Graphs

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In mathematics, a graph is a way of representing relational data. A graph G(V, E) consists of a **vertex set** V, and an **edge** set $E \subseteq V \times V$.

Often vertices are referred to as nodes.

In a **directed graph**, there can be an edge (v_0, v_1) as well as an edge (v_1, v_0) . This is good for representing asymmetric relations like v_1 is better than v_0 at some task.

In an **undirected graph**, the edge (v_0, v_1) is the same as the edge (v_1, v_0) . This is good for representing relations like friendship.

In a multigraph, there can be multiple edges between the same vertices. Multigraphs can be directed or undirected.

We'll primarily consider undirected graphs today.

The **neighbors** of a vertex v are all vertices that participate in an edge with v $N(v) = \{w \in V \mid (v, w) \in E\}$

The **degree** of a vertex is the size of its neighborhood set.

Applications of Graphs

Graphs come up in a variety of situations studied in scientific computing

- 1. Studying social networks (e.g. Facebook)
- 2. Studying food webs
- 3. Control processes
- 4. PDE meshes

and more!

Representing Graphs

There are a variety of ways we might represent graphs on a computer

Here are some common representations:

- 1. Edge list
- 2. Adjacency list
- 3. Ajacency matrix
- 4. ...

We'll typically treat the vertex set as $[0,1,\ldots,N-1]$ where N is the number of vertices in the graph

Edge Lists

An edge list is exactly what you might think - a list of edges.

For example:

```
elist = [(0,1), (1,2), (2,3)]
elist
[(0, 1), (1, 2), (2, 3)]
```

Adjacency List

An adjacency list is a list of lists - every vertex has a list of neighbors

For our example above, we would have

Adjacency Matrix

An adjacency matrix A is a |V| imes |V| matrix, where $\$A[i,j] = egin{cases} 1 & (i,j) \in E \\ 0 & ext{otherwise} \end{cases} \$$ Continuing our example, we would have

```
import numpy as np
A = np.zeros((4,4))
for e in elist:
    A[e[0], e[1]] = 1
    A[e[1], e[0]] = 1
```

the adjacency matrix of an undirected graph is always symmetric (why?)

Often adjacency matrices are sparse, so it makes sense to use a sparse matrix format.

Exercises

Assume we are working with undirected graphs

- 1. Write a function to return an adjacency list from an edge list
- 2. Write a function to return an adjacency matrix from an adjacency list
- 3. Write a function to return an edge list from an adjacency matrix

```
# Your code here
```

A Graph Class

Usually, there is data associated with vertices and/or edges in a graph.

Let's define a graph class that allows us to store data.

We'll represent the graph as an edge list.

```
class Graph(object):
   def __init__(self):
       self.elist = []
self.edata = dict() # edge data
        self.ndata = dict() # node data
   def add_node(self, i, **kwargs):
        add a node to the graph, with data indexed by keywords
        self.ndata[i] = dict(**kwargs)
   def add_edge(self, i, j, **kwargs):
        add an edge to the graph, with data indexed by keywords
        self.elist.append((i,j))
        self.edata[(i,j)] = dict(**kwargs)
   def node_data(self, i):
        if i in self.ndata.keys():
           return self.ndata[i]
        else:
            raise ValueError("No such node!")
   def edge_data(self, i, j):
        if (i,j) in self.edata.keys():
            return self.edata[(i,j)]
        elif (j,i) in self.edata.keys():
           return self.edata[(j,i)]
        else:
            raise ValueError("No such edge!")
   def edge_list(self):
        return self.elist
   def adjacency_list(self):
   def adjacency_matrix(self):
        pass
```

```
G = Graph()
G.add_node(0, name="dog")
G.add_node(1, name="cat")
G.add_node(2)
G.add_edge(0,1, weight=0.5)
```

```
print(G.node_data(2))
print(G.edge_data(0,1))
```

```
{} {'weight': 0.5}

G.edge_list()
```

```
[(0, 1)]
```

Exercise

- 1. Implement the adjacency_list method
- $2. \ Implement \ the \ {\tt adjacency_matrix} \ method$

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