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HW 6 #1, Walter Coe, 2-17-16

```
clear; clc;
```

Table P6-1 row c, pg. 328

```
lengths = [3 10 6 8];  
omega2 = rad2deg(-15);  
p = [10*cosd(80) 10*sind(80)];
```

Solve

```
[angles, angularRates, lengths, linearRates, points, p, vp] = four_bar_func([0 90 0 0],omega2,lengths,p,[1 0])  
  
omega3_ = angularRates(3);  
omega4_ = angularRates(4);  
vpx = vp(1);  
vpy = vp(2);
```

```
angles =
```

```
0    90.0000   -23.5814    71.7979
```

```
angularRates =
```

```
1.0e+03 *
```

```
0    -0.8594   -2.7994   -1.5060
```

```
lengths =
```

```
3    10     6     8
```

```
linearRates =
```

```
1.0e+04 *
```

```

0      0
0.8594 0
1.1445 -0.3763
0      0

```

points =

```

0      0
0      10.0000
5.4990 7.5997
3.0000 0

```

p =

```

5.5312 18.3310

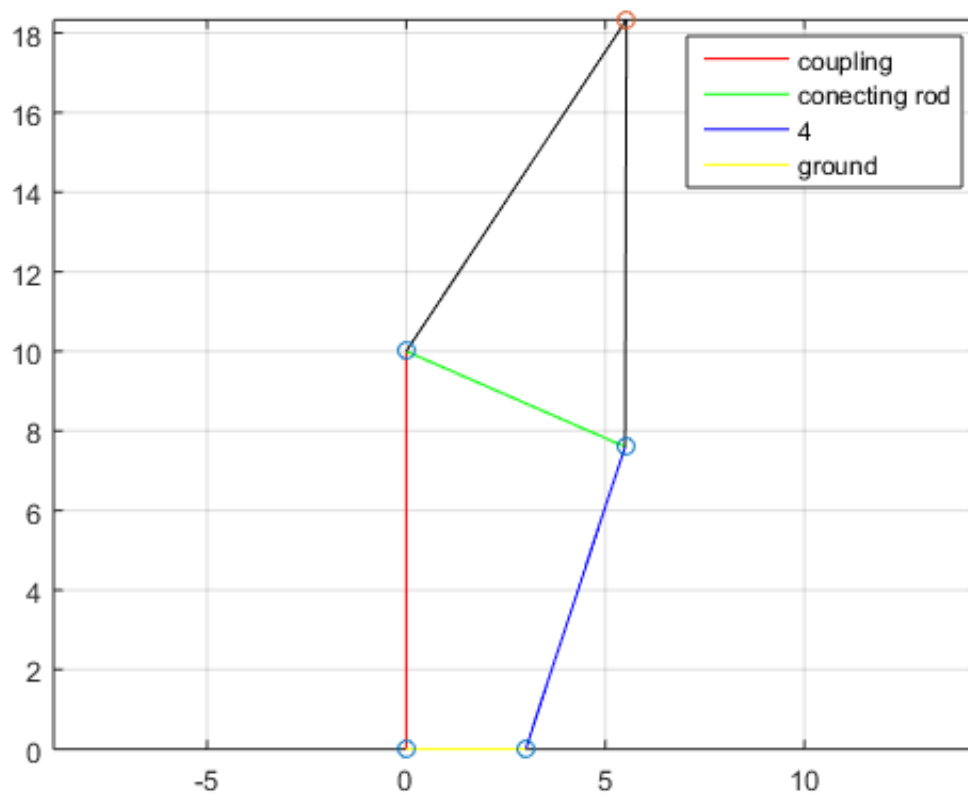
```

vp =

```

1.0e+04 *
3.1917 -1.5484

```



Measure across theta2 range

```

theta2 = 0:1:90;

for i=1:length(theta2)

    [angles, angularRates, lengths, linearRates, points, p, vp] = four_bar_func([0 theta2(i) 0 0],o
mega2,lengths,p,[0 0]);

    omega3(i) = angularRates(3);
    omega4(i) = angularRates(4);
    Vpx(i) = vp(1);
    Vpy(i) = vp(2);
    V2(i) = linearRates(2);

end

```

Report

```

disp(['omega3 is: ', num2str(omega3_), ' degrees per second']);
disp(['omega4 is: ', num2str(omega4_), ' degrees per second']);
disp(['Vpx is: ', num2str(vp(1)), ' cm per second']);
disp(['Vpy is: ', num2str(vp(2)), ' cm per second']);

figure(2); clf;
plot(theta2, omega3, theta2, omega4);
legend('Omega3', 'Omega4');
xlabel('theta2')
ylabel('angular rates in deg/sec')

figure(3); clf;
plot(theta2, Vpx, theta2, Vpy);
legend('Vpx', 'Vpy');
xlabel('theta2')
ylabel('linear rates in cm/sec')
%
% figure(4); clf;
% plot(theta2, V2);
% legend('V2');
% xlabel('theta2')
% ylabel('linear rates in deg/sec')

```

```

omega3 is: -2799.4495 degrees per second
omega4 is: -1505.9711 degrees per second
Vpx is: 30741.3203 cm per second
Vpy is: -124840.0769 cm per second

```

