LAA Assignment

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```
In [ ]: from helper_functions import luGEPP, luSolve
   import scipy.linalg as sp
   import numpy as np
   import time
   import pandas as pd

In [ ]: st = time.perf_counter()
   time.sleep(5)
   en = time.perf_counter()
   en-st
```

Out[]: 5.000906399975065

Helper functions

```
In [ ]: def luGEPP(A):
            Input: A square matrix (A)
            Function: Performs the LU decompositon of the input matrix using
            Gaussian Elimination with Partial Pivoting such that PA = LU.
            Output: Permutation Matrix (P)
            Unit Lower Triangular Matrix (L)
            Upper Triangular Matrix (U)
            Time Taken for the factorisation process (t)
            n = len(A)
            A = A.astype(float)
            P = np.identity(n, dtype=float)
            L = np.zeros((n,n),dtype=float)
            U = np.copy(A)
            st = time.perf counter()
            for i in range(n):
                max_pivot = abs(U[i:,i])
                if max(max_pivot) == 0:
                     print("unable to find nonzero pivot")
                     break
                max_row = np.argmax(abs(U[i:,i])) + i
                U[[i, max_row]] = U[[max_row, i]]
                P[[i, max_row]] = P[[max_row, i]]
                L[[i, max_row]] = L[[max_row, i]]
                for j in range(i+1, n):
                    L[j,i] = U[j,i] / U[i,i]
                    U[j,i:] = L[j,i] * U[i,i:]
            np.fill_diagonal(L, 1.0)
            en = time.perf_counter()
            t = (en-st)*1000
            return P, L, U, t
        def forward_sub(L, Pb):
            Forward Substitution to find y such that Ly = Pb
            n = len(L)
            y = np.zeros(n, dtype=float)
            for i in range(n):
```

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y[i] = Pb[i] - sum(L[i,:i] * y[:i])
    return y
def backward_sub(U, y):
    Backward Substitution to find x such that Ux = y
    n = len(U)
    x = np.zeros(n, dtype=float)
    for i in range(n-1, -1, -1):
        x[i] = (y[i] - sum(U[i,i+1:] * x[i+1:])) / U[i,i]
    return x
def luSolve(A, b):
    Input: A square matrix (A) and a column vector (b) of size same as that of A.
    Function: Computes a column vector (x) using the luGEPP() to factorise A,
    and then, doing backward and forward substitution to solve for x such that, Ax = b.
    Output: Column vector (x) with same size as b.
    Time Taken (in ms) to get the solution (t).
    P, L, U, \underline{} = luGEPP(A)
    Pb = np.dot(P, b)
    st = time.perf_counter()
    y = forward sub(L, Pb)
    x = backward_sub(U, y)
    en = time.perf_counter()
    t = (en-st)*1000
    return x,t
```

Driver Code

```
In [ ]: N = [10, 50, 100, 400, 800, 1000]
        factorTime = {
             'Size':N,
            "SciPy factoriser (ms)":[],
             "Self factoriser (ms)": []
         solveTime = {
             'Size':N,
             "SciPy solver (ms)":[],
             "Self solver (ms)": []
             }
        matNorm = {
             'Size':N,
             "Matrix Norm Scipy":[],
             "Matrix Norm Self":[],
             "Vector Norm Scipy":[],
             "Vector Norm Self":[]
             }
In [ ]: for n in N:
            A = 200*np.random.random_sample(size=(n,n))-100
             b = 20*np.random.random_sample(size=n)-20
             # Scipy factoriser
             factorST = time.perf counter()
             P, L, U = sp.lu(A)
             factorEND = time.perf_counter()
            factorT = (factorEND - factorST)*1000
             factorTime["SciPy factoriser (ms)"].append(factorT)
```

```
# Self factoriser
p, 1, u, ft = luGEPP(A)
factorTime["Self factoriser (ms)"].append(ft)
# Scipy solver
solveST = time.perf_counter()
X = sp.lu_solve(sp.lu_factor(A), b)
solveEND = time.perf_counter()
solveT = (solveEND - solveST)*1000
solveTime["SciPy solver (ms)"].append(solveT)
# Self solver
x, st = luSolve(A,b)
solveTime["Self solver (ms)"].append(st)
# Norm of (PA-LU) for Scipy factoriser
matNorm["Matrix Norm Scipy"].append(np.linalg.norm(P.T@A - L@U))
# Norm of (PA-LU) for Self factoriser
matNorm["Matrix Norm Self"].append(np.linalg.norm(p@A-l@u))
# Norm of (Ax-b) for Scipy solver
matNorm["Vector Norm Scipy"].append(np.linalg.norm(A@X-b))
# Norm of (Ax-b) for Self solver
matNorm["Vector Norm Self"].append(np.linalg.norm(A@x-b))
```

Factorization Time Comparison

Out[]:		Size	SciPy factoriser (ms)	Self factoriser (ms)	Time Difference (ms)
	0	10	0.5586	1.3131	0.7545
	1	50	0.2288	12.8834	12.6546
	2	100	40.2254	29.2221	-11.0033
	3	400	9.6145	334.6275	325.0130
	4	800	27.2704	1415.8016	1388.5312
	5	1000	44.6676	2332.9476	2288.2800

Solver Time Comparison

Out[]:		Size	SciPy solver (ms)	Self solver (ms)	Time Difference (ms)
	0	10	0.2965	0.0749	-0.2216
	1	50	0.1621	0.4464	0.2843
	2	100	9.1784	2.3594	-6.8190
	3	400	8.2130	15.1024	6.8894
	4	800	23.5115	57.1029	33.5914
	5	1000	49.2274	96.5267	47.2993

Matrix (PA-LU) and Vector (Ax-b) Norm Comparison

Out[]:		Size	Matrix Norm Difference	Vector Norm Difference
	0	10	1.524314e-14	-1.472951e-14
	1	50	4.518089e-13	1.128427e-12
	2	100	1.657303e-12	3.569810e-12
	3	400	1.887651e-11	3.161320e-11
	4	800	3.553470e-11	9.776235e-11
	5	1000	6.105484e-11	-2.943371e-10