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## Extra Practice Questions - Dynamic Programming

Thomas Walsh / Investment, Finance & Asset Pricing, 2025/6

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### 1 Short Horizon Cake Eating

Consider a consumer with initial wealth  $W = 100$  who lives for  $T = 3$  periods with discount factor  $\beta = 0.9$  and utility function  $u(c) = \ln(c)$ . Time is discrete and runs for  $t = 1, 2, 3$ .

- (a) Write down the consumer's sequential optimization problem with the appropriate constraint(s).
- (b) Formulate this as a recursive (Bellman) problem. Clearly identify the state variable(s), control variable(s), and write the value function.
- (c) Using either the Sequential or Recursive approach, obtain the Euler equation and derive the optimal consumption path  $\{c_1, c_2, c_3\}$ .
- (d) Verify your solution obeys the resource constraint ("we can't eat more cake in total than we had at the start"). How do we know this resource constraint will hold with *equality* in this problem?

### 2 Envelope Condition Application

Consider the infinite horizon problem:

$$V(W) = \max_{c, W'} \{u(c) + \beta V(W')\} \quad \text{s.t.} \quad W' = W - c$$

- (a) Take the first-order condition (FOC) with respect to  $c$ . You can substitute the constraint into the Bellman equation directly, BUT a Lagrangian will likely be more useful.
- (b) Derive the envelope condition  $V_W(W)$ , the slope of the value function.
- (c) Combine the FOC and envelope condition to obtain the Euler equation.
- (d) Explain intuitively what the envelope condition represents in this context.

### 3 Investment with Productivity Shocks

A firm faces the following optimization problem:

$$V(\theta, K) = \max_{K'} \left\{ \theta K^\alpha - (K' - (1 - \delta)K) - \frac{\phi}{2} (K' - (1 - \delta)K)^2 + \beta \mathbb{E}[V(\theta', K')] \right\}$$

where  $\theta$  follows a two-state Markov process (meaning only the current state matters for the distribution of future states tomorrow). The exogenous state (business conditions) can take two values, high and low:  $\theta \in \{\theta_L, \theta_H\}$  with transition matrix:

$$P = \begin{pmatrix} 0.7 & 0.3 \\ 0.2 & 0.8 \end{pmatrix} \quad \text{where you can think of each element as } P_{ij} = P(j|i)$$

- (a) Identify all state variables (2) and control variables (2) in this problem.
- (b) What is the persistence of each business conditions state, that is, the probability that tomorrow's conditions are the same as today's, for each state  $\theta_L$  and  $\theta_H$ ? Which state is more persistent? What does this imply about the firm's expectations (think about the duration of spells of good and bad times)?
- (c) Write out explicitly what  $\mathbb{E}[V(\theta', K')]$  means given the current state  $\theta = \theta_L$ .
- (d) Derive the first-order condition for optimal investment.
- (e) Interpret the role of the adjustment cost parameter  $\phi$  in the investment decision.

### 4 Stationarity and Time Consistency

Consider the infinite horizon Bellman equation:

$$V(W) = \max_{W'} \{u(W - W') + \beta V(W')\}$$

- (a) What does it mean for the value function to be "stationary"? Write this property mathematically.
- (b) Suppose you solve this problem and obtain policy function  $W' = f(W)$ . If you start with  $W_0 = 10$  and compute  $W_1 = f(10)$ , explain why applying the same function  $f(\cdot)$  again gives the optimal  $W_2$ .

## 5 Marginal Q and Investment

In the adjustment cost model, we derived:

$$q = 1 + \phi I = \beta \mathbb{E}[\pi_{K'}(\theta', K') + (1 - \delta)q']$$

- (a) Provide an economic interpretation of marginal Q (what does  $q$  represent?).
- (b) If current  $q = 1.2$  and  $\phi = 2$ , calculate the optimal level of investment  $I$ .
- (c) Suppose productivity is expected to be high next period with certainty ( $\theta' = \theta_H$  with probability 1). Explain intuitively how this affects current investment through the expectation term.
- (d) What happens to investment when  $q < 1$ ? Is this economically sensible given the model structure?

## 6 Discretization for Numerical Solution

You want to solve the following problem numerically:

$$V(k) = \max_{k' \in [0, k_{max}]} \{k^\alpha - k' + (1 - \delta)k + \beta V(k')\}$$

with  $\alpha = 0.3$ ,  $\delta = 0.1$ ,  $\beta = 0.96$ , and  $k_{max} = 50$ .

- (a) You want to set up a grid for capital with  $N_k = 100$  points. Write the Matlab command to do this.
- (b) Describe the structure of your value function iteration algorithm (you don't need to write actual code, just outline the steps).
- (c) How would you check for convergence in your algorithm?
- (d) What is a reasonable initial guess  $V_0(k)$  to start the iteration? Justify your choice.

## 7 Reducing Choice Variables and Computation

Consider two formulations of the same problem:

**Formulation A:**

$$V(W) = \max_{c, W'} \{u(c) + \beta V(W')\} \quad \text{s.t.} \quad c + W' = W$$

**Formulation B:**

$$V(W) = \max_{W'} \{u(W - W') + \beta V(W')\}$$

- (a) Explain the relationship between these two formulations.
- (b) Solve Formulation A by setting up the Lagrangian with multiplier  $\lambda$ . Derive the FOCs and envelope condition.
- (c) Solve Formulation B directly. Show that you obtain the same Euler equation as in part (b).
- (d) Which formulation is computationally more efficient for numerical solution? Why? (Hint: what does the max operator mean computationally)

## 8 Bellman Operator and Convergence

Define the Bellman operator as a manipulation of an input function, which gives out another function according to:

$$\mathcal{T}[V](W) = \max_c \{u(c) + \beta V(W - c)\}$$

- (a) Explain what it means for  $V^*$  to be a “fixed point” of the Bellman operator  $\mathcal{T}$ .
- (b) How are we utilizing Blackwell’s Sufficient Conditions when we do Value Function Iteration (VFI) numerically with (say) Matlab?
- (c) If we start the VFI recursions with  $V_{n=0}(z, k) = \text{zeros}(Nz, Nk)$ ; What is the first value function iteration doing? What is happening as iterations increase?