

WALLABY Pilot Survey Data Release 1: Description of Kinematic Parameters and Data Products

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1 Overview

This document describes the kinematic model parameters and data products that are contained in the first WALLABY Pilot Data Release (PDR1). A full description of the sources is found in the (Westmeier et al. 2022) and a more complete description of the kinematic modelling is found in (Deg et al. 2022)

2 Kinematic Model Parameters

The kinematic models are generated through the WALLABY Kinematic Analysis Proto-Pipeline ([WKAPP](#)). This pipeline utilizes the 3D kinematic modelling codes [FAT](#)¹ (Fully Automated TIRiFiC) and [3DBAROLO](#)² (3D-Based Analysis of Rotating Objects From Line Observations) as well as [MCG-SUITE](#)³ (Mock Cube Generator Suite) to fit the observed cubes and construct an average model.

In brief, sources in WALLABY PDR1 are modelled using both FAT and 3DBAROLO. The two fits are visually inspected and, if both are of sufficient quality, WKAPP constructs an optimized model by averaging the two fits and producing model data products using MCGSUITE.

2.1 List of Kinematic Model Parameters

A full list of the kinematic model specific parameters is contained in [Table 1](#). These are not the complete set of parameters contained in the kinematic model catalogue. The extra set of parameters are from the source catalogue and allow for cross-matching between the two sets of parameters.

Going through the additional parameters that appear in the catalogue:

- **name** – The official WALLABY source name, which is the form “WALLABY Jhhmmss±ddmmss” in accordance with the official IAU naming scheme.
- **ra** and **dec** – The right ascension and declination in degrees from the source catalogue.
- **freq** – The central frequency of the galaxy in Hz from the source catalogue.
- **team_release** The name of a set of sources from each source finding run.
- **team_release_kin** The name of a set of kinematic models corresponding to the sources found in the run.

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¹[Kamphuis et al. 2015](#)

²[Di Teodora et al. 2015](#)

³[Spekkens et al., in prep](#)

Name	Type	Unit	Description
<code>X_model</code>	double	px	x-coordinate of the kinematic center [†]
<code>e_X_model</code>	double	px	Uncertainty in <code>X_model</code> [†]
<code>Y_model</code>	double	px	y-coordinate of the kinematic center. [†]
<code>e_Y_model</code>	double	px	Uncertainty in <code>Y_model</code> [†]
<code>RA_model</code>	double	deg	Right ascension (J2000) of the kinematic center
<code>e_RA_model</code>	double	deg	Uncertainty in <code>RA_model</code> [†]
<code>DEC_model</code>	double	deg	Declination (J2000) of the kinematic center
<code>e_DEC_model</code>	double	deg	Uncertainty in <code>DEC_model</code> [†]
<code>Vsys_model</code>	double	km s ⁻¹	Heliocentric systemic velocity
<code>e_Vsys_model</code>	double	km s ⁻¹	Uncertainty in <code>Vsys_model</code>
<code>Inc_model</code>	double	deg	Inclination
<code>e_Inc_model</code>	double	deg	Uncertainty in <code>Inc_model</code>
<code>PA_model</code>	double	deg	Position angle in pixel coordinates (counterclockwise from x=0) [†]
<code>e_PA_model</code>	double	deg	Uncertainty in <code>PA_model</code> [†]
<code>PA_model_g</code>	double	deg	Position angle in equatorial coordinates (East of North)
<code>e_PA_model_g</code>	double	deg	Uncertainty in <code>PA_model_g</code>
<code>Rad</code>	double array	arcsec	Radial grid for <code>Vrot_model</code>
<code>Vrot_model</code>	double array	km s ⁻¹	Rotation curve
<code>e_Vrot_model</code>	double array	km s ⁻¹	Uncertainty in <code>Vrot_model</code> from the averaging process
<code>e_Vrot_model_inc</code>	double array	km s ⁻¹	Uncertainty in <code>Vrot_model</code> due to <code>e_Inc_model</code>
<code>Rad_SD</code>	double array	arcsec	Radial grid for <code>SD_model</code> and <code>SD_F0_model</code>
<code>SD_model</code>	double array	M _⊙ pc ⁻²	Projected surface density profile
<code>e_SD_model</code>	double array	M _⊙ pc ⁻²	Uncertainty in <code>SD_model</code>
<code>SD_F0_model</code>	double array	M _⊙ pc ⁻²	Deprojected surface density profile using a cos(<code>Inc_model</code>) correction
<code>e_SD_F0_model_inc</code>	double array	M _⊙ pc ⁻²	The uncertainty in <code>SD_F0_model</code> due to <code>e_Inc_model</code>
<code>QFlag_model</code>	integer		Kinematic model quality flag

[†] In pixel coordinates relative to the preprocessed cubelet, which starts from the point (1,1).

Table 1: WKAPP model parameters.

File suffix	Type	Description
_AvgMod.txt	ascii file	Model parameters
_DiagnosticPlot.png	PNG file	Model summary plot
_ProcData.fits	FITS cube	Pre-processed cubelet
_ModCube.fits	FITS cube	Model realization with pre-processed cubelet properties
_DiffCube.fits	FITS cube	Data - model cube with pre-processed cubelet properties
_ModRotCurve.fits	FITS binary table	Table containing the model rotation curve parameters
_ModSurfDens.fits	FITS binary table	Table containing the model surface density parameters
_ModGeo.fits	FITS binary table	Table containing the model geometry parameters
_FullResProcData.fits	FITS cube	Full spectral resolution cubelet with velocity units
_FullResModelCube.fits	FITS cube	Model realization with full resolution cubelet properties
_FATInput.txt	ascii file	The input file of the FAT run
_FATMod.txt	ascii file	The results of the FAT run
_BaroloInput.txt	ascii file	The input file of the 3DBAROLO run
_BaroloMod.txt	ascii file	The geometry and rotation curve results of the 3DBAROLO run
_BaroloSurfDens.txt	ascii file	The surface density results of the 3DBAROLO run

Table 2: WKAPP data products available for each successfully modelled PDR1 source.

3 Kinematic Model Data Products

There are a number of data products that may be downloaded for each kinematic model. These are available on both [CASDA](#) and [CADC](#). Table 2 lists the various data products. It should be noted that only FITS format products are currently available from CASDA.