Walter **Zimmer**



Technical University of Munich (TUM)

School of Information, Computation and Technology (CIT)

Department of Computer Engineering (CE) Chair of Artificial Intelligence & Robotics

Schleissheimerstr. 90A, 85748 Garching (Munich), Germany

PhD, Machine Learning Research Associate

"It's a no-brainer for me that at some point our cars will have the ability to drive themselves." - Sebastian Thrun (Waymo co-founder)

☑ zimmer@cs.tum.edu

Munich, Germany

in LinkedIn

GitHub

☆ Homepage

€ Academic

Scholar

% +49 156 783 65392

Research Gate

(ID) ORCID

Youtube

◆ IEEE Xplore

Leet Code

HackerRank



SUMMARY

Machine Learning research associate with over 7 years of experience specializing in developing robust and real-time 3D computer vision algorithms for safety-critical systems. Proven ability to leverage multi-modal data (video, point cloud, text) for real-world applications, with 30+publications (15 first author, h-index: 13) in leading premier Al conferences and journals (CVPR, ECCV, ICCV, ICML, T-PAMI).

- 7 years of academic research, 6 years of industry experience in autonomous driving, computer vision & deep learning
- Awarded 1st Prize of IEEE ITSS Best Dissertation Award, \$2,000 P by IEEE Intelligent Transportation Systems Society (ITSS)
- Published >30 articles (15 first author): CVPR, ECCV, ICCV, ICML, T-PAMI, T-IV, ITSC, IV. Total: >720 citations, h-index: 13
- Studied at 4 universities (2 stays abroad in US & NL), Awarded 10 scholarships & awards (Best Student Paper & Thesis Awards)
- Obtained 46 training certificates, attended 19 conferences, supervised 44 student projects, lectured 4 seminars
- Developed 8 open-source software projects (>1,000 GitHub (2), participated in 6 hackathons, organized 13 int. workshops
- Reviewed 120 articles: 21 conf. & 10 journals, served as associate editor (ITSC, IJ-CAV), program chair (RSS'25, CAIP'25)



SKILLS

- Programming Languages: C++, Python, C, Java, C#, Go, JavaScript, TypeScript, MATLAB, Bash. >2,000 code commits.
- Tools: PyCharm, VS Code, Eclipse, Intelli], Colab, Blender, CARLA, Unreal Engine, Unity, ROS, Docker, Kubernetes, Git, UNIX
- · Libraries: PyTorch3D, TensorFlow, JAX, OpenCV, Open3D, NumPy, SciPy, Pandas, Matplotlib, Scikit-learn, spaCy, PCL, Ceres
- Methodologies: Agile, Scrum, Kanban, DevOps, MLOps, CI/CD, TDD, Pair Programming, Code Reviews, UML, Design Patterns
- Languages: German (native), English (fluent, Certificate: Level C2), Russian (fluent), Spanish (basic), French (basic), Dutch (basic)
- **Certifications**: **45 training certificates**: Udacity Self-Driving Car Engineer Nanodegree, Udacity: Intro to Artificial Intelligence, Udacity Intro to Machine Learning, Modern C++ Software Design, Self-Driving Cars Perception, Scientific Paper Writing
- · Soft Skills: Leadership, Communication, Teamwork, Problem Solving, Creativity, Time Management, Presentation Skills
- Research Skills: Literature Review, Experiment Design, Data Analysis, Paper Writing, Peer Review, Conference Presentation
- Academic Skills: Acad. Writing, Grant Writing, Funding Acquisition, Interviewing, Hiring, Mentoring, Workshop Organization
- Teaching Skills: Seminar Design, Lecture Preparation & Delivery, Assessment, Student Supervision, Curriculum Development
- Industry Skills: Tech. Project Management, Agile SW Development, Rapid Prototyping, Product Design, Entrepreneurship

RESEARCH INTERESTS

- Interests: Autonomous Driving, Machine Learning, Deep Learning, Computer Vision, Robotics, Software Engineering,
- Focus: 3D Perception, Multi-Object Tracking, Sensor Fusion, Vision-Language Models (VLMs), Cooperative Perception
- Applications: Autonomous Vehicles, Intelligent Transportation Systems, Digital Twins, Traffic Scene Understanding
- Techniques: Data Mining, Active Learning, Labeling Pipelines, Dataset Curation, Multi-Modal Sensor Fusion (Camera, LiDAR)
- Research Goals: Enhance 3D perception for autonomous driving, improve model generalization, develop robust sensor fusion
- Future Work: Apply vision-language models to understand traffic scenes, develop cooperative perception methods

Technical University of Munich (TUM), Chair of Al and Robotics (AIR)

Machine Learning Research Engineer, advised by: Prof. Dr.-Ing. habil. Alois C. Knoll

Munich, Germany
Mar 2020 — May 2025

- Focused on 3D perception (3D object detection, tracking and sensor data fusion) for AD (Python, C++, ROS, PyTorch, Open3D)
- Authored dissertation on Roadside 3D Perception for Autonomous Driving, 320 p., 135k words, defended on June 23, 2025
- · Awarded 1st Prize of IEEE ITSS Best Dissertation Award, \$2,000 pby IEEE Intelligent Transportation Systems Society (ITSS)
- ∘ Published 27 peer-reviewed articles within last 3 years: 15 conf. & 5 journal articles, ∑=723 citations, h-index: 13
 - 2025: 2x NeurlPS'25 (in review), ICML'25, 3x ICCV'25, 2x ITSC'25, ICVES'25 (in review), UniDAS-FAS'25, OJ-ITS'25 (IF:5.3)
 - 2024: 2x CVPR'24, ECCV'24, 2x ITSC'24, IV'24, T-PAMI'24 (IF:20.8), 3x T-IV'24 (IF:14.0)
 - 2023: ICCV'23, ITSC'23 (oral, IEEE ITSS Best Student Paper Award ♥, IV'23 (oral)
- Presented at I4 conferences: CVPR'24 (oral), ECCV'24, 2x ITSC'24, IV'24, 2x ITSC'23 (oral & panel discussion), IV'23 (oral), MobilTUM'23, VDI'23, IV'22 (oral), VDI'22, ITS World Congress'21, IV'19,
- Attended 19 conferences in total incl. Automated Driving Symposium '22, IV'21, TechAD'21, IV'20, IROS'20
- Reviewed 120 articles for 21 conferences (ICCV'25, CVPR'25, IROS'25, WACV'25, RSS'25, CoRL'25, IV'25, ITSC'25, CAIP'25, ECCV'24, ITSC'24, IV'24, ICCV'23, ITSC'23, IV'23, ITSC'22, IV'22, ITSC'21, IV'21, IV'20, IV'19), 10 journals (T-PAMI'25, R-AL'25, T-MM'25, T-ITS'25, T-PAMI'24, RA-L'24, T-ITS'24, RA-L'23, T-ITS'23, T-IV'24)
- Served as associate editor: ITSC & IJ-CAV, program chair for RSS'25 and CAIP'25, and session chair for ITSC'24 and IV'24
- Organized 13 workshops: ICCV'25, 2x CVPR'25, ITSC'25, 2x IV'25, CAIP'25, ECCV'24, 2x ITSC'24, IV'24, IV'24, IV'21
- Studied 8 TUM graduate school courses: Modern C++ Software Design, SCRUM Professional, MLOps, Entrepreneurial Thinking, 2x Leadership Seminar, Scientific Paper Writing, Dissertation Writing. Collected 16 ECTS
- Presented at 2 PhD retreats, studied Graph Neural Networks (GNNs) at DeepLearn'22 Summer School on Deep Learning
- Interviewed >100 students, supervised 44 student projects: 37 thesis students (7 with industry partners, e.g. BMW, Siemens, DLR, SETLabs): 2 ITS Bavaria Best Thesis Awards (Cash Prize: 2 x 500 EUR), guided 7 research assistants (HiWis)
- Lectured 4 seminars: Adv. Foundation & Perception Models for Aut. Driving (SS'25), 2x 3D Perception for Aut. Driving (WS'21/22, SS'22), Visual Feature Learning for Aut. Driving (SS'21), guest lecture at Uni. of California San Diego, UCSD, 2021
- Awarded 27 training certificates: Self-Driving Cars Perception (31h), Scientific Writing (2 days), Modern C++ (3 days)
- Developed 8 open-source software projects, e.g. 3D BAT, InfraDet3D, CoopDet3D, ActiveAnno3D: >1,000 GitHub
- Participated in 6 hackathons: HackaTUM: '16, '19 (1. place, 1,500 EUR \(\frac{1}{2}\)), '22, SDHacks' 18, WirVSVirusHackathon'20
- Uni. of California San Diego (UCSD), Lab for Intelligent and Safe Automobiles (LISA)

San Diego, USA

Visiting Scholar, 2 scholarships: PROMOS and StMWK, advised by: Prof. Dr. Mohan M. Trivedi

Sep 2018 — Mar 2019

- Implemented 3D BAT annotation toolbox to auto-label datasets, achieved 13,800 3D labels per hour, published paper at IV'19
- Collaborated with PhD students on 3D perception methods for autonomous driving, developed 3D object detection algorithms

TUDelft Delft University of Technology (TUD)

Master of Science, Computer Science

Delft, The Netherlands Sep 2017 — Mar 2018

- Awarded DAAD scholarship (Erasmus Program) to study I semester at Delft University of Technology, Netherlands
- Passed 10 courses (46 ECTS): Al, ML, CV, Software Engineering, Intelligent Vehicles and Dutch language course

Technical University of Munich (TUM)

Master of Science, Computer Science

Munich, Germany

Sep 2016 — Aug 2018

- Studied Autonomous Driving, Machine Learning, Deep Learning, Computer Vision, Robotics, Software Engineering
- Demonstrated CV project: Intelligent Garage Door Opening System at Living Lab Conn. Mobility (LLCM) conference
- Interned at AUDI AG: Master's thesis in multi-modal 3D object detection for autonomous driving, Grade: 1.3 (3.7/4.0 US)
- Passed 27 exams (7 in addition) and collected 161 ECTS credits instead of 120 required for the M.Sc. degree

№ DHBW Cooperative State University (DHBW)

Mosbach, Germany

Bachelor of Science, Dual Student in Computer Science, in coop. with SSI Schaefer IT Solutions GmbH

Sep 2013 — Sep 2016

- Studied ML, CV & SWE, dual study program. Submitted thesis on student projects each semester. Total: 210 ECTS credits
- Attended International Program of Engineering (IPE) in the final semester, passed 12 exams. Final GPA: 1.7 (3.3/4.0 US)

IIII Research Assistant

Technical University of Munich (TUM)

Mar 2020 — May 2025

Munich, Germany

- Coordinated 2 research projects: Providentia++ (2020-2022) and AUTOtech.agil (2022-2025)
- 1) Providentia++ (BMDV) (Mar 2020 Aug 2022):
- · Constructed and maintained the A9 Test Field for Autonomous Driving (8 sensor stations, 81 sensors, 20 Gbps data rate)
- Developed 3D perception algorithms and generated datasets (Python, C++, ROS, PyTorch3D, Open3D)
- · Created a live digital twin of the real traffic in a reconstructed map of the A9 Test Field in the CARLA simulator, enabling real-time traffic visualization (Python, C++, Unreal Engine, CARLA, Blender, ROS, Open3D, Docker, Git, UNIX)
- 2) AUTOtech.agil (Oct 2022 May 2025):
- Created an infrastructure intersection dataset and received the IEEE ITSS Best Student Paper Award at ITSC'23
- Streamed live digital twin on public website for the A9 Test Field for Aut. Driving (Python, Open3D, ROS, Docker, Git, UNIX)
- Calibrated and setup vehicle onboard sensors and infrastructure sensors (camera, LiDAR, GPS, IMU) for data collection
- Created TUMTraf V2X Cooperative Perception dataset (IEEE/CVF Conf. on Computer Vision and Pattern Recognition 2024)
- Implemented a framework for cooperative fusion of vehicle and infrastructure data based on camera and LiDAR sensors

STTech Autonomous Systems Engineer

Apr 2019 — Mar 2020

STTech GmbH Munich, Germany

- Developed intelligent self-driving highway agents for complex traffic scenarios in CARLA (Python, TensorFlow, C++)
- Built automatic navigation stacks for self-driving robots, local and global path planning (Python, C++, ROS)
- Calibrated vehicle onboard cameras and robots for data collection (Python, C++, OpenCV)
- Implemented automatic recommendation systems using NLP (Python, spaCy, Deep Graph Library (DGL)

Om Internship

Mar 2018 — Sep 2018

Ingolstadt, Germany

AUDI AG, Sensor Data Fusion Department

- Prototyped deep learning applications for autonomous driving
- Calibrated vehicle onboard sensors (camera, LiDAR) to improve sensor fusion (Python, C++, ROS, ADTF)
- Developed a point cloud annotation tool to label 3D objects in LiDAR data for training 3D object detectors (C++)
- Built 3D object detection pipelines for point cloud data based on PointNet++ and AVOD (Python, TensorFlow)
- Implemented 3D object detectors for multi-modal camera-LiDAR sensor fusion (Python, TensorFlow, C++, ADTF, Docker)
- Improved 86.5% of the ground truth frames of the AUDI dataset by applying custom correction methods

SIEMENS Research Assistant

Oct 2016 — Aug 2017

Siemens AG Munich, Germany

- Developed data extraction and filtering pipelines to process large-scale data (Python, NumPy, Pandas, SciPy)
- Implemented web-based visualization dashboards (JavaScript, NodeJS, AngularJS, d3.js, HTML5, CSS3)

Software Engineer SSI Schaefer IT Solutions GmbH

Sep 2013 — Feb 2018

Giebelstadt, Germany

- Implemented 3D simulations for warehouse automations (Java, OpenGL, LWJGL, WebGL, Three.js, WebSockets)
- Created data visualization and data analytic tools (web development): [avaScript, WebGL, Angular]S, Node]S, d3.js, HTML5
- Developed warehouse management software (Java, Java EE, JPA, JavaFX, Jenkins, JUnit, SQL, Hibernate, JIRA)
- Collaborated in a team of 4 to build the WAMAS Lighthouse Product using Java EE Server Architectures (Wildfly, EJB, JPA, CDI, REST and Microservices), Java SE Tools (Java RX, Java FX, XML, OPC/UA, Hibernate, SWT), and DevOps Tools (Scum, Git, Maven, Eclipse, Ant, NodelS, VS Code, Jenkins, JIRA)
- Obtained skills in Software Development Life Cycle (SDLC), Solution Architecture, Agile Methodologies, Spring Boot, Process Optimization, Product Development, Software/Enterprise Architecture, Gitlab, Team Management, Team Building

TUM Traffic Datasets (, O)

Mar 2020 — May 2025

- Curated datasets by hosting labeling events & using advanced tools to generate high-quality 3D labels
- Processed and retrieved data from rosbag recordings, implemented a data pipeline for the TUM Traffic Datasets
- Built data mining & labeling pipelines (Outcome: 12 Traffic Datasets), improved dataset quality for foundation models
- Applied active learning for data selection to reduce the labeling effort by 50%
- Balanced and augmented datasets to ensure diversity and representativeness in training data
- Awarded IEEE ITSS Best Student Paper Award at ITSC'23 for the TUM Traffic Intersection Dataset
- Computed detection and tracking metrics and evaluated methods on TUM datasets (>2,400 downloads)
- Curated TUMTraffic-VideoQA Dataset for multi-modal video question answering & robust perception of traffic scenarios
- Proposed benchmark with 3 new tasks: multi-choice video QA, referred object captioning & spatial-temporal grounding
- Evaluated and benchmarked model performance on public datasets (Waymo Open Dataset and nuScenes)

A9 Test Field for Autonomous Driving (20)

Mar 2020 — May 2025

- o Operated & maintained real-world Test Field for Autonomous Driving (8 sensor stations, 81 sensors, 20 Gbps data rate)
- Built scalable data infrastructures for the A9 Test Field, enabling real-time data storage, processing and visualization
- Developed end-to-end data pipelines for streaming digital twins of the traffic, integrating roadside sensor data
- Ensured 24/7 availability (99.99% uptime) of live digital twins from roadside sensors through maintenance and updates
- Innovated representations of digital twins with live 3D visualizations of the A9 Test Field for Autonomous Driving

Multi-Modal 3D Object Detection and Tracking (, 🐠)

Mar 2023 — Sep 2024

- Implemented a multi-task perception system integrating 3D object detection, 3D multi-object tracking, and segmentation
- Deployed perception models on infrastructure systems like the A9 Test Field, enabling real-time detection
- Developed a multi-modal sensor fusion architecture, evaluated on TUM Traffic Datasets, improved segmentation and detection accuracy by +29.83 mAP using deep fusion of camera and LiDAR data instead of late fusion
- Showed that fusing LiDARs with cameras improves 3D object detection by +1.90 mAP compared to camera-only
- Designed a training and evaluation pipeline for large-scale 3D object detection tasks, optimizing model performance
- Enhanced semantic segmentation models for roadside infrastructure perception
- Built a robust multi-object tracking system, enhancing temporal consistency in dynamic traffic scenarios

Cooperative Perception Using Vehicle and Roadside Infrastructure Data (,, @)

Mar 2023 — Sep 2024

- Developed a cooperative perception system (CoopDet3D), integrating vehicle and roadside infrastructure data
- Fused vehicle and roadside infrastructure sensor data (camera+LiDAR), enabling improved 3D object detection and tracking
- Achieved improvement of +14.36 mAP by fusing vehicle & roadside infrastructure data compared to vehicle data only
- Implemented a robust and real-time 3D tracking algorithm, enhancing perception in dynamic traffic environments
- Developed a transformer-based deep fusion model (CoopCMT), improved 3D mAP by +8.53 compared to vehicle data only

Accident Detection (, •)

Mar 2024 — May 2025

- · Led a group of students for an accident detection study, managed and directed students to work on the project
- Created digital traffic twins using cameras, radars, and LiDAR sensors (Python, C++, ROS, PyTorch, CARLA)
- Mined rare traffic scenarios in large datasets to enhance model generalization, particularly for edge cases like accidents
- Developed algorithms for long-tail detection by analyzing sensor data, insights include 12 detected real-world accidents
- Used JAX to optimize neural network training pipelines, resulting in a significant speedup of large-scale model deployments



TEACHING

SS 2025 Masterseminar - Advanced Foundation and Perception Models for Autonomous Driving (IN2107), TUM

SS 2022 Masterseminar - 3D Perception for Autonomous Driving (IN2107, IN4448), Technical Uni. of Munich

WS 2021/22 Masterseminar - 3D Perception for Autonomous Driving (IN2107, IN4448), Technical Uni. of Munich

SS 2021 Masterseminar - Visual Feature Learning for Autonomous Driving (IN2107, IN4959), TUM

Apr 14, 2021 ECE 285 Autonomous Driving Systems (Guest Lecture), University of California San Diego (UCSD)

SCHOLARSHIPS

- 2017: Awarded **DAAD** scholarship **?** for I semester at TU Delft University, NL. Passed **I0** courses in AD & ML
- ° 2018: Awarded **StMWK scholarship** Visiting Scholar research stay at Uni. of California San Diego, UCSD, LISA Lab, USA
- o 2019: Awarded **PROMOS scholarship** Visiting Scholar research stay at Uni. of California San Diego, UCSD, LISA Lab, USA

Awards

- ° 2025: Awarded 1st Prize of IEEE ITSS Best Dissertation Award, \$2,000 ♥ by IEEE Intelligent Transportation Systems Society
- 2023: IEEE ITSS Best Student Paper Award 👽 at IEEE International Conference on Intelligent Transportation Systems
- 2019: hackaTUM hackathon Challenge Winner Award. I. Place \P at AID challenge (121 teams in total), **Prize: 1,500 EUR**
- 2018: Nomination for **research stay at UCSD** (16% selection rate 👽) funded by Bavarian State Ministry of Science (StMWK)
- 2017: TUM ranking: Within the **best 28%** of master students after 3 semesters, passed 27 exams (131 ECTS)
- ∘ 2016: Awarded Bachelor's degree within the **best 10-20% 9** of students at DHBW Mosbach. GPA: 1.7 (3.3/4.0 US)

CERTIFICATES

- 2025 IEEE Intelligent Vehicles Symposium 2025, Cluj-Napoca, Romania.
 Participation Certificate. Workshop: DLIVA: Data-Driven Learning for Intelligent Vehicles
- 2025 **IEEE/CVF Computer Vision and Pattern Recognition Conference 2025, Nashville, USA.**Participation Certificate. Workshop: DriveX: Foundation Models for V2X-Based Cooperative Autonomous Driving
- 2024 ECVA European Conference on Computer Vision, Milano, Italy.
 Participation Certificate. Paper: Transfer Learning from Simulated to Real Scenes for Monocular 3D Object Detection
- 2024 IEEE International Conference on Intelligent Transportation Systems 2024, Edmonton, Canada.
 Participation Certificate. 2 paper presentations:
 WARM-3D: A Weakly-Supervised Sim2Real Domain Adaptation Framework for Roadside Monocular 3D Object Detection,
 GraphRelate3D: Context-Dependent 3D Object Detection with Inter-Object Relationship Graphs
- 2024 IEEE/CVF Computer Vision & Pattern Recognition Conference 2024, Seattle, USA.
 Participation Certificate. Paper presentation: TUMTraf V2X Cooperative Perception Dataset (CVPR'2024)
- 2024 IEEE Intelligent Vehicles Symposium 2024, Jeju Island, Korea. Participation Certificate. Paper presentation: ActiveAnno3D: An Active Learning Framework for Multi-Modal 3D Object Detection.
- 2023 Training Certificate: ADAS Validation. I day: Sim to real-world testing. Learn to validate ADAS systems.
- 2023 Training Certificate: Leadership Seminar in the Alps. Leadership skills, practical application of techniques, 16 hours.
- 2023 IEEE Intelligent Transportation Systems Conf. 2023, Bilbao, Spain. Participation Certificate. **Oral** paper presentation: TUMTraf Intersection Dataset: All You Need for Urban 3D Camera-LiDAR Roadside. **IEEE Best Student Paper Award**
- 2023 IEEE Intelligent Vehicles Symp. 2023, Anchorage, Alaska, USA. Oral paper presentation: InfraDet3D: Multi-Modal 3D Object Detection based on Roadside Infrastructure Camera and LiDAR Sensors.
- 2023 Training Certificate: Dissertation Writers' Workshop. Scientific and compelling writing, 14 hours.
- 2023 First Aid Training Certificate. First aid training for company first aiders, I day.
- 2022 TUM Hackathon (hackaTUM) Certificate. Rohde&Schwarz Object Detection Challenge, 3 days.
- 2022 Training Certificate: Leadership Seminar in the Alps. Leadership skills, practical application of techniques. 36 hours.
- 2022 Int. Gran Canaria Summer School on Deep Learning. Participation Certificate. 40 hours of lectures. 5 days.
- 2022 IEEE Intelligent Vehicles Symposium (IV 2022), Aachen, Germany. Participation Certificate. Oral paper presentation: A9-Dataset: Multi-Sensor Infrastructure-Based Dataset for Mobility Research.
- 2022 Int. Scientific Conf. Mobility & Transport, MobilTUM, Singapore. Participation Certificate. Paper presentation: Real-time and Robust 3D Object Detection with Roadside LiDARs.

- 2022 Training Certificate: MLOps Operationalizing Data Science. Bring ML models to production, kedro, 21 hours, 3 days.
- 2021 IEEE Intelligent Vehicles Symposium (IV 2021), Nagoya, Japan. Participation Certificate, 30 hours of presentations.
- 2021 Training Certificate: Scientific Paper Writing. Analyzing & evaluating papers, effective self-editing tools, 14 hours.
- SBS Training Certificate Safety-appropriate Behavior and Rescue.
 2 days safety course & exam: Rescue from high-altitude workplaces.
- Training Certificate: Scrum Basics and Scrum Master Exam Preparation.3 days: agile practices, Scrum Framework, Artifacts, Team, Events.
- 2021 Training Certificate: Develop your Entrepreneurial Thinking. Participation Certificate, TUM Graduate School, 11 hours.
- 2021 Training Certificate: Self-Driving Cars. Self-driving software stack and hardware (sensors), 35 hours.
- 2021 Training Certificate: Visual Perception for Self-Driving Cars. Calibration, Detection, Tracking, Segmentation, 31 hours.
- 2020 COVID-19 Hackathon Certificate. Participation Certificate. We-VS-Virus hackathon.
- 2020 Training Certificate: Modern C++ Software Design. Klaus Iglberger: Advanced C++ training, 3 days.
- 2020 IEEE Intelligent Vehicles Symposium (IV 2020), Las Vegas, USA. Certificate of Participation: 19 Oct to 13 Nov 2020.
- 2020 Training Certificate: Goal Setting Skills. Learn how to set and achieve your goals.
- 2020 Training Certificate: Algorithmic Toolbox (UCSD). Design efficient algorithms, 40 hours.
- 2019 Participation Certificate: TUM Hackathon (hackaTUM). Aut. Intelligent Driving (AID) Challenge Winner, 1,500 EUR Prize. Aut. generating 3D environments to enable the learning of self-driving AI models in a virtual environment.
- 2019 IEEE Intelligent Vehicles Symposium (IV 2019), Paris, France. Participation Certificate. Poster presentation: 3D BAT: A Semi-Automatic, Web-based 3D Annotation Toolbox for Full-Surround, Multi-Modal Data Streams, 5 days.
- 2019 UCSD HardHack Hardware Hackathon. 2-day-long hackathon.
- 2019 UCSD Entrepreneurship Certificate Program. Certified in entrepreneurship, 16 hours.
- 2019 UCSD Lean Six Sigma White and Yellow Belt Certificate. Certified in process and quality improvement, I day.
- 2018 UCSD Strengths-Based Leadership Training Certificate. 6 sessions to become a leader and know your strengths.
- 2018 iLead Leadership Development Program Certificate. Training for acquiring leadership skills, 10 sessions.
- 2018 SD Hacks (hackathon). Participation Certificate. Develop an automated RC car.
- 2018 Interpersonal Relationships Seminar Certificate. Training on intercultural communication.
- 2018 MOVE-II Satellite, IDP Certificate. Implementation of Mission Control Center, MOVE-II satellite, 14 months.
- 2017 Language certificate. DAAD English language certificate, level: C1.
- 2016 Intercultural Competence & Communication Certificate. Build intercultural communication skills, 3 days (17 hours).
- TUM Hackathon (HackaTUM) Certificate. Participation Certificate. Prototype development and presentation to jury and several companies. Smart Garage Door, 3 days.
- 2016 International Program in Engineering (IPE). International semester in Automation Systems Engineering (Automation, Simulative Engineering, Embedded Systems), passed 12 exams.
- 2014 Train the Trainer Certificate. Certified trainer, passed two exams.
- 2013 ACX Application Developer Certificate. Certified Java Application Developer.
- 2013 Physics Award Certificate. Certified for outstanding achievements in Physics.



- [1] Walter Zimmer, Christian Creß, Huu Tung Nguyen, Alois C. Knoll, "TUMTraf Intersection Dataset: All You Need for Urban 3D Camera-LiDAR Roadside Perception," in 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), oral, IEEE ITSS Best Student Paper Award , Sep. 2023, pp. 1030–1037. doi: 10.1109/ITSC57777.2023.10422289.
- [2] **Walter Zimmer**, Gerhard Arya Wardana, Suren Sritharan, Xingcheng Zhou, Rui Song, Alois C. Knoll, "TUMTraf V2X Cooperative Perception Dataset," in 2024 IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), Jun. 2024, pp. 22668–22677. doi: 10.1109/CVPR52733.2024.02139.
- [3] Walter Zimmer, Ross Greer, Xingcheng Zhou, Rui Song, Hu Cao, Daniel Lehmberg, Marc Pavel, Ahmed Alaaeldin Ghita, Akshay Gopalkrishnan, Holger Caesar, Mohan M. Trivedi, Alois C. Knoll, "Towards Vision Zero: The Accid3nD Dataset," in Accepted for IEEE/CVF International Conference on Computer Vision, ICCV, Honolulu, Hawai'i, USA, Oct. 2025, p. 10. doi: https://doi.org/10.48550/arXiv.2503.12095.
- [4] **Walter Zimmer**, Akshay Rangesh, Mohan Trivedi, "3D BAT: A Semi-Automatic, Web-based 3D Annotation Toolbox for Full-Surround, Multi-Modal Data Streams," in *Proc. of the IEEE IV Symposium*, 2019, pp. 1816–1821. doi: 10.1109/IVS.2019.8814071.
- [5] Christian Creß*, **Walter Zimmer***, Leah Strand*, Maximilian Fortkord*, Siyi Dai*, Venkatnarayanan Lakshminarasimhan*, Alois Knoll*, "A9-Dataset: Multi-Sensor Infrastructure-Based Dataset for Mobility Research," in 2022 IEEE Intelligent Vehicles Symposium (IV), oral, Jun. 2022, pp. 965–970. doi: 10.1109/IV51971.2022.9827401.
- [6] Walter Zimmer, Joseph Birkner, Marcel Brucker, Huu Tung Nguyen, Stefan Petrovski, Bohan Wang, Alois C. Knoll, "InfraDet3D: Multi-Modal 3D Object Detection based on Roadside Infrastructure Camera and LiDAR Sensors," in 2023 IEEE Intelligent Vehicles Symposium (IV), oral, Jun. 2023, pp. 1–8. doi: 10.1109/IV55152.2023.10186723.
- [7] Sondos Mohamed*, **Walter Zimmer***, Ross Greer, Ahmed Alaaeldin Ghita, Modesto Castrillón-Santana, Mohan Trivedi, Alois Knoll, Salvatore Mario Carta, Mirko Marras, "Transfer Learning from Simulated to Real Scenes for Monocular 3D Object Detection," in *Computer Vision ECCV 2024 Workshops*, A. Del Bue, C. Canton, J. Pont-Tuset, and T. Tommasi, Eds., Cham: Springer Nature Switzerland, 2025, pp. 309–325. doi: 10.1007/978-3-031-91813-1_20.
- [8] **Walter Zimmer**, Ross Greer, Xingcheng Zhou, Rui Song, Marc Pavel, Daniel Lehmberg, Ahmed Ghita, Akshay Gopalkrishnan, Mohan M. Trivedi, Alois C. Knoll, "Safety-Critical Learning for Long-Tail Events: The TUM Traffic Accident Dataset," in *Int. Conference on Robotics and Automation, 40th Anniversary (ICRA@40)*, Netherlands, Sep. 2024, p. 10.
- [9] Ahmed Ghita*, Bjørk Antoniussen*, **Walter Zimmer***, Ross Greer*, Christian Creß, Andreas Møgelmose, Mohan M. Trivedi, Alois C. Knoll, "ActiveAnno3D An Active Learning Framework for Multi-Modal 3D Object Detection," in 2024 IEEE Intelligent Vehicles Symposium (IV), Jun. 2024, pp. 1699–1706. doi: 10.1109/IV55156.2024.10588452.
- [10] **Walter Zimmer**, Jialong Wu, Xingcheng Zhou, Alois C. Knoll, "Real-Time And Robust 3D Object Detection with Roadside LiDARs," in *Proc. of the Int. Scientific Conference on Mobility and Transport: Mobility Innovations for Growing Megacities*, Singapore: Springer Nature, 2023, pp. 199–219. doi: 10.1007/978-981-19-8361-0_13.
- [11] **Walter Zimmer**, Ross Greer, Xingcheng Zhou, Rui Song, Marc Pavel, Daniel Lehmberg, Ahmed Ghita, Akshay Gopalkrishnan, Mohan Trivedi, Alois Knoll, "Enhancing Highway Safety: Accident Detection on the A9 Test Stretch Using Roadside Sensors," *16. Uni-DAS* e.V. Workshop Fahrerassistenzsysteme und automatisiertes Fahren (FAS), Feb. 2025, doi: 10.48550/arXiv.2502.00402.
- [12] **Walter Zimmer**, Emec Ercelik, Xingcheng Zhou, Xavier Jair Diaz Ortiz, Alois Knoll, "A Survey of Robust 3D Object Detection Methods in Point Clouds," [Under Review], doi: https://doi.org/10.48550/arXiv.2204.00106.
- [13] **Walter Zimmer**, Marcus Grabler, Alois Knoll, "Real-time and robust 3D object detection within road-side LiDARs using domain adaptation," [Under Review], 2022, doi: https://doi.org/10.48550/arXiv.2204.00132.
- [14] **Walter Zimmer**, Ramandika Pranamulia, Xingcheng Zhou, Mingyu Liu, Alois C. Knoll, "PointCompress3D A Point Cloud Compression Framework for Roadside LiDARs in Intelligent Transportation Systems," *Accepted for IEEE Int. Conf. on Intelligent Transportation Systems (ITSC)*, Nov. 2025, doi: 10.48550/arXiv.2405.01750.
- [15] **Walter Zimmer**, Carsten Müller, "Solving the Container Shipment Problem with the Focus on Special Goods Using Genetic Algorithms," [Under Review], [Online]. Available: https://rxiv.org/pdf/1911.0157v1.pdf
- [16] Xingcheng Zhou, Konstantinos Larintzakis, Hao Guo, **Walter Zimmer**, Mingyu Liu, Hu Cao, Jiajie Zhang, Venkatnarayanan Lakshminarasimhan, Leah Strand, Alois C. Knoll, "TUMTraffic-VideoQA: A Benchmark for Unified Spatio-Temporal Video Understanding in Traffic Scenes," *IEEE/CVF Int. Conf. on Machine Learning (ICML)*, 2025, doi: 10.48550/arXiv.2502.02449.

- [17] Rui Song, Chenwei Liang, Yan Xia, **Walter Zimmer**, Hu Cao, Holger Caesar, Andreas Festag, Alois Knoll, "CoDa-4DGS: Dynamic Scene Rendering with Context and Deformation Awareness for Autonomous Driving," *Accepted for IEEE/CVF International Conference on Computer Vision (ICCV 2025)*, 2025.
- [18] Ruiyang Hao, Haibao Yu, Jiaru Zhong, Chuanye Wang, Jiahao Wang, Yiming Kan, Wenxian Yang, Siqi Fan, Huilin Yin, Jianing Qiu, Yao Mu, Jiankai Sun, Li Chen, **Walter Zimmer**, Dandan Zhang, Shanghang Zhang, Mac Schwager, Ping Luo, Zaiqing Nie, "Research Challenges and Progress in the End-to-End V2X Cooperative Autonomous Driving Competition," *Accepted for IEEE/CVF International Conference on Computer Vision Workshop (ICCVW 2025)*, 2025.
- [19] Rui Song, Chenwei Liang, Hu Cao, Zhiran Yan, **Walter Zimmer**, Markus Gross, Andreas Festag, Alois Knoll, "Collaborative Semantic Occupancy Prediction with Hybrid Feature Fusion in Connected Automated Vehicles," in *IEEE/CVF Conf. on Computer Vision and Pattern Recognition (CVPR)*, Jun. 2024, pp. 17996–18006. doi: 10.1109/CVPR52733.2024.01704.
- [20] Aral Hekimoglu, Philipp Friedrich, **Walter Zimmer**, Michael Schmidt, Alvaro Marcos-Ramiro, Alois Knoll, "Multi-Task Consistency for Active Learning," in 2023 IEEE/CVF International Conference on Computer Vision Workshops (ICCVW), Oct. 2023, pp. 3407–3416. doi: 10.1109/ICCVW60793.2023.00366.
- [21] Xingcheng Zhou, Deyu Fu, **Walter Zimmer**, Mingyu Liu, Venkatnarayanan Lakshminarasimhan, Leah Strand, Alois C. Knoll, "WARM-3D: A Weakly-Supervised Sim2Real Domain Adaptation Framework for Roadside Monocular 3D Object Detection," in 2024 IEEE 27th International Conference on Intelligent Transportation Systems (ITSC), 2024, pp. 3489–3496. doi: 10.1109/ITSC58415.2024.10919929.
- [22] Xingcheng Zhou, Mingyu Liu, Ekim Yurtsever, Bare Luka Zagar, **Walter Zimmer**, Hu Cao, Alois C. Knoll, "Vision Language Models in Autonomous Driving: A Survey and Outlook," in *IEEE Trans. on Intelligent Vehicles, IF: 14.0*, 2024, pp. 1–20. doi: 10.1109/TIV.2024.3402136.
- [23] Mingyu Liu, Ekim Yurtsever, Jonathan Fossaert, Xingcheng Zhou, **Walter Zimmer**, Yuning Cui, Bare Luka Zagar, Alois C. Knoll, "A Survey on Autonomous Driving Datasets: Statistics, Annotation Quality, and a Future Outlook," in *IEEE Trans. on Intelligent Vehicles*, *IF*: 14.0, 2024, pp. 1–29. doi: 10.1109/TIV.2024.3394735.
- [24] Mingyu Liu, Ekim Yurtsever, Marc Brede, Jun Meng, Walter Zimmer, Xingcheng Zhou, Bare Luka Zagar, Yuning Cui, Alois C. Knoll, "GraphRelate3D: Context-Dependent 3D Object Detection with Inter-Object Relationship Graphs," in 2024 IEEE 27th International Conference on Intelligent Transportation Systems (ITSC), 2024, pp. 3481–3488. doi: 10.1109/ITSC58415.2024.10919972.
- [25] Salvatore Carta, Modesto Castrillón-Santana, Mirko Marras, Sondos Mohamed, Alessandro Sebastian Podda, Roberto Saia, Marco Sau, **Walter Zimmer**, "RoadSense3D: A Framework for Roadside Monocular 3D Object Detection," in *Proc. of ACM Conf. on User Modeling, Adaptation and Personalization (UMAP)*, Italy, Jun. 2024, pp. 452–459. doi: 10.1145/3631700.3665236.
- [26] Xinyi Li, Zijian Ma, Yinlong Liu, **Walter Zimmer**, Hu Cao, Feihu Zhang, Alois Knoll, "Transformation Decoupling Strategy based on Screw Theory for Deterministic Point Cloud Registration with Gravity Prior," *IEEE Trans. on Pattern Analysis and Machine Intelligence, IF:* 20.8, pp. 1–18, 2024, doi: 10.1109/TPAMI.2024.3442234.
- [27] Christian Creß, **Walter Zimmer**, Nils Purschke, Bach Ngoc Doan, Sven Kirchner, Venkatnarayanan Lakshminarasimhan, Leah Strand, Alois C. Knoll, "TUMTraf Event: Calibration and Fusion Resulting in a Dataset for Roadside Event-Based and RGB Cameras," in *IEEE Trans. on Intelligent Vehicles*, *IF*: 14.0, 2024, pp. 1–19. doi: 10.1109/TIV.2024.3393749.
- [28] Chuheng Wei, Ziye Qin, **Walter Zimmer**, Guoyuan Wu, Matthew J. Barth, "HeCoFuse: Cross-Modal Complementary V2X Cooperative Perception with Heterogeneous Sensors," *Accepted for IEEE Int. Conf. on Intelligent Transportation Systems (ITSC)*, 2025.
- [29] Lars Ullrich, **Walter Zimmer**, Ross Greer, Knut Graichen, Alois C. Knoll, Mohan Trivedi, "A New Perspective On Al Safety Through Control Theory Methodologies," *Accepted for IEEE Open Journal of Intelligent Transport. Systems, IF: 5.3*, Jun. 2025, doi: 10.48550/arXiv.2506.23703.
- [30] Raphael van Kempen, Markus Schön, Jonas Maier, Boris Böhlen, Gergely Bilkei-Gorzo, Esther Hekele, David Philipp Klüner, Fabian Thomsen, Kai-Björn Gemlau, Benedikt Schulz, Nils Gehrke, Matti Henning, Thomas Schulik, Philip Mayer, Lars Ullrich, **Walter Zimmer**, Martin Alfranseder, Timo Woopen, Felix Berkel, Björn Klamann, Richard Schubert, Markus Maurer, Max Hartmann, Moritz Berghöfer, Jens Giesler, Anton Kuznietsov, Dorsa Zaheri, Claudia Hannig, Stephan Rauber, Rolf Ernst, Eduardo Molinos, Dominik Neidhart, Stefan Leinen, David Brecht, Oleksandr Solomakha, Christian Geller, Hermann von Hasseln, Dieter Moormann, Bastian Lampe, Dominik Spychalski, Christian Kehl, Christian Creß, Steven Peters, Paul-David Rostocki, Stefan Katzenbeisser, Norbert Siepenkötter, Christoph Stiller, Nils Rack, Bernhard Rumpe, Knut Graichen, Melina Lutwitzi, Lotte

Wagner-Douglas, Dan Greiner, Lukas Jung, Marlon Steiner, Alexander Blödel, Valentyna Afanasenko, Deepak-Kumar Gautam, Jakob Bahle, Arlinda Elmazi, Kai Furmans, Lena Wirtz, Bassam Alrifaee, Marco Konersmann, Lutz Eckstein, Stefan Kowalewski, Ralph Mader, Dennis Niedballa, Lukas Zanger, Martin Lauer, Michael Buchholz, Swapnil Sunil Roge, Ingmar Kallfass, Robin Dehler, Thomas Specker, Jean-Pierre Busch, Marc Leuffen, Xingcheng Zhou, Nick Le Large, Ida Feger, Dominik Püllen, Heinrich Gotzig, Hans-Christian Reuss, Olaf Uszynski, Julius Beerwerth, Andreas Sailer, Felix Steinfurth, Markus Lienkamp, Martin Lilienthal, Gideon Arndt, Frank Diermeyer, Marcel Grandinetti, Lorenz Bayerlein, Charlotte Hermann, Alois Knoll, Klaus Dietmayer, Sebastian Abel, Mohamad Alayan, Christoph Krauß, Niklas Braun, Kaiwen Wang, Carlos Fernandez, "AUTOtech.agil: Architecture and Technologies for Orchestrating Automotive Agility," 2023. doi: https://doi.org/10.18154/RWTH-2023-09783.

- [31] Hu Cao, Xingzhuo Yan, Jiong Liu, Rui Song, **Walter Zimmer**, Yan Xia, Guang Chen, Alois Knoll, "Integrating Events and Frames with Energy-Driven Cross-Modality Fusion Module for Steering Prediction," *Neural Information Processing Systems (NeurIPS)* 2025, [Under Review], 2025.
- [32] Yuping Wang, Shuo Xing, Cui Can, Renjie Li, Hongyuan Hua, Kexin Tian, Zhaobin Mo, Xiangbo Gao, Keshu Wu, Sulong Zhou, Hengxu You, Juntong Peng, Junge Zhang, Zehao Wang, Mingxuan Yan, **Walter Zimmer**, Peiran Li, Chia-Ju Chen, Rui Song, Yue Huang, Ryan Rossi, Lichao Sun, Hongkai Yu, Zhiwen Fan, Frank Hao Yang, Yuhao Kang, Chenxi Liu, Eun Hak Lee, Xuan Di, Liu Ren, Alois Knoll, Xiaopeng Li, Shuiwang Ji, Xinyue Ye, Masayoshi Tomizuka, Marco Pavone, Tianbao Yang, Jing Du, Ming-Hsuan Yang, Hua Wei, Ziran Wang, Yang Zhou, Jiachen Li, Zhengzhong Tu, "Generative Al for Autonomous Driving: Frontiers and Opportunities," *Neural Information Processing Systems (NeurIPS)* 2025, [Under Review], p. 10, 2025.
- [33] Jiajie Zhang, Mingyu Liu, Xingcheng Zhou, **Walter Zimmer**, Christian Creß, Venkatnarayanan Lakshminarasimhan, Leah Strand, Alois C. Knoll, "TUMTraf CrossVision: A Multi-View Multi-Modal Vision Dataset for Arterial Intersection Traffic Surveillance," Submitted to IEEE International Conference on Vehicular Electronics and Safety (ICVES). [Under Review], 2025.
- [34] Yuping Wang, Shuo Xing, Cui Can, Renjie Li, Hongyuan Hua, Kexin Tian, Zhaobin Mo, Xiangbo Gao, Keshu Wu, Sulong Zhou, Hengxu You, Juntong Peng, Junge Zhang, Zehao Wang, Rui Song, Mingxuan Yan, **Walter Zimmer**, Xingcheng Zhou, Peiran Li, Zhaohan Lu, Chia-Ju Chen, Yue Huang, Ryan A. Rossi, Lichao Sun, Hongkai Yu, Zhiwen Fan, Frank Hao Yang, Yuhao Kang, Ross Greer, Chenxi Liu, Eun Hak Lee, Xuan Di, Xinyue Ye, Liu Ren, Alois Knoll, Xiaopeng Li, Shuiwang Ji, Masayoshi Tomizuka, Marco Pavone, Tianbao Yang, Jing Du, Ming-Hsuan Yang, Hua Wei, Ziran Wang, Yang Zhou, Jiachen Li, Zhengzhong Tu, "Generative Al for Autonomous Driving: Frontiers and Opportunities," [Under Review], p. 129, 2025, doi: https://doi.org/10.48550/arXiv.2505.08854.
- [35] Alois Knoll, Mingyu Liu, Xingcheng Zhou, Christian Creß, **Walter Zimmer**, "Real-time Digital Twins for Intelligent Traffic Systems," *Accepted as Book Chapter in Foundations of Digital Twins*. Elsevier, p. 24, 2025.
- ★ equal contribution

THESIS

- 2024 PhD Thesis: Roadside 3D Perception for Autonomous Driving, IEEE ITSS Best Dissertation Award, 1st Prize, \$2,000 P. TUM
- 2018 **Master's Thesis:** Automatic Correction of 3D Ground Truth Information for Piloted Driving Functions based on Velodyne Point Clouds and Camera Images Using Deep Learning Methods. Technical University of Munich (TUM) in cooperation with AUDI AG
- 2016 **Bachelor's Thesis:** Development of a 3D Simulation Environment for Warehouse Automation Systems. Cooperative State University (DHBW) Mosbach in cooperation with SSI Schaefer IT Solutions GmbH

STUDENT RESEARCH ASSISTANT SUPERVISION (7 STUDENTS)

Suren Sritharan: Monocular 3D Object Detection	Oct 2021 — July 2022
 Maximilian Leonhard Schmid: 2D Web-based Visualization of Digital Twins 	Oct 2021 — July 2022
 Umaid Bin Zubair: 3D Visualization of Digital Twins 	Oct 2021 — July 2022
Zumrud Shukurlu: Sensor Calibration	Oct 2021 — July 2022
Mansoor Nasir Cheema: Monocular 3D Object Detection	Aug 202 I — July 2022
Siyi Dai: Sensor Calibration and Data Annotation	Aug 2021 — July 2022
Marcel Bruckner: Sensor Calibration and Stabilization	Aug 2021 — July 2022

STUDENT SUPERVISION (37 STUDENTS)

Supervised 3D Perception on Roadside LiDARs Under Different Weather Situations Chaima Ghaddab	Jan 2024 — July 2024 <i>Master's Thesi</i> s
Domain Adaptation for Road-Side Vision-Based 3D Object Detection Deyu Fu	Jan 2024 — July 2024 <i>Master's Thesis</i>
Real-time Multi-view Road-side 3D Object Detection Samyak Jain	Jan 2024 — July 2024 <i>Master's Thesis</i>
Real-Time Point Cloud Compression on Roadside LiDARs Ramandika Pranamulia	Oct 2023 — Mar 2024 Guided Research Thesis
Accident Detection on the A9 Test Stretch Using Roadside Sensors Marc Pavel	Oct 2023 — Mar 2024 Interdisciplinary Project Thesis
Accident Detection on the A9 Test Stretch Using Roadside Sensors Daniel Lehmberg	Oct 2023 — Mar 2024 Interdisciplinary Project Thesis
■ 3D Tracking on Roadside LiDARs Vitus Becker	Oct 2023 — Feb 2024 Bachelor's Thesis
Monocular Roadside 3D Perception based on Ammodal Instance Segmentation Bach Ngoc Doan	Oct 2023 — Feb 2024 Bachelor's Thesis
■ Vehicle-Infrastructure Cooperative 3D Object Detection to Support Autonomous Driving Functions Suren Sritharan	Jan 2023 — Dec 2024 Interdisciplinary Project Thesis
■ Camera-LiDAR Fusion Using On-board Vehicle and Infrastructure Sensors ITS Bavaria Best Master's Thesis Award 2023, Price: 500 EUR Gerhard Wardana	Apr 2023 — Oct 2023 Master's Thesis
Active Learning for 3D Object Detection and Labeling Ahmed Alaaeldin Ghita	Apr 2023 — Dec 2023 Master's Thesis
Multi-Modal 3D Object Detection in Long Range and Low-Resolution Conditions of Sensors Egemen Kopuz	Mar 2023 — Nov 2023 Master's Thesis
Point Clouds Localization Using Vehicle and Infrastructure LiDARs Omar Elsobky	Jan 2023 — Dec 2023 <i>Master's Thesis</i>
Real-Time 3D Object Detection on Infrastructure LiDARs using Transformers Tung Nguyen	May 2022 — Aug 2023 Interdisciplinary Project Thesis
Multi-Vehicle Detection and Tracking in Aerial Image Sequences based on Deep Learning Somesh Khandelia	Oct 2022 — Apr 2023 Master's Thesis
■ Deep Multimodal Sensor Fusion for 3D Perception in Autonomous Vehicles Using Occupancy Networks ITS Bavaria Best Master's Thesis Award 2023, Price: 500 EUR Omar Zayed	Nov 2022 — May 2023 Master's Thesis
Improving the Realism of a Real-Time Digital Twin of Road Traffic Using the CARLA Simulator Robin Brase	Oct 2022 — Feb 2023 Bachelor's Thesis
■ Monocular 3D Object Detection Using HD Maps Joseph Birkner	June 2022 — May 2023 Master's Thesis
Real-Time and Multi-Modal 3D Object Detection on the Autonomous Driving Test Stretch Using Camera and LiDAR Sensors Stefan Petrovski	June 2022 — Feb 2023 <i>Master's Thesi</i> s

Automatic Calibration of Infrastructure LiDAR and Camera Sensors Bohan Wang	May 2022 — Jan 2023 <i>Master's Thesis</i>
■ Monocular 3D Object Detection on Infrastructure Cameras using Transformers Anna Fedorova	Mar 2022 — Aug 2022 Guided Research Thesis
■ proAnno - An Automatic and Intelligent 3D Sensor Data Annotation Framework for Autonomous Driving Georgiy Nefedov	Mar 2022 — July 2022 Bachelor's Thesis
Unsupervised LiDAR-based 3D Object Detection Using Infrastructure Sensors Marcel Brucker	Mar 2022 — Nov 2022 <i>Master's Thesis</i>
A Neural Network-based Scenario Detection Framework for Road Perception Ugurcan Polat	Nov 2021 — May 2022 Master's Thesis
Multi-Task Active Learning for Autonomous Driving Philipp Friedrich	Nov 2021 — May 2022 Master's Thesis
Accident Prevention Backend Framework to Support Autonomous Driving Noir Nigmatov	Nov 2021 — May 2022 <i>Master's Thesis</i>
Real-Time and Robust 3D Object Detection within Multi LiDAR Systems on the Autonomous Driving Test Stretch Using Cross-Sensor Domain Adaptation Marcus Grabler	Nov 2021 — May 2022 <i>Master's Thesis</i>
■ Traffic Trajectory Prediction Framework within Providentia++ Using HD Maps Jurek Olden	Nov 2021 — May 2022 <i>Master's Thesis</i>
Accident Prevention Frontend Framework to Support Autonomous Driving Mohammad Nannaa	Nov 2021 — Mar 2022 Bachelor's Thesis
Real-Time Monocular 3D Object Detection to Support Autonomous Driving Leon Blumenthal	Oct 2021 — Feb 2022 Bachelor's Thesis
Deep Traffic Scenario Mining, Detection, Classification and Generation on the Autonomous Driving Test Stretch using the CARLA Simulator Aaron Kaefer	Apr 2021 — Feb 2022 Master's Thesis
■ Traffic Trajectory Prediction Framework within Providentia++ Jurek Olden	Dec 2020 — July 2021 Guided Research Thesis
Real-Time and Multi-Modal 3D Object Detection on the Providentia++ Test Stretch Maximilian Fortkord	May 2021 — Dec 2021 <i>Master's Thesis</i>
Real-time LiDAR-based 3D Object Detection on the Providentia++ Test Stretch Using a Single-Stage Architecture Jialong Wu	Apr 2021 — Dec 2021 <i>Master's Thesis</i>
Real-Time and Multi-Modal 3D Object Detection for Autonomous Driving Xavier Diaz	Nov 2020 — Oct 2021 Master's Thesis
■ Vehicle Position Estimation on Surveillance Dynamic Vision Sensor Armin Baur	Nov 2020 — Sep 2021 Master's Thesis
LiDAR-based 3D Object Detection on the Highway A9 Xingcheng Zhou	Oct 2020 — Nov 2021 Master's Thesis

TALKS

June 23, 2025	Roadside 3D Perception for Autonomous Driving, Final PhD Defense Presentation, Munich Germany
June 12, 2025	Roadside 3D Perception for Autonomous Driving , IEEE/CVF Computer Vision and Pattern Recognition Conference 2025, Nashville, USA
Mar 31, 2025	Enhancing Highway Safety: Accident Detection on the A9 Test Stretch Using Roadside Sensors , 16. Uni-DAS e.V. Workshop Fahrerassistenzsysteme und automatisiertes Fahren (FAS) 2025, Irsee, Germany
Sep 30, 2024	Transfer Learning from Simulated to Real Scenes for Monocular 3D Object Detection , ECVA European Conference on Computer Vision (ECCV), Milan, Italy
Sep 27, 2024	GraphRelate3D: Context-Dependent 3D Object Detection with Inter-Object Relationship Graphs, IEEE International Conference on Intelligent Transportation Systems (ITSC), Edmonton, Canada
Sep 27, 2024	WARM-3D: A Weakly-Supervised Sim2Real Domain Adaptation Framework for Roadside Monocular 3D Object Detection, IEEE International Conference on Intelligent Transportation Systems (ITSC), Edmonton, Canada
Sep 23, 2024	Safety-Critical Learning for Long-Tail Events: The TUM Traffic Accident Dataset, International Conference on Robotics and Automation, 40th Anniversary (ICRA40), Rotterdam, Netherlands
June 21, 2024	TUMTraf V2X Cooperative Perception Dataset , IEEE/CVF Conference on Computer Vision and Pattern Recognition, Seattle, WA, USA, Poster Presentation.
June 3, 2024	ActiveAnno3D: An Active Learning Framework for Multi-Modal 3D Object Detection, IEEE Intelligent Vehicles Symposium (IV), Jeju Island, Korea, Poster presentation.
Dec 19, 2023	A9 Test Field for Autonomous Driving, Munich Datageeks, Munich, Germany, Invited talk
Sep 30, 2023	TUMTraf Intersection Dataset: All You Need for Urban 3D Camera-LiDAR Roadside Perception, Best Student Paper Award . IEEE Int. Conf. on Intelligent Transportation Systems (ITSC), Spain, oral presentation.
Sep 24, 2023	Building Reliable Datasets for Autonomous Vehicles , IEEE International Conference on Intelligent Transportation Systems Workshop (ITSC), Bilbao, Spain, Panel discussion
June 6, 2023	InfraDet3D: Multi-Modal 3D Object Detection based on Roadside Infrastructure Camera and LiDAR Sensors, IEEE Intelligent Vehicles Symposium (IV), Anchorage, AK, USA, Oral presentation.
June 6, 2022	A9-Dataset: Multi-Sensor Infrastructure-Based Dataset for Mobility Research , IEEE Intelligent Vehicles Symposium (IV), Aachen, Germany, Oral presentation.
Apr 7, 2022	Real-Time And Robust 3D Object Detection with Roadside LiDARs, 12th International Scientific Conference on Mobility and Transport: Mobility Innovations for Growing Megacities, Oral presentation.
Oct 13, 2021	Creating a Real-time Digital Twin of the Traffic - From Sensor Data to Virtualization, ITS World Congress, Hamburg, Germany, Oral presentation.
Apr 14, 2021	3D Bounding Box Annotation (3D BAT) Toolbox and Its Application in 3D Object Detection , University of California San Diego (UCSD), Guest Lecture
June 9, 2019	3D BAT: A Semi-Automatic, Web-based 3D Annotation Toolbox for Full-Surround, Multi-Modal Data Streams, IEEE Intelligent Vehicles Symposium (IV), Paris, France, Poster presentation.

ACADEMIC SERVICE

Associate Editor:

0	2025	IEEE International	Conference on	Intelligent	Transportation S	vstems

Program Chair:

。 2025	RSS Robotics Science and Systems 2025		RSS'25		
。 2025	International Conference in Computer Analysis of Image Processing 2025				
Session C	Session Chair:				
。 2024	IEEE International Conference on Intelligent Transportation Systems 2024		ITSC'24		
。 2024	IEEE Intelligent Vehicles Symposium 2024		IV'24		
Journal R	Reviewer				
。 2025	IEEE Transactions on Pattern Analysis and Machine Intelligence 2025	IF: 20.8	T-PAMI'25		
。 2025	IEEE Robotics and Automation Letters 2025	IF: 4.6	RA-L'25		
。 2025	IEEE Transactions on Multimedia 2025	IF: 8.4	T-MM'25		
。 2025	IEEE Transactions on Intelligent Transportation Systems 2025	IF: 7.9	T-ITS'25		
。 2024	IEEE Transactions on Pattern Analysis and Machine Intelligence 2024	IF: 20.8	T-PAMI'24		
。 2024	IEEE Robotics and Automation Letters 2024	IF: 4.6	RA-L'24		
。 2024	IEEE Transactions on Intelligent Transportation Systems 2024	IF: 7.9	T-ITS'24		
。 2024	IEEE Transactions on Intelligent Vehicles 2024	IF: 14.0	T-IV'24		
。 2023	IEEE Robotics and Automation Letters 2023	IF: 4.6	RA-L'23		
。 2023	IEEE Transactions on Intelligent Transportation Systems 2023	IF: 7.9	T-ITS'23		
Conferer	nce Reviewer				
。 2025	IEEE International Conference on Robot Learning 2025		CoRL'25		
。 2025	IEEE/CVF International Conference on Computer Vision 2025		ICCV'25		
。 2025	IEEE/RSJ International Conference on Intelligent Robots and Systems 2025		IROS'25		
。 2025	IEEE/CVF Conference on Computer Vision and Pattern Recognition 2025		CVPR'25		
。 2025	IEEE/CVF Winter Conference on Applied Computer Vision 2025		WACV'25		
。 2025	RSS Robotics Science and Systems 2025		RSS'25		
。 2025	IEEE International Conference on Intelligent Transportation Systems 2025		ITSC'25		
。 2025	IEEE Intelligent Vehicles Symposium 2025		IV'25		
。 2025	International Conference in Computer Analysis of Image Processing 2025		CAIP'25		
。 2024	ECVA European Conference on Computer Vision 2024		ECCV'24		
。 2024	IEEE International Conference on Intelligent Transportation Systems 2024		ITSC'24		
。 2024	IEEE Intelligent Vehicles Symposium 2024		IV'24		
。 2023	IEEE International Conference on Computer Vision 2023		ICCV'23		
。 2023	IEEE International Conference on Intelligent Transportation Systems 2023		ITSC'23		
。 2023	IEEE Intelligent Vehicles Symposium 2023		IV'23		
。 2022	IEEE International Conference on Intelligent Transportation Systems 2022		ITSC'22		
。 2022	IEEE Intelligent Vehicles Symposium 2022		IV'22		
。 2021	IEEE International Conference on Intelligent Transportation Systems 2021		ITSC'21		
。 2021	IEEE Intelligent Vehicles Symposium 2021		IV'2I		
。 2020	IEEE Intelligent Vehicles Symposium 2020		IV'20		
。 2019	IEEE Intelligent Vehicles Symposium 2019		IV'19		



- Nov 18, 2025 **Walter Zimmer**, Ross Greer, Rui Song, Xingcheng Zhou, Max Ronecker, Chuheng Wei, Lars Ullrich, Haibao Yu, Christian Geller, Jiajie Zhang, Stephany Berrio Perez, Alina Roitberg, Daniel Watzenig, Zhengzhong Tu, Jiaqi Ma, Holger Caesar, Mohan Trivedi, Alois C. Knoll, DriveX 3rd Workshop on Foundation Models for V2X-Based Cooperative Autonomous Driving, IEEE Int. Conf. on Intelligent Transportation Systems (ITSC) 2025, Australia
- Nov 18, 2025 Ross Greer, Mohan Trivedi, **Walter Zimmer**, Max Ronecker, Vision and Language-Oriented Representations (VALOR): 2nd Workshop on Semantics, Safety, and Explainability in Intelligent Transportation Systems, IEEE Int. Conference on Intelligent Transportation Systems (ITSC) 2025, Gold Coast, Australia
- Oct 19, 2025 **Walter Zimmer**, Ross Greer, Chuheng Wei, Max Ronecker, Haibao Yu, Rui Song, Xingcheng Zhou, Jiajie Zhang, Stephany Berrio Perez, Akshay Gopalkrishnan, Lars Ullrich, Zewei Zhou, Tianhui Cai, Yifan Liu, Haoxuan Ma, Alina Roitberg, Daniel Watzenig, Jiaqi Ma, Holger Caesar, Mohan Trivedi, Alois C. Knoll, DriveX 2nd Workshop on Foundation Models for V2X-Based Cooperative Autonomous Driving, IEEE/CVF International Computer Vision Conference (ICCV) 2025, Honolulu, Hawai'i, USA
- Sep 19, 2025 **Walter Zimmer**, Ross Greer, Sondos Mohamed, Andrea Atzori, Max Ronecker, Chuheng Wei, Haibao Yu, Rui Song, Xingcheng Zhou, Holger Caesar, Stephany Berrio Perez, Alina Roitberg, Daniel Watzenig, Salvatore Carta, Modesto Castrillón-Santana, Mirko Marras, Jiaqi Ma, Matthew Barth, Brendan Morris, Stewart Worrall, Mohan Trivedi, Alois C. Knoll, Challenges and Advances in V2X-Driven Scene Understanding for Smart Cities, The Int. Conference in Computer Analysis of Images and Patterns (CAIP) 2025, Las Palmas de Gran Canaria, Spain
- June 11, 2025 **Walter Zimmer**, Ross Greer, Max Ronecker, Chuheng Wei, Haibao Yu, Rui Song, Xingcheng Zhou, Holger Caesar, Stephany Berrio Perez, Alina Roitberg, Daniel Watzenig, Mohan Trivedi, Alois C. Knoll, DriveX 1st Workshop on Foundation Models for V2X-Based Cooperative Autonomous Driving, IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR) 2025, Nashville, USA
- June 11, 2025 Haibao Yu, Jianing Qiu, Yao Mu, Jiankai Sun, Li Chen, Walter Zimmer, Jiaru Zhong, Dandan Zhang, Fei Gao, Shanghang Zhang, Mac Schwager, Ping Luo, Zaiqing Nie, 2nd MEIS Workshop on Multi-Agent Embodied Intelligent Systems Meet Generative-Al Era: Opportunities, Challenges and Futures, IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR) 2025, Nashville, USA
- June 22, 2025 **Walter Zimmer***, Ross Greer*, Felix Hauser*, Madhumitha Sakthi*, Mohan Trivedi*, Frank Bieder*, Mert Keser, Florian Geissler, Jörg Reichardt, Ömer Şahin Taş, Christoph Stiller, Akshay Gopalkrishnan, Rui Song, Max Ronecker, Xingcheng Zhou, Andrei Bulzan, Banglore Ravi Kiran, Senthil Yogamani, Chuheng Wei, Lars Ullrich, Christian Geller, Stephany Berrio Perez, Holger Caesar, Alois C. Knoll, Workshop on Data-Driven Learning for Intelligent Vehicle Applications, IEEE Intelligent Vehicles Symposium (IV'25), Cluj-Napoca, Romania
- June 22, 2025 Meng Lu, Christian Geller, Raphael van Kempen, Lutz Eckstein, Michael Buchholz, Frank Diermeyer, Timo Woopen, Walter Zimmer, Adrian Zlocki, 14th Workshop and Industry Panel on Cooperative Automated Driving and Future Mobility Systems, IEEE Intelligent Vehicles Symposium (IV'25), Cluj-Napoca, Romania
- Sep 27, 2024 Mohan M. Trivedi*, Ross Greer*, **Walter Zimmer***, Stephany Berrio Perez, Nachiket Deo, Xingcheng Zhou, Akshay Gopalkrishnan., Vision and Language Oriented Representation (VALOR): Topics in Semantics, Safety, and Explainability in Intelligent Transportation, IEEE Int. Conf. on Intelligent Transportation Systems (ITSC'24)
- Sep 29, 2024 Haibao Yu*, **Walter Zimmer***, Jianing Qiu, Jiankai Sun, Li Chen, Mac Schwager, Ping Luo, Ruigang Yang, Si Liu, Zaiqing Nie, Multi-Agent Autonomous Systems Meet Foundation Models: Challenges and Futures, 18th IEEE European Conference on Computer Vision 2024 (ECCV'24), Milano, Italy
- June 2, 2024 **Walter Zimmer**, Rui Song, Bernd Gaßmann, Stephany Berrio Perez, Christian Creß, Xingcheng Zhou, Alois C. Knoll, 5th Workshop on Data-Driven Intelligent Vehicle Applications (DDIVA'24), IEEE Intelligent Vehicles Symposium (IV'24), Jeju Island, Korea
- June 4, 2023 **Walter Zimmer**, Christian Creß, Bernd Gaßmann, Emeç Erçelik, Neslihan Köse Cihangir, Fabian Oboril, Alois C. Knoll, 4th Workshop on Data-Driven Intelligent Vehicle Applications (DDIVA'23), IEEE Intelligent Vehicles Symposium (IV'23), Anchorage, Alaska, USA
- June 3, 2021 **Walter Zimmer**, Emeç Erçelik, Esra İçer, Neslihan Köse Cihangir, Alois C. Knoll, 3rd Workshop on Data-Driven * equal contribution * httelligent Vehicle Applications (DDIVA'21), IEEE Intelligent Vehicles Symposium (IV'21), Nagoya, Japan

OPEN-SOURCE SOFTWARE PROJECTS

- 🞧 3D BAT: A Semi-Automatic, Web-based 3D Annotation Toolbox for Full-Surround, Multi-Modal Data Streams
- • proCalib: A Calibration Framework for Roadside Sensors
- CARLA dev tools
- • YOLOv7-TRT: A 2D Object Detector for Roadside Sensors
- MonoDet3D: A Monocular 3D Object Detector for Roadside Sensors
- • InfraDet3D: A Multi-modal 3D Object Detection Framework based on Roadside Infrastructure Camera and LiDAR Sensors
- TUM Traffic Dataset Development Kit
- ∘ ♠ CoopDet3D: A Cooperative 3D Object Detector for V2X Perception Systems
- • ActiveAnno3D: An Active Learning Framework for Multi-Modal 3D Object Detection
- • PointCompress3D: A Point Cloud Compression Framework for Roadside LiDARs in Intelligent Transportation Systems
- • AccidentDet3D: Automated Accident Detection for Roadside Sensors

Press (Selected Media Coverage)

English:

- 🖺 AUTOtech.agil: Architectures and Tools for Future Mobility, Newsletter, Issue 1, 2024
- 🔳 Looking Far Ahead and Around Corners with Digital Twins, Research Highlights, Faszination Forschung, page 34-43, 2022
- 🖺 Bavaria: A Testbed for the Future of Mobility, Invest in Bavaria, 23 February 2022

German:

- 🔳 hoch³ die Zeitung der TU Darmstadt. Themenschwerpunkt der Ausgabe: Die Mobilität von morgen: An der TU Darmstadt wird auf Spitzenniveau interdisziplinär zum automatisierten Fahren geforscht, TU Darmstadt, 2024
- Ill Konsortium präsentiert Forschungsergebnisse zur offenen Software- und Hardware-Architektur für das Mobilitätssystem der Zukunft 🔐, RWTH Aachen University, 2024
- 🖺 Eine offene Software- und Hardware-Architektur für zukünftige Fahrzeuge 🕞, RWTH Aachen University, 2023
- · 📳 Weit voraus und um die Ecke schauen mit digitalen Zwillingen, Forschungshighlights, Faszination Forschung, S. 34-43, 2022
- 🖺 Schnell durch den Stau: Intelligente Verkehrssteuerung auf dem Vormarsch, Hessischer Rundfunk, 21 May 2022
- 📳 Daten aus dem realen Verkehr bilden die Basis von Analyse und Simulation, Straßenverkehrstechnik, April 2022
- 🔳 Simulation der Welt mit digitalen Zwillingen, European News Agency, April 29, 2022
- E-Mobilität oder wie bewegen wir uns morgen?, all-electronics, April 26, 2022
- 🔳 Mehr Staus durch selbstfahrende Autos 📭, Handelsblatt, April 19, 2022
- 📳 Forscher geben Datensätze zur Verkehrsoptimierung frei, AutomotivelT, March 1, 2022
- 📳 Künstliche Intelligenz auf dem Prüfstand: Wo stehen wir, wo geht es hin?, SIEMENS Podcast, January, 2022
- ° 🔳 Intelligente Straßen der Zukunft, BR 1, October 27, 2021
- 🖺 Die Straße der Zukunft ist digital, Bayerische Staatszeitung, October 2021
- 🖺 Motion Zweite Ausgabe: Der vernetzte Verkehr, ÖAMTC, October 4, 2021
- 🔳 Dem Verkehr auf der Spur, VDI Nachrichten, August 20, 2021
- III Umfeldsensorik: "Autoindustrie kann nicht weiter auf Ego-Perspektive beharren.", Automobil Industrie, July 20, 202 I
- 🔳 Verkehrsleitsystem mit KI: Jeder, der nicht im Straßenverkehr getötet wird, ist ein enormer Gewinn., Next Mobility, July 2021
- 📳 Vorsehung auf der Bundesstraße 📭, Süddeutsche Zeitung, June 22, 2021
- ° 🖺 Digitaler Schutzengel auf den Straßen 🕞, Münchner Merkur, June 7, 2021
- 📳 🕞 "Digitaler Zwilling im Verkehr", automotivelT, January 2021
- Echtzeitverkehr in der Cloud, Vision Mobility, March 2021
- III TUM erforscht "digitalen Zwilling", VISION mobility, February 3, 2021
- 📳 "Car-to-X-Vernetzung ist das A und O", AutomotivelT, January 21, 2021
- 🖺 Digitale Zwillinge orchestrieren den Verkehr der Zukunft, Huawei Magazin, December 2, 2020
- 🔳 Sensoren und Kameras auf dem digitalen Testfeld Autobahn, Deutschlandfunk Kultur, September 21, 2020
- 📳 🕞 Die Iernende Autobahn, Süddeutsche Zeitung, August 21, 2020
- ° 🖺 Die Straße der Autobahn spricht mit unseren Autos, Die Welt, September 4, 2015





Prof. Dr.-Ing. habil. Alois C. Knoll
Technical Uni. of Munich (TUM)
School of Computation, Information and
Technology (CIT)
Dep. of Computer Engineering (CE)
Chair of Artificial Intelligence

Paltzmannstr. 3, 85748 Garching, Germany

4 +49 (89) 289-18109

Robotics & Real-time Systems

☑ k@tum.de



Prof. Dr. Holger Caesar
Delft University of Technology
Mechanical Engineering Faculty
Dep. of Cognitive Robotics
Intelligent Vehicles Section

Mekelweg 2, 2628 CD, Delft, The Netherlands

431 15 27 82419

☑ H.Caesar@tudelft.nl



Jun.Prof. Dr.-Ing. Alina Roitberg University of Stuttgart Institute for Al, Intelligent Sensing

Universitätsstr. 3270569 Stuttgart, Germany

+49 711 685 88160

and Perception

☑ alina.roitberg@ki.uni-stuttgart.de



Distinguished Prof. Dr. Mohan Trivedi

Jacobs School of Engineering
Dep. of Electrical and Computer Eng. (ECE)
University of California San Diego, (UCSD)
Lab. of Intelligent and Safe Automobiles (LISA)

9500 Gilman Drive, La Jolla CA 92093-0434, USA

+1 858-822-0075

☑ mtrivedi@ucsd.edu



Prof. Dr. Ross Greer

University of California, Merced, (UCM) School of Engineering Department of Computer Science and Engineering (CSE) Laboratory for Machine Intelligence, Interaction, and Imagination (Mi³)

♥ 5200 Lake Road, Merced, CA 95343, USA

L +1 916 8046791

☑ rossgreer@ucmerced.edu



Prof. Dr. Brendan Morris

University of Nevada, Las Vegas Department of Electrical and Computer Engineering (ECE)

◆ 4505 South Maryland Parkway Las Vegas, NV 89154-4026, USA

L +1 702-774-1480

☑ brendan.morris@unlv.edu