```
式
e ::=
                                                Expression
                               定数
                                                Constant
                               プリミティブ演算
  op(e_1,\ldots,e_n)
                                                 Arithmetic
                               条件分岐
  if e_1 then e_2 else e_3
                                                Conditional
 \mathtt{let}\ x = e_1\ \mathtt{in}\ e_2
                               変数定義
                                                 Variable declaration
                               変数の読み出し
                                                 Variable dereference
 let rec x y_1 \ldots y_n = e_1 in e_2 再帰関数定義
                                                Recursive function
                               関数呼び出し
                                                Function call
  e e_1 \ldots e_n
                               組の作成
                                                 Tuple
  (e_1,\ldots,e_n)
                                                Decomposition of a tuple
  let (x_1, \ldots, x_n) = e_1 in e_2
                               組の読み出し
                                                Array creation
 Array.create e_1 e_2
                               配列の作成
                                                Indexing an array
                               配列の読み出し
 e_1.(e_2)
                                                Assignment to an array
                               配列への書き込み
 e_1.(e_2) \leftarrow e_3
```

図 1: MinCaml の抽象構文(型は省略)

Abstract syntax of MinCaml (Type is omitted)

$$au::=$$
 au
 au

MinCaml types

op is a primitive operator that takes values

op is a primitive operator that takes values of
$$\pi 1$$
, ..., πn and gives a value of $\pi 1$, ..., πn and gives a value of $\pi 1$, ..., πn and gives a value of $\pi 1$, ..., πn and gives a value of $\pi 1$, ..., πn and gives a value of $\pi 1$, ..., πn and gives a value of $\pi 1$, ..., πn and gives a value of $\pi 1$.

$$\begin{array}{c}
\Gamma \vdash e_1 : \pi 1 & \dots & \Gamma \vdash e_n : \pi_n \\
\hline
\Gamma \vdash e_1 : \text{bool} & \Gamma \vdash e_2 : \tau & \Gamma \vdash e_3 : \tau \\
\hline
\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau & \hline{\Gamma \vdash e_1 : \tau_1} & \Gamma, x : \tau_1 \vdash e_2 : \tau_2 \\
\hline
\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau & \hline{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2} & \hline{\Gamma \vdash x : \tau} \\
\hline
\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau & \hline{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2} & \hline{\Gamma \vdash x : \tau} \\
\hline
\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau & \hline{\Gamma \vdash e_1 : \tau_1} & \dots \rightarrow \tau_n \rightarrow \tau \\
\hline
\Gamma \vdash x : \tau_1 \rightarrow \dots \rightarrow \tau_n \rightarrow \tau, y_1 : \tau_1, \dots, y_n : \tau_n \vdash e_1 : \tau \\
\hline
\Gamma \vdash x : \tau_1 \rightarrow \dots \rightarrow \tau_n \rightarrow \tau \vdash e_2 : \tau' & \hline{\Gamma \vdash e_1 : \tau_1} & \dots & \Gamma \vdash e_n : \tau_n \\
\hline
\Gamma \vdash e_1 : \tau_1 & \dots & \Gamma \vdash e_n : \tau_n \\
\hline
\Gamma \vdash e_1 : \tau_1 & \dots & \Gamma \vdash e_n : \tau_n \\
\hline
\Gamma \vdash e_1 : \text{int } \Gamma \vdash e_2 : \tau \\
\hline
\Gamma \vdash e_1 : \text{int } \Gamma \vdash e_2 : \tau \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{ int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{ int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{ int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{ int } \\
\hline
\Gamma \vdash e_1 : \tau \text{ array } \Gamma \vdash e_2 : \text{ int } \\
\hline
\Gamma \vdash e_1 : (e_2) \mapsto e_3 : \text{ unit}$$

MinCaml's typing rule

```
e ::=
                c
                op(x_1,\ldots,x_n)
                if x = y then e_1 else e_2
                if x \leq y then e_1 else e_2
                let x = e_1 in e_2
                let rec x y_1 \ldots y_n = e_1 in e_2
                x y_1 \ldots y_n
                (x_1,\ldots,x_n)
                let (x_1,\ldots,x_n)=y in e
                x.(y)
                x.(y) \leftarrow z
図 4: MinCaml の K 正規形(外部配列・外部関数適用は省略)
```

K-normal-form in MinCaml External arrays and External function application are omitted

```
\mathcal{K}: \mathtt{Syntax.t} \rightarrow \mathtt{KNormal.t}
  \mathcal{K}(c)
  \mathcal{K}(\mathsf{not}(e))
                                                                \mathcal{K}(\text{if } e \text{ then false else true})
  \mathcal{K}(e_1 = e_2)
                                                            = \mathcal{K}(\text{if }e_1=e_2 \text{ then true else false})
  \mathcal{K}(e_1 \leq e_2)
                                                            = \mathcal{K}(\text{if } e_1 \leq e_2 \text{ then true else false})
  \mathcal{K}(op(e_1,\ldots,e_n))
                                                            = let x_1 = \mathcal{K}(e_1) in ... let x_n = \mathcal{K}(e_n) in op(x_1, \ldots, x_n)
                                                                                                              op が論理演算・比較以外の場合
                                                                                                                              op is NOT a logical operator
 \mathcal{K}(\texttt{if not } e_1 \texttt{ then } e_2 \texttt{ else } e_3)
                                                            = \mathcal{K}(\text{if } e_1 \text{ then } e_3 \text{ else } e_2)
                                                                                                                                                 nor comparator
  \mathcal{K}(\text{if } e_1 = e_2 \text{ then } e_3 \text{ else } e_4)
                                                            = let x = \mathcal{K}(e_1) in let y = \mathcal{K}(e_2) in
                                                                  if x = y then \mathcal{K}(e_3) else \mathcal{K}(e_4)
 \mathcal{K}(\text{if } e_1 \leq e_2 \text{ then } e_3 \text{ else } e_4)
                                                            = let x = \mathcal{K}(e_1) in let y = \mathcal{K}(e_2) in
                                                                   if x \leq y then \mathcal{K}(e_3) else \mathcal{K}(e_4)
                                                            =~\mathcal{K}(	ext{if }e_1=	ext{false then }e_3 	ext{ else }e_2)
 \mathcal{K}(\text{if }e_1 \text{ then } e_2 \text{ else } e_3)
                                                                                                               e<sub>1</sub> が論理演算・比較以外の場合
                                                                  let x=\mathcal{K}(e_1) in \mathcal{K}(e_2) el is not a logical expression nor comparation
  \mathcal{K}(\text{let } x = e_1 \text{ in } e_2)
  \mathcal{K}(x)
 \mathcal{K}(	ext{let rec }x\ y_1\ \dots\ y_n=e_1\ 	ext{in }e_2)\ =\ 	ext{let rec }x\ y_1\ \dots\ y_n=\mathcal{K}(e_1)\ 	ext{in }\mathcal{K}(e_2)
                                                            = let x = \mathcal{K}(e) in let y_1 = \mathcal{K}(e_1) in ... let y_n = \mathcal{K}(e_n) in
  \mathcal{K}(e \ e_1 \ \dots \ e_n)
                                                                  x y_1 \ldots y_n
                                                           = let x_1 = \mathcal{K}(e_1) in ... let x_n = \mathcal{K}(e_n) in (x_1, \ldots, x_n)
  \mathcal{K}(e_1,\ldots,e_n)
  \mathcal{K}(\text{let }(x_1,\ldots,x_n)=e_1 \text{ in } e_2)
                                                            = let y = \mathcal{K}(e_1) in let (x_1, \ldots, x_n) = y in \mathcal{K}(e_2)
                                                           = let x = \mathcal{K}(e_1) in let y = \mathcal{K}(e_2) in create_array x \ y
  \mathcal{K}(\texttt{Array.create}\;e_1\;e_2)
                                                            = let x = \mathcal{K}(e_1) in let y = \mathcal{K}(e_2) in x.(y)
  \mathcal{K}(e_1.(e_2))
  \mathcal{K}(e_1.(e_2) \leftarrow e_3)
                                                            = let x = \mathcal{K}(e_1) in let y = \mathcal{K}(e_2) in let z = \mathcal{K}(e_3) in
                                                                  x.(y) \leftarrow z
図 5: K 正規化(論理値の整数化と、insert_let による最適化は省略)。右辺に出現していて左辺に出現
```

Conversion to K-normal-form (conversion of logical values to integers and optimization by insert=let is omitted). Variables that occur in right-hand-side but not in left- are regarded as fresh.

していない変数は、すべて新しい (fresh) とする。

```
\alpha: \mathtt{Id.t} \ \mathtt{M.t} \to \mathtt{KNormal.t} \to \mathtt{KNormal.t}
         \alpha_{\varepsilon}(c)
         \alpha_{\varepsilon}(op(x_1,\ldots,x_n))
                                                                                                    = op(\varepsilon(x_1), \ldots, \varepsilon(x_n))
         \alpha_{\varepsilon}(\text{if } x = y \text{ then } e_1 \text{ else } e_2)
                                                                                                    = if \varepsilon(x) = \varepsilon(y) then \alpha_{\varepsilon}(e_1) else \alpha_{\varepsilon}(e_2)
         \alpha_{\varepsilon}(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                                                                    = if \varepsilon(x) \leq \varepsilon(y) then \alpha_{\varepsilon}(e_1) else \alpha_{\varepsilon}(e_2)
         \alpha_{\varepsilon}(\text{let } x = e_1 \text{ in } e_2)
                                                                                                    = \ \ \operatorname{let} \, x' = \alpha_\varepsilon(e_1) \, \operatorname{in} \, \alpha_{\varepsilon, x \mapsto x'}(e_2)
                                                                                                     = \varepsilon(x)
         \alpha_{\varepsilon}(x)
         \alpha_{\varepsilon}(\texttt{let rec } x \ y_1 \ \dots \ y_n = e_1 \ \texttt{in} \ e_2) \ = \ \texttt{let rec} \ x' \ y_1' \ \dots \ y_n' = \alpha_{\varepsilon, x \mapsto x', y_1 \mapsto y_1', \dots, y_n \mapsto y_n'}(e_1) \ \texttt{in}
                                                                                                             \alpha_{\varepsilon,x\mapsto x'}(e_2)
         \alpha_{\varepsilon}(x \ y_1 \ \dots \ y_n)
                                                                                                    = \varepsilon(x) \varepsilon(y_1) \ldots \varepsilon(y_n)
                                                                                                = (\varepsilon(x_1), \ldots, \varepsilon(x_n))
         \alpha_{\varepsilon}((x_1,\ldots,x_n))
                                                                                          = \text{ let } (x_1', \dots, x_n') = \varepsilon(y) \text{ in } \alpha_{\varepsilon, x_1 \mapsto x_1', \dots, x_n \mapsto x_n'}(e)
         \alpha_{\varepsilon}(\text{let }(x_1,\ldots,x_n)=y \text{ in } e)
                                                                                                    = \varepsilon(x).(\varepsilon(y))
         \alpha_{\varepsilon}(x.(y))
         \alpha_{\varepsilon}(x.(y) \leftarrow z)
                                                                                                    = \varepsilon(x).(\varepsilon(y)) \leftarrow \varepsilon(z)
```

図 6: α 変換。 ε は α 変換前の変数を受け取って、 α 変換後の変数を返す写像。右辺に出現していて左辺に出現していない変数 (x' など)は、すべて fresh とする。

α conversion

 ε is a mapping that maps a variable that occur in the original expression to the corresponding variable in the resulting expression. Variables that occur in the right-hand-side and not in the left- (such as x') are considered fresh.

```
\beta: \mathtt{Id.t} \ \mathtt{M.t} \rightarrow \mathtt{KNormal.t} \rightarrow \mathtt{KNormal.t}
       \beta_{\varepsilon}(c)
       \beta_{\varepsilon}(op(x_1,\ldots,x_n))
                                                                                 = op(\varepsilon(x_1), \ldots, \varepsilon(x_n))
       \beta_{\varepsilon}(\text{if } x=y \text{ then } e_1 \text{ else } e_2)
                                                                              = if \varepsilon(x) = \varepsilon(y) then \beta_{\varepsilon}(e_1) else \beta_{\varepsilon}(e_2)
                                                                                = if \varepsilon(x) \leq \varepsilon(y) then \beta_{\varepsilon}(e_1) else \beta_{\varepsilon}(e_2) Case 1: \beta \varepsilon(e_1) = y
       \beta_{\varepsilon}(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                                                                                                                     \beta_{\varepsilon}(e_1) が変数 y の場合
       \beta_{\varepsilon}(\text{let } x = e_1 \text{ in } e_2)
                                                                                 = \beta_{\varepsilon,x\mapsto y}(e_2)
                                                                                 = let x=eta_{arepsilon}(e_1) in eta_{arepsilon}(e_2) eta_{arepsilon}(e_1) が変数でない場合
      \beta_{\varepsilon}(let x=e_1 in e_2)
                                                                                                                                                            Case 2: \beta\epsilon(e1) is not a variable
                                                                                  = \varepsilon(x)
       \beta_{\varepsilon}(\text{let rec } x \ y_1 \ \dots \ y_n = e_1 \ \text{in} \ e_2) = \text{let rec } x \ y_1 \ \dots \ y_n = \beta_{\varepsilon}(e_1) \ \text{in} \ \beta_{\varepsilon}(e_2)
                                                                                 = \varepsilon(x) \varepsilon(y_1) \ldots \varepsilon(y_n)
       \beta_{\varepsilon}(x \ y_1 \ \dots \ y_n)
       \beta_{\varepsilon}((x_1,\ldots,x_n))
                                                                                 = (\varepsilon(x_1), \ldots, \varepsilon(x_n))
       \beta_{\varepsilon}(\text{let }(x_1,\ldots,x_n)=y \text{ in } e)
                                                                               = let (x_1,\ldots,x_n)=\varepsilon(y) in \beta_{\varepsilon}(e)
       \beta_{\varepsilon}(x.(y))
                                                                                 = \varepsilon(x).(\varepsilon(y))
                                                                                 = \quad \varepsilon(x).(\varepsilon(y)) \leftarrow \varepsilon(z)
       \beta_{\varepsilon}(x.(y) \leftarrow z)
図 7: \beta 簡約。 \varepsilon は \beta 簡約前の変数を受け取って、\beta 簡約後の変数を返す写像。 \varepsilon(x) が定義されていない場
```

β-reduction

合は、 $\varepsilon(x) = x$ とみなす。

 ϵ is a mapping that maps a variable that occurs in the original expression to a variable in the resulting expression. When ϵ does not map x, we regard $\epsilon(x) = x$; in other words, ϵ maps x to itself, by default.

in case, A(e1) is formed " let ... in e1' " and e1' is not a let-form.

Here "let ... in" stands for 0 or more nesting of let bindings.

```
\mathcal{A}: 	exttt{KNormal.t} 
ightarrow 	exttt{KNormal.t}
                \mathcal{A}(c)
                                                                              = c
                \mathcal{A}(op(x_1,\ldots,x_n))
                                                                                   op(x_1,\ldots,x_n)
                                                                              = if x=y then \mathcal{A}(e_1) else \mathcal{A}(e_2)
                \mathcal{A}(\text{if } x = y \text{ then } e_1 \text{ else } e_2)
                \mathcal{A}(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                                              = if x \leq y then \mathcal{A}(e_1) else \mathcal{A}(e_2)
                \mathcal{A}(	exttt{let}\ x = e_1\ 	exttt{in}\ e_2)
                                                                              = let \dots in let x=e_1' in \mathcal{A}(e_2)
                                                                                             \mathcal{A}(e_1) = \mathsf{let} \, \ldots \, \mathsf{in} \, e_1' という形で
                                                                                             (let ... in は 0 個以上の let の列)、
                                                                                            e_1' は let でない
                \mathcal{A}(x)
                                                                                    let rec x y_1 \ldots y_n = \mathcal{A}(e_1) in \mathcal{A}(e_2)
                \mathcal{A}(\texttt{let rec } x \ y_1 \ \dots \ y_n = e_1 \ \texttt{in} \ e_2)
                \mathcal{A}(x \ y_1 \ \dots \ y_n)
                                                                                    x y_1 \ldots y_n
                \mathcal{A}((x_1,\ldots,x_n))
                                                                              = (x_1, \ldots, x_n)
                \mathcal{A}(\mathsf{let}\ (x_1,\ldots,x_n)=y\ \mathsf{in}\ e)
                                                                              = let (x_1,\ldots,x_n)=y in \mathcal{A}(e)
                \mathcal{A}(x.(y))
                                                                              = x.(y)
                \mathcal{A}(x.(y) \leftarrow z)
                                                                              = x.(y) \leftarrow z
                                                              図 8: ネストした 1et の簡約
```

Reduction of nested "let"

5

Example:

A(N)

```
Suppose that:

A(M) =

let y = e1' in

let z = e2' in

M1

A(let x = M in N) will be

let y = e1' in

let z = e2' in

let x = M1 in
```

... (の) 場合 = in case ...

```
\mathcal{I}: (\mathtt{Id.t\ list} \times \mathtt{KNormal.t}) \ \mathtt{M.t} \rightarrow \mathtt{KNormal.t} \rightarrow \mathtt{KNormal.t}
      \mathcal{I}_{\varepsilon}(c)
      \mathcal{I}_{\varepsilon}(op(x_1,\ldots,x_n))
                                                                          = op(x_1,\ldots,x_n)
                                                                      = if x=y then \mathcal{I}_arepsilon(e_1) else \mathcal{I}_arepsilon(e_2)
      \mathcal{I}_{\varepsilon}(\texttt{if } x = y \texttt{ then } e_1 \texttt{ else } e_2)
      \mathcal{I}_{\varepsilon}(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                                      = if x \leq y then \mathcal{I}_{\varepsilon}(e_1) else \mathcal{I}_{\varepsilon}(e_2)
      \mathcal{I}_{\varepsilon}(let x=e_1 in e_2)
                                                                        = let x = \mathcal{I}_{\varepsilon}(e_1) in \mathcal{I}_{\varepsilon}(e_2)
      \mathcal{I}_{\varepsilon}(x)
      \mathcal{I}_{\varepsilon}(\text{let rec }x\;y_1\;\ldots\;y_n=e_1\;\text{in }e_2) = \varepsilon'=\varepsilon, x\mapsto ((y_1,\ldots,y_n),e_1)\; \xi\; \mathsf{LT}
                                                                                let rec x y_1 \ldots y_n = \mathcal{I}_{\varepsilon'}(e_1) in \mathcal{I}_{\varepsilon'}(e_2)
                                                                                                                                         size(e_1) \leq th の場合
      \mathcal{I}_{\varepsilon}(\text{let rec } x \ y_1 \ \dots \ y_n = e_1 \ \text{in} \ e_2) = \text{let rec } x \ y_1 \ \dots \ y_n = \mathcal{I}_{\varepsilon}(e_1) \ \text{in} \ \mathcal{I}_{\varepsilon}(e_2)
                                                                                                                                         size(e_1) > th の場合
                                                                          = \alpha_{y_1\mapsto z_1,\dots,y_n\mapsto z_n}(e) \varepsilon(x)=((z_1,\dots,z_n),e) の場合
      \mathcal{I}_{\varepsilon}(x \ y_1 \ \dots \ y_n)
                                                                                                                     \varepsilon(x) が定義されていない場合
      \mathcal{I}_{\varepsilon}(x \ y_1 \ \ldots \ y_n)
                                                                       = x y_1 \dots y_n
      \mathcal{I}_{\varepsilon}((x_1,\ldots,x_n))
                                                                         = (x_1, \ldots, x_n)
                                                                                                                               ε is not defined for x
      \mathcal{I}_{\varepsilon}(let (x_1,\ldots,x_n)=y in e)
                                                                      = let (x_1,\ldots,x_n)=y in \mathcal{I}_{\varepsilon}(e)
      \mathcal{I}_{\varepsilon}(x.(y))
                                                                         = x.(y)
      \mathcal{I}_{\varepsilon}(x.(y) \leftarrow z)
                                                                          = x.(y) \leftarrow z
       size(c)
       size(op(x_1,\ldots,x_n))
       size(if \ x = y \ then \ e_1 \ else \ e_2)
                                                                      = 1 + size(e_1) + size(e_2)
       size(if \ x \leq y \ then \ e_1 \ else \ e_2)
                                                                      = 1 + size(e_1) + size(e_2)
       size(let x = e_1 \text{ in } e_2)
                                                                       = 1 + size(e_1) + size(e_2)
       size(x)
       size(let rec x y_1 \dots y_n = e_1 \text{ in } e_2) = 1 + size(e_1) + size(e_2)
       size(x y_1 \ldots y_n)
       size((x_1,\ldots,x_n))
       size(\mathtt{let}\ (x_1,\ldots,x_n)=y\ \mathtt{in}\ e)
                                                                      = 1 + size(e)
       size(x.(y))
       size(x.(y) \leftarrow z)
```

図 9: インライン展開。 ε はサイズの小さい関数名を受け取って、仮引数と本体を返す写像。th はインライン展開する関数の最大サイズ(ユーザ指定)。

Inline expansion: the environment ε takes a name of small-sized function and gives its virtual argument names and body. "th" stands for the expansion threshold: the maximum-allowed size of the function. Its value is specified by the user (compiler's command-line option?).

Japanese translation:

- 1. C の場合: In case a condition C holds
- 2. それ以外の場合: otherwise
- 3. $\epsilon(x)$ と $\epsilon(y)$ が等しい定数: ϵ gives the same constant values for x and y
- 4. ε(x) と ε(y) が異なる定数: ε gives different contant values for x and y
- 5. $\epsilon(x)$ と $\epsilon(y)$ が定数: both $\epsilon(x)$ and $\epsilon(y)$ are constant values (more strictly, ϵ is defined for both x and y)

```
\mathcal{F}: \mathtt{KNormal.t} \ \mathtt{M.t} 
ightarrow \mathtt{KNormal.t} 
ightarrow \mathtt{KNormal.t}
               \mathcal{F}_{\varepsilon}(c)
              \mathcal{F}_{\varepsilon}(op(x_1,\ldots,x_n))
                                                                                                                                                                                                                                                                                                            op(\varepsilon(x_1),\ldots,\varepsilon(x_n))=c の場合
                                                                                                                                                                                           = c
              \mathcal{F}_{\varepsilon}(op(x_1,\ldots,x_n))
                                                                                                                                                                                                                                                                                                                                                                                              それ以外の場合
                                                                                                                                                                                          = op(x_1,\ldots,x_n)
              \mathcal{F}_{\varepsilon}(\text{if } x=y \text{ then } e_1 \text{ else } e_2)
                                                                                                                                                                                       = \mathcal{F}_{\varepsilon}(e_1)
                                                                                                                                                                                                                                                                                                          \varepsilon(x) と \varepsilon(y) が等しい定数の場合
              \mathcal{F}_{\varepsilon}(\text{if } x = y \text{ then } e_1 \text{ else } e_2) \qquad \qquad = \mathcal{F}_{\varepsilon}(e_2) \qquad \qquad \varepsilon(x) \ \mathcal{E}(y) \ \mathcal{E}(x) \ \mathcal{E}(y) \ \mathcal{E}(x) \ \mathcal
                                                                                                                                                                                                                                                                                                             \varepsilon(x) と \varepsilon(y) が異なる定数の場合
                                                                                                                                                                                                                                                                                                                                                                                           それ以外の場合
              \mathcal{F}_{\varepsilon}(if x \leq y then e_1 else e_2) = \mathcal{F}_{\varepsilon}(e_1) \varepsilon(x) と \varepsilon(y) が定数で、\varepsilon(x) \leq \varepsilon(y) の場合
              \mathcal{F}_{\varepsilon}(\texttt{if } x \leq y \texttt{ then } e_1 \texttt{ else } e_2)
                                                                                                                                                                                = \mathcal{F}_{\varepsilon}(e_2) \varepsilon(x) と \varepsilon(y) が定数で、\varepsilon(x) > \varepsilon(y) の場合
              \mathcal{F}_{\varepsilon}(\texttt{if } x \leq y \texttt{ then } e_1 \texttt{ else } e_2)
                                                                                                                                                                                = if x \leq y then \mathcal{F}_{arepsilon}(e_1) else \mathcal{F}_{arepsilon}(e_2) それ以外の場合
                                                                                                                                                                                           \mathcal{F}_{\varepsilon}(let x=e_1 in e_2)
                                                                                                                                                                                                             let x = e'_1 in \mathcal{F}_{\varepsilon, x \mapsto e'_1}(e_2)
              \mathcal{F}_{\varepsilon}(x)
              \mathcal{F}_{arepsilon}(let rec x\ y_1\ \dots\ y_n=e_1 in e_2) = let rec x\ y_1\ \dots\ y_n=\mathcal{F}_{arepsilon}(e_1) in \mathcal{F}_{arepsilon}(e_2)
              \mathcal{F}_{\varepsilon}(x \ y_1 \ \ldots \ y_n)
                                                                                                                                                                                          = x y_1 \dots y_n
              \mathcal{F}_{\varepsilon}((x_1,\ldots,x_n))
                                                                                                                                                                                          = (x_1,\ldots,x_n)
              \mathcal{F}_{\varepsilon}(let (x_1,\ldots,x_n)=y in e)
                                                                                                                                                                                           = let x_1 = y_1 in ... let x_n = y_n in \mathcal{F}_{\varepsilon}(e)
                                                                                                                                                                                                                                                                                                                                               \varepsilon(y) = (y_1, \dots, y_n) の場合
              \mathcal{F}_{\varepsilon}(let (x_1,\ldots,x_n)=y in e)
                                                                                                                                                                                       = let (x_1,\ldots,x_n)=y in \mathcal{F}_{\varepsilon}(e)
               \mathcal{F}_{\varepsilon}(x.(y))
                                                                                                                                                                                           = x.(y)
              \mathcal{F}_{\varepsilon}(x.(y) \leftarrow z)
                                                                                                                                                                                           = x.(y) \leftarrow z
                                                                                            図 10: 定数畳み込み。\varepsilon は変数を受け取って、定数を返す写像。
```

Constant folding: ϵ is a mapping that takes a variable name and gives its associated constant value, if any.

```
\mathcal{E}: \mathtt{KNormal.t} 	o \mathtt{KNormal.t}
   \mathcal{E}(c)
                                                       = c
   \mathcal{E}(op(x_1,\ldots,x_n))
                                                     = op(x_1,\ldots,x_n)
                                                     = if x=y then \mathcal{E}(e_1) else \mathcal{E}(e_2)
   \mathcal{E}(\text{if } x = y \text{ then } e_1 \text{ else } e_2)
   \mathcal{E}(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                     = if x \leq y then \mathcal{E}(e_1) else \mathcal{E}(e_2)
                                                                         effect(\mathcal{E}(e_1)) = false かつ x \notin FV(\mathcal{E}(e_2)) の場合
   \mathcal{E}(\text{let } x = e_1 \text{ in } e_2)
   \mathcal{E}(\texttt{let } x = e_1 \texttt{ in } e_2)
                                                       = let x = \mathcal{E}(e_1) in \mathcal{E}(e_2)
                                                                                                                          それ以外の場合
   \mathcal{E}(x)
   \mathcal{E}(\text{let rec } x \ y_1 \ \dots \ y_n = e_1 \ \text{in} \ e_2) \ = \ \mathcal{E}(e_2)
                                                                                                                x \notin FV(\mathcal{E}(e_2)) の場合
   \mathcal{E}(	ext{let rec } x \ y_1 \ \dots \ y_n = e_1 \ 	ext{in} \ e_2) = 	ext{let rec } x \ y_1 \ \dots \ y_n = \mathcal{E}(e_1) \ 	ext{in} \ \mathcal{E}(e_2) それ以外の場合
   \mathcal{E}(x \ y_1 \ \dots \ y_n)
                                                     = x y_1 \dots y_n
   \mathcal{E}((x_1,\ldots,x_n))
                                                     = (x_1,\ldots,x_n)
                                                                                            \{x_1,\ldots,x_n\}\cap FV(\mathcal{E}(e))=\emptyset の場合
   \mathcal{E}(\text{let }(x_1,\ldots,x_n)=y \text{ in } e)
                                                    = \mathcal{E}(e)
                                                                                                                       それ以外の場合
   \mathcal{E}(\text{let }(x_1,\ldots,x_n)=y \text{ in } e)
                                                     = let (x_1,\ldots,x_n)=y in \mathcal{E}(e)
   \mathcal{E}(x.(y))
                                                       = x.(y)
   \mathcal{E}(x.(y) \leftarrow z)
                                                       = x.(y) \leftarrow z
effect: {	t KNormal.t} 	o {	t bool}
                          effect(c)
                                                                                     = false
                           effect(op(x_1,\ldots,x_n))
                                                                                     = false
                          effect(if x = y then e_1 else e_2)
                                                                                 = effect(e_1) \vee effect(e_2)
                          effect(if \ x \leq y \ then \ e_1 \ else \ e_2) = effect(e_1) \lor effect(e_2)
                           effect(let x = e_1 in e_2)
                                                                                    = effect(e_1) \vee effect(e_2)
                          effect(x)
                                                                                    = false
                          effect(let rec x y_1 ... y_n = e_1 in e_2) = effect(e_2)
                           effect(x \ y_1 \ \ldots \ y_n)
                                                                                    = true
                          effect((x_1,\ldots,x_n))
                                                                                    = false
                          effect(let(x_1,\ldots,x_n)=y in e)
                                                                                    = effect(e)
                           effect(x.(y))
                                                                                     = false
                           effect(x.(y) \leftarrow z)
                                                                                     = true
                                                       図 11: 不要定義削除 (1/2)
```

Elimination of redundant definitions (1/2)

FV: stands for "a set of free variables": x is free in e iff x's definition is not given in e. Free variables of e is a set of variables that are free in e.

The effect system used in this analysis collects all the defined variables in an expression.

Set notation Φ: empty set

 $A \cup B$: set union, $A \cap B$: set intersection

A \ B: { a in A | a not in B }

```
FV: {	t KNormal.t} 
ightarrow {	t S.t}
            FV(c)
            FV(op(x_1,\ldots,x_n))
                                                             = \{x_1,\ldots,x_n\}
            FV(if x=y then e_1 else e_2)
                                                             = \{x, y\} \cup FV(e_1) \cup FV(e_2)
            FV(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                            = \{x,y\} \cup FV(e_1) \cup FV(e_2)
                                                             = FV(e_1) \cup (FV(e_2) \setminus \{x\})
            FV(let x = e_1 \text{ in } e_2)
            FV(x)
                                                             = \{x\}
            FV(\text{let rec } x \ y_1 \ \dots \ y_n = e_1 \ \text{in} \ e_2) = ((FV(e_1) \setminus \{y_1, \dots, y_n\}) \cup FV(e_2)) \setminus \{x\}
            FV(x y_1 \ldots y_n)
                                                            = \{x, y_1, \ldots, y_n\}
            FV((x_1,\ldots,x_n))
                                                            = \{x_1,\ldots,x_n\}
                                                          = \{y\} \cup (FV(e) \setminus \{x_1, \dots, x_n\})
            FV(let (x_1,\ldots,x_n)=y in e)
            FV(x.(y))
                                                             = \{x, y\}
            FV(x.(y) \leftarrow z)
                                                             = \{x, y, z\}
                                                図 12: 不要定義削除 (2/2)
```

Elimination of redundant definisions (2/2)

```
プログラム全体
P ::=
 (\{D_1,\ldots,D_n\},e)
                                       トップレベル関数定義の集合とメインルーチンの式
                                       トップレベル関数定義
                                       関数のラベルと仮引数、自由変数、および本体
 L_x(y_1,\ldots,y_m)(z_1,\ldots,z_n)=e
e ::=
                              P: a set of the whole program that consists of definitions of
                              top-level function definitions and a main routine.
 op(x_1,\ldots,x_n)
                              D: the syntax of top-level function definition, which consists
 if x = y then e_1 else e_2
                              of function label (= name), a list of ... arguments, a list of
 if x \leq y then e_1 else e_2
                              free variables, and its function body.
 let x = e_1 in e_2
 make\_closure \ x = (\mathtt{L}_x, (y_1, \ldots, y_n)) in e クロージャ生成
 apply\_closure(x, y_1, \dots, y_n)
                                       クロージャを用いた関数呼び出し
                                       クロージャを用いない関数呼び出し (known function call)
 apply\_direct(L_x, y_1, \dots, y_n)
 (x_1,\ldots,x_n)
                              make closure: closure creation
 \mathtt{let}\ (x_1,\ldots,x_n)=y\ \mathtt{in}\ e
                              apply_closure: function call using a closure
 x.(y)
                              apply_direct: function call without using a closure (this
 x.(y) \leftarrow z
                              more efficient than apply_closure)
```

Closure language

Closure conversion convertes a KNF form into an instance of the closure language. This syntactic definition gives the structure of the MinCaml program after closure conversion is performed on KNF. Note that this definition does not have "let rec" any more

```
\mathcal{C}: \mathtt{KNormal.t} \rightarrow \mathtt{Closure.t}
          \mathcal{C}(c)
          \mathcal{C}(op(x_1,\ldots,x_n))
                                                               = op(x_1,\ldots,x_n)
          C(\text{if } x = y \text{ then } e_1 \text{ else } e_2)
                                                              = if x = y then \mathcal{C}(e_1) else \mathcal{C}(e_2)
          C(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                            = if x \leq y then \mathcal{C}(e_1) else \mathcal{C}(e_2)
          C(let x = e_1 \text{ in } e_2)
                                                              = let x = \mathcal{C}(e_1) in \mathcal{C}(e_2)
          \mathcal{C}(x)
           \mathcal{C}(	ext{let rec } x \; y_1 \; \ldots \; y_n = e_1 \; 	ext{in} \; e_2) \;\; = \;\; \mathcal{D} \; 	ext{に} \; \mathtt{L}_x(y_1,\ldots,y_n)(z_1,\ldots,z_m) = e_1' \; を加え、
                                                                     make\_closure \ x = (L_x, (z_1, \ldots, z_m)) in e_2'を返す
                                                                           ただし e'_1 = C(e_1), e'_2 = C(e_2),
                                                                           FV(e'_1) \setminus \{x, y_1, \dots, y_n\} = \{z_1, \dots, z_m\}
          C(x y_1 \ldots y_n)
                                                               = apply\_closure(x, y_1, \dots, y_n)
           \mathcal{C}((x_1,\ldots,x_n))
                                                               = (x_1,\ldots,x_n)
          C(\text{let }(x_1,\ldots,x_n)=y \text{ in } e)
                                                              = let (x_1,\ldots,x_n)=y in \mathcal{C}(e)
           \mathcal{C}(x.(y))
                                                              = x.(y)
                                                              = x.(y) \leftarrow z
          \mathcal{C}(x.(y) \leftarrow z)
FV: \mathtt{Closure.t} 	o \mathtt{S.t}
                FV(c)
                FV(op(x_1,\ldots,x_n))
                                                                                    = \{x_1,\ldots,x_n\}
                                                                                   = \{x,y\} \cup FV(e_1) \cup FV(e_2)
                FV(if x = y then e_1 else e_2)
                FV(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                                                  = \{x,y\} \cup FV(e_1) \cup FV(e_2)
                 FV(let x = e_1 \text{ in } e_2)
                                                                                   = FV(e_1) \cup (FV(e_2) \setminus \{x\})
                FV(x)
                                                                                    = \{x\}
                 FV(\mathit{make\_closure}\ x = (\mathtt{L}_x, (y_1, \ldots, y_n))\ \mathsf{in}\ e) \ = \ \{y_1, \ldots, y_n\} \cup (FV(e) \setminus \{x\})
                 FV(apply\_closure(x, y_1, ..., y_n))
                                                                                   = \{x, y_1, \dots, y_n\}
                FV(apply\_direct(L_x, y_1, \ldots, y_n))
                                                                                    = \{y_1, \dots, y_n\}
                 FV((x_1,\ldots,x_n))
                                                                                   = \{x_1,\ldots,x_n\}
                 FV(let (x_1, \ldots, x_n) = y in e)
                                                                                   = \{y\} \cup (FV(e) \setminus \{x_1, \dots, x_n\})
                FV(x.(y))
                                                                                    = \{x, y\}
                FV(x.(y) \leftarrow z)
                                                                                    = \{x, y, z\}
図 14: 賢くない Closure 変換 \mathcal{C}(e)。 \mathcal{D} はトップレベル関数定義の集合を記憶しておくためのグローバル
```

Naive closure conversion. D is a global variable that holds a set of top-level function definitions.

変数。

```
\mathcal{C}: \mathtt{S.t} 
ightarrow \mathtt{KNormal.t} 
ightarrow \mathtt{Closure.t}
       \mathcal{C}_s(	ext{let rec } x \ y_1 \ \dots \ y_n = e_1 \ 	ext{in} \ e_2) \ = \ \mathcal{D} \ 	ext{に} \ 	ext{L}_x(y_1, \dots, y_n)() = e_1' \ 	ext{を加え、}
                                                                   make\_closure \ x = (L_x, ())  in e_2'を返す
                                                                          ただし e'_1 = C_{s'}(e_1), e'_2 = C_{s'}(e_2), s' = s \cup \{x\},
                                                                          FV(e_1')\setminus\{y_1,\ldots,y_n\}=\emptyset の場合
       \mathcal{C}_s(	ext{let rec } x \ y_1 \ \dots \ y_n = e_1 \ 	ext{in} \ e_2) \ = \ \mathcal{D} \ 	ext{に} \ 	ext{L}_x(y_1, \dots, y_n)(z_1, \dots, z_m) = e_1' \ 	ext{を加え、}
                                                                    make\_closure \ x = (\mathtt{L}_x, (z_1, \ldots, z_m)) in e_2'を返す
                                                                          ただし e'_1 = C_s(e_1), e'_2 = C_s(e_2),
                                                                          FV(e'_1) \setminus \{y_1, \dots, y_n\} \neq \emptyset,
                                                                          FV(e_1') \setminus \{x, y_1, \dots, y_n\} = \{z_1, \dots, z_m\} の場合
       C_s(x y_1 \ldots y_n)
                                                             = apply\_closure(x, y_1, \dots, y_n) x \notin s の場合
       C_s(x y_1 \ldots y_n)
                                                             = apply\_direct(L_x, y_1, \dots, y_n)
                                                                                                                        x \in s の場合
          図 15: やや賢い Closure 変換 C_s(e)。 s は自由変数がないとわかっている関数の名前の集合。
```

An improved but not so smart enough closure conversion. s is a set of names of functions that are known to contain no free variables in their definitions.

```
C: S.t \rightarrow \texttt{KNormal.t} \rightarrow \texttt{Closure.t}
     \mathcal{C}_s(	ext{let rec } x \ y_1 \ \dots \ y_n = e_1 \ 	ext{in} \ e_2) \ = \ \mathcal{D} \ 	ext{に} \ 	ext{L}_x(y_1, \dots, y_n)() = e_1' \ 	ext{を加え、}
                                                                   make\_closure \ x = (L_x, ()) \ in \ e_2'を返す
                                                                          ただし e'_1 = C_{s'}(e_1), e'_2 = C_{s'}(e_2), s' = s \cup \{x\},
                                                                          FV(e_1')\setminus\{y_1,\ldots,y_n\}=\emptyset かつ x\in FV(e_2') の場合
     C_s(let rec x y_1 \ldots y_n = e_1 in e_2) = \mathcal{D} \ \mathtt{KL}_x(y_1, \ldots, y_n)() = e_1' \ \mathtt{を加え}, e_2' \mathtt{を返す}
                                                                          ただし e'_1 = C_{s'}(e_1), e'_2 = C_{s'}(e_2), s' = s \cup \{x\},
                                                                          FV(e_1')\setminus\{y_1,\ldots,y_n\}=\emptyset かつ x\not\in FV(e_2') の場合
     \mathcal{C}_s(	ext{let rec } x \; y_1 \; \ldots \; y_n = e_1 \; 	ext{in} \; e_2) \;\; = \;\; \mathcal{D} \; に \; \mathsf{L}_x(y_1,\ldots,y_n)(z_1,\ldots,z_m) = e_1' \; を加え、
                                                                   make\_closure \ x = (L_x, (z_1, \ldots, z_m)) in e_2'を返す
                                                                          ただし e'_1 = C_s(e_1), e'_2 = C_s(e_2),
                                                                          FV(e'_1) \setminus \{y_1, \dots, y_n\} \neq \emptyset,
                                                                          FV(e'_1) \setminus \{x, y_1, \dots, y_n\} = \{z_1, \dots, z_m\} の場合
     C_s(x y_1 \ldots y_n)
                                                             = apply\_closure(x, y_1, \dots, y_n)
                                                                                                                                 x \notin s の場合
     C_s(x y_1 \ldots y_n)
                                                             = apply\_direct(L_x, y_1, \dots, y_n)
                                                                                                                                 x \in s の場合
                                                 図 16: もっと賢い Closure 変換 C_s(e)
```

Smarter closure conversion.

```
P ::=
 (\{D_1,\ldots,D_n\},E)
D ::=
 \mathtt{L}_x(y_1,\ldots,y_n)=E
                           命令の列
E ::=
                           代入
 x \leftarrow e; E
                           返値
  e
                           式
                           即値
  c
                           ラベル
  L_x
                           算術演算
  op(x_1,\ldots,x_n)
  if x=y then E_1 else E_2 比較&分岐
  if x \leq y then E_1 else E_2 比較&分岐
                           mov 命令
                          クロージャを用いた関数呼び出し
  apply\_closure(x, y_1, \dots, y_n)
                           クロージャを用いない関数呼び出し
  apply\_direct(L_x, y_1, \ldots, y_n)
                           ロード
  x.(y)
                           ストア
  x.(y) \leftarrow z
                           変数xの値をスタック位置yに退避する
  save(x, y)
                           スタック位置 y から値を復元する
  \mathtt{restore}(y)
                 図 17: 仮想マシンコードの構文
```

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```
\mathcal{V}: \mathtt{Closure.prog} 	o \mathtt{SparcAsm.prog}
                                                                        = (\{\mathcal{V}(D_1), \dots, \mathcal{V}(D_n)\}, \mathcal{V}(e))
 \mathcal{V}((\{D_1,\ldots,D_n\},e))
 \mathcal{V}: \mathtt{Closure.fundef} 	o \mathtt{SparcAsm.fundef}
                                                                        = L_x(y_1, \ldots, y_n) = z_1 \leftarrow R_0.(4); \ldots; z_n \leftarrow R_0.(4n); \mathcal{V}(e)
 \mathcal{V}(\mathsf{L}_x(y_1,\ldots,y_n)(z_1,\ldots,z_n)=e)
 \mathcal{V}: \mathtt{Closure.t} 	o \mathtt{SparcAsm.t}
 \mathcal{V}(c)
                                                                        = c
 \mathcal{V}(op(x_1,\ldots,x_n))
                                                                        = op(x_1,\ldots,x_n)
 \mathcal{V}(\text{if } x = y \text{ then } e_1 \text{ else } e_2)
                                                                        = if x = y then \mathcal{V}(e_1) else \mathcal{V}(e_2)
 V(\text{if } x \leq y \text{ then } e_1 \text{ else } e_2)
                                                                        = if x \leq y then \mathcal{V}(e_1) else \mathcal{V}(e_2)
 \mathcal{V}(\text{let } x = e_1 \text{ in } e_2)
                                                                        = x \leftarrow \mathcal{V}(e_1); \mathcal{V}(e_2)
 \mathcal{V}(x)
 \mathcal{V}(\textit{make\_closure}\ x = (\mathtt{L}_x, (y_1, \ldots, y_n))\ \mathsf{in}\ e) \ = \ x \leftarrow \mathtt{R_{hp}}; \mathtt{R_{hp}} \leftarrow \mathtt{R_{hp}} + 4(n+1); z \leftarrow \mathtt{L}_x; x.(0) \leftarrow z;
                                                                               x.(4) \leftarrow y_1; \dots; x.(4n) \leftarrow y_n; \mathcal{V}(e)
 \mathcal{V}(apply\_closure(x, y_1, \dots, y_n))
                                                                        = apply\_closure(x, y_1, \dots, y_n)
 \mathcal{V}(apply\_direct(L_x, y_1, \dots, y_n))
                                                                        = apply\_direct(L_x, y_1, \dots, y_n)
 \mathcal{V}((x_1,\ldots,x_n))
                                                                        = y \leftarrow R_{hp}; R_{hp} \leftarrow R_{hp} + 4n;
                                                                               y.(0) \leftarrow x_1; \dots; y.(4(n-1)) \leftarrow x_n; y
 \mathcal{V}(\text{let }(x_1,\ldots,x_n)=y \text{ in } e)
                                                                        x_{i_1} \leftarrow y.(4(i_1-1)); \dots; x_{i_m} \leftarrow y.(4(i_m-1)); \mathcal{V}(e)
 \mathcal{V}(x.(y))
                                                                        = y' \leftarrow 4 \times y; x.(y')
 \mathcal{V}(x.(y) \leftarrow z)
                                                                        = y' \leftarrow 4 \times y; x.(y') \leftarrow z
図 18: 仮想マシンコード生成 \mathcal{V}(P), \mathcal{V}(D) および \mathcal{V}(e)。右辺に出現して左辺に出現しない変数は fresh
とする。R_{hp} はヒープポインタ(専用レジスタ)。e_1; e_2 はダミーの変数 x について x \leftarrow e_1; e_2 の略記。
```

 $x \leftarrow E_1; E_2$ は、 $E_1 = (x_1 \leftarrow e_1; \dots; x_n \leftarrow e_n; e)$ として、 $x_1 \leftarrow e_1; \dots; x_n \leftarrow e_n; x \leftarrow e; E_2$ の略記。

```
FV: \mathtt{S.t} 	o \mathtt{SparcAsm.t} 	o \mathtt{S.t}
                                           FV_s(x \leftarrow e; E)
FV_s(e)
                                           = FV_s(e)
FV: \mathtt{S.t} 	o \mathtt{SparcAsm.exp} 	o \mathtt{S.t}
FV_s(c)
                                           = s
FV_s(L_x)
FV_s(op(x_1,\ldots,x_n))
                                         = \{x_1, \dots, x_n\} \cup s
FV_s(\text{if } x = y \text{ then } E_1 \text{ else } E_2) = \{x, y\} \cup FV_s(E_1) \cup FV_s(E_2)
FV_s(\text{if } x \leq y \text{ then } E_1 \text{ else } E_2) = \{x,y\} \cup FV_s(E_1) \cup FV_s(E_2)
                                          = \{x\} \cup s
FV_s(apply\_closure(x, y_1, \dots, y_n)) = \{x, y_1, \dots, y_n\} \cup s
FV_s(apply\_direct(L_x, y_1, \dots, y_n)) = \{y_1, \dots, y_n\} \cup s
FV_s(x.(y))
                                          = \{x, y\} \cup s
FV_s(x.(y) \leftarrow z)
                                          = \{x, y, z\} \cup s
FV_s(\mathtt{save}(x,y))
                                          = \{x\} \cup s
FV_s(\mathtt{restore}(y))
```

図 19: 命令の列 E および式 e において生きている変数の集合 $FV_s(E)$ および $FV_s(e)$ 。s は E や e の後で使われる変数の集合。以後の FV(E) は $FV_\emptyset(E)$ の略記。

```
\mathcal{R}: \mathtt{SparcAsm.prog} \to \mathtt{SparcAsm.prog}
\mathcal{R}((\{D_1,\ldots,D_n\},E))
                                                               = (\{\mathcal{R}(D_1), \dots, \mathcal{R}(D_n)\}, \mathcal{R}_{\emptyset}(E, x, ()))
                                                                                                                                                         x はダミーの fresh な変数
\mathcal{R}: \mathtt{SparcAsm.fundef} \to \mathtt{SparcAsm.fundef}
\mathcal{R}(\mathsf{L}_x(y_1,\ldots,y_n)=E)
                                                               = L_x(R_1, \ldots, R_n) = \mathcal{R}_{x \mapsto R_0, y_1 \mapsto R_1, \ldots, y_n \mapsto R_n}(E, R_0, R_0)
\mathcal{R}: \mathtt{Id.t} \ \mathtt{M.t} \rightarrow \mathtt{SparcAsm.t} \times \mathtt{Id.t} \times \mathtt{SparcAsm.t} \rightarrow \mathtt{SparcAsm.t} \times \mathtt{Id.t} \ \mathtt{M.t}
\mathcal{R}_{\varepsilon}((x \leftarrow e; E), z_{\texttt{dest}}, E_{\texttt{cont}}) \ = \ E'_{\texttt{cont}} = (z_{\texttt{dest}} \leftarrow E; E_{\texttt{cont}}),
                                                                        \mathcal{R}_{\varepsilon}(e,x,E'_{\mathtt{cont}}) = (E',\varepsilon'),
                                                                        r \notin \{ \varepsilon'(y) \mid y \in FV(E'_{cont}) \},
                                                                        \mathcal{R}_{\varepsilon',x\mapsto r}(E,z_{\mathtt{dest}},E_{\mathtt{cont}})=(E'',\varepsilon'') 

 \tau\tau
                                                                        ((r \leftarrow E'; E''), \varepsilon'')
                                                                                                                                                                  x がレジスタでない場合
\mathcal{R}_{\varepsilon}((r \leftarrow e; E), z_{\mathtt{dest}}, E_{\mathtt{cont}}) = E'_{\mathtt{cont}} = (z_{\mathtt{dest}} \leftarrow E; E_{\mathtt{cont}}),
                                                                        \mathcal{R}_{\varepsilon}(e, r, E'_{\mathtt{cont}}) = (E', \varepsilon'),
                                                                        \mathcal{R}_{\varepsilon'}(E,z_{\mathtt{dest}},E_{\mathtt{cont}}) = (E'',\varepsilon'') \ \texttt{\& LT}
                                                                        ((r \leftarrow E'; E''), \varepsilon'')
                                                               = \mathcal{R}_{\varepsilon}(e, x, E_{\mathtt{cont}})
                                                                                                                                                                                              (次図参照)
\mathcal{R}_{\varepsilon}(e, x, E_{\mathtt{cont}})
```

図 20: 単純なレジスタ割り当て $\mathcal{R}(P)$, $\mathcal{R}(D)$ および $\mathcal{R}_{\varepsilon}(E, z_{\mathsf{dest}}, E_{\mathsf{cont}})$ 。 ε は変数からレジスタへの写像、 z_{dest} は E の結果をセットする変数、 E_{cont} は E の後に実行される命令の列。 $\mathcal{R}_{\varepsilon}(E, x, E_{\mathsf{cont}})$ の返り値はレジスタ割り当てされた命令の列 E' と、E の後のレジスタ割り当てを表す写像 ε' の組。[ファイル regAlloc.notarget-nospill.ml 参照]

```
\mathcal{R}: \mathtt{Id.t} \ \mathtt{M.t} \rightarrow \mathtt{SparcAsm.exp} \times \mathtt{Id.t} \times \mathtt{SparcAsm.t} \rightarrow \mathtt{SparcAsm.t} \times \mathtt{Id.t} \ \mathtt{M.t}
  \mathcal{R}_{\varepsilon}(c, z_{\mathtt{dest}}, E_{\mathtt{cont}})
                                                                                                 = (c, \varepsilon)
  \mathcal{R}_{\varepsilon}(\mathsf{L}_x, z_{\mathtt{dest}}, E_{\mathtt{cont}})
                                                                                                = (L_x, \varepsilon)
  \mathcal{R}_{\varepsilon}(op(x_1,\ldots,x_n),z_{\mathtt{dest}},E_{\mathtt{cont}})
                                                                                                = (op(\varepsilon(x_1), \ldots, \varepsilon(x_n)), \varepsilon)
  \mathcal{R}_{\varepsilon}(\text{if }x=y \text{ then } E_1 \text{ else } E_2, z_{\texttt{dest}}, E_{\texttt{cont}}) \quad = \quad \mathcal{R}_{\varepsilon}(E_1, z_{\texttt{dest}}, E_{\texttt{cont}}) = (E_1', \varepsilon_1),
                                                                                                         \mathcal{R}_{\varepsilon}(E_2, z_{\mathtt{dest}}, E_{\mathtt{cont}}) = (E'_2, \varepsilon_2),
                                                                                                         \varepsilon' = \{ z \mapsto r \mid \varepsilon_1(z) = \varepsilon_2(z) = r \},
                                                                                                         \{z_1,\ldots,z_n\}=
                                                                                                                   (\mathit{FV}(E_{\mathtt{cont}}) \setminus \{z_{\mathtt{dest}}\} \setminus \mathit{dom}(\varepsilon')) \cap \mathit{dom}(\varepsilon) \,\, \xi \,\, \mathsf{LT}
                                                                                                         ((\mathtt{save}(\varepsilon(z_1), z_1); \ldots; \mathtt{save}(\varepsilon(z_n), z_n);
                                                                                                            if \varepsilon(x) \leq \varepsilon(y) then E_1' else E_2', \varepsilon')
  \mathcal{R}_{\varepsilon}(if x \leq y then E_1 else E_2, z_{\mathtt{dest}}, E_{\mathtt{cont}}) = 同様
  \mathcal{R}_{\varepsilon}(x, z_{\mathtt{dest}}, E_{\mathtt{cont}})
                                                                                                = (\varepsilon(x), \varepsilon)
  ((\mathtt{save}(\varepsilon(z_1), z_1); \dots; \mathtt{save}(\varepsilon(z_n), z_n);
                                                                                                             apply\_closure(\varepsilon(x), \varepsilon(y_1), \ldots, \varepsilon(y_n))), \emptyset)
  \mathcal{R}_{\varepsilon}(apply\_direct(\mathtt{L}_x,y_1,\ldots,y_n),z_{\mathtt{dest}},E_{\mathtt{cont}})
                                                                                                = 同様
  \mathcal{R}_{\varepsilon}(x.(y), z_{\mathtt{dest}}, E_{\mathtt{cont}})
                                                                                                = (\varepsilon(x).(\varepsilon(y)), \varepsilon)
  \mathcal{R}_{\varepsilon}(x.(y) \leftarrow z, z_{\texttt{dest}}, E_{\texttt{cont}})
                                                                                                = (\varepsilon(x).(\varepsilon(y)) \leftarrow \varepsilon(z), \varepsilon)
  \mathcal{R}_{\varepsilon}(\mathtt{save}(x,y),z_{\mathtt{dest}},E_{\mathtt{cont}})
                                                                                                = (save(\varepsilon(x), y), \varepsilon)
  \mathcal{R}_{\varepsilon}(\mathtt{restore}(y), z_{\mathtt{dest}}, E_{\mathtt{cont}})
                                                                                                = (restore(y), \varepsilon)
図 21: 単純なレジスタ割り当て \mathcal{R}_{\varepsilon}(e, z_{\mathsf{dest}}, E_{\mathsf{cont}})。 \mathcal{R}_{\varepsilon}(e) の右辺で変数 x のレジスタ \varepsilon(x) が定義されて
いない場合は、\mathcal{R}_{\varepsilon}(e) = \mathcal{R}_{\varepsilon}(x \leftarrow \mathtt{restore}(x); e) とする。ただしレジスタ r については \varepsilon(r) = r とする。
[ファイル regAlloc.notarget-nospill.ml 参照]
```

```
\mathcal{T}: \mathtt{Id.t} 	o \mathtt{SparcAsm.t} \times \mathtt{Id.t} 	o \mathtt{bool} \times \mathtt{S.t}
                                                                \mathcal{T}_x((y \leftarrow e; E), z_{\texttt{dest}})
                                                                       そうでなければ T_x(E, z_{dest}) = (c_2, s_2) として (c_2, s_1 \cup s_2)
                                                                = \mathcal{T}_x(e, z_{	exttt{dest}})
\mathcal{T}_x(e, z_{\mathtt{dest}})
\mathcal{T}: \mathtt{Id.t} \rightarrow \mathtt{SparcAsm.exp} \times \mathtt{Id.t} \rightarrow \mathtt{bool} \times \mathtt{S.t}
\mathcal{T}_x(x, z_{	exttt{dest}})
                                                                = (false, \{z_{dest}\})
\mathcal{T}_x(\text{if } y = z \text{ then } E_1 \text{ else } E_2, z_{\text{dest}}) = \mathcal{T}_x(E_1, z_{\text{dest}}) = (c_1, s_1),
                                                                      (c_1 \wedge c_2, s_1 \cup s_2)
                                                               = 同上
T_x(\text{if } y \leq z \text{ then } E_1 \text{ else } E_2, z_{\texttt{dest}})
\mathcal{T}_x(apply\_closure(y_0, y_1, \dots, y_n), z_{\texttt{dest}}) = (true, \{R_i \mid x = y_i\})
T_x(apply\_direct(L_y, y_1, \dots, y_n), z_{dest}) = \exists \bot
                                                                                                                                         それ以外の場合
                                                                = (false, \emptyset)
\mathcal{T}_x(e, z_{\mathtt{dest}})
```

図 22: 変数 x に割り当てるレジスタ r を選ぶときに使う targeting $T_x(E, z_{\mathsf{dest}})$ および $T_x(e, z_{\mathsf{dest}})$ 。E や e で関数呼び出しがあったかどうかを表す論理値 e と、e を割り当てると良いレジスタの集合 e の組を返す。前々図の「e がレジスタでない場合」において、e とする。[ファイル regAlloc.target-nospill.ml 参照]

```
\mathcal{R}: \mathtt{Id.t} \ \mathtt{M.t} 	o \mathtt{SparcAsm.t} 	imes \mathtt{Id.t} 	imes \mathtt{SparcAsm.t} 	o \mathtt{SparcAsm.t} 	imes \mathtt{Id.t} \ \mathtt{M.t} \mathcal{R}_{\varepsilon}((x \leftarrow e; E), z_{\mathtt{dest}}, E_{\mathtt{cont}}) \ = \ E'_{\mathtt{cont}} = (z_{\mathtt{dest}} \leftarrow E; E_{\mathtt{cont}}), \\ \mathcal{R}_{\varepsilon}(e, x, E'_{\mathtt{cont}}) = (E', \varepsilon'), \\ y \in FV(E'_{\mathtt{cont}}), \\ \mathcal{R}_{\varepsilon' \setminus \{y \mapsto \varepsilon'(y)\}, x \mapsto \varepsilon'(y)}(E, z_{\mathtt{dest}}, E_{\mathtt{cont}}) = (E'', \varepsilon'') \ \succeq \mathtt{LT} \\ \left\{ \ ((\mathtt{save}(\varepsilon(y), y); \varepsilon'(y) \leftarrow E'; E''), \varepsilon'') \quad y \in dom(\varepsilon) \ \mathcal{O} \ \succeq \ \succeq \ x \ \mathcal{D}^{\varepsilon} \cup \mathcal{D}^{\varepsilon} \times \mathcal{
```

図 23: spilling をするレジスタ割り当て $\mathcal{R}_{\varepsilon}(E, z_{\mathtt{dest}}, E_{\mathtt{cont}})$ [ファイル regAlloc.target-latespill.ml 参照]

```
\mathcal{S}: \mathtt{SparcAsm.prog} \to \mathtt{string}
    \mathcal{S}((\{D_1,\dots,D_n\},E)) \quad = \quad \mathtt{.section} \ \mathtt{".text"}
                                                   \mathcal{S}(D_1)
                                                   . . .
                                                   S(D_n)
                                                   .global min_caml_start
                                                   min_caml_start:
                                                   save %sp, -112, %sp
                                                   \mathcal{S}(E, \%g0)
                                                   ret
                                                   restore
    \mathcal{S}: \texttt{SparcAsm.fundef} \to \texttt{string}
    \mathcal{S}(L_x(y_1,\ldots,y_n)=E) = x:
                                                   \mathcal{S}(E,\mathtt{R}_0)
                                                   retl
                                                   nop
    \mathcal{S}: \texttt{SparcAsm.t} \times \texttt{Id.t} \rightarrow \texttt{string}
    \mathcal{S}((x \leftarrow e; E), z_{\texttt{dest}})
                                            = \mathcal{S}(e, x)
                                                   \mathcal{S}(E, z_{	exttt{dest}})
    \mathcal{S}(e,z_{\texttt{dest}})
                                            = \mathcal{S}(e, z_{\mathtt{dest}})
図 24: 単純なアセンブリ生成 \mathcal{S}(P),\,\mathcal{S}(D) および \mathcal{S}(E,z_{\mathtt{dest}})
```

```
\mathcal{S}: \mathtt{SparcAsm.exp} \times \mathtt{Id.t} \rightarrow \mathtt{string}
                \mathcal{S}(c, z_{\mathtt{dest}})
                                                                                                    \mathtt{set}\ c, z_{\mathtt{dest}}
                \mathcal{S}(L_x, z_{\mathtt{dest}})
                                                                                                    \operatorname{set} L_x, z_{\operatorname{dest}}
                S(op(x_1,\ldots,x_n),z_{\tt dest})
                                                                                                    op \ x_1, \ldots, x_n, z_{\texttt{dest}}
                \mathcal{S}(	ext{if } x=y 	ext{ then } E_1 	ext{ else } E_2, z_{	ext{dest}})
                                                                                                 cmp \ x, y
                                                                                                    bne b_1
                                                                                                    nop
                                                                                                    \mathcal{S}(E_1, z_{	t dest})
                                                                                                    b b_2
                                                                                                    nop
                                                                                                    b_1:
                                                                                                    \mathcal{S}(E_2,z_{\mathtt{dest}})
                                                                                                    b_2:
                \mathcal{S}(	ext{if } x \leq y 	ext{ then } E_1 	ext{ else } E_2, z_{	ext{dest}})
                                                                                                  同様
                \mathcal{S}(x, z_{\mathtt{dest}})
                                                                                                    \mathtt{mov}\ x, z_{\mathtt{dest}}
                \mathcal{S}(apply\_closure(x, y_1, \dots, y_n), z_{\texttt{dest}})
                                                                                                    shuffle((x, y_1, \ldots, y_n), (R_0, R_1, \ldots, R_n))
                                                                                                    st R_{ra}, [R_{st} + 4\#\varepsilon]
                                                                                                    ld[R_0], R_{n+1}
                                                                                                    call R_{n+1}
                                                                                                    add \mathbf{R}_{\mathrm{st}}, 4(\#\varepsilon+1), \mathbf{R}_{\mathrm{st}} ! delay\ slot
                                                                                                    \operatorname{sub} R_{\operatorname{st}}, 4(\#\varepsilon+1), R_{\operatorname{st}}
                                                                                                    ld [R_{st} + 4\#\varepsilon], R_{ra}
                                                                                                    mov R_0, z_{dest}
                S(apply\_direct(L_x, y_1, \dots, y_n), z_{dest})
                                                                                            = shuffle((y_1, \ldots, y_n), (R_1, \ldots, R_n))
                                                                                                    \mathtt{st}\ \mathtt{R}_{\mathtt{ra}}, [\mathtt{R}_{\mathtt{st}} + 4\#\varepsilon]
                                                                                                    add R_{\rm st}, 4(\#\varepsilon+1), R_{\rm st} ! delay\ slot
                                                                                                    \operatorname{sub} R_{\operatorname{st}}, 4(\#\varepsilon+1), R_{\operatorname{st}}
                                                                                                    ld [R_{st} + 4\#\varepsilon], R_{ra}
                                                                                                    \mathtt{mov}\ \mathtt{R}_0, z_{\mathtt{dest}}
                S(x.(y), z_{\text{dest}})
                                                                                            = 1d [x+y], z_{\text{dest}}
                S(x.(y) \leftarrow z, z_{\texttt{dest}})
                                                                                            = st z, [x+y]
                                                                                            = もしy \not\in dom(\varepsilon)なら\varepsilonにy \mapsto 4\#\varepsilonを加えて
                \mathcal{S}(\mathtt{save}(x,y),z_{\mathtt{dest}})
                                                                                                    st x, [\mathbf{R}_{\mathsf{st}} + \varepsilon(y)]
                \mathcal{S}(\mathtt{restore}(y), z_{\mathtt{dest}})
                                                                                            = 1d [R_{st} + \varepsilon(y)], z_{dest}
図 25: 単純なアセンブリ生成 S(e, z_{\text{dest}})。\varepsilon はスタック位置を記憶するグローバル変数。\#\varepsilon は \varepsilon の要素の
```

図 25: 単純なアセンブリ生成 $S(e, z_{\sf dest})$ 。 ε はスタック位置を記憶するグローバル変数。 $\#\varepsilon$ は ε の要素の個数。 $\mathit{shuffle}((x_1, \ldots, x_n), (r_1, \ldots, r_n))$ は x_1, \ldots, x_n を r_1, \ldots, r_n に適切な順序で移動する命令。

```
\mathcal{S}: \mathtt{S.t} \rightarrow \mathtt{SparcAsm.t} \times \mathtt{Id.t} \rightarrow \mathtt{S.t} \times \mathtt{string}
S_s((x \leftarrow e; E), z_{\texttt{dest}})
                                                            = \mathcal{S}_s(e, x) = (s', S),
                                                                  (s'', SS')
\mathcal{S}_s(e, z_{	exttt{dest}})
                                                            = S_s(e, z_{\tt dest})
\mathcal{S}: \mathtt{S.t} \rightarrow \mathtt{SparcAsm.exp} \times \mathtt{Id.t} \rightarrow \mathtt{S.t} \times \mathtt{string}
S_s(\text{if } x = y \text{ then } E_1 \text{ else } E_2, z_{\text{dest}}) = S_s(E_1, z_{\text{dest}}) = (s_1, S_1),
                                                                  (s_1 \cap s_2,
                                                                    cmp \ x, y
                                                                    bne b_1
                                                                    nop
                                                                    S_1
                                                                    b b_2
                                                                    nop
                                                                    b_1:
                                                                    S_2
                                                                   b_2:)
S_s(if x \leq y then E_1 else E_2, z_{\text{dest}}) = 同様
                                                                                                                    y \in s の場合
S_s(\mathtt{save}(x,y), z_{\mathtt{dest}})
                                                            = (s, nop)
S_s(\mathtt{save}(x,y),z_{\mathtt{dest}})
                                                            = もしy \notin dom(\varepsilon)なら\varepsilonにy \mapsto 4\#\varepsilonを加えて
                                                                  (s \cup \{y\}, \mathtt{st}\ x, [\mathtt{R}_{\mathtt{st}} + \varepsilon(y)])
                                                                                                                    y \notin s の場合
S_s(e, z_{\tt dest})
                                                            = (s,以前と同様)
                                                                                                              上述以外の場合
```

図 26: 無駄な save を省略するアセンブリ生成 $S_s(E, z_{\tt dest})$ および $S_s(e, z_{\tt dest})$ 。s はすでに save された変数の名前の集合。以前の $S(E, z_{\tt dest})$ は $S_\emptyset(E, z_{\tt dest}) = (s, S)$ として S の略記とする。

```
\mathcal{S}: \texttt{SparcAsm.fundef} \to \texttt{string}
                                                                                                                                                          \mathcal{S}(\mathsf{L}_x(y_1,\ldots,y_n)=E)
                                                                                                                                                                         x:
                                                                                                                                                                         S
\mathcal{S}: \mathtt{S.t} \rightarrow \mathtt{SparcAsm.exp} \times \mathtt{Id.t} \rightarrow \mathtt{S.t} \times \mathtt{string}
\mathcal{S}_s(\text{if } x=y \text{ then } E_1 \text{ else } E_2, \text{tail}) \ = \ \mathcal{S}_s(E_1, \text{tail}) = (s_1, S_1),
                                                                                                                                                                         (\emptyset,
                                                                                                                                                                            cmp \ x, y
                                                                                                                                                                            \mathtt{bne}\ b
                                                                                                                                                                            nop
                                                                                                                                                                            S_1
                                                                                                                                                                            b:
                                                                                                                                                                            S_2
S_s(\text{if } x \leq y \text{ then } E_1 \text{ else } E_2, \text{tail}) =
                                                                                                                                                                         同様
S_s(apply\_closure(x, y_1, \dots, y_n), \texttt{tail}) =
                                                                                                                                                                        (\emptyset,
                                                                                                                                                                            shuffle((x, y_1, \ldots, y_n), (R_0, R_1, \ldots, R_n))
                                                                                                                                                                            ld[R_0], R_{n+1}
                                                                                                                                                                            {\tt jmp}\ {\tt R}_{n+1}
                                                                                                                                                                            nop)
S_s(apply\_direct(L_x, y_1, \dots, y_n), tail) =
                                                                                                                                                                             shuffle((y_1,\ldots,y_n),(\mathtt{R}_1,\ldots,\mathtt{R}_n))
                                                                                                                                                                            \mathbf{b} \ x
                                                                                                                                                                            nop)
                                                                                                                                                         = S_s(e, \mathbf{R}_0) = (s', S) \                   <math>     <math>     <math>     <math>     <math>     <math>     <math>   <math>     <math>     <math>     <math>   <math>     <math>       <math>     <math>     <math>       <math>     <math>     <math>       <math>     <math>     <math>     <math>     <math>         <math>     <math>     <math>     <math>       <math>     <math>     <math>       <math>     <math>       <math>     <math>         <math>     <math>       <math>     <math>     <math>         <math>     <math>       <math>       <math>       <math>       <math>     <math>       <math>       <math>       <math>     <math>       <math>       <math>       <math>       <math>     <math>     <math>       <math>       <math>       <math>       <math>         <math>             <math>           <math>         <math>         <math>             <math>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            
\mathcal{S}_s(e, \mathtt{tail})
                                                                                                                                                                         (\emptyset,
                                                                                                                                                                            S
                                                                                                                                                                            retl
                                                                                                                                                                                                                                                                     上述以外の場合
                                                                                                                                                                            nop)
```

図 27: 末尾呼び出し最適化をするアセンブリ生成 $S_s(D)$ および $S_s(e, z_{\texttt{dest}})$ 。 $z_{\texttt{dest}} = \texttt{tail}$ の場合が末尾。