

Exam 3 review; finishing up angular momentum

Physics 211
Syracuse University, Physics 211 Spring 2019
Walter Freeman

April 3, 2019

Announcements

- HW7 is due next Monday before the building closes to your TA's mailbox
- **Group exam 3: Friday during recitation.**
- **Exam 3: Tuesday during the normal time**

- HW7 is due next Monday before the building closes to your TA's mailbox
- **Group exam 3: Friday during recitation.**
- **Exam 3: Tuesday during the normal time**
- Upcoming review:
 - “Catchup” review: Thursday, my office, 1:45-3:45 (intended for students who feel behind)
 - Friday: we are hoping to have extra coaches in the Clinic 12-5
 - Saturday: 2:30-5:30, in the Clinic (moving to Stolkin if there is demand)

- HW7 is due next Monday before the building closes to your TA's mailbox
- **Group exam 3: Friday during recitation.**
- **Exam 3: Tuesday during the normal time**
- Upcoming review:
 - “Catchup” review: Thursday, my office, 1:45-3:45 (intended for students who feel behind)
 - Friday: we are hoping to have extra coaches in the Clinic 12-5
 - Saturday: 2:30-5:30, in the Clinic (moving to Stolkin if there is demand)
- No recitation next Wednesday (we'll be grading)
- Recitation next Friday: workshop for the paper

Format:

- Either four full-length problems, or three full-length problems and a few short answer questions
- Questions on work and energy, the conservation of momentum, and the conservation of angular momentum

Format:

- Either four full-length problems, or three full-length problems and a few short answer questions
- Questions on work and energy, the conservation of momentum, and the conservation of angular momentum

No individual reference sheets:

- We realized they hurt more than helped
- Today: suggest things to me that you want on your reference sheet
- I'll typeset it for you and give it to you on the exam

Conservation of angular momentum

These problems are approached in exactly the same way as conservation of *linear* momentum problems: write down expressions for L_i and L_f and set them equal (if there are no external forces that alter how things rotate, called *torques*).

$$L = I\omega$$

$$\sum L_i = \sum L_f$$

Conservation of angular momentum

If I kept the mass of the Earth the same, but enlarged it so that it had twice the diameter, how long would a day be?

(Remember, the total angular momentum, $L = I\omega$, stays the same)

A: 6 hours

B: 12 hours

C: 24 hours

D: 48 hours

E: 96 hours

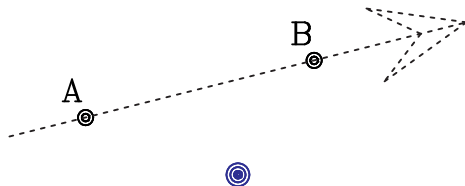
Angular momentum of a single object

A single object moving in a straight line also has angular momentum.

$$L = mv_{\perp}r = mvr_{\perp}$$

If we are to trust this relation, then the angular momentum of an object moving with constant \vec{v} should be constant!

Is the angular momentum the same at points A and B?



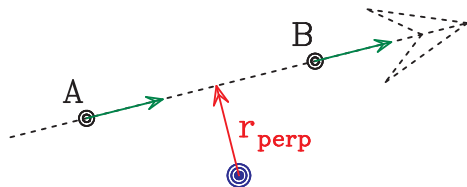
Angular momentum of a single object

A single object moving in a straight line also has angular momentum.

$$L = mv_{\perp}r = mvr_{\perp}$$

Is the angular momentum the same at points A and B?

Yes: r_{\perp} (and v) are the same at both points.



An example problem

How much will I speed up when I pull the dumbbells to my chest?

An example problem

A child of mass m runs at speed v straight east and jumps onto a merry-go-round of mass M and radius R , landing $2/3$ of the way toward the outside. If she lands south of the axis, how fast will it be turning once she lands?

We'll do this together on the document camera.

An example problem

A child of mass m runs at speed v straight east and jumps onto a merry-go-round of mass M and radius R , landing $2/3$ of the way toward the outside. If she lands south of the axis, how fast will it be turning once she lands?

We'll do this together on the document camera.

(The solution is on the next slide, for those studying these notes later)

The solution to our example

We use conservation of angular momentum:

$$\begin{aligned}\sum L_i &= \sum L_f \\ L_{\text{child},i} &= L_{\text{child}+\text{disk},f}\end{aligned}$$

Model the child as a point object moving at a constant velocity:

$$L_{\text{child},i} = mv_{\perp}r = \frac{2}{3}mvR$$

This gives us $\frac{2}{3}mvR = I_{\text{total}}\omega_f$. We now need I_{total} .

After the child jumps on, $I_{\text{total}} = I_{\text{disk}} + I_{\text{child}} = \frac{1}{2}MR^2 + \frac{2}{3}mR^2$. Thus,

$$\frac{2}{3}mvR = \left(\frac{1}{2}MR^2 + \frac{2}{3}mR^2 \right) \omega_f$$

Solve for ω_f :

$$\omega_f = \frac{\frac{2}{3}mvR}{\left(\frac{1}{2}MR^2 + \frac{2}{3}mR^2 \right)}$$

Review: Rotational kinetic energy

A rotating object carries kinetic energy too.

- Translational kinetic energy: $KE_{\text{trans}} = \frac{1}{2}mv^2$
- Rotational kinetic energy: $KE_{\text{rot}} = \frac{1}{2}I\omega^2$

I is the **moment of inertia**, a rotational analogue to mass.

- Depends on the mass distribution of an object, as well as the total mass
- $I = mR^2$, if all of the mass is a distance R from the axis of rotation
- For other objects $I = \lambda mR^2$, where λ depends on the object's shape
- The moment of inertia is larger if the mass is further from the center

Review: Rolling motion

If an object is *rolling without slipping*, it is both translating and rotating.

Its translational velocity v_{trans} is equal to ωr , where r is the radius of the part that is rolling.

Example: kinetic energy of a rolling cylinder ($I = \frac{1}{2}I\omega^2$)

$$\begin{aligned} KE &= KE_{\text{trans}} & + KE_{\text{rot}} &= \frac{1}{2}mv^2 & + \frac{1}{2}I\omega^2 \\ &= \frac{1}{2}mv^2 & + \frac{1}{2}\frac{1}{2}mr^2\omega^2 \\ &= \frac{1}{2}mv^2 & + \frac{1}{4}mv^2 \\ &= \frac{3}{4}mv^2 \end{aligned}$$

Review: The work-energy theorem

Work is the change in kinetic energy.

$$\frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 + W_{\text{all}} = \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2$$

Work = $\vec{F} \cdot \Delta\vec{s}$, or ...

- $F_{\parallel}\Delta s$ (component of force parallel to motion, times the distance moved)
- $F(\Delta s)_{\parallel}$ (force, times the distance moved in the direction of that force)
- $F\Delta s \cos \theta$ (either way, this is the trigonometry you wind up with)

Note that:

- Forces that are in the direction of motion increase the speed of objects, and do positive work
- Forces that are opposite the direction of motion decrease the speed of objects, and do negative work
- Forces perpendicular to the direction of motion do no work at all

Review: Potential energy

Potential energy is an alternate way of keeping track of the work done by conservative forces:

- $PE_{\text{grav}} = mgh$
- $PE_{\text{spring}} = \frac{1}{2}kx^2$

If you're tracking the work due to gravity or elasticity using potential energy, don't also include it in your work term. See the next slide:

Review: Conservation of energy

$$PE_i + \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 + W_{\text{other}} = PE_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2$$

Review: Conservation of energy

$$\begin{array}{ccccccc} \text{PE}_i & + & \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 & + & W_{\text{other}} & = & \text{PE}_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 \\ \text{(initial PE)} & + & \text{(initial KE)} & + & \text{(other work)} & = & \text{(final PE)} + \text{(final KE)} \end{array}$$

Review: Conservation of energy

$$\begin{array}{ccccccc} PE_i & + & \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 & + & W_{\text{other}} & = & PE_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 \\ \text{(initial PE)} & + & \text{(initial KE)} & + & \text{(other work)} & = & \text{(final PE)} + \text{(final KE)} \\ \text{(total initial mechanical energy)} & + & \text{(other work)} & = & \text{(total final mechanical energy)} \end{array}$$

Review: Conservation of energy

$$\begin{array}{ccccccc} PE_i & + & \frac{1}{2}mv_i^2 + \frac{1}{2}I\omega_i^2 & + & W_{\text{other}} & = & PE_f + \frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 \\ \text{(initial PE)} & + & \text{(initial KE)} & + & \text{(other work)} & = & \text{(final PE)} + \text{(final KE)} \\ \text{(total initial mechanical energy)} & + & & + & \text{(other work)} & = & \text{(total final mechanical energy)} \end{array}$$

Since conservation of energy is the broadest principle in science, it's no surprise that we can do this!

Power is just the rate of doing work.

Since velocity is the rate of being displaced, this gives us:

$$P = \vec{F} \cdot \vec{v}$$

What would you all like to talk about?