

**NANYANG TECHNOLOGICAL UNIVERSITY****SEMESTER 2 EXAMINATION 2017-2018****MA2011 - MECHATRONICS SYSTEM INTERFACING**

April/May 2018

Time Allowed: 2½ hours

**INSTRUCTIONS**

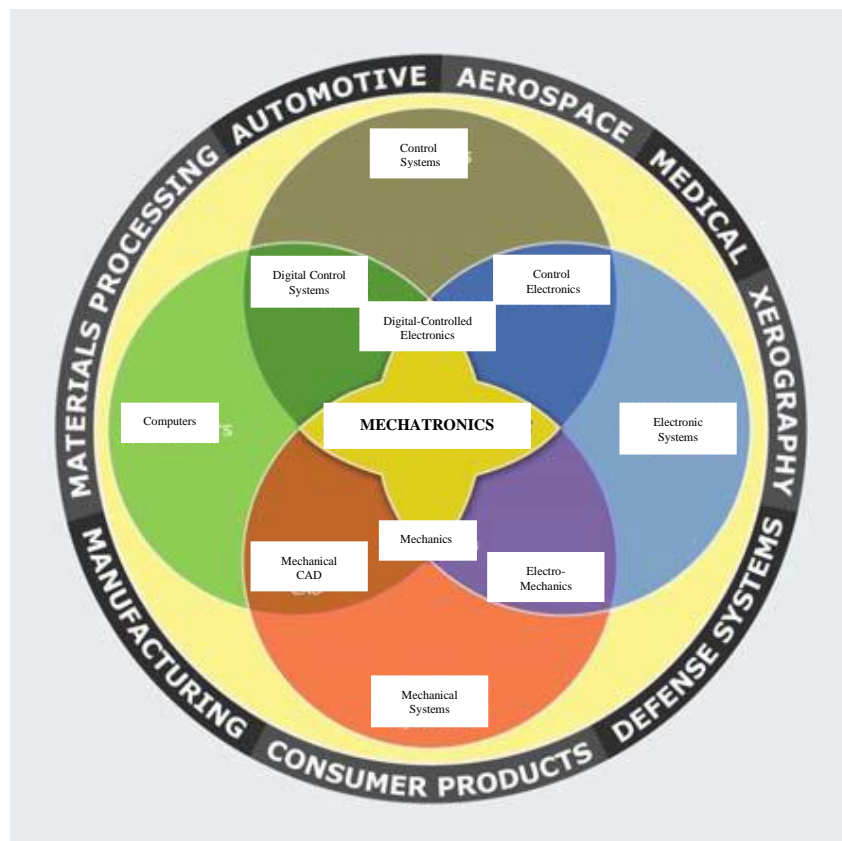
1. This paper contains **FOUR (4)** questions and comprises **FOUR (4)** pages.
2. Answer **ALL** questions.
3. All questions carry equal marks.
4. This is a **RESTRICTED OPEN-BOOK** examination. One double sided A4 reference sheet is allowed.

- 1(a) Give five different definitions of “Mechatronics”.

(10 marks)

- (b) Based on Figure 1, describe in detail what is a typical mechatronics system.

(15 marks)



**Figure 1:** A Mechatronics System.

2. Figure 2 shows a periodic waveform.

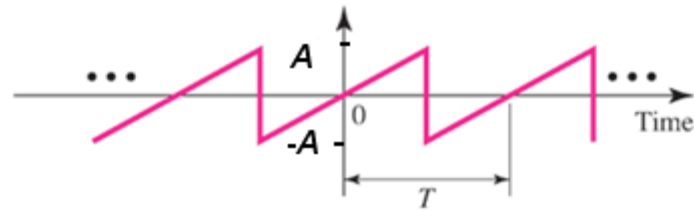


Figure 2: A waveform.

- (a) Define the function  $f(t)$  over the period  $T$ .  
(5 marks)
- (b) Calculate the coefficients  $A_n$  and  $B_n$  in the Fourier series of the waveform.  
(10 marks)
- (c) Using the Frequency-Domain representation of the Fourier Series, show the spike diagram of the frequency spectrum.  
(10 marks)

3. A solid disk, with its height along the z-direction, has to remain centered at the origin of the X-Y plane, as shown in the cross-sectional view in Figure 3(a). To monitor variations from the centered position, a pair of inductive sensors is used for each axis. Specifically for the x-axis, two inductive sensors  $L_1$  and  $L_2$ , are arranged symmetrically, with respect to the disk, as shown in Figure 3(a), and electrically connected to a Wheatstone bridge, as shown in Figure 3(b).

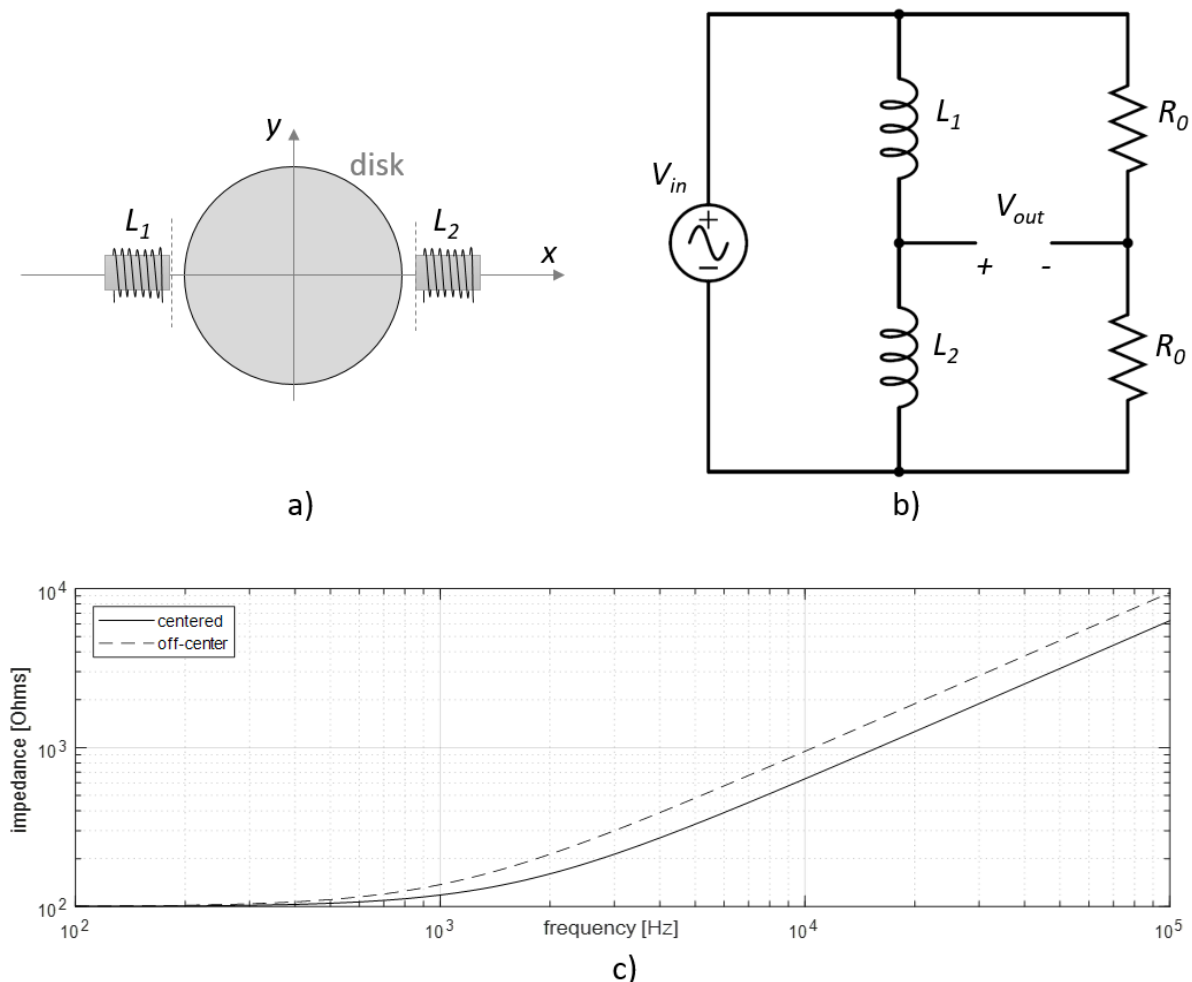


Figure 3

- (a) When the disk is perfectly centered along the x-axis, each inductive sensor is characterized by intrinsic resistance  $r_0$  and inductance  $L_0$ . However, an inductance change of  $L_0 + \Delta L$  is observed when the distance from the disk is off-center. Based on the values of the amplitude response in Figure 3(c), determine
- an approximate value for  $r_0$ ,
  - an approximate value for  $L_0$
  - an approximate value for  $\Delta L$ .

(10 marks)

Note: Question 3 continues on page 4.

- (b) Consider the Wheatstone bridge in Figure 3(b), with an AC driving input and with similar bridge resistances ( $R_0$ ).

- (i) Derive **a symbolic expression** of the bridge output  $V_{out}$  as a function of  $r_0$ ,  $L_0$ ,  $\Delta L$  and input frequency, assuming that inductance varies linearly with the distance.

(Note: if the inductance of  $L_2$  changes  $L_0 + \Delta L$ , the inductance for  $L_1$  will change as  $L_0 - \Delta L$ )

(5 marks)

- (ii) Sketch the frequency response of the amplitude  $|V_{out}/V_{in}|$  between 100-100,000 Hz.

(5 marks)

- (c) Considering the bridge as a filter, with input  $V_{in}$  and output  $V_{out}$ , determine whether it is a low-pass or high-pass filter and its cut-off frequency in the case of off-centered disk.

(5 marks)

4. A DC motor driven at a nominal voltage  $V_0 = 10V$ , is designed to provide a rated torque 0.5 Kg.cm, at a rated speed of 6,500 rpm, drawing a rated current of 4,000 mA. At no load, the motor requires 500 mA of current and its speed reaches 9000 rpm.

- (a) On your answer book, draw on the same graph the Speed vs. Torque, Current vs. Torque and output Power vs. Torque responses.

**NOTE:** The rated values refer to one possible (suggested) operating point, not the stall point. You can assume linearity.

(8 marks)

- (b) Determine, at the nominal voltage, the maximum power (in Watts) which can be delivered to a mechanical load as well as the torque, speed and efficiency at such optimal operating point.

(5 marks)

- (c) Based on previous calculations and the information reported above, determine the friction coefficient of the bearings (assuming a linear model) and the amount of friction torque in the no-load conditions.

(7 marks)

- (d) Compute the *efficiency* of the motor when operating at the rated speed and when operating at maximum power transfer conditions.

(5 marks)

END OF PAPER