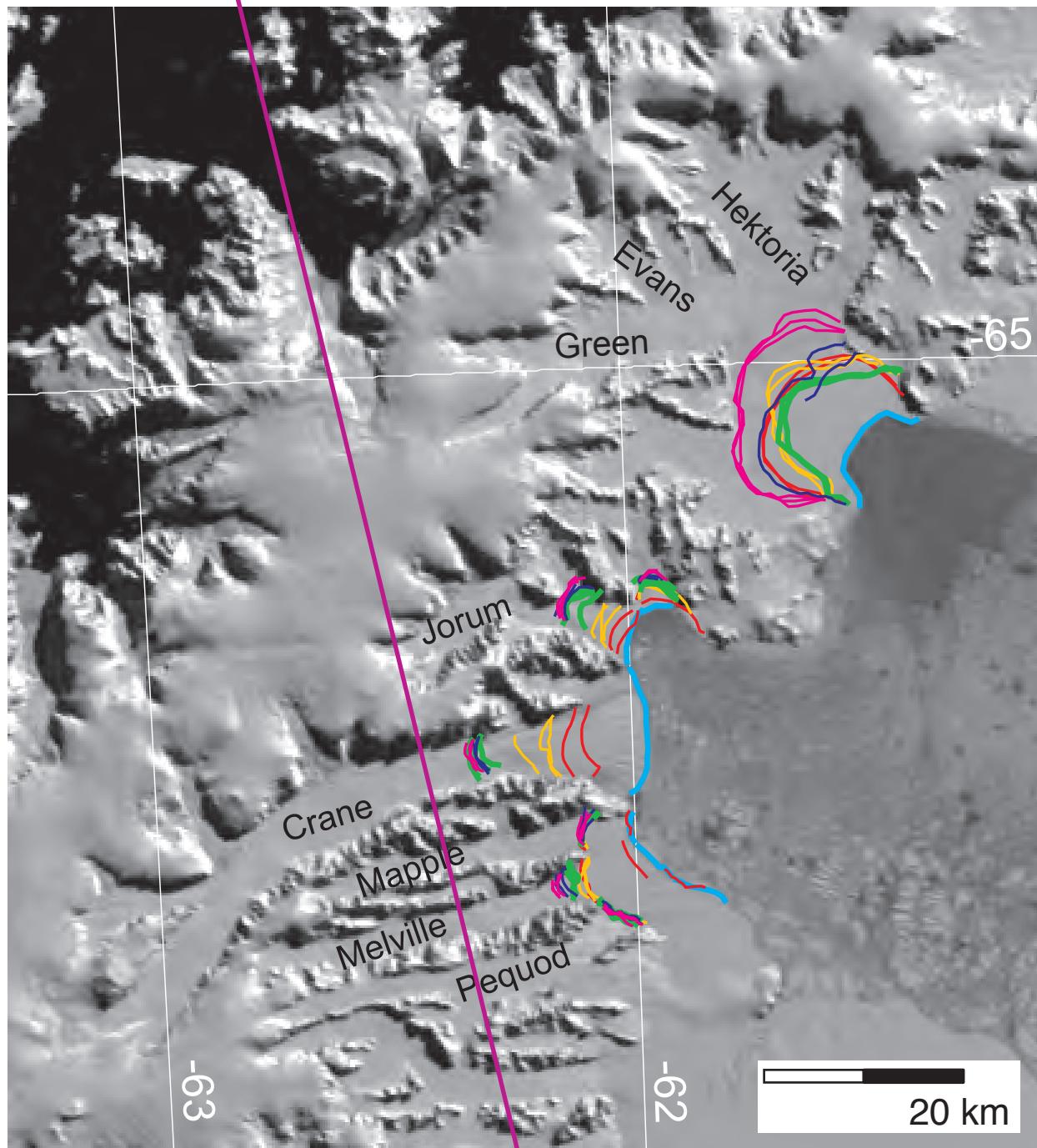
steady state front position

model velocity matches
observations

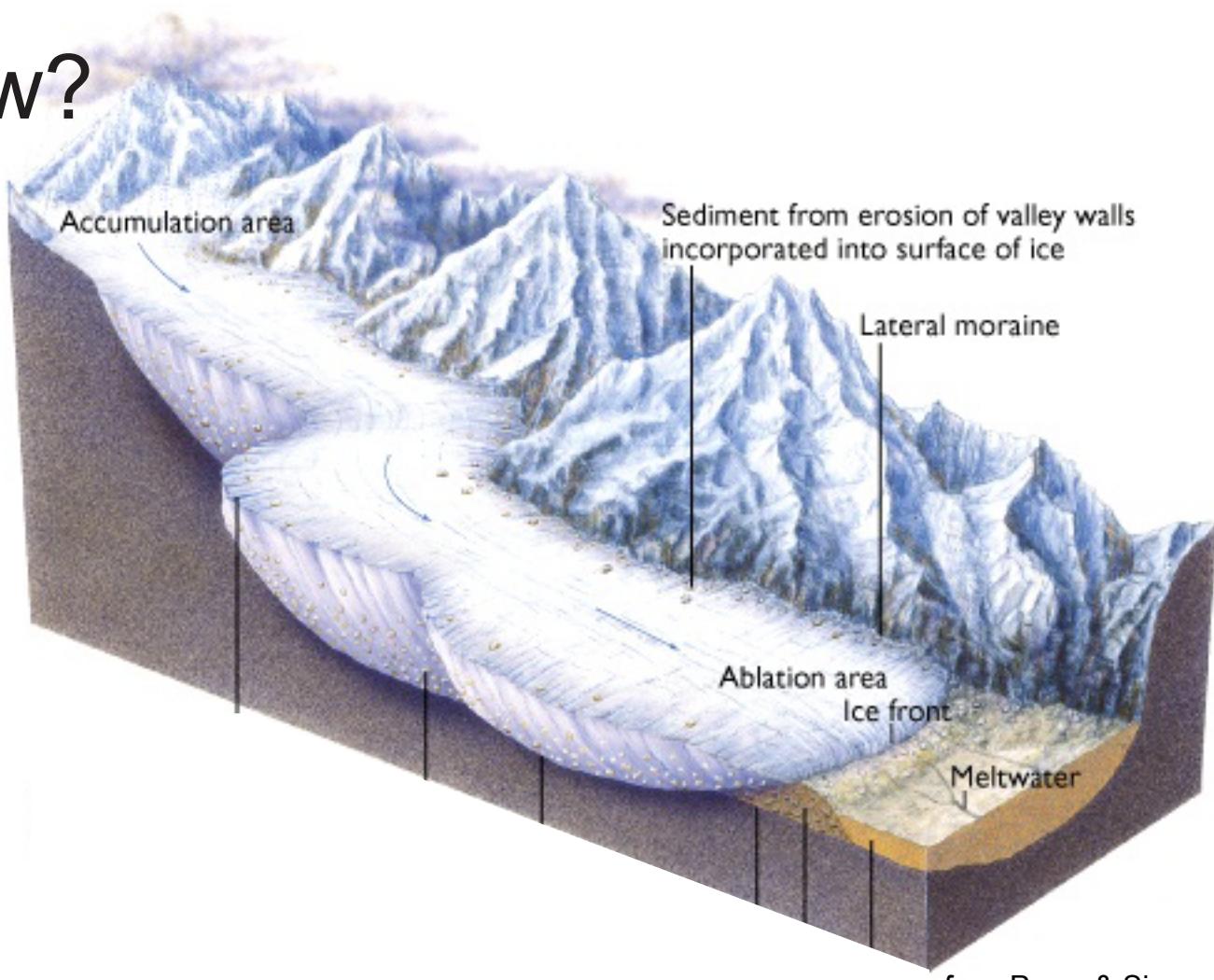
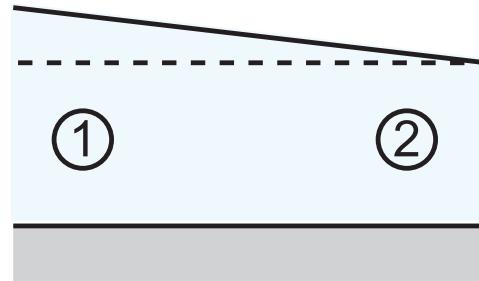


ICESat laser altimeter
track 0018

patterns emerge over time



Why does ice flow?

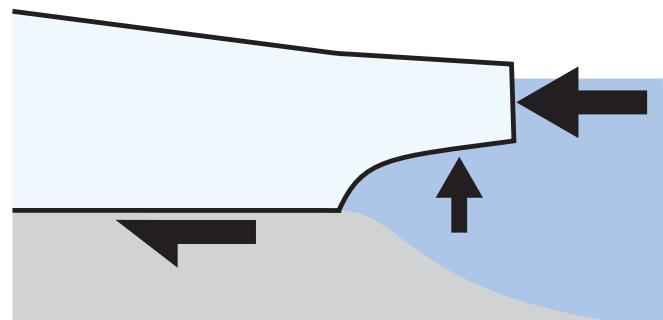


gravitational driving stress:

extra pressure at ① compared to ② yields
a stress gradient, ice deforms (flows) in response

resistive stresses:

forces applied at boundaries yield stresses
that must balance (or “dissipate”) the driving stress



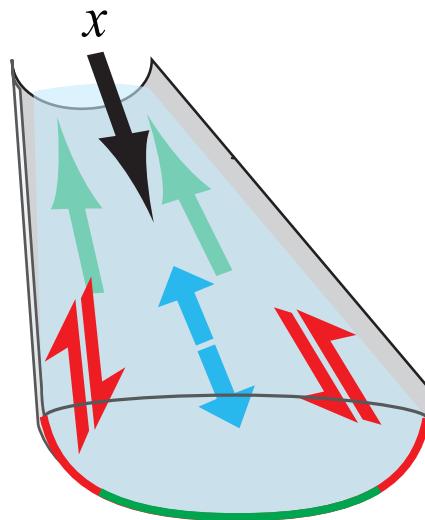
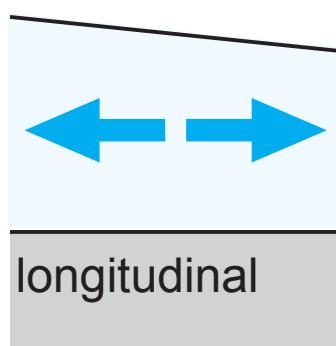
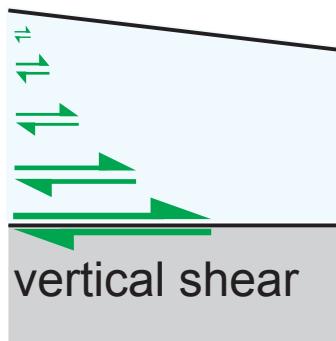
glacier flow

conservation of momentum

$$\frac{\partial \tau_{ij}}{\partial x_i} + \rho g_j = 0 \quad i,j \in \{x,y,z\}$$

$$x : \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} = 0 \quad , \quad z : \frac{\partial \tau_{zz}}{\partial z} + \frac{\partial \tau_{zy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial x} = \rho g$$

stresses

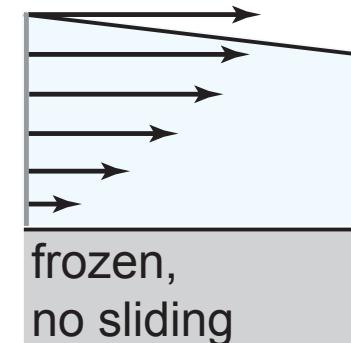


↔ vertical shear

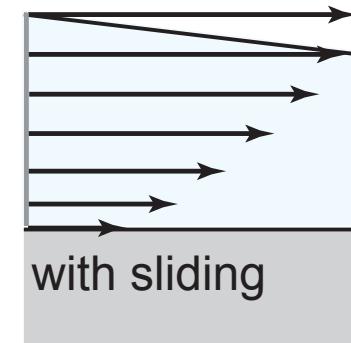
↔ lateral shear

↔ longitudinal stress

horizontal velocity



frozen,
no sliding



with sliding

glacier flow

constitutive relationship between stress τ_{ij} and strain rate $\dot{\varepsilon}_{ij}$

$$\dot{\varepsilon}_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad u_i \text{ ice velocity}$$

for isotropic ice:

$$\dot{\varepsilon}_{ij} = A \tau_e^{n-1} \tau_{ij}$$

τ_e frame-invariant effective stress

n empirical

A empirical “rate factor” (has an Arrhenius form)
temperature-dependent

