## RECITATION QUESTIONS: PHYSICS WITH CRITTERS 14 FEBRUARY

Would you like your pets to star in a PHY211 problem? Last year our final exam was all students' dogs and cats doing stuff. Send their picture and a description of what they like to do to wafreema@syr.edu and they'll be famous!

Two very small cats, Ryan and Koa, are sitting on a smooth table when the table begins to tip. Ryan has a mass of  $m_r$  and Koa has a mass of  $m_k$ .

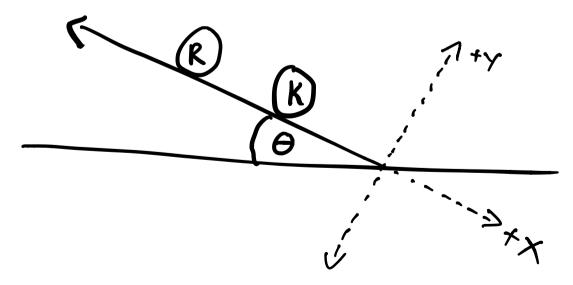
The coefficients of friction between the kitties and the table are the following (Koa is slightly fuzzier underneath since she has only three feet). Their masses are also given; it's up to you to determine if they matter.

	Ryan	Koa
$\mu_k$	0.4	0.3
$\mu_s$	0.5	0.4
mass (kg)	3.4	3.6

As the angle  $\theta$  between the table and the horizontal becomes larger and larger, eventually the cats will slide off the table.<sup>2</sup>

Remember two things about friction for this problem:

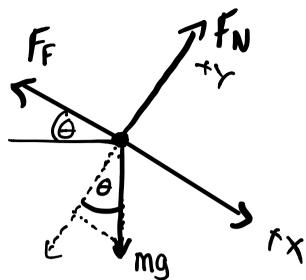
- 1. If two things are already sliding past one another, the force of kinetic friction between them is equal to  $\mu_k F_N$  in whatever direction opposes that motion;
- 2. If two things are not sliding, the force of static friction is however big it needs to be in order to stop them from sliding, up to a maximum of  $\mu_s F_N$ .
- a) Draw a cartoon of the problem, and choose a coordinate system. Recall what you learned last recitation about choosing coordinate systems that make your life easy.



<sup>&</sup>lt;sup>1</sup>This problem was inspired by the joke: "Q: Two kittens are sitting on a roof. Which one slides off first? A: The one with the smallest mew."

<sup>&</sup>lt;sup>2</sup>They will land on their feet, since they are graceful cats. Our previous physics cat Toby is a klutz and would land on her head and then whine for more dinner, which is why we're not using her for this problem. But she's cute.

b) Draw a force diagram for the cat. Make it nice and large, since you'll need to do trigonometry to decompose the weight force into components.



- c) Decompose the weight force into components. Do this as always: draw a right triangle with the weight force as its hypotenuse, and with its legs aligned with your coordinate system. Then, figure out which angle in the right triangle is the same as  $\theta$ . (Do this on your diagram above.)
- d) Write down Newton's second law  $\sum F = ma$  in both x- and y-directions.

$$Z^{7}F_{X} = Mg SIn(\theta) - F_{F} = Mq_{X}$$
  
 $Z^{7}F_{Y} = F_{N} - mg cos(\theta) = Mq_{Y}$ 

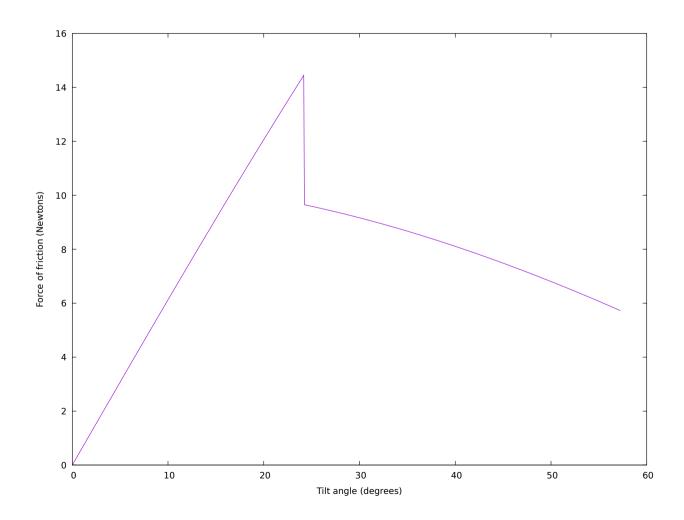
e) Right before the cat begins to slide off the table, what is true about the frictional force on them? Use this mathematical condition to solve for the angle  $\theta$  at which each cat begins to slip off the table.

Before they slide, 
$$F_F = F_{us} = Ms \cdot F_N$$
  
 $Mg Sin(\theta) - Ms F_N = 0$   $Mg Sin(\theta) - Ms Mg Mg Cos(\theta) - F_N = 0  $\Rightarrow$   $tan(\theta) = Ms$   
 $\theta_1 = Ryan$$ 

f) Right after Ryan begins to slide, what will his acceleration be? What will Koa's be?

mg sin(
$$\theta_1$$
) -  $M_S$  · mg cos( $\theta_1$ ) = ma  
 $a_R = g(sin(\theta_1) - M_{K_1} cos(\theta_1))$   
 $a_K = g(sin(\theta_2) - M_{K_1} cos(\theta_2))$ 

g) Here is a graph of the frictional force (whether static or kinetic) vs. tilt angle. Interpret as many of its features as you can; call your TA and/or coach over to join your conversation.

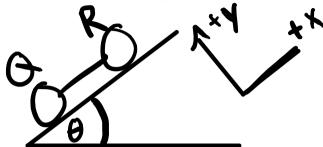


Last year, Ohana Benevides was our head TA; she has two adorable dogs, Rum and Quanta. Rum (pronounced "room") is a lot bigger than Quanta.

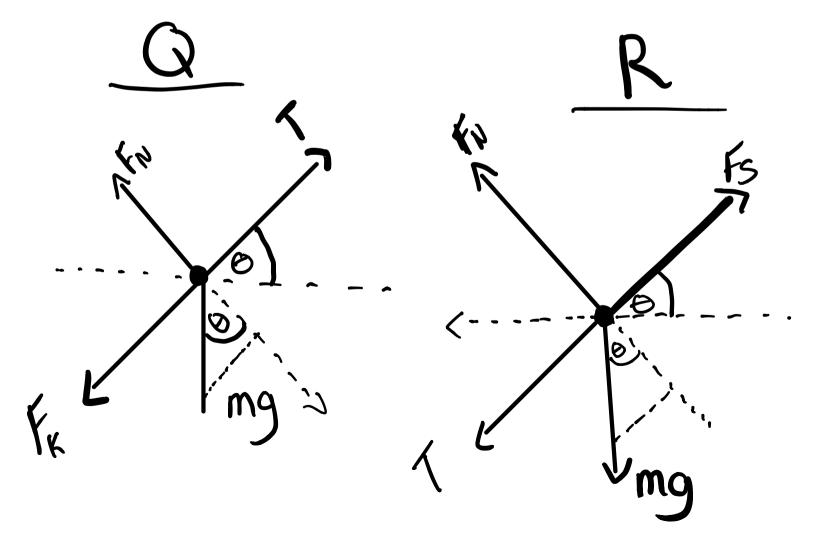
Rum has mass  $m_R$  and coefficient of static friction  $\mu_s$ ; Quanta and her sled have mass  $m_Q$  and coefficient of kinetic friction  $\mu_k$ . (Remember that traction is just a special kind of static friction, and so the maximum traction force that Rum can exert is also equal to  $\mu_s F_N$ .)

Rum is trying to pull Quanta and her sled up a hill sloping up at an angle  $\theta$  at a constant speed. In this problem, you'll solve for the steepest hill that they can climb.

a) Draw a cartoon of the problem, and choose a coordinate system.



b) Draw a force diagram for each dog.



c) Write down Newton's second law in both directions – that is, $\sum F_x = ma_x$ and $\sum F_y = ma_y$ – in both directions.	
TE T - E - Magsing = mag, 127E = T+E - magsing	9
$\sum F_{x} = T - F_{K} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g \sin\theta = m_{\alpha}a_{x} / \sum F_{x} = -1 + F_{x} - m_{\alpha}g$	ay
$\Sigma F_{y} = F_{N} - m_{g} \cos \theta = m_{q} $ $\Sigma F_{y} = F_{N} - m_{g} \cos \theta = m_{q} $	NR
d) This will result in four equations. Plug in things that you know. (What do you know about their accelerations?) This will result in four equations with four unknowns. What is true about the traction force on Rum when he's climbing the steepest hill that he can? Underneath each equation, identify the	·Υ
physical meaning of each term (i.e. "component of Quanta's weight parallel to the slope").	
ax is the same for both.	
T= Tension in the rope	
Fr = Force of Kinetic Friction of the sliding sled.	
ty = Force of static triction that kum reeks	
Fn: the force normal to the plane. It is equal to the vertical component of gravity.	
e) Discuss how you'd do the algebra to solve these equations; if you have time, work on doing so.  The tension is the same for both.	
T= maa + mag sin(8) + Mkmg cos(8) - ()	
T= Ms mgcos(0)-mrgsin0-mra -(2)	

maa+magsin & + Mk mg cos(b) = Ms mag cos - magsin & - mag
maa+ maa = Ms . mag cos(b) - magsin (b) - magsin & - Mk mg cos e

$$Q = \frac{m_R g(M_S \cdot \cos(\theta) - \sin(\theta)) - m_Q g(\sin \theta - M_K \cos \theta)}{m_Q + m_R}$$