

PHY211 Lecture 4

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Vectors

Describing vectors

- You've probably used vectors before without really thinking about it
 - "Walk one block east" – displacement vector
 - "Driving northbound at 100 km/h" – velocity vector
 - "The wind was blowing from the west at 30 km/h" – velocity vector
- Anything that points a direction, and has some magnitude is a vector
 - Can even think of just a direction as a vector of magnitude 1

Describing vectors

Mathematically

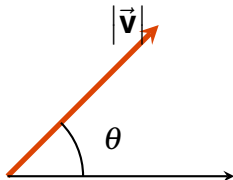
- It's easy to draw a picture of an arrow pointing some direction with some length



Describing vectors

Mathematically

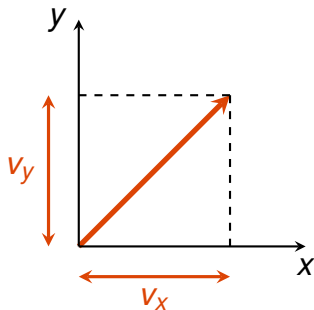
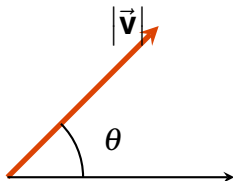
- It's easy to draw a picture of an arrow pointing some direction with some length
- Use direction and magnitude



Describing vectors

Mathematically

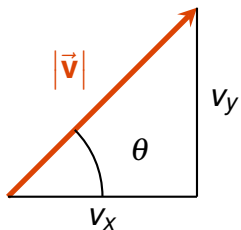
- It's easy to draw a picture of an arrow pointing some direction with some length
- Use direction and magnitude
- Or components along some axes



Conversions

We'll have to do this a lot!

- Best bet – always draw the relevant triangle with the vector on the hypotenuse
 - Make it its own picture!



$$|\vec{v}| \equiv v$$

$$v_x = v \cos(\theta)$$

$$v_y = v \sin(\theta)$$

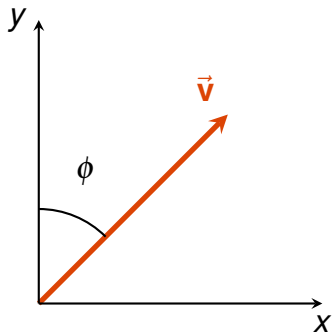
$$v = \sqrt{v_x^2 + v_y^2}$$

$$\tan(\theta) = v_y / v_x$$

Question

For this vector, what is v_y ?

- A $v \cos(\phi)$
- B $v \sin(\phi)$
- C $v \tan(\phi)$
- D $v / \cos(\phi)$



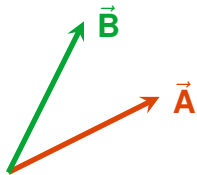
Vector placement

- Vectors **do not “save” their start position**
- Example: if you move from point A to point B, then the vector between them is your displacement. If you **need to know the starting point**, then you have additional quantities describing the position of A
- This means these are the same vectors:



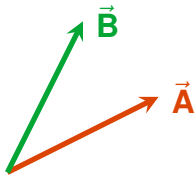
Adding graphically

What is $\vec{A} + \vec{B}$?

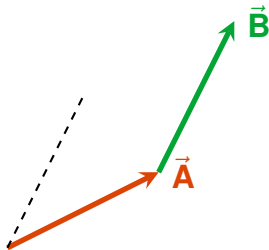


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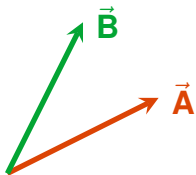


Move tip-to-tail

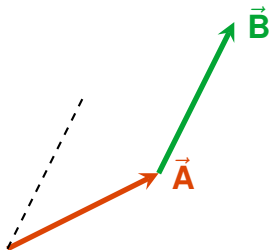


Adding graphically

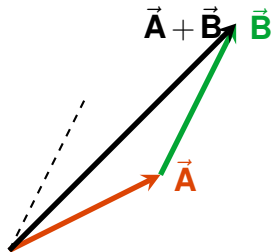
What is $\vec{A} + \vec{B}$?



Move tip-to-tail



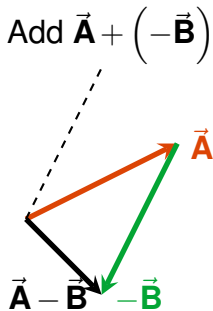
Draw from start to finish



Subtracting graphically

What is $\vec{A} - \vec{B}$?

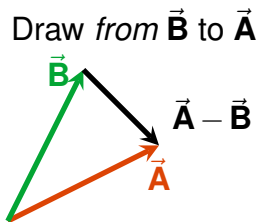
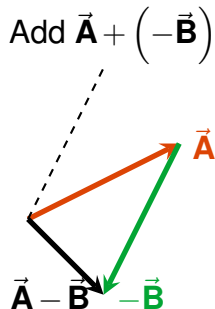
Two options



Subtracting graphically

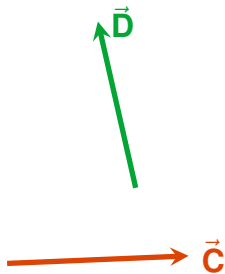
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Two options

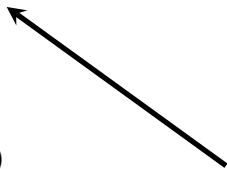


Subtraction question

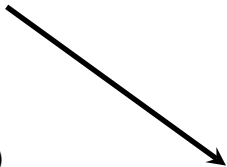
You have the following two vectors, and you want to draw $\vec{D} - \vec{C}$. Which result is correct?



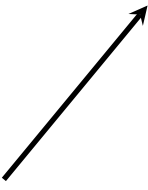
(a)



(b)



(c)



(d)



Why components?

- Drawing is useful to get a picture in your head of what is going on, so it will help us make our graphs and sketches to solve problems
- But components are easier to use with numbers
- Can simply add x , y , and z components separately

$$\left(\vec{\mathbf{A}} + \vec{\mathbf{B}}\right)_x = A_x + B_x$$

$$\left(\vec{\mathbf{A}} + \vec{\mathbf{B}}\right)_y = A_y + B_y$$

$$\left(\vec{\mathbf{A}} + \vec{\mathbf{B}}\right)_z = A_z + B_z$$

Pre-lecture question 1

- What form does the trajectory of a particle have if the distance the particle travels from any point A to point B is equal to the magnitude of the displacement from A to B?
- A L-shape
- B Curved
- C Straight line

Pre-lecture question 2

- ☐ If an object experiences an acceleration in the y direction, does the x-component of its velocity change?
- ☐ A Yes
- ☐ B No

Pre-lecture question 3

- If an object moves 3 meter along the positive x direction, then turns and moves 4 meter along the negative y direction, what is the magnitude of its displacement?
- A 0 m
 - B 7 m
 - C 5 m
 - D -5 m

Simultaneous problems

with constant acceleration

- Just have two sets of the same equations, the only thing they share is **time**!

$$v_x(t) = v_{x,0} + a_x t$$

$$x(t) = x_0 + v_{x,0} t + \frac{1}{2} a_x t^2$$

$$v_y(t) = v_{y,0} + a_y t$$

$$y(t) = y_0 + v_{y,0} t + \frac{1}{2} a_y t^2$$

- This covers a lot of what we will do this semester!

Unit vector form

- Sometimes (in the book) you will see the components written out on one line
- This is done by writing each component as a vector pointing in the x , y , or z direction
- Then the sum of these component vectors is the full thing
- Uses the notation of unit vectors

$\hat{i} \equiv x \text{ direction}$

$\hat{j} \equiv y \text{ direction}$

$\hat{k} \equiv z \text{ direction}$

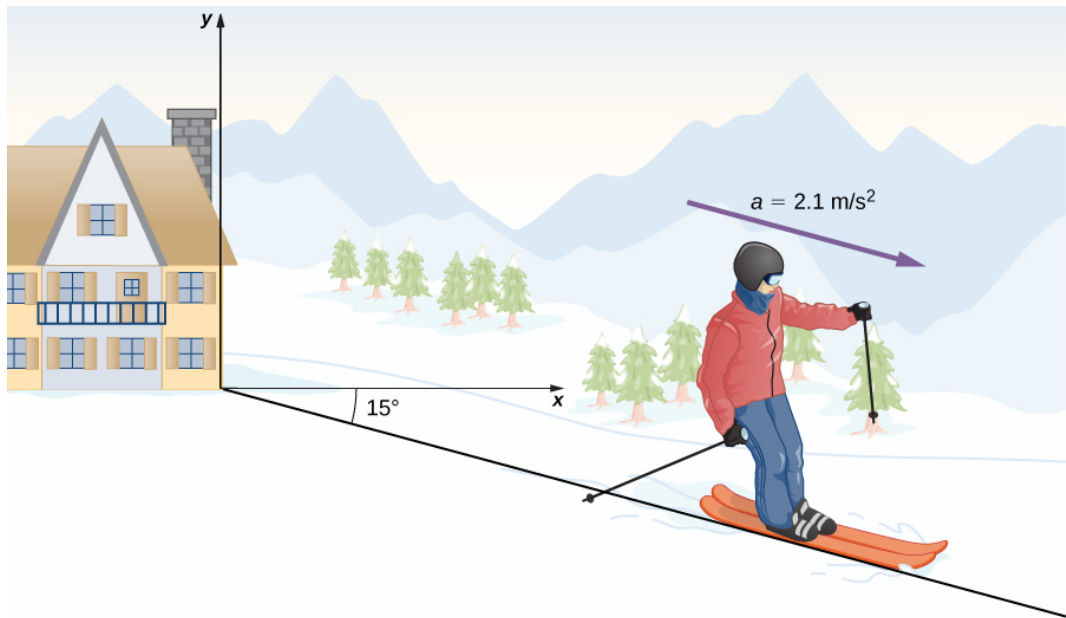
$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

Vector recap

What do we need to know?

- We will use vectors all year to describe physics!
- You should be able to draw vectors; add and subtract them graphically
 - Very helpful for setting up problems and checking if your answer makes sense!
 - **Example:** if the velocity arrow you want to solve for points towards $-x$, your v_x should be negative at the end!
- For most problems you have to do **components**
 - Be able to convert magnitude and angle to x and y components
 - Components are often like two separate problems that just share time t
- Today we will practice this in context of motion

Skier example



Skier math

The figure shows a skier moving with an acceleration of 2.1 m/s^2 down a slope of 15° at $t = 0$. With the origin of the coordinate system at the front of the lodge, her initial position and velocity are

$$\vec{r}(0) = (75.0\hat{i} - 50.0\hat{j}) \text{ m}$$

and

$$\vec{v}(0) = (4.1\hat{i} - 1.1\hat{j}) \text{ m/s}.$$

- (a) What are the x - and y -components of the skier's position and velocity as functions of time?
- (b) What are her position and velocity at $t = 10.0 \text{ s}$?

Problem solving steps

Key strategy for the class!

- 1 Draw a picture – it helps visualize things
- 2 Choose axes – which way is positive? Where is zero?
- 3 When is $t = 0$?
- 4 For motion problems use the equations of motion
- 5 Translate the question into one about your variables
- 6 Do algebra to solve for the unknowns
- 7 Calculate a numerical answer
- 8 Does your answer make sense?

Simplifying things

- Can you think of an easier way to do the last problem?

Simplifying things

- Can you think of an easier way to do the last problem?
- Why not define $+x$ in the direction of acceleration?
- In two dimensions you can pick the angle of your axes!

Example

A spaceship is drifting with a velocity $\vec{v} = 100\text{ m/s}\hat{i} + 200\text{ m/s}\hat{j}$ at $t = 0$. It then turns on its engine which provides a constant acceleration. Four seconds later the spaceship's velocity is $\vec{v} = 100\text{ m/s}\hat{j}$. What is the spaceship's acceleration in component form? What is the magnitude of acceleration? What is the position as a function of time?



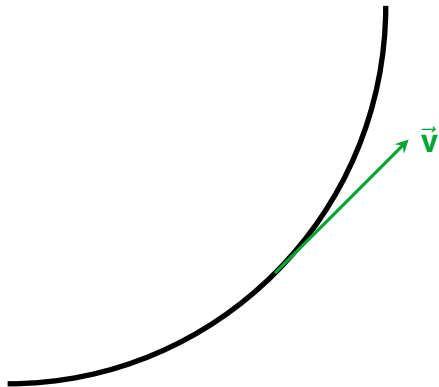
Vectors and motion

- Once we can move in more than one dimension, need to worry about *relative* direction of position, velocity, and acceleration
- In 1D, acceleration had to point either with velocity, or opposite
- But in 2 or 3D we can **turn**



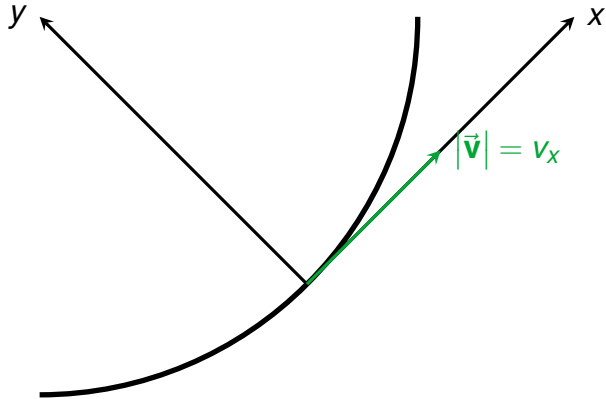
Does that make sense?

- Let's look at the *components* of \vec{a} with a good choice of axis



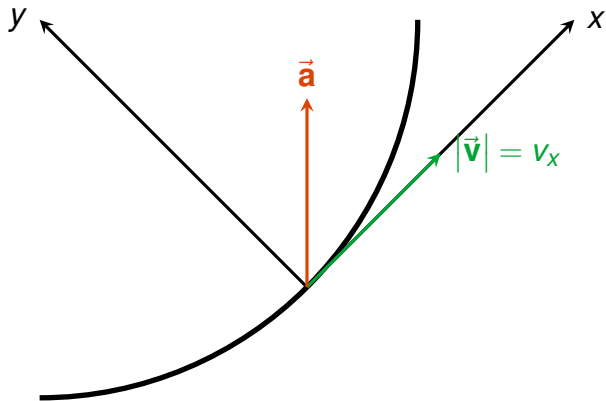
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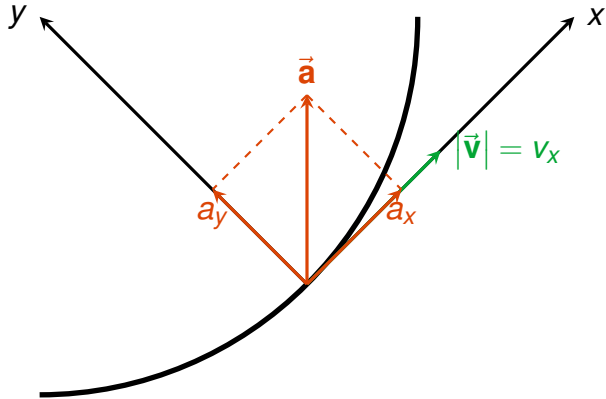
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Radial and tangential

- Velocity is always **tangential** to the path – that's basically its definition!
It tells you where you are going in the next instant of time

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- Velocity is always **tangential** to the path – that's basically its definition!
It tells you where you are going in the next instant of time
- Acceleration can have a **tangential** component – that makes you speed up or slow down
- And a **radial** component – that makes you turn!

Reminders

- Read sections 4.3 for next Tuesday and do pre-lecture questions
- First homework due tomorrow at recitation