1D kinematics: solving problems

Physics 211 Syracuse University, Physics 211 Spring 2016 Walter Freeman

January 23, 2017

On solving problems

You can recognize truth by its beauty and simplicity. When you get it right, it is obvious that it is right—at least if you have any experience—because usually what happens is that more comes out than goes in.... Inexperienced students make guesses that are very complicated, [but] the truth always turns out to be simpler than you thought.

-Richard Feynman, quoted by K. C. Cole, in Sympathetic Vibrations: Reflections on Physics as a Way of Life (1985)

Nature uses only the longest threads to weave her patterns, so each small piece of her fabric reveals the organization of the entire tapestry.

-Richard Feynman, The Character of Physical Law (1965)

Announcements

- Homework 1 due tomorrow
- I'm seeing lots of you in the Clinic; I'd like to see lots more
- Clinic hours today: 5:10-6:50
- "Physics practice", on the quadratic formula: Wednesday night at 7:30-8:30 PM, location TBA

"Ask a Physicist"

Submit questions!

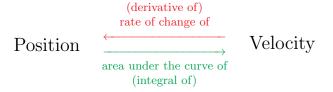
Today

- Review material from last time
- Position, velocity, and acceleration graphs
- Rotational kinematics
- Problem-solving method for kinematics problems
- Sample problems

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- Homework help?

Last time: Position, velocity, and acceleration



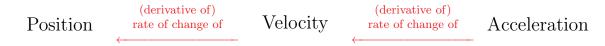
Last time: Position, velocity, and acceleration



Position, velocity, and acceleration



Position, velocity, and acceleration



Kinematics

• If we know acceleration as a function of time, how do we get from there to position vs. time?

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- A. Look at the slope of the acceleration vs. time graph to get velocity, and then look at its slope to get position
- B. Look at the area under the curve of the acceleration vs. time graph to get velocity, and then look at the area under that graph to get position
- C. Take two derivatives of the acceleration vs. time graph to get position vs. time
- D. Take two integrals of the acceleration vs. time graph to get position vs. time

The "kinematics equations"

$$v(t) = at + v_0$$

 $x(t) = \frac{1}{2}at^2 + v_0t + x_0$

These equations are valid when...

- A. Acceleration is constant
- B. Velocity is constant
- C. The object moves in only one direction
- D. They are always valid

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- A: these are the expressions for x(t) and v(t) when acceleration is constant!

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First: Write the position and velocity equations, substituting in things you know. (Here, take ground level to be y=0, and upward to be the positive direction.)

A:
$$x(t) = \frac{1}{2}gt^2 + h$$
 and $v(t) = -gt$
B: $x(t) = -\frac{1}{2}gt^2 + v_0t + h$ and $v(t) = -gt$
C: $x(t) = -\frac{1}{2}gt^2 + h$ and $v(t) = gt$
D: $x(t) = -\frac{1}{2}gt^2 + h$ and $v(t) = -gt$
E: $x(t) = -\frac{1}{2}gt^2 + v_0t$ and $v(t) = -gt$

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Second: Phrase the question in terms of your algebraic variables.

From the previous: $x(t) = -\frac{1}{2} + h$ and v(t) = -gt

(Here, take ground level to be y = 0, and upward to be the positive direction.)

- A: "What is the value of t when v = 0?"
- B: "What is the value of x when t = 0?"
- C: "What is the value of x when v = 0?"
- D: "What is the value of t when x = h?"
- E: "What is the value of t when x = 0?"

How long does it take an object to fall a height h?

Third: Do the algebra your sentence tells you to do: "What is the value of t when x = 0?"

From the previous: $x(t) = -\frac{1}{2} + h$ and v(t) = -gt

(Here, take ground level to be y = 0, and upward to be the positive direction.)

A: $\sqrt{2g/h}$

B: h/\underline{g}

C: $\sqrt{2h/g}$

D: 2h/g

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$$x(t) = \frac{1}{2}at^{2} + v_{0}t + x_{0}$$

$$h = -\frac{1}{2}gt^{2} + v_{0}t$$

$$0 = -\frac{1}{2}gt^{2} + v_{0}t - h$$

- \rightarrow You need the quadratic formula for this nonzero a, v_0 , and position
- The quadratic formula gives you two answers, but there's clearly only one
- In this case, both roots are positive. Do you want (A) the larger one, or (B) the smaller one?

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- The quadratic formula gives you two answers, but there's clearly only one
- In this case, both roots are positive. Do you want (A) the larger one, or (B) the smaller one?
- The homework asks you to address this idea.
- Hint: graph position vs. time, and interpret the question graphically
- What is the *mathematical* interpretation of the quadratic formula?

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I am standing at the bottom of a hole of depth h. Someone throws a ball down to me at speed v_0 . How fast is it going when it reaches me?

First: Write equations for x(t) and v(t), putting in the things you know. (Here, take ground level as zero, and downward to be positive.)

A:
$$x(t) = \frac{1}{2}gt^2$$
 and $v(t) = -gt$
B: $x(t) = -\frac{1}{2}gt^2 + v_0t + h$ and $v(t) = -gt$
C: $x(t) = \frac{1}{2}gt^2 + v_0t$ and $v(t) = gt$
D: $x(t) = \frac{1}{2}gt^2 - v_0t$ and $v(t) = -gt$
E: $x(t) = -\frac{1}{2}gt^2 - v_0t$ and $v(t) = -gt$

I am standing at the bottom of a hole of depth h. Someone throws a ball down to me at speed v_0 . How fast is it going when it reaches me?

Second: Ask a question in terms of your algebraic variables. (Here, take ground level as zero, and downward to be positive.)

A: "What is v at the time when x is h?"

B: "What is v at the time when x is 0?"

C: "What is t at the time when x is h?"

D: "What is v at the time when x is -h?"

E: "What is x at the time when v is 0?"

I am standing at the bottom of a hole of depth h. Someone throws a ball down to me at speed v_0 . How fast is it going when it reaches me?

Third: Do the algebra. I'll demonstrate this on the document camera. This requires two steps: first find the time, then find v.

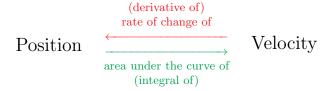
• A bucket is being lowered from a cliff at a rate of 10 m/s. You drop a rock off the cliff when the bucket is 10 m beneath the top. How long does it take for the rock to land in the bucket?

Same idea as before; see example on the document camera.

Rotational kinematics

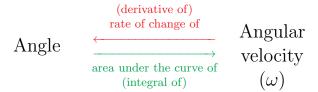
- Linear motion: care about position as a function of time
- Rotational motion: care about angle as a function of time
- Everything we just did translates to rotational kinematics exactly!

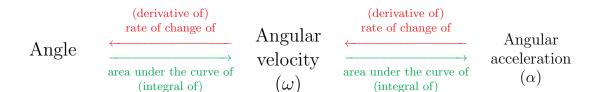
Position, velocity, and acceleration



Position, velocity, and acceleration







Angle
$$\begin{array}{c} \text{(derivative of)} \\ \text{rate of change of} \\ \\ \xrightarrow{\text{area under the curve of}} \\ \text{(integral of)} \end{array} \begin{array}{c} \text{(derivative of)} \\ \\ \text{Angular} \\ \\ \text{velocity} \\ \\ \text{(ω)} \end{array} \begin{array}{c} \text{(derivative of)} \\ \\ \text{rate of change of} \\ \\ \xrightarrow{\text{rate of change of}} \\ \\ \text{Angular} \\ \\ \text{acceleration} \\ \\ \text{(α)} \end{array}$$

$$x(t) = x_0 + v_0 t + \frac{1}{2} a t^2$$
$$\theta(t) = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

Angle
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$$x(t) = x_0 + v_0 t + \frac{1}{2}at^2$$

$$\theta(t) = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

 \rightarrow Angular kinematics works in exactly the same way as translational kinematics!

- Angle θ the angle through which something has turned.
- Measured in revolutions, radians, degrees...

- Angular velocity ω ("omega", not "dubya") the rate at which something is turning
- Measured in revolutions per second, radians per second, degrees per second...

- Angular acceleration α ("alpha", not "fish") the rate at which something's rate of turning is changing
- \bullet Measured in $\frac{rev}{s^2},\,\frac{rad}{s^2},\,\frac{deg}{s^2}...$

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