

# **EX8029 Datasheet**

eSP870 Camera Module with patterned IR Illuminator



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# **Revision History**

Rev	Date	Comments
1.0	January 10, 2017	Initial release.



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#### 1 Introduction

This document contains technical information of the dual sensor camera module with Etron eSP870 depth-map camera controller and patterned IR illuminator. The module can provide either or both color video and/or depth-map video streams. eSP870 depth-map controller is compliant to UVC1.1 and USB3.0 standard. Therefore, the module requires no specific drivers and provides high bandwidth for video transmission. The camera module can be integrated into applications involving gesture control, body gaming, and 3D scanning. The camera module is also a demonstration of the eSP870 reference design for its compact size and flexible form factor.



Figure 1. 3cm Baseline Module

Table 1. Key Parameters

Parameter	Description
Controller	eSP870U
IR pattern illuminator wavelength	850nm +/-10 nm
IR pattern illuminator number of features	>10,000
Video Resolution	Please refer to Table 4 on page 8.
Lens	1LS1022G by AOET
Image Sensor	OV9714 by OVT
Power Source	USB bus power (5V/900mA by USB3.0; 5V/500mA by USB2.0)
PC Connection	USB3.0 & USB2.0
PID (Product ID)	0568
VID (Vender ID)	1e4e
Power Source	USB Connector
Power Voltage	+5V
Operating Current With Patterned IR Illuminator	≦350mA
Operating Current Without Patterned IR Illuminator	≦280mA
Suspend Current	≦15mA

#### Note:

Operating current is measured under below criteria.

- 1. Image output is delivered by YUV format at USB3.0.
- 2. Depth-map resolution: VGA at 30fps.



#### 1.1 Pin Information of USB3.0 Connector

Pin assignments and pin descriptions of USB3.0 micro B type connector are listed below.

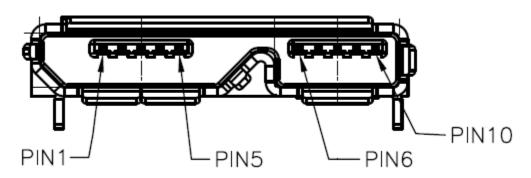


Figure 2. Connector Drawing

Table 2. Pin Descriptions

Pin No.	Signal	Description	Mating Sequence
1	VBUS	Power	Second
2	D-	LIOD differential main	Thind
3	D+	USB differential pair	Third
4	ID(GND)	Slave device ID	Second
5	GND	Ground for signal return	Second
6	StdA_SSRX-	Consultation of the section of the s	
7	StdA_SSR+	SuperSpeed receiver differential pair	
8	GND_DRAIN	Ground for signal return	Last
9	StdA_SST-		
10	StdA_SST+	SuperSpeed receiver differential pair	
Shell	Shield	Connector metal shell	First

### 1.2 Ordering Information

Table 3. Available Part Number

Part Number	Description
eAP87003B	eSP870 Camera Module with patterned IR Illuminator



#### 1.3 Depth Accuracy

Depth accuracy is the minimum difference of distance at which the movement of same target can be distinguished and leads to at least 1 pixel difference of disparity on sensor plane. This is the meaning of the blue trend in the figures below.

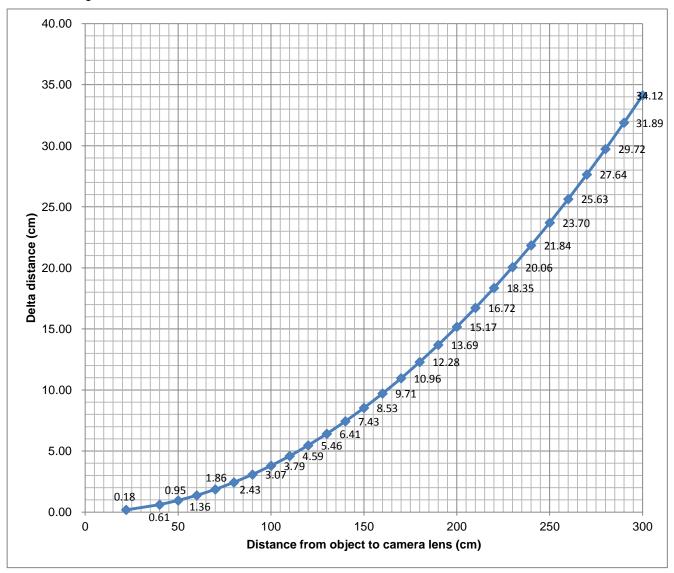


Figure 3. Depth Accuracy Chart of 3cm Baseline (Depth resolution: 640x480)

#### Note:

- 1. Delta Distance means absolute value of the difference between distance of two locations of a measured object while it moves away from or moves forward to the camera module.
- 2. The accuracy shown above is a theoretical calculation based on perfect lighting condition and component specification. It is subject to change and would be downgraded in a real scenario.
- 3. The chart is generated based on below hardware configuration.
  - Lens: 1LS1022G by AOET
  - Sensor: OV9714 by OVT
- 4. Depth resolution of this figure: 640x480



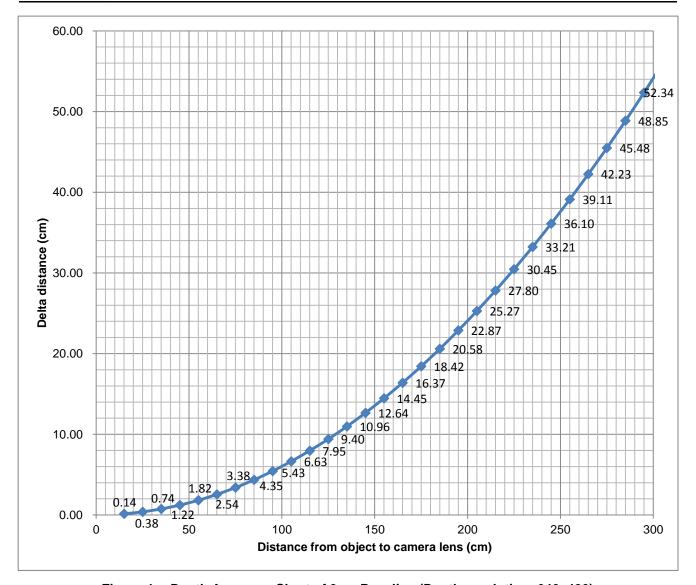


Figure 4. Depth Accuracy Chart of 3cm Baseline (Depth resolution: 640x400)

#### Note:

- 1. Delta Distance means absolute value of the difference between distance of two locations of a measured object while it moves away from or moves forward to the camera module.
- 2. The accuracy shown above is a theoretical calculation based on perfect lighting condition and component specification. It is subject to change and would be downgraded in a real scenario.
- 3. The chart is generated based on below hardware configuration.
  - Lens: 1LS1022G by AOET
  - Sensor: OV9714 by OVT
- 4. Depth resolution of this figure: 640x400



## 2 Video Output

Table 4. Video Output

Table 4. Video Output							
		Interface &	EP1 Color (2D or 3D)		EP2 (Depth-map)		
Mode	Denotation	Compression	Video Resolution	YUV (fps)	Video Resolution	Bitmap Frame Rate	Comment
1	L' + D	USB 3.0	640x400	90/60/30	640x400	90/60/30	
2	L' + D	USB 3.0	640x480	30	640x480	30	[1]
3	L' + R' + D	USB 3.0	1280x400	90/60/30	640x400	90/60/30	Calibration
4	L' + R' + D	USB 3.0	640x240	90/60/30	320x240	90/60/30	[1], Calibration
5	L' + D	USB 3.0	320x240	90/60/30	320x240	90/60/30	[1]
6	L+D	USB 3.0	800x600	30	640x480	30	[1]
7	L+R+D	USB 3.0	1600x600	30	640x480	30	[1]
8	L+R+D	USB 3.0	800x300	90/60/30	320x240	90/60/30	[1]
9	L+R	USB 3.0	2560x720	30	-	-	
10	L+R	USB 3.0	1280x400	90/60/30	-	-	
11	L' + R'	USB 3.0	1280x480	30	-	-	
12	L(R)	USB 3.0	1280x720	60/30	-	-	[1], Default
13	D	USB 3.0	-	-	640x400	90/60/30	
14	D	USB 3.0	-	-	640x480	30	[1]
15	D	USB 3.0	_	-	320x240	90/60/30	[1]
16	L' + D	USB 2.0	640x480	15	640x480	15	[1]
17	L' + D	USB 2.0	640x400	15	640x400	15	
18	L' + D	USB 2.0	320x240	60/30	320x240	60/30	[1]
19	L' + R' + D	USB 2.0	640x240	30	320x240	30	
20	L+D	USB 2.0	800x600	15	640x480	15	[1]
21	L+R+D	USB 2.0	1600x600	5	640x480	5	[1]
22	L+R	USB 2.0	2560x720	5	-	-	
23	L+R	USB 2.0	1280x480	15	-	-	
24	L' + R'	USB 2.0	1280x480	15	-	-	
25	L(R)	USB 2.0	1280x720	10	-	-	Default
26	D	USB 2.0	-	-	640x400	30	
27	D	USB 2.0	-	-	640x480	30	[1]
28	D	USB 2.0	-	-	320x240	90/60/30	[1]
29	L' + D	USB 2.0 / MJPEG	640x480	30	640x480	30	[1]
30	L' + D	USB 2.0 / MJPEG	640x400	30	640x400	30	
31	L' + D	USB 2.0 / MJPEG	320x240	90/60/30	320x240	90/60/30	[1]
32	L' + R' + D	USB 2.0 / MJPEG	640x240	90/60/30	320x240	90/60/30	[1]
33	L+D	USB 2.0 / MJPEG	800x600	30	640x480	30	[1]
34	L+R+D	USB 2.0 / MJPEG	1600x600	30	640x480	30	[1]
35	L+R	USB 2.0 / MJPEG	2560x720	30	-	-	
36	L' + R'	USB 2.0 / MJPEG	1280x480	30	-	-	
37	L(R)	USB 2.0 / MJPEG	1280x720	30	-	-	

<sup>1. [1]</sup> Rectified FOV will be about 20% less after rectification.

<sup>2.</sup> L' means Rectified Left. D means Depth.



## 3 Key Parameters of Image Sensor

Table 5. Key Parameters of OV9714

V. I.			
Vendor	OVT		
Model	OV9714		
Active Array Size	1296 x 812		
	Core	1.5VDC ± 5%	
Power Supply	Analog	2.6 ~ 3.0V	
	I/O	1.7 ~ 3.0V	
	Active	35mA	
Power Requirement	Standby	30uA	
	XSHUTDOWN	5uA	
	Operating Temperature	-30°C to 85°C junction temperature	
Temperature Range	Stable Image Temperature	0°C to 50°C junction temperature	
CRA	28.7°		
Pixel Size	3.0 x 3.0um		
Optical Size	1/4"		
Output format	12-bit RGB RAW		

Note:

These values are subject to change based on real scenarios.



## 4 Key Parameters of Lens

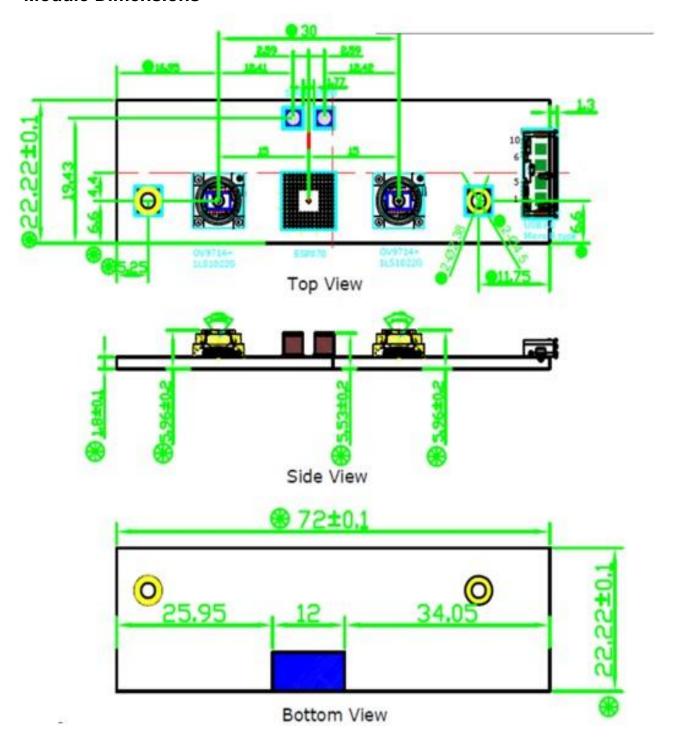
Table 6. Key Parameters of 1LS1022G

Table 6. Key Farameters of TLS1022G		
Vendor	AOET	
Model	1LS1022G	
	Vertical	42.0°
FOV (Field of View)	Horizontal	63.2°
	Diagonal	71.4° ± 3%
FNO	2.8 ± 5%	
Mount Dimension	M6 x P0.35 mm	
TV-Distortion	≦1.5%	
EFL (Effective Focal Length)	3.11mm	
CRA	30°	
Optical Size	1/4"	
	T abs>90%	430nm ~ 630nm
Wavelength (normal cut filter)	T50%	650 ± 10nm
	T abs<3%	695nm ~ 1080nm

Table 7. Spectrum Specification of IR Cute Filter



### **5** Module Dimensions





### 6 Reference Documents

Image IC	Etron eSP870 datasheet revision 2.4 or above	
Sensor OmniVision OV9714 datasheet revision 1.0 or above		
Lens AOTE 1LS1022G datasheet		