

MNTF Mathematics for New Technologies in Finance

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Approximation

Weierstrass

Weierstrass Approximation Theorem

A is dense in $C(\mathcal{X}, \mathbb{R}^m) = \{f_i | f_i \in C_{pw}^0, f_i \in \mathcal{X} \rightarrow \mathbb{R}^m, \mathcal{X} \subset \mathbb{R}^n\}$ if

1. A contains all polynomial functions: $\mathcal{P} \subset A$
 1. A is vector subspace of $C : A \subset C(\mathcal{X}, \mathbb{R}^m)$
 - $f_1(x) + f_2(x) = f_3(x) \quad \forall f_1, f_2 \in A, \exists f_3 \in A$
 - $cf_1(x) = f_2(x) \quad \forall c \in \mathbb{R}, \forall f_1 \in A, \exists f_2 \in A$
 2. A is closed under multiplication : $f_1(x)f_2(x) = f_3(x) \quad \forall f_1, f_2 \in A, \exists f_3 \in A$
 3. A contains constant function : $f(v) = c \quad \forall v \in \mathcal{X}, \exists f \in A$
2. points separation : $f(v) \neq f(w) \quad \forall v \neq w \wedge v, w \in \mathcal{X}$

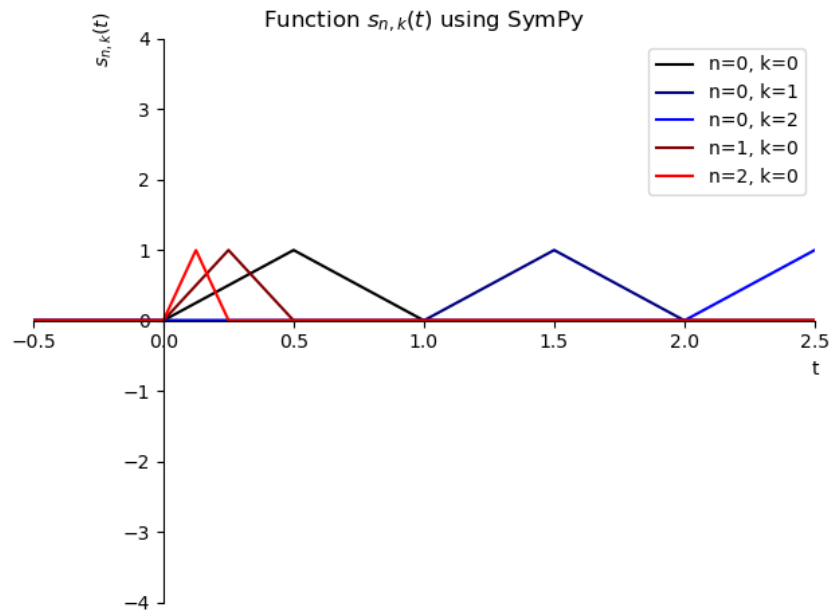
for shallow NN with ReLU

- ☐ contains all polynomial functions
 - ☐ vector space
 - ☐ closed under multiplication
 - ☒ contains constant function
- ☒ points separation

\Rightarrow NN with ReLU is dense in $C(\mathcal{X}, \mathbb{R}^m)$

Faber-Schauder

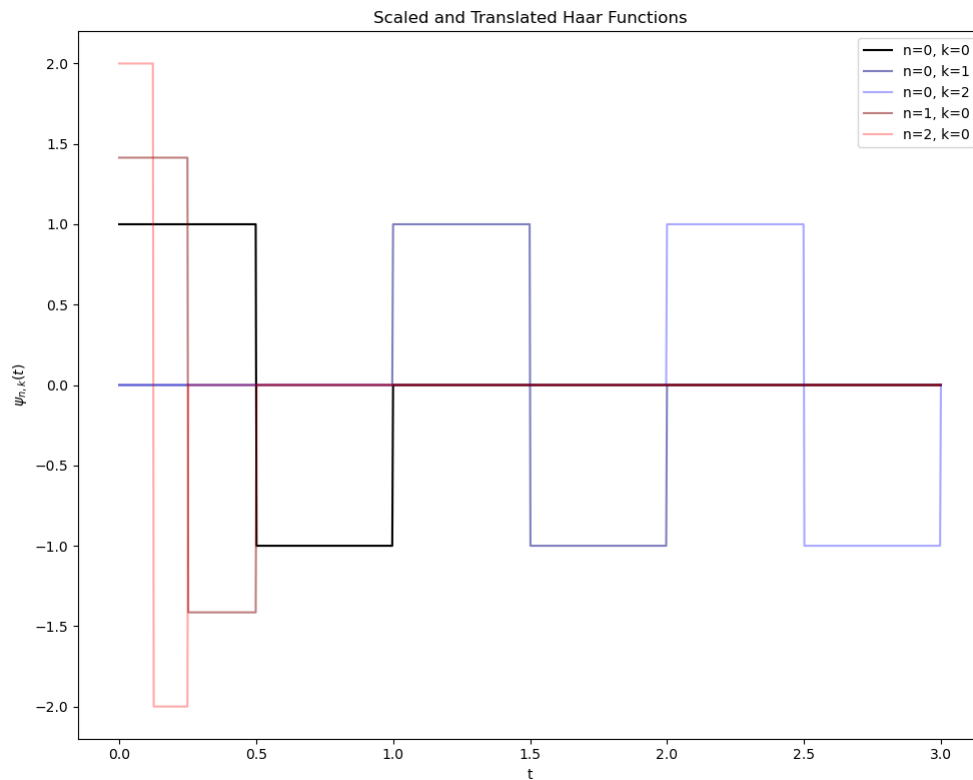
Faber-Schauder basis : $s_{n,k} = 2^{1+\frac{n}{2}} \int_0^t \psi_{n,k}(u) du \quad n, k \in \mathbb{Z}$



$$v = \sum_{n=0}^{\infty} \alpha_n b_n \quad \forall v \in \mathbb{R}, \exists \alpha_n \in \mathbb{R}, \exists b_n \in \{s_{*,*}\}$$

- equivalent to the linear combination of ReLU

Haar function : $\psi_{n,k}(t) = 2^{n/2} \psi(2^n t - k) \quad n, k \in \mathbb{Z} \quad \psi(t) = \begin{cases} 1 & t \in [0, \frac{1}{2}) \\ -1 & t \in [\frac{1}{2}, 1) \\ 0 & \text{otherwise} \end{cases}$



- $\text{supp}(\psi_{n,k}) = [k2^{-n}, (k+1)2^{-n})$
- $\int_{\mathbb{R}} \psi_{n,k}(t) dt = 0$
- $\|\psi_{n,k}\|_{L^2(\mathbb{R})} = 1$
- $\int_{\mathbb{R}} \psi_{n_1,k_1} \psi_{n_2,k_2} dt = \delta_{n_1 n_2} \delta_{k_1 k_2}$

Banach

\mathcal{A} is Banach space if :

1. Cauchy sequence : $\|f_m - f_n\| \leq \epsilon \quad \forall \epsilon > 0, \exists N_\epsilon \in \mathbb{N}, \forall m, n > N_\epsilon$
2. completeness : $\|f - f_m\| \leq \epsilon \quad \forall \epsilon > 0, m \rightarrow \infty$

Signature

for path/curve $X_t \in \mathbb{R}^d$, $X_t = [X^1(t) \quad X^2(t) \quad \dots \quad X^d(t)]^\top$, signature could determine the curve in tree like equivalences

n-th level of signature : $S(X)_{a,b}^{i_1, i_2, \dots, i_n} = \int_a^b \int_a^{t_{n-1}} \dots \int_a^{t_2} dX_{t_1}^{i_1} \dots dX_{t_n}^{i_n} \quad n \leq d$

- $S(X)_{a,b}^{i_1, i_2, \dots, i_n} \in \mathbb{R}^{n^{\otimes d}}$, it's a d dimension tensor with each dimension of span n

signature : $S(X)_{a,b} = (1, S(X)_{a,b}^{i_1}, S(X)_{a,b}^{i_1, i_2}, \dots, S(X)_{a,b}^{i_1, i_2, \dots, i_d})$

- the maximum length of $S(X)_{a,b}$ is $d^0 + d^1 + d^2 + \dots + d^d = \frac{d^{d+1}-1}{d-1}$
- the length of depth M is $d^0 + \dots + d^M = \frac{d^{M+1}-1}{d-1}$

normally we got : X_a^i denotes i -th component at time a of vector of function X

- $S(X)_{a,b}^i = \int_a^b dX = X_b^i - X_a^i$
- $S(X)_{a,b}^{i,j} = \int_a^b \int_a^{t_2} dX_{t_1}^i dX_{t_2}^j = \int_a^b (X_{t_2}^i - X_a^i) dX_{t_2}^j \stackrel{X=\alpha t+\beta}{=} \frac{1}{2} (X_b^i - X_a^i)(X_b^j - X_a^j)$
- $S(X)_{a,b}^{i,j,k} = \int_a^b \int_a^{t_3} \int_a^{t_2} dX_{t_1}^i dX_{t_2}^j dX_{t_3}^k \stackrel{X=\alpha t+\beta}{=} \frac{1}{6} (X_b^i - X_a^i)(X_b^j - X_a^j)(X_b^k - X_a^k)$
- shuffle product rule : $S(X)_{a,b}^I S(X)_{a,b}^J = \sum_{K=\text{shuff}([I_1, \dots, J_1, \dots])} S(X)_{a,b}^K$
 - example : $S(X)_{a,b}^1 S(X)_{a,b}^2 = S(X)_{a,b}^{1,2} + S(X)_{a,b}^{2,1}$

Financial Market

Notation

- S_t^i : i -th asset prices at time t , $S \in \mathbb{R}^{N \times d+1}$, normally S^0 represent bank account
- ϕ_t^i : holdings/strategy in i -th assets at time t
- V_t : value of portfolio at time t , $V_t = \sum_i \phi_t^i S_t^i$

self-financing : $dV(t) = \sum_{i=1}^n \phi^i(t) dS^i(t)$

- $\sum_i \phi_{t+1}^i S_t^i = \sum_i \phi_t^i S_t^i \quad \forall t \in [0, N)$

value process : $V_{t+1} - V_t = \sum_i \phi_t^i (S_{t+1}^i - S_t^i) \quad \forall t \in [0, N)$

martingale : $\mathbb{E}[X_{n+1} | X_1, \dots, X_n] = X_n$

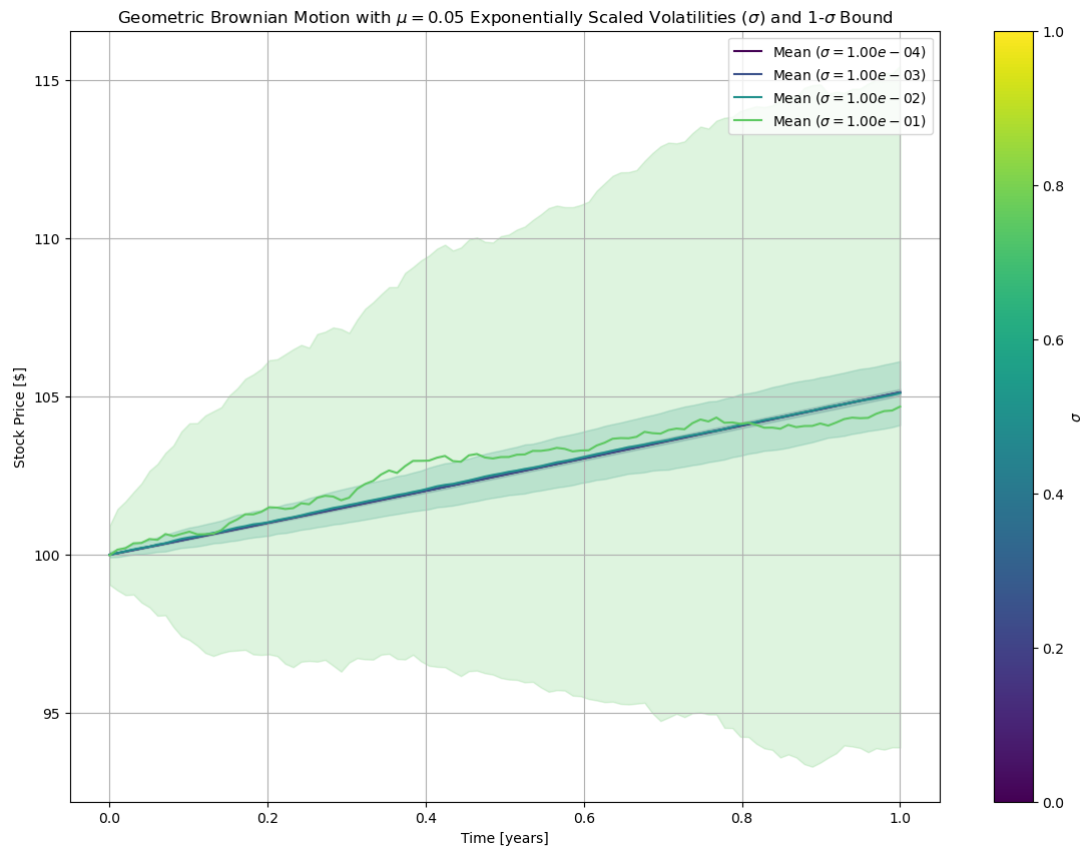
$$\text{arbitrage : } \underbrace{P(V_t \geq 0) = 1}_{\text{no risk of losing money}} \wedge \underbrace{P(V_t \neq 0) > 0}_{\text{portfolio value} > 0} \quad t \in (0, T), \quad \underbrace{V_0 = 0}_{\text{requires no initial value}}$$

Stochastic Differential Equation

Brownian motion/Wiener process : $W_{t+1} - W_t \sim \mathcal{N}(0, 1) \quad W_0 = 0 \rightarrow W_t$

Geometric Brownian motion : $dS_t = \mu S_t dt + \sigma S_t dW_t \Leftrightarrow S_t = S_0 e^{(\mu - \frac{\sigma^2}{2})t + \sigma W_t}$

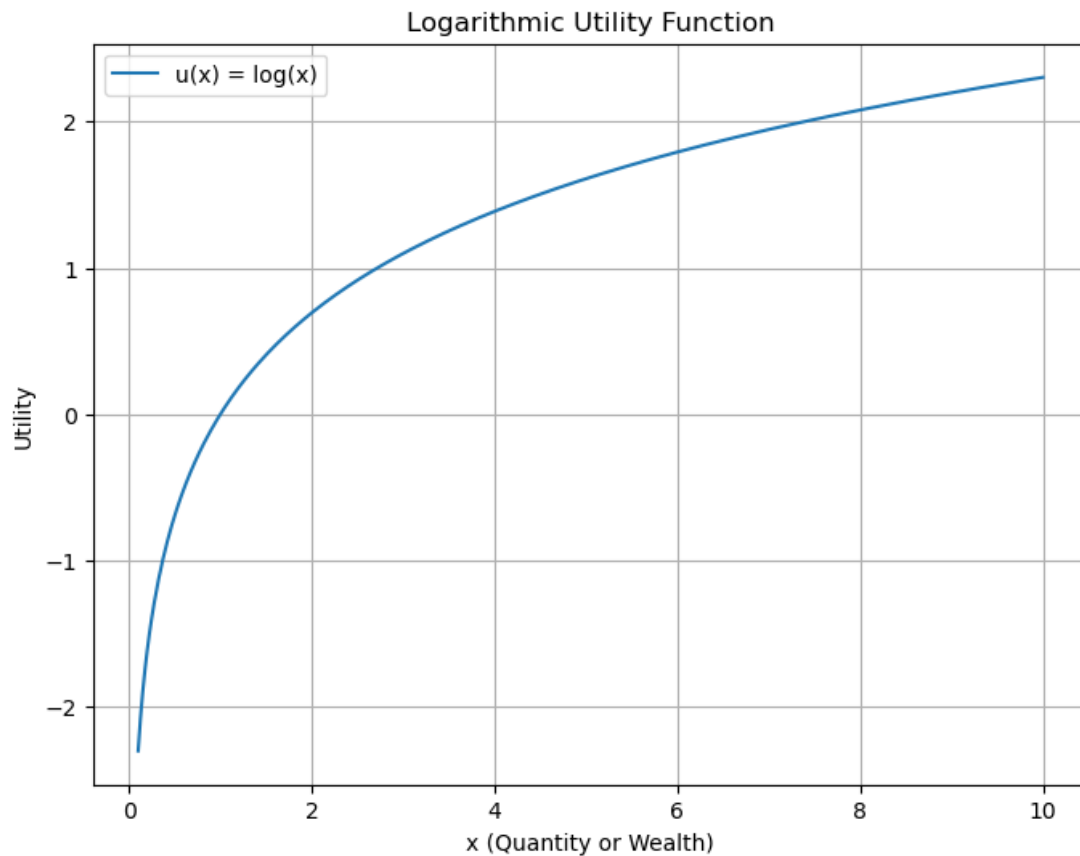
- W_t is brownian motion/wiener process
- μ, σ is the expectation/variance for the GBM



Utility

utility function u : the additional utility or satisfaction from consuming one more unit of a good decreases as more of the good is consumed.

- concave : $f''(x) < 0$
- monotone increase : $f'(x) > 0$



expected utility optimization problem : $\operatorname{argmax}_{\phi_t^i} E[u(V_N)]$

Local Volatility Model : $dS_t = rS_t dt + \sigma(S_t, t)S_t dW_t$

- S_t : underlying asset price at time t
- r risk-free interest rate
- $\sigma(S_t, t)$: local volatility function
- W_t is the Brownian motion/ Wiener process

Local Stochastic volatility model :
$$\begin{aligned} dS_t &= \mu S_t dt + \sqrt{\nu_t} S_t dW_t \\ d\nu_t &= \alpha_t(\nu) dt + \beta_t(\nu) dW'_t \end{aligned}$$

- $\alpha_t(\nu), \beta_t(\nu)$: functions based on ν
- W_t, W'_t : Wiener process with correlation factor ρ
- ν_t : model the variance of S_t , it relies on another stochastic process, so LSV is not a standard SDE

Heston model : $d\nu_t = \kappa(\theta - \nu_t)dt + \xi\sqrt{\nu_t}dW'_t$

- θ : long term variance
- κ : rate of variance reverts toward it's long term
- ξ : volatility of volatility, the variance of ν_t
- ambitious approach
 - modeling $\theta, \kappa, \xi, \rho, \mu$ where ρ is the correlation between W_t, W'_t
- modest approach
 - modeling θ, κ, ξ , and ρ, μ from empirical

Ito's lemma : $df(S, t) = \left(\frac{\partial f}{\partial t} + \mu \frac{\partial f}{\partial S} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial S^2} \right) dt + \sigma \frac{\partial f}{\partial S} dW_t$ $\underbrace{dS(t) = \mu dt + \sigma dW_t}_{\text{Stochastic Differential Equation}}$

Black Scholes equation : $\frac{\partial C}{\partial t} + rK \frac{\partial C}{\partial K} + \frac{1}{2} \sigma^2 K^2 \frac{\partial^2 C}{\partial K^2} - rC = 0$: derive from Ito's lemma

- $C(K, t)$: European call option price, equivalent to value V
- K : strike price, equivalent to assets/stock price S

Dupire's formula : $-\frac{\partial C}{\partial T} - rK \frac{\partial C}{\partial K} + \frac{1}{2} \sigma^2 K^2 \frac{\partial^2 C}{\partial K^2} - \Delta C = 0$

- when $r = 0$, $\sigma^2 = \frac{2\partial_T C}{K^2 \partial_K^2 C}$

Breeden-Litzenberger formula : $\partial_K^2 C(T, K) dK = p_T(K) dK$

- $p_T(K) dK$ is the risk neutral probability, $p_T(K) = p(S_t \in [K, K + dK])$

Deep portfolio optimization

$$\begin{aligned} dS_t &= S_t \mu dt + S_t \sigma dW_t \\ dX_t &= \alpha_t X_t \frac{dS_t}{S_t} + (1 - \alpha) X_t r dt \\ \max_{\alpha} \mathbb{E}[u(X_T)] \end{aligned}$$

- X_t is the money at time t
- α_t is strategy how much portion of money in the stock rather than in the bank at time t
- S_t is the stocks prices, governed by parameter μ and σ , with W_t a brownian motion or wiener process
- r is the interest rate saved in bank
- u is the utility function, normally $u(x) = \frac{x^{\gamma}-1}{\gamma}$

analytical solution : $\alpha^* = \frac{\mu-r}{\sigma^2(1-\gamma)}$

Deep Hedging

$$\begin{aligned} dS_t &= S_t \mu dt + S_t \sigma dW_t \\ \min_{H, \pi} \mathbb{E} \left[\left\| f(S_T) - \pi - \int_0^T H_t dS_t \right\|^2 \right] \end{aligned}$$

- S_t is the risky stocks prices, governed by parameter μ and σ , with W_t a brownian motion or wiener process
- $f(S_t)$ is financial claim, the payoff is $f(S_T) = \max(S_T - K, 0)$ for European call, K is the strike price
- π the price of the option, the upfront payment you received
- H_t is the hedge strategy at time t
- T is the expire date

Deep Calibration

Heston Calibration

$$dX_t = \left((q - r) - \frac{1}{2}Y_t \right) dt + \sqrt{Y_t} dW_t^1$$

$$dY_t = (\theta - \kappa Y_t) dt + \sigma \sqrt{Y_t} dW_t^2$$

$$\operatorname{argmin}_{\theta, \kappa, \sigma} \sum_{t=0}^T \|X_t - \log(S_t)\|^2$$

- r : interest rate
- q : dividend
- S_t : price of assets
- X_t : predicted log price : $X_0 = \log(S_0)$
- Y_t : variance of Heston model : $Y_0 = \nu_0$

Utility Calibration

$$dS_t = S_t \alpha_t l(t, S_t) dW_t$$

$$\operatorname{argmin}_l \left\| \mathbb{E} \left[\max(S_T - K, 0) - C(K, T) - \int_0^T H_t dS_t \right] \right\|^2$$

- α_t is exogenous process at time
- $l(t, S_t)$ is leverage function
- S_t is the stocks prices, with W_t a brownian motion or wiener process
- H_t is the hedge strategy at time t
- K is the strike price of European call
- C is the European call option market price

Deep Simulation

model controlled differential equation

$$dX_t = \sum_{i=0}^d \sigma(A_i X_t + b_i) du_i(t)$$

- A_i, b_i are randomly generated matrices/vectors
 - u_i is control coefficient learned by network
 - σ is the sigmoid//tanh function
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Reinforcement Learning

- a, s : action $a \in A$, state $s \in S$
- V, V^* : value function, optimal value function, $V \in S \times T \rightarrow \mathbb{R}$
- $\pi(s)$: policy, $\pi \in S \rightarrow A$
- $c(t, s, a)$: cost function, $c \in T \times S \times A \rightarrow \mathbb{R}$
- $r, R(s, a)$: reward, reward function, $r \in \mathbb{R}, R \in S \times A \rightarrow \mathbb{R}$
- $Q(s, a)$: Q/state action function, return the priority for each state and action, $Q \in S \times A \rightarrow \mathbb{R}$

[DPP] Dynamic programming principle :

$$V^*(t, s) = \max_a \left\{ \int_t^T c(\tau, s(\tau), a(\tau)) d\tau + V^*(T, s(T)) \right\}$$

$$\bullet V(s) = \max_a \left(R(s, a) + \gamma \sum_{s' \in S} P(s'|s, a) V(s') \right)$$

[HJB] Hamilton-Jacobi-Bellman equation : $\frac{\partial V(s, t)}{\partial t} + \max_a \left(\frac{\partial V(s, t)}{\partial s} \cdot f(t, s, a) + c(t, s, a) \right) = 0$

- $f(t, s, a)$: system dynamics, how state change over time, $\frac{ds(t)}{dt} = f(t, s, a)$
- $V^*(s) = \max_{a \in A} \left(R(s, a) + \gamma \sum_{s' \in S} P(s'|s, a) V^*(s') \right)$

Bellman equation : $Q(s, a) = r + \gamma \max_{a'} Q(s', a')$

Value Iteration : $V^{(n+1)} = \max_a \{ R(s, a) + \gamma \sum_{s'} P(s'|s, a) V^{(n)}(s') \}$

$$V^{\pi^{(n)}}(s) = R(s, \pi(s)) + \gamma \sum_{s'} P(s'|s, \pi(s)) V^{\pi^{(n)}}(s')$$

Policy Iteration :

$$\pi^{(n+1)} = \operatorname{argmax}_{\pi} \left\{ R(s, a) + \gamma \sum_{s'} P(s'|s, a) V^{\pi^{(n)}}(s') \right\}$$

Q learning(environment-known/model-based) :

$$Q(s, a) \leftarrow R(s, a) + \sum_{s'} P(s'|s, a) \left[\gamma \max_{a'} Q(s', a') \right]$$

Q learning(environment-unknown/model-free) :

$$Q(s, a) \leftarrow (1 - \alpha) Q(s, a) + \alpha \left[r + \gamma \max_{a'} Q(s', a') - Q(s, a) \right]$$

Optimization

inverse calibration : $\operatorname{argmin}_{\theta} \| \mathbf{d} - \mathcal{N}_{\theta} \|^2$

- \mathbf{d} is the observed data
- \mathcal{N}_{θ} $\theta \in \Theta$ is the pool of the model

optimization approach : $\operatorname{argmin}_{\theta} \| \mathbf{d} - \mathcal{N}_{\theta} \|^2 + \lambda R_{\theta}$

- θ model parameters
- R_{θ} : regularization term ($|\cdot|$: lasso(L1) or $\|\cdot\|^2$: ridge(L2))

bayesian optimization :

$$P(M_i|\mathbf{d}) = \frac{P(\mathbf{d}|M_i)P(M_i)}{P(\mathbf{d})} \propto P(\mathbf{d}|M_i)P(M_i)$$

- $P(M_i|\mathbf{d})$ posterior probability of model M_i given data \mathbf{d}
- $P(\mathbf{d}|M_i)$ likelihood of data given model M_i
- $P(M_i)$: prior probability of model M_i
- $P(\mathbf{d})$: evidence likelihood

for linear model $Y \sim \mathcal{N}(\theta X, \sigma^2 \mathbf{I})$, $\theta \sim \mathcal{N}(0, \tau^2 \mathbf{I})$, the maximizing posterior of $p(\theta|x, y)$ is ridge regression:

$$\begin{aligned} \operatorname{argmax}_{\theta} p(\theta|x, y) &\propto \operatorname{argmax}_{\theta} p(\theta)p(y|x, \theta) \\ &\propto \operatorname{argmax}_{\theta} \exp\left(-\theta^\top \mathbf{I} \theta / \tau^2\right) \exp\left(-(y - \theta x)^\top \mathbf{I} (y - \theta x) / \sigma^2\right) \\ &\propto \operatorname{argmin}_{\theta} \frac{\sigma^2}{\tau^2} \|\theta\|^2 + \|y - \theta x\|^2 \end{aligned}$$

[SGLD] Stochastic Gradient Langevin Dynamics : gradient descent plus noise :

$$d\theta_t = \frac{1}{2} \nabla \log p(\theta_t | x_1, \dots, x_n) dt + dW_t$$

- escape from local minimal