

## Exam 3 review

Physics 211  
Syracuse University, Physics 211 Spring 2017  
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April 12, 2017

# Announcements

- HW8 is due next Tuesday
- **Group exam 3: Friday during recitation. You may bring a reference sheet.**
- **Exam 3: Tuesday during the normal time**

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- HW8 is due next Tuesday
- **Group exam 3: Friday during recitation. You may bring a reference sheet.**
- **Exam 3: Tuesday during the normal time**
- **Alternate date/time for Exam 3: Wednesday, 7:30 PM**
- **Review sessions:**
  - **Monday, 2PM-5PM: Physics Clinic (Walter)**
  - **Saturday or Sunday: reviews run by coaches (will announce by email)**

# Homework questions?

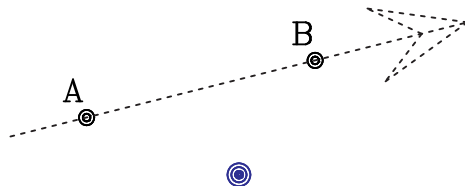
# Angular momentum of a single object

A single object moving in a straight line also has angular momentum.

$$L = mv_{\perp}r = mvr_{\perp}$$

If we are to trust this relation, then the angular momentum of an object moving with constant  $\vec{v}$  should be constant!

Is the angular momentum the same at points A and B?



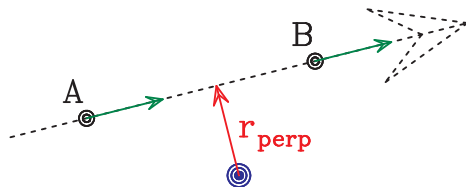
# Angular momentum of a single object

A single object moving in a straight line also has angular momentum.

$$L = mv_{\perp}r = mvr_{\perp}$$

Is the angular momentum the same at points A and B?

Yes:  $r_{\perp}$  (and  $v$ ) are the same at both points.



What happens to the person on the platform if they catch the ball?

# Angular momentum demonstrations

What happens to the person on the platform if they catch the ball?  
What happens when they throw it?



## Review: The work-energy theorem

- Translational work-energy theorem:  
 $\frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2 = \vec{F} \cdot \vec{d} = Fd \cos \theta$  (if this is constant)
- Rotational work-energy theorem:  $\frac{1}{2}I\omega_f^2 - \frac{1}{2}I\omega_i^2 = \tau \Delta \theta$

Potential energy is an alternate way of keeping track of the work done by conservative forces:

- $PE_{\text{grav}} = mgh$
- $PE_{\text{spring}} = \frac{1}{2}kx^2$

# Review: Conservation of energy

$$PE_i + \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 + W_{\text{other}} = PE_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2$$

# Review: Conservation of energy

$$\begin{array}{ccccccc} \text{PE}_i & + & \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 & + & W_{\text{other}} & = & \text{PE}_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 \\ \text{(initial PE)} & + & \text{(initial KE)} & + & \text{(other work)} & = & \text{(final PE)} + \text{(final KE)} \end{array}$$

# Review: Conservation of energy

$$\begin{array}{ccccccc} PE_i & + & \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 & + & W_{\text{other}} & = & PE_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 \\ \text{(initial PE)} & + & \text{(initial KE)} & + & \text{(other work)} & = & \text{(final PE)} + \text{(final KE)} \\ \text{(total initial mechanical energy)} & + & \text{(other work)} & = & \text{(total final mechanical energy)} \end{array}$$

## Review: Conservation of energy

$$\begin{array}{ccccccc} PE_i & + & \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 & + & W_{\text{other}} & = & PE_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 \\ \text{(initial PE)} & + & \text{(initial KE)} & + & \text{(other work)} & = & \text{(final PE)} + \text{(final KE)} \\ \text{(total initial mechanical energy)} & + & & + & \text{(other work)} & = & \text{(total final mechanical energy)} \end{array}$$

Since conservation of energy is the broadest principle in science, it's no surprise that we can do this!

# Review: rotational motion

Translation	Rotation
Position $\vec{s}$ Velocity $\vec{v}$ Acceleration $\vec{a}$	Angle $\theta$ Angular velocity $\omega$ Angular acceleration $\alpha$
Kinematics: $\vec{s}(t) = \frac{1}{2}\vec{a}t^2 + \vec{v}_0t + \vec{s}_0$	$\theta(t) = \frac{1}{2}\alpha t^2 + \omega_0t + \theta_0$
Force $\vec{F}$ Mass $m$ Newton's second law $\vec{F} = m\vec{a}$	Torque $\tau$ Rotational inertia $I$ Newton's second law for rotation $\tau = I\alpha$
Kinetic energy $KE = \frac{1}{2}mv^2$ Work $W = \vec{F} \cdot \Delta\vec{s}$ Power $P = \vec{F} \cdot \vec{v}$	Kinetic energy $KE = \frac{1}{2}I\omega^2$ Work $W = \tau\Delta\theta$ Power $P = \tau\omega$
Momentum $\vec{p} = m\vec{v}$	Angular momentum $L = I\omega$

# Review: computing torques and static equilibrium

“Signpost problem” from recitation

# Review: combining translational and rotational motion

“Yo-yo problem” from recitation



What would you like to talk about?