

RECITATION QUESTIONS – ANGULAR MOMENTUM

APRIL 9

Work and Energy

In this recitation, you will discover for yourself one of the most useful laws of mechanics – the *work-energy theorem*.

Our starting point is the “third kinematics relation”

$$v_f^2 - v_i^2 = 2a\Delta x$$

which you worked out in recitation a while back and have found useful in this most recent segment.

1. One Dimension

For this part of the assignment

Consider a constant force F acting on an object of mass m moving only in the x -direction as it moves; its change in position during some interval (from “before” to “after”) is Δx . (We call Δx – the change in the x -position during some motion – the *x -displacement*.)

1. Our goal here is to rewrite the “third kinematics equation” so that the right-hand side references only the *forces* that act on the object, rather than its acceleration. You know that $F = ma$. Multiply both sides of that equation by some factor so that the right-hand side becomes only the force multiplied by the x -displacement. What do you get?

2. This equation will become a good friend in the next few weeks, so we give the terms that appear in it special meanings. There are two terms on the left, representing the final and initial *kinetic energy* during the motion. (Kinetic energy is a type of energy associated with motion.)

What is the formula for the kinetic energy of something? *Give only the general form – one term, either initial or final.*

3. The right-hand side of this equation – force times displacement – is also new thing we have not met before, called *work*.

In one dimension, we have two choices for our coordinate system: we can choose either right or left to be positive. Does the value of *work* depend on which coordinate system you choose? *(If you want, come up with a hypothetical situation: choose a direction for the force and the displacement, and then think about the result in each coordinate system.)*

4. Under what conditions is work positive? Under what conditions is it negative?
5. Does the *kinetic energy* that you found above depend on your choice of coordinate system? Why or why not?

6. The result you got above is called the *work-energy theorem*. It says, in words:

$$(\text{change in kinetic energy due to a force}) = (\text{work done by that force}).$$

2. Two Dimensions

Like the rest of kinematics, the “third kinematics equation” applies separately for x and y directions. Since the work-energy theorem is based on the third kinematics equation, let’s see how we can modify the above result for motion in more than one dimension.

1. Begin by writing down the “third kinematics equation” in both x and y . (You will need double subscripts, such as v_{fy} ; that is okay.)
2. You know that Newton’s second law applies separately in x and y ; that is $\vec{F} = m\vec{a}$ implies both $F_x = ma_x$ and $F_y = ma_y$. As you did before, multiply both sides of the equations by $\frac{1}{2}m$, then substitute the force in for the right-hand side.
3. In the past, we emphasized the fact that x – and y –directions were independent, and we could not combine them without great care. However, we’ll do that now. *Add the two equations* above together. (Yes, it is gross, but it won’t be gross for long. It will simplify greatly in two steps!)
4. Group the terms on the left-hand side so that all the “initial” terms are together, and all the “final” terms are together. (In doing this, we are trying to figure out what the initial and final kinetic energy in two dimensions looks like.)
5. You may see right away how to simplify the left-hand side. If you don’t, think about the Pythagorean theorem; if you are still stuck, ask a GTA or coach for help. (*You may use the simple symbol v , without an arrow, for “the magnitude of the velocity.”*) Write your simplified form of the work-energy theorem in two dimensions below.
6. In two dimensions, what is an expression for the kinetic energy? Does it depend on which coordinate system you choose, or which direction the velocity vector is pointing?

7. Now, let's think about the right-hand side – the “work side”. You have found that

$$(\text{work in two dimensions}) = F_x \Delta x + F_y \Delta y$$

A moment ago, you found that the kinetic energy doesn't have a direction or depend on the coordinate system. If that is true for the left-hand side of an equation, it must also be true for the right-hand side! Here we will see why.

Imagine that you have a force \vec{F} acting 30 degrees south of east on an object that moves a distance d due east. Draw arrows representing the force vector and the displacement vector below.

8. Using the definition of work $W = F_x \Delta x + F_y \Delta y$, calculate the work that the force does on the object during the motion using two different coordinate systems:

- A coordinate system where the positive x -direction is pointing in the direction of the displacement
- A coordinate system where the positive x -direction is pointing in the direction of the force

Do you think that the work depend on the coordinate system you choose? The result you got here is true for arbitrary coordinate systems as well; you can prove that using sum and difference trig identities if you want to, but we won't make you do that – we have better things to do and so do you!

9. Note that Δx and Δy are components of the displacement vector $\Delta \vec{s} = (\Delta x, \Delta y)$. Our form for the work $W = F_x \Delta x + F_y \Delta y$ has the form $A_x B_x + A_y B_y$. This combination occurs quite a bit in physics, so we give it a special name: the **dot product**. Specifically,

$$A_x B_x + A_y B_y = \vec{A} \cdot \vec{B}.$$

Rewrite your version of the work-energy theorem so that the work is written in terms of a dot product between force and displacement. Then label the three terms:

- work
- initial kinetic energy
- final kinetic energy

Note that *none* of them depend on coordinate system!